

$$= \frac{e^{z_1}}{\sum_{j=1}^{10} e^{z_j}} + \frac{e^{z_2}}{\sum_{j=1}^{10} e^{z_j}} + \dots + \frac{e^{z_{10}}}{\sum_{j=1}^{10} e^{z_j}}$$

$$= \frac{\sum_{j=1}^{10} e^{z_j}}{\sum_{j=1}^{10} e^{z_j}} = 1. \quad \dots (b)$$

The softmax function takes as input a vector z of K real numbers, and normalizes it into a probability distribution consisting of K probabilities proportional to the exponentials of

$$f(z_i) = \frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

See
Eqn (b).

Now, move to the 2nd Half of
DCNN.

2022F-108a-Yolo-architecture-loss-function-2022-10-10.pdf

Typical Classification/
Recognition Results
are in Bounding Boxes

<https://arxiv.org/pdf/1506.02640v5.pdf>

S Divvala, Ross Girshick, Ali Farhadi
Allen Institute for AI, Facebook AI Research <http://pjreddie.com/yolo/>

Joseph Redmon*, Santosh Divvala[†], Ross Girshick*, Ali Farhadi[†]
University of Washington*, Allen Institute for AI[†], Facebook AI Research*
<http://pjreddie.com/yolo/>

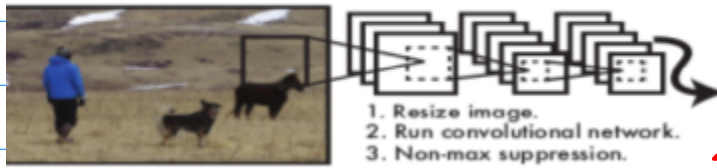


Figure 1: The YOLO Detection System. (1) resizes the input image to 448×448 , (2) runs a convolutional network, and (3) thresholds the resulting confidence scores.

YOLO runs at 45 FPS. A smaller version, Fast YOLO, runs astounding 155 FPS. It performs DPM (deformable parts models) and R-CNN.

Then, we would like to Achieve
Semantic Segmentation.

Pixel by pixel
Based Segmentation/
Detection/
Recognition



PART II (After the midterm)

April 4 (Tue)

Roadmap: Yolo (You-Only-Look-ONCE)

Semantic Segmentation.

Project Assignment to be Implemented
Due 2½ weeks. April 20th.
(Thursday)

CMPE258

Spring 2023

Homework (In-Class Presentation)
Requirements Due April 6 (Thu).

1° One Paragraph Description (Abstract)
of the proposed Semester-Long
Project.

2° Title

Team members : First Name,
Last Name,
Major

Team Coordinator.
Contact E-mail.

3° Abstract Part.

Objective(s) : a) What is the
proposed work;

b) What is the coding / training /
Testing Task involved in
the project ?

c) Anticipated Result ?
And deliverable ?

d) Tools, platform, programming
Language Version, T.F.,

Pytorch, ChatGPT etc.

Also, Define Python Packages,

OpenCV.

Example: On Yolo.

Ref:

2022F-106-README-Tiny-Yolo4-GP...

Note 1: ³⁴Readme for Yolo github
Installation & Testing.
for the
project.

Title: README Tiny Yolo v4 GPU Ubuntu

Document Number: 105-1b

CTI One Corporation

Table 1a. Document History

2022-10-6	Establish this document, document archive: (base) harry@workstation:~/yolo-2022-10-19\$	YY
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1. Setup YOLO v4 environment

1.1. Clone the GitHub folder;

\$ git clone https://github.com/pythonlessons/TensorFlow-2.x-YOLOv3.git

1.2. Create YAML file for building the YOLO v4 Anaconda environment;

Create TensorFlow-2.x-YOLOv3/conda-gpu.yml as the following;

=====

name: yolo4-gpu

Ref: Introduction

2022F-108a-Yolo-architecture-loss-function-2022-10-10.pdf

Base-Line Ref for Yolo Technique

2022S-112-yolo-paper.pdf

You Only Look Once:
Unified, Real-Time Object Detection

Joseph Redmon*, Santosh Divvala*[†], Ross Girshick[¶], Ali Farhadi*[†]

University of Washington*, Allen Institute for AI[†], Facebook AI Research[¶]

<http://pjreddie.com/yolo/>

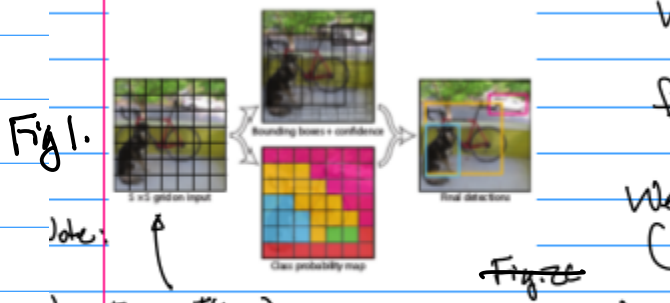
Lecture Notes: Base Line Ref/Requirements.

2022F-101-cmpe 258-note-2022-11-1.pdf

Example: Notations for Yolo.
Ref, pp 36.

CMPE258
Oct. 13, 22

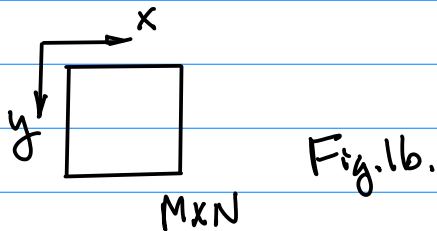
2. Bounding Boxes $B_{ij}(x, y) \dots (z)$
 i for x -direction, j for y -direction



1. Image $I(x, y)$ is divided into $S \times S$ Grids.
Denote it as $G_{p,q}(x, y), \dots (i)$
where $p, q = 0, 1, 2, \dots$ indicate the

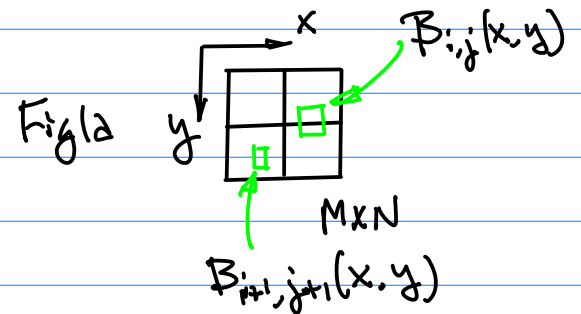
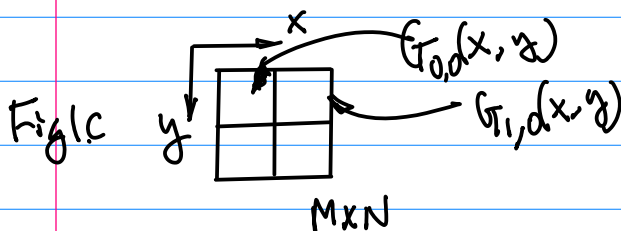
1. Image $I(x, y)$. with Resolution

$M \times N$
No. of Col. No. of Rows.



Divide $I(x, y)$ into $S \times S$ Grids.
Each Grid is Denoted as

$G(x, y) \dots (i)$
 p, q matches to x
Where $p, q = 0, 1, 2, \dots, S-1$



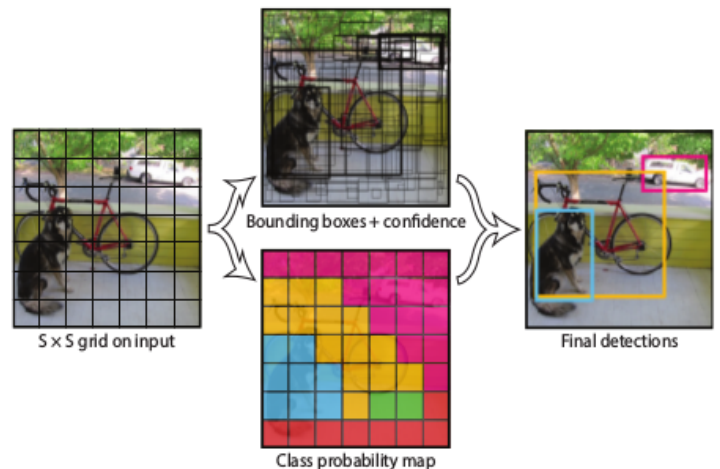
3. Five Parameters to define each Bounding Box.

(x, y) : Location of the top Left Corner of $B_{ij}(x, y)$

w, h : Width and Height of $B_{ij}(x, y)$

f : Confidence level, Probability distribution to Describe the likelihood of the B.B. (B^2) belongs to a certain Class of objects.

$(x, y, w, h, f) \dots (3)$



Note 1. α . $\text{Grid}(x, y)$ Grid.

Figure 2: The Model. Our system models detection as a regression problem. It divides the image into an $S \times S$ grid and for each grid cell predicts B bounding boxes, confidence for those boxes, and C class probabilities. These predictions are encoded as an $S \times S \times (B * 5 + C)$ tensor.

$b, B_{ij}(x, y)$ Class probability.
 $c, (x, y, w, h, f)$ Probability
 Confidence.