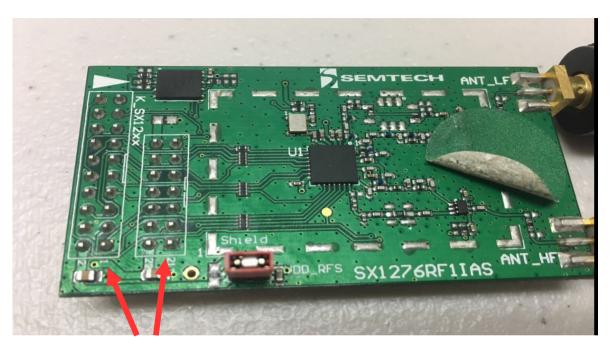
Lora RF Module





Sx1276 SCH	LPC1769 PIN
RFI_LF(P.1)	SCK1
VR_ANA(P.2)	VIO3V3
VBAT1 (P.3)	MOSI1
VR_DIG(P.4)	GND
NRESET(P.7)	SSEL1
DIO0(P.8)	MISO1
DIO2(P.10)	GPIO (P 0.2)
RFO_HF(P.22)	VIO3V3
VBAT2(P.24)	GND
GND(CON_P.32)	GND
VDD_FEM(CON_P.34)	VIO3V3

```
struct wheelsToScale wheelScale:
int main(void) {
     unifiedMotorInit();
     LoRabegin(915000000);
     for (;;) {
           rfcontrollerprocessing();
void rfcontrollerprocessing() {
     packetSize = parsePacket(0);
     if (packetSize) {
           while (available()) {
                 emergencyStop = false;
                 receiveData = read();
                 //printf("%c",receiveData);
                 //Hat Switch control
                 switch (receiveData) {
                 case 'O':
                       AGVStop();
                       isGoingBackwards = false;
                       isGoingForwards = false;
                       break:
                 case 'X':
                 case 'Y':
                 case 'Z':
```

Acknowledgement: Thanks for CTI One Corporation make this code available for Dr. Harry Li for CMPE 245 use.

```
case 'C':
                       AGVStop();
                       isGoingBackwards = false;
                       isGoingForwards = false:
                       emergencyStop = true;
                       trueStart = false:
                       break:
                 case 'A':
                 case 'B':
                 case 'D':
                 case 'E':
                 case 'F':
                       if (!isGoingBackwards) {
                             isGoingForwards = true;
                             if (receiveData == 'A') {
                                   AGVStraightForward(current speed, current speed);
                                   trueStart = true:
                             } else if (receiveData == 'B') {
//
                             speed up by 20% and speed down by 10%
                                   AGVRightTurn(current speed + (current speed * 1 /
5),
                                              current speed - (current speed * 1 / 10));
                                   trueStart = true:
                             } else if (receiveData == 'D') {
                             speed up by 20% and speed down by 10%
//
                                   AGVLeftTurn(current speed - (current speed * 1 / 10),
                                              current speed + (current speed * 1 / 5));
                                   trueStart = true:
```

```
} else if (receiveData == 'E') {
                      if (current speed <= 10 * SPEED SHIFT) //scaling -- Maximum speed will be 30
                            current speed += SPEED SHIFT; //scaling and speeding up
                      if (trueStart)
                            AGVStraightForward(current speed, current speed);
                 } else if (receiveData == 'F') {
                      if (current speed >= SPEED SHIFT)
                            current speed -= SPEED SHIFT;
                      if (current speed < 10)
                            current speed = 10:
                      if (trueStart)
                            AGVStraightForward(current speed, current speed);
           break;
           default:
           //other button
           break:
```

```
* LoRa.c
* Created on: Oct 29, 2016
* LoRa.cpp
  Created on: Oct 29, 2016
#include <stdio.h>
#include <stddef.h>
#include "LoRa.h"
#include "ssp.h"
#include "extint.h"
// registers
#define REG_FIFO
                         0x00
#define REG OP MODE
                             0x01
#define REG FRF MSB
                            0x06
#define REG FRF MID
                           0x07
#define REG FRF LSB
                           80x0
#define REG PA CONFIG
                             0x09
#define REG LNA
                         0x0c
#define REG_FIFO_ADDR_PTR
                               0x0d
#define REG_FIFO_TX_BASE_ADDR_0x0e
#define REG_FIFO_RX_BASE_ADDR_0x0f
#define REG_FIFO_RX_CURRENT_ADDR_0x10
#define REG IRQ FLAGS
                             0x12
#define REG RX NB BYTES
                              0x13
#define REG PKT RSSI VALUE
                                0x1a
#define REG PKT SNR VALUE
                                0x1b
```

```
#define REG MODEM CONFIG 1
                               0x1d
#define REG MODEM CONFIG 2
                               0x1e
#define REG_PREAMBLE_MSB
                              0x20
#define REG PREAMBLE LSB
                             0x21
#define REG PAYLOAD LENGTH
                              0x22
#define REG RSSI WIDEBAND
                             0x2c
#define REG DETECTION OPTIMIZE 0x31
#define REG DETECTION THRESHOLD 0x37
#define REG SYNC WORD
                            0x39
#define REG DIO MAPPING 1
                             0x40
#define REG VERSION
                          0x42
// modes
#define MODE LONG RANGE MODE
                                  0x80
#define MODE SLEEP
                          0x00
#define MODE STDBY
                          0x01
#define MODE TX
                        0x03
#define MODE RX CONTINUOUS
                               0x05
#define MODE RX SINGLE
                            0x06
// PA config
#define PA BOOST
                        0x80
// IRQ masks
#define IRQ TX DONE MASK
                              0x08
#define IRQ PAYLOAD CRC ERROR MASK 0x20
#define IRQ RX DONE MASK
                              0x40
```

```
#define MAX PKT LENGTH
                                   255
           LOW 0
#define
#define HIGH
#define function not required 0
int packetIndex=0;
int implicitHeaderMode=0;
int frequency=0;
#if function not required
void (* onReceive)(int);
#endif
char receiveLora=0:
#if function not required
void onReceivedata(int packetSize) {
 // received a packet
 printf("Received packet ");
 int i=0;
 // read packet
 for (i = 0; i < packetSize; i++) {
  printf("%c\n",(char)read());
 // print RSSI of packet
 print(" with RSSI ",packetRssi());
```

```
void EINT3 IRQHandler(void)
     LPC SC->EXTINT = EINT3;
                                     /* clear interrupt */
     printf("Interrupt triggered\n");
     // Toggle Led On
     //LPC GPIO0->FIOPIN ^= (1<<2);
     handleDio0Rise();
     /*Clear interrupts */
     LPC GPIOINT->IO0IntClr = 0xFFFFFFF;
#endif
void gpioInit()
     // Select P0.2 as GPIO for RESET
     LPC PINCON->PINSEL0 &= ~(3<<4):
     // P0.3 as GPIO
     LPC PINCON->PINSEL0 &= ~(3<<6):
     // P0.2 as output For RESET
     LPC GPIO0->FIODIR |= (1<<2);
     // P0.3 as input For DIO0
     //LPC GPIO0->FIODIR &= ~(1<<3):
     //LPC GPIOINT->IO0IntEnR |= (1<<3);
     //NVIC EnableIRQ(EINT3 IRQn);
```

```
void digitalWrite(uint8 t pin, uint8 t value)
                                                       // set SS high
                                                       CHIP DESELECT():
     printf("Pin : %d, value %d\n",pin,value);
                                                       //digitalWrite( ss, HIGH);
     if(value == 1)
                                                       SSP1Init():
                                                       // start SPI
           LPC GPIO0->FIOPIN |= (1<<pin);
                                                       //SPI.begin();
                                                       // check version
     else if(value == 0)
                                                       version = readRegister(REG_VERSION).
                                                        // printf("Version is %x\n",version);
           LPC GPIO0->FIOPIN &= \sim(1<<pin);
                                                       if (version != 0x12) {
                                                         return 0;
int LoRabegin(long frequency)
                                                       // put in sleep mode
                                                       sleep():
 // setup pins
                                                       // set frequency
     uint8 t version =0;
                                                        setFrequency(frequency);
     int i=0:
                                                       // set base addresses
     gpioInit();
                                                       writeRegister(REG_FIFO_TX_BASE_ADDR, 0);
 // perform reset
                                                       writeRegister(REG FIFO RX BASE ADDR, 0);
 digitalWrite(LORA DEFAULT RESET PIN, LOW);
                                                       // set LNA boost
 for(i=0;i<100000;i++);
                                                       writeRegister(REG_LNA, readRegister(REG_LNA) | 0x03);
 digitalWrite(LORA DEFAULT RESET PIN, HIGH);
                                                       // set output power to 17 dBm
 for(i=0;i<10000000;i++);
                                                       setTxPower(17):
                                                       // put in standby mode
                                                       idle();
                                                       return 1;
```

```
void end()
                                           int LoRaendPacket()
 // put in sleep mode
                                            uint8 t rOut=0;
 sleep();
                                            // put in TX mode
                                            writeRegister(REG_OP_MODE, MODE_LONG_RANGE_MODE | MODE_TX);
 // stop SPI
                                            // wait for TX done
 //SPI.end();
                                            while((readRegister(REG IRQ FLAGS) & IRQ TX DONE MASK) == 0);
                                            // clear IRQ's
                                            writeRegister(REG IRQ FLAGS, IRQ TX DONE MASK);
int LoRabeginPacket(int implicitHeader)
                                            return 1;
 // put in standby mode
 idle();
                                           int parsePacket(int size)
 if (implicitHeader)
                                                int packetLength = 0;
                                                int irgFlags = readRegister(REG_IRQ_FLAGS);
  implicitHeaderMode();
                                                if (size > 0)
 else {
                                                      implicitHeaderMode();
                                                      writeRegister(REG_PAYLOAD_LENGTH, size & 0xff);
  explicitHeaderMode();
                                                else
 // reset FIFO address and paload length
                                                      explicitHeaderMode();
 writeRegister(REG FIFO ADDR PTR, 0);
 writeRegister(REG PAYLOAD LENGTH, 0);
                                                // clear IRQ's
 return 1:
                                                writeRegister(REG_IRQ_FLAGS, irgFlags);
```

```
if ((irgFlags & IRQ RX DONE MASK) && (irgFlags & IRQ PAYLOAD CRC ERROR MASK) == 0)
     // received a packet
     packetIndex = 0:
     // read packet length
     if ( implicitHeaderMode)
          packetLength = readRegister(REG_PAYLOAD_LENGTH);
     else
          packetLength = readRegister(REG_RX_NB_BYTES);
     // set FIFO address to current RX address
     writeRegister(REG_FIFO_ADDR_PTR, readRegister(REG_FIFO_RX_CURRENT_ADDR));
     // put in standby mode
    idle():
else if (readRegister(REG_OP_MODE) != (MODE_LONG_RANGE_MODE | MODE_RX_SINGLE))
    // not currently in RX mode
     // reset FIFO address
     writeRegister(REG_FIFO_ADDR_PTR, 0);
    // put in single RX mode
     writeRegister(REG_OP_MODE, MODE LONG RANGE MODE | MODE RX SINGLE);
return packetLength;
```

```
int packetRssi()
     return (readRegister(REG_PKT_RSSI_VALUE) - (_frequency < 868E6 ? 164 : 157));
float packetSnr()
     return ((int8 t)readRegister(REG_PKT_SNR_VALUE)) * 0.25;
size t writebyte(uint8 t byte)
     return write(&byte, sizeof(byte));
size t write(const uint8 t *buffer, size t size)
     int currentLength = readRegister(REG_PAYLOAD_LENGTH);
     size t i=0;
     // check size
     if ((currentLength + size) > MAX_PKT_LENGTH)
           size = MAX PKT LENGTH - currentLength;
     // write data
     for (i = 0; i < size; i++)
           writeRegister(REG FIFO, buffer[i]);
     // update length
     writeRegister(REG PAYLOAD LENGTH, currentLength + size);
     return size:
```

```
int available()
     return (readRegister(REG_RX_NB_BYTES) - packetIndex);
int read()
     if (!available()) {
           return -1;
     packetIndex++;
     return readRegister(REG_FIFO);
int peek()
     if (!available()) {
           return -1;
     // store current FIFO address
     int currentAddress = readRegister(REG_FIFO_ADDR_PTR);
     // read
     uint8 t b = readRegister(REG_FIFO);
     // restore FIFO address
     writeRegister(REG FIFO ADDR PTR, currentAddress);
     return b:
```

```
void flush()
#if function not required
void onReceive(void(*callback)(int))
     onReceive = callback;
    //writeRegister(REG DIO MAPPING 1, 0x00);
    if (callback)
         writeRegister(REG_DIO_MAPPING_1, 0x00);
         //attachInterrupt(digitalPinToInterrupt(_dio0), onDio0Rise, RISING);
    else
        //detachInterrupt(digitalPinToInterrupt(_dio0));
```

```
void idle()
   writeRegister(REG_OP_MODE, MODE_LONG_RANGE_MODE | MODE_STDBY);
void sleep()
   writeRegister(REG_OP_MODE, MODE_LONG_RANGE_MODE | MODE_SLEEP);
void setTxPower(int level)
    if (level < 2)
       level = 2;
   else if (level > 17)
       level = 17;
    writeRegister(REG_PA_CONFIG, PA_BOOST | (level - 2));
```

```
void setFrequency(long frequency)
     frequency = frequency:
     printf("frequency is %d,%d\n",frequency, frequency);
     uint64_t frf = ((uint64 t)frequency << 19) / 32000000;
     writeRegister(REG_FRF_MSB, (uint8_t)(frf >> 16));
     writeRegister(REG FRF MID, (uint8 t)(frf >> 8));
     writeRegister(REG_FRF_LSB, (uint8_t)(frf >> 0));
void setSpreadingFactor(int sf)
     if (sf < 6)
          sf = 6:
     else if (sf > 12)
          sf = 12:
     if (sf == 6)
          writeRegister(REG_DETECTION_OPTIMIZE, 0xc5);
          writeRegister(REG DETECTION THRESHOLD, 0x0c);
     else
          writeRegister(REG_DETECTION_OPTIMIZE, 0xc3);
          writeRegister(REG DETECTION THRESHOLD, 0x0a);
     writeRegister(REG_MODEM_CONFIG_2, (readRegister(REG_MODEM_CONFIG_2) & 0x0f) | ((sf << 4) & 0xf0));
```

```
void setSignalBandwidth(long sbw)
 int bw;
 if (sbw \leq 7.8E3) {
  bw = 0:
 } else if (sbw <= 10.4E3) {
  bw = 1:
 } else if (sbw <= 15.6E3) {
  bw = 2:
 } else if (sbw <= 20.8E3) {
  bw = 3:
 } else if (sbw <= 31.25E3) {
  bw = 4:
 } else if (sbw <= 41.7E3) {
  bw = 5:
 } else if (sbw <= 62.5E3) {
  bw = 6:
 } else if (sbw <= 125E3) {
  bw = 7;
 } else if (sbw <= 250E3) {
  bw = 8:
 } else /*if (sbw <= 250E3)*/ {
  bw = 9:
 writeRegister(REG MODEM CONFIG 1, (readRegister(REG MODEM CONFIG 1) & 0x0f) | (bw << 4));
```

```
void setCodingRate4(int denominator)
 if (denominator < 5) {
  denominator = 5:
 } else if (denominator > 8) {
  denominator = 8:
 int cr = denominator - 4;
 writeRegister(REG MODEM CONFIG 1, (readRegister(REG MODEM CONFIG 1) & 0xf1) | (cr << 1));
void setPreambleLength(long length)
 writeRegister(REG_PREAMBLE_MSB, (uint8_t)(length >> 8));
 writeRegister(REG PREAMBLE LSB, (uint8 t)(length >> 0));
void setSvncWord(int sw)
 writeRegister(REG SYNC WORD, sw);
```

```
void crc()
 writeRegister(REG_MODEM_CONFIG_2, readRegister(REG_MODEM_CONFIG_2) | 0x04);
void noCrc()
 writeRegister(REG_MODEM_CONFIG_2, readRegister(REG_MODEM_CONFIG_2) & 0xfb);
uint8 t random()
 return readRegister(REG_RSSI_WIDEBAND);
void explicitHeaderMode()
 implicitHeaderMode = 0;
 writeRegister(REG_MODEM_CONFIG_1,
readRegister(REG_MODEM_CONFIG_1) & 0xfe);
```

```
void implicitHeaderMode()
 implicitHeaderMode = 1:
 writeRegister(REG_MODEM_CONFIG_1, readRegister(REG_MODEM_CONFIG_1) | 0x01);
#if function not_required
void handleDio0Rise()
 int irgFlags = readRegister(REG_IRQ_FLAGS);
 int i=0;
 // clear IRQ's
 writeRegister(REG_IRQ_FLAGS, irgFlags);
 if ((irgFlags & IRQ PAYLOAD CRC ERROR MASK) == 0) {
  // received a packet
  packetIndex = 0;
  // read packet length
  int packetLength = implicitHeaderMode ? readRegister(REG_PAYLOAD_LENGTH) :
readRegister(REG RX NB BYTES);
  // set FIFO address to current RX address
  writeRegister(REG_FIFO_ADDR_PTR, readRegister(REG_FIFO_RX_CURRENT_ADDR));
// if ( onReceive) {
     onReceive(packetLength);
  for (i = 0; i < packetLength; i++)
     receiveLora = read();
     printf("Receive data is %c\n",receiveLora);
  // reset FIFO address
  writeRegister(REG_FIFO_ADDR_PTR, 0);
```

#endif

```
uint8 t readRegister(uint8_t address)
 return singleTransfer(address & 0x7f, 0x00);
void writeRegister(uint8 t address, uint8 t value)
    singleTransfer(address | 0x80, value);
uint8 t singleTransfer(uint8 t address, uint8 t value)
 uint8 t response=0;
 //digitalWrite(_ss, LOW);
 CHIP SELECT();
 //SPI.beginTransaction(_spiSettings);
 response = ssp1Transfer(address);
 //printf("response %x\n",response);
 response = ssp1Transfer(value);
 //printf("response %x\n",response);
 CHIP DESELECT();
 //digitalWrite( ss, HIGH);
 return response;
```

```
#if function_not_required
void onDio0Rise()
{
    handleDio0Rise();
}
#endif
Harry Li, Ph.D.
```