CmpE258 Spring 2023 (Part III) 1/

April 20 (Thursday).

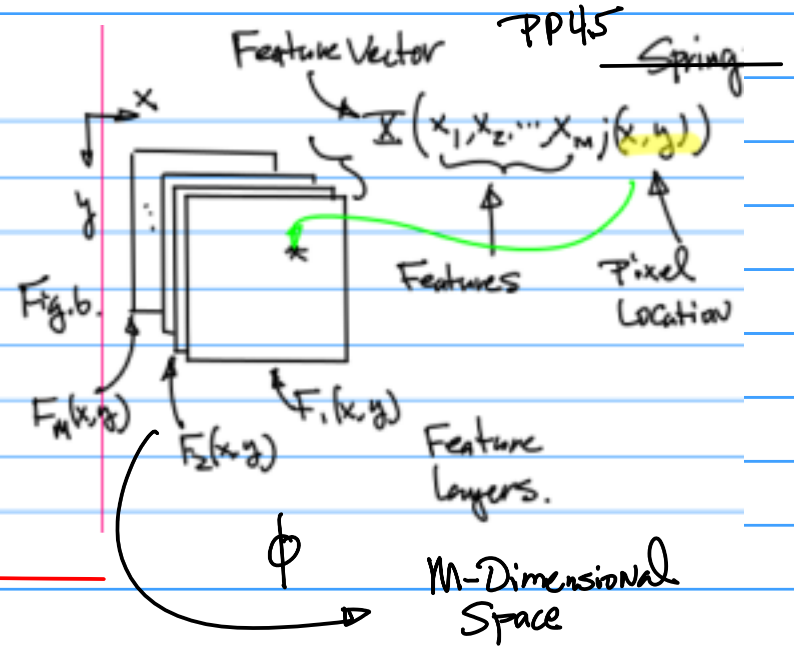
Note 1. Final Exam.

Cluster Analysis. "Mapping"

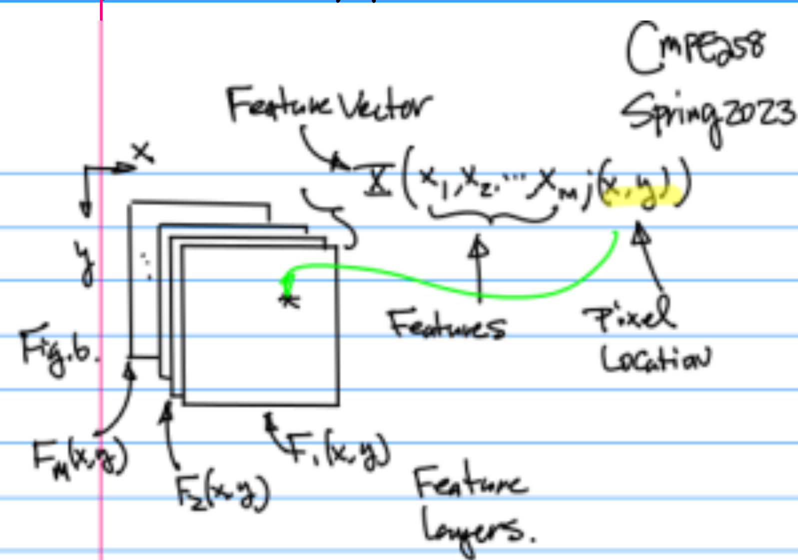
Group II Classes

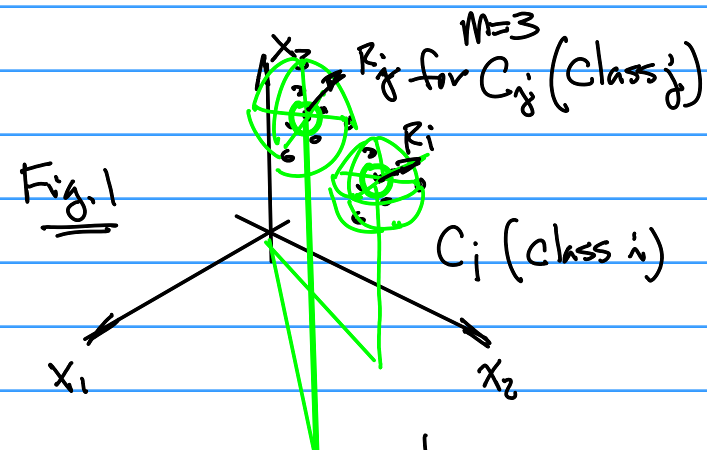
Group II classes are those classes which meet TR, T, R, TWR, MTR, TRF, MTI MTWR, TWRF, RF, TF, TRS.

Regular Class Start Times	Final Examination Days	Final Examination
7:00 through 8:25 AM	Monday, May 22	7:15-9:30 AM
8:30 through 9:25 AM	Wednesday, May 17	7:15-9:30 AM
9:30 through 10:25 AM	Friday, May 19	9:45 AM-12:00 PM
10:30 through 11:25 AM	Tuesday, May 23	9:45 AM-12:00 PM
11:30 AM through 12:25 PM	Thursday, May 18	9:45 AM-12:00 PM
12:30 through 1:25 PM	Monday, May 22	12:15-2:30 PM
1:30 through 2:25 PM	Wednesday, May 17	12:15-2:30 PM
2:30 through 3:25 PM	Friday, May 19	2:45-5:00 PM
3:30 through 4:25 PM*	Tuesday, May 23	2:45-5:00 PM
4:30* through 5:25 PM*	Thursday, May 18	2:45-5:00 PM



From Notes Part II, pp.45



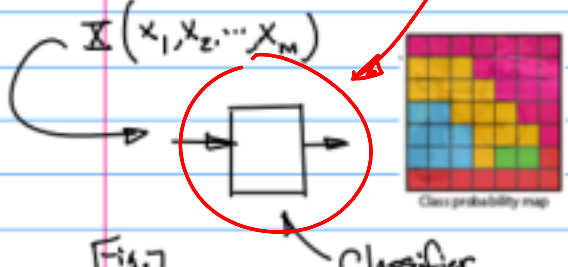


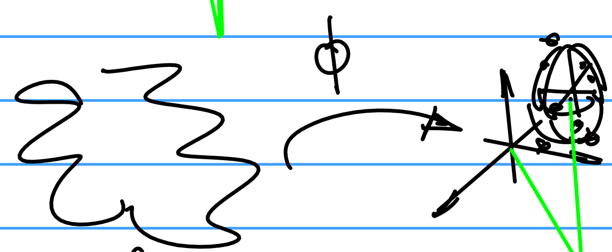
$X(x_1, x_2, \cdots x_M; (x,y))$

$\downarrow$

$X(x_1, x_2, \cdots x_M)$

Cluster Analysis Technique.





$X(x_1, x_2, \cdots, x_N)$

$I(x,y) \rightarrow$ Feature $\xrightarrow{\phi}$ Classification

pixel(s) $\quad X(x_1, x_2, \cdots, x_N) \quad C_i$

Prob(C_i)

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(II.)

2/

Note: $\sum_{i=1}^{N} \text{Prob}(C_i) = 1$ (Previously M)

Number of Classes.

from "Heurestics" Expert Knowledge.

Consider K-mean Cluster Algorithm.

github.

2022S-114c-Kmean-handCalculation...

2022S-114c-KmeanCluster-v3-2022-... PPT

Example: K-mean Cluster Algorithm.

First, Notation. Note 1. Vectors

Given a set of observations $(\mathbf{x}_1, \mathbf{x}_2, \ldots, \mathbf{x}_n)$,

e.g. $\underline{X}_1 = (x_{11}, x_{12}, \cdots, x_{1N})$ ...(1)

first observation

For $\underbrace{\underline{X}_i}_{\text{Observation } i}$ $\quad x_{ij}$

Component j for the Observation i

Note: if for d-dimensional Vector, then Eqn(1) has its $N = d$

K-mean partition the n observations into k ($\leq n$) sets $\mathbf{S} = \{S_1, S_2, \ldots, S_k\}$ ...(2)

$\{\underline{X}_i \mid i = 1, 2, \cdots, N\}$

K-Classes.

S_i for Class i

Note 1. Note 2 Squared Distance

$$\underset{\mathbf{S}}{\arg\min} \sum_{i=1}^{k} \sum_{\mathbf{x} \in S_i} \|\mathbf{x} - \boldsymbol{\mu}_i\|^2 = \underset{\mathbf{S}}{\arg\min} \sum_{i=1}^{k} |S_i| \operatorname{Var} S_i \quad \ldots(3)$$

a. "Argmin" minimization

b. "S" Domain, "Scope" of the minimization

Example for $\|\vec{x} - \vec{\mu}_i\|^2$,

if $\vec{x} = (x_1, x_2)$, $\vec{\mu}_i = (\mu_{i1}, \mu_{i2})$

then

$$\|\vec{x} - \vec{\mu}_i\|^2 = \left(\sqrt{(x_1 - \mu_{i1})^2 + (x_2 - \mu_{i2})^2}\right)^2$$

$$= (x_1 - \mu_{i1})^2 + (x_2 - \mu_{i2})^2 \quad \ldots(4)$$

Note 3. "$\sum_{x \in S_i}$" Notation $\sum_{i=1}^{M} x_i$

Summation for each & every x as Long as it is from the set S_i

Note 4: from Eqn(3), we have

S_i : Collection of Vectors $\underline{X}$ belonging to Class i

Note 5: $\sum_{i=1}^{k} \to$ to Cover the Collection of all Classes.

Note 6: $\vec{\mu}_i$ ① $\vec{\mu}_i = (\mu_{i1}, \mu_{i2}, \cdots, \mu_{id})$

② Cluster for the Class i

April 25 (Tue)

Note 1. Quick update on Project Progress Report. (Next Lecture)

Example: Continuation of K-mean Cluster Algorithm.

$$S_i^{(t)} = \{x_p : \|x_p - m_i^{(t)}\|^2 \le \|x_p - m_j^{(t)}\|^2 \ \forall j, 1 \le j \le k\}$$

... (1)

Ref

20225-114c-Kmean-handCalculation1-c

Note 1: A set of Feature Vectors

$S_i^{(t)}$ ← Captured at step t; i ← Class id: ith Class

$S_i^{(t)} = \{ \vec{X}_p \quad \}$

index, p = 1, 2, ...

just like Notation i, j, or k

$S_i^{(t)} = \{ \vec{X}_p : \quad \}$

Condition

$\| \vec{X}_p - \vec{m}_i^{(t)} \|^2$

Distance (squared) at time (t) to the Cluster of class i

$\| \vec{X}_p - \vec{m}_j^{(t)} \|^2$

... ... to the Cluster class j

" $\forall j$ " for Any j, such as

$1 \le j \le k$ covers all the different classes.

Hand Calculation Example

Given the following feature vectors use K-mean Algorithm to find the clusters.

$X_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $X_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $X_3 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $X_4 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$X_5 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ $X_6 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ $X_7 = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$ $X_8 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$

$X_9 = \begin{pmatrix} 6 \\ 6 \end{pmatrix}$ $X_{10} = \begin{pmatrix} 7 \\ 6 \end{pmatrix}$ $X_{11} = \begin{pmatrix} 8 \\ 6 \end{pmatrix}$ $X_{12} = \begin{pmatrix} 6 \\ 7 \end{pmatrix}$

$X_{13} = \begin{pmatrix} 7 \\ 7 \end{pmatrix}$ $X_{14} = \begin{pmatrix} 8 \\ 7 \end{pmatrix}$ $X_{15} = \begin{pmatrix} 9 \\ 7 \end{pmatrix}$ $X_{16} = \begin{pmatrix} 7 \\ 8 \end{pmatrix}$

$X_{17} = \begin{pmatrix} 8 \\ 8 \end{pmatrix}$ $X_{18} = \begin{pmatrix} 9 \\ 8 \end{pmatrix}$ $X_{19} = \begin{pmatrix} 8 \\ 9 \end{pmatrix}$ $X_{20} = \begin{pmatrix} 9 \\ 9 \end{pmatrix}$

Sol: Step 1. Define K=2 per Heuristics. Expert Knowledge

Note: "0" Initial step.

Let cluster

$\vec{m}_1^0 = \vec{X}_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ ... (1)

$\vec{m}_2^0 = \vec{X}_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ ... (2)

Initial Arbitrary Values

"1" Class 1

And Arbitrarily assign Feature Vectors into 2 Classes.

Step 2. Use Eqn (1) To Compute the distance

$\| \vec{X}_p - \vec{m}_i^{(t)} \|^2$

and $\| \vec{X}_p - \vec{m}_j^{(t)} \|^2$

To Evaluate the Grouping of $\vec{X}_p$ to the Class i per Eqn (1).

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If Eqn(1) holds good, then $\vec{X}_p$ Stays in the Class i.
O/w Re-assign $\vec{X}_p$ to the Class j.

Step 3. Update the Cluster (when New Grouping is formed)

$$m_1^{(t)}\Big|_{t=1} = \frac{1}{N} \sum_{\vec{X}_p \in S_1} \vec{X}_p$$

$\vec{X}_j$

$$m_i^{(t+1)} = \frac{1}{|S_i^{(t)}|} \sum_{x_j \in S_i^{(t)}} x_j \quad \ldots (2)$$

Total Number of Feature Vectors in the Class i

Step 4. Carry out the Computation with the New Cluster.
(To Decide if the grouping is final or to Continue updating Cluster Values)

Note: "Stop" if No Regrouping
O/W. Continue By Repeating the process, e.g. update Cluster Values, the Evaluate the grouping.

Step 5. Perform the Computation as Described in Step 4. which Leads to

C_1 (Class 1): $S_1 = \{\vec{X}_1, \vec{X}_2, \cdots, \vec{X}_8\}$

$S_2 = \{\vec{X}_9, \vec{X}_{10}, \cdots, \vec{X}_{20}\}$

then, update the Cluster $\vec{m}_1^{(t)}, \vec{m}_2^{(t)}$.

↓

Check. No New Grouping

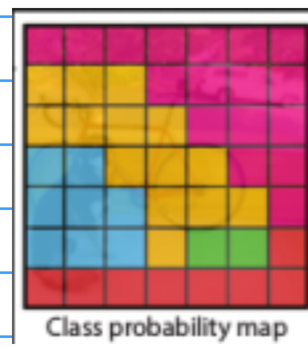
↓

$\vec{m}_1^{(t+1)}, \vec{m}_2^{(t+1)}$ are the same.

∴ Stop. (Converged).

Discussion On Probability Distribution map.

(a)



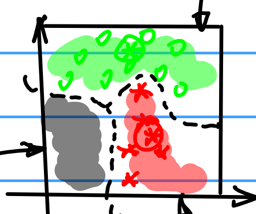
Feature Vector map.

(b)

Boundary for the Classification

Regular K-mean Cluster Algorithm

(c)



C_3

C_1

C_2

Fig. 1

$$\text{Prob}(C_1) \stackrel{?}{=} \frac{\text{Area of Black Pixels}}{\text{Area of } \Omega \text{ (Image Plane)}} \quad \ldots (3a)$$

where Area of Black Pixels can be computed.

Area of Ω(Image Plane) = Resolution of the image plane.

For Example, 448x448

Similarly, find

$$Prob(C_2) = \frac{\text{Area of Red Pixels}}{\text{Area of } \Omega(\text{Image Plane})} \quad \ldots (3b)$$

$$Prob(C_3) = \frac{\text{Area of green Pixels}}{\text{Area of } \Omega(\text{Image Plane})} \quad \ldots (3c)$$

then

$$\sum_{i=1}^{N} \Big|_{N=3} Prob(C_i) = 1 \quad \ldots (4)$$

Since

$$\sum_{i=1}^{3} Prob(C_i) = Prob(C_1) + Prob(C_2) + Prob(C_3) \quad \ldots (4\text{-}b)$$

$$= \frac{\text{Area of Black Pixels}}{\text{Area of } \Omega(\text{Image Plane})} + \frac{\text{Area of Red Pixels}}{\text{Area of } \Omega(\text{Image Plane})} + \frac{\text{Area of green Pixels}}{\text{Area of } \Omega(\text{Image Plane})}$$

$$= \frac{\text{Area of } \Omega(\text{Image Plane})}{\text{Area of } \Omega(\text{Image Plane})} = 1.$$

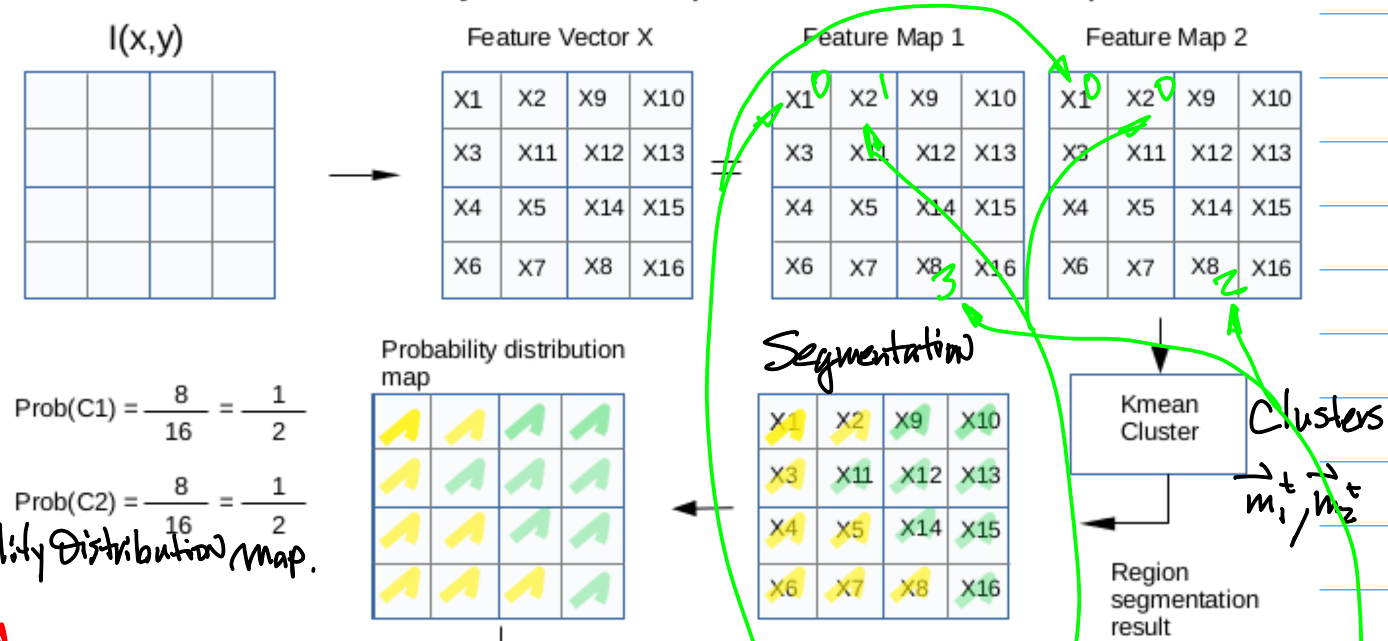
//

(The following Notes were added After the Class After Recovering from the Laptop Computer Shut down. For Additional lecture Notes Check the Class Zoom Recording).

2022S-114c-Kmean-prob-map-hl-2023-4-26.pdf

Step 1. Feature Vectors

Probability Distribution Map and Kmean Cluster Technique



From Probability Distribution Map.

Prob(Ci) = Prob(Ci/Obj) Prob(Obj) ... (1)
Prob(Ci/Obj) = Prob(Ci) / Prob(Obj) ... (2)

Application Example: Given ROI_i(x,y) with feature vector X, find it Prob(Ci/Obj) = ? by using equation (2)

Harry Li, Ph.D., SJSU

$X_1=\begin{bmatrix}0\\0\end{bmatrix}$ $X_2=\begin{bmatrix}1\\0\end{bmatrix}$ $X_3=\begin{bmatrix}0\\1\end{bmatrix}$ $X_4=\begin{bmatrix}1\\1\end{bmatrix}$

$X_5=\begin{bmatrix}2\\1\end{bmatrix}$ $X_6=\begin{bmatrix}1\\2\end{bmatrix}$ $X_7=\begin{bmatrix}2\\2\end{bmatrix}$ $X_8=\begin{bmatrix}3\\2\end{bmatrix}$

$X_9=\begin{bmatrix}6\\6\end{bmatrix}$ $X_{10}=\begin{bmatrix}7\\6\end{bmatrix}$ $X_{11}=\begin{bmatrix}8\\6\end{bmatrix}$ $X_{12}=\begin{bmatrix}6\\7\end{bmatrix}$

$X_{13}=\begin{bmatrix}7\\7\end{bmatrix}$ $X_{14}=\begin{bmatrix}8\\7\end{bmatrix}$ $X_{15}=\begin{bmatrix}9\\7\end{bmatrix}$ $X_{16}=\begin{bmatrix}7\\8\end{bmatrix}$

$X_{17}=\begin{bmatrix}8\\8\end{bmatrix}$ $X_{18}=\begin{bmatrix}9\\8\end{bmatrix}$ $X_{19}=\begin{bmatrix}8\\9\end{bmatrix}$ $X_{20}=\begin{bmatrix}9\\9\end{bmatrix}$

Objective: To find the Probability of an Detected object Belonging to Class i.

Requirements: 1° Hand Calculation of K-mean Cluster Algorithm;

2° Use K-mean Algorithm to Perform Image Segmentation, then Find Probability Distribution Map.

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Note1: Loss function Composition: $f_{Loss} = \sum_{i=1}^{K} \lambda_i f_{Loss,i}$ ...(1)

where $\sum_{i=1}^{K} \lambda_i = 1$.

No. of Bounding Boxes on a grid S

Entire Image

$$\lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^{B} \mathbb{1}_{ij}^{\text{obj}} \left[(x_i - \hat{x}_i)^2 + (y_i - \hat{y}_i)^2 \right]$$ Location

$$+ \lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^{B} \mathbb{1}_{ij}^{\text{obj}} \left[\left(\sqrt{w_i} - \sqrt{\hat{w}_i} \right)^2 + \left(\sqrt{h_i} - \sqrt{\hat{h}_i} \right)^2 \right]$$ Shape

$$+ \sum_{i=0}^{S^2} \sum_{j=0}^{B} \mathbb{1}_{ij}^{\text{obj}} \left(C_i - \hat{C}_i \right)^2$$ ← Confidence

λ'

$$+ \lambda_{\text{noobj}} \sum_{i=0}^{S^2} \sum_{j=0}^{B} \mathbb{1}_{ij}^{\text{noobj}} \left(C_i - \hat{C}_i \right)^2$$

$$+ \sum_{i=0}^{S^2} \mathbb{1}_{i}^{\text{obj}} \sum_{c \in \text{classes}} (p_i(c) - \hat{p}_i(c))^2$$ Probability Distribution

λ''

Note2:

Unit function

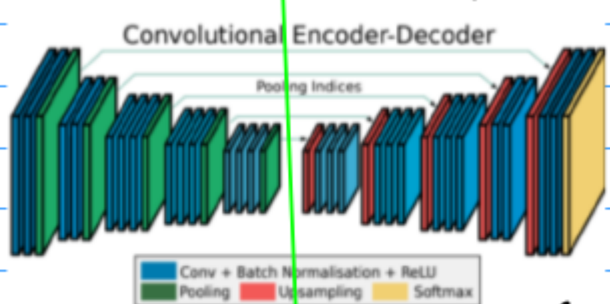
$\mathbb{1}_{ij}^{obj} = \begin{cases} 1 & \text{if Object exists} \\ 0 & \text{o/w} \end{cases}$ ...(2)

Location 50%, Shape 20%, ... etc.

Semantic Segmentation

2022F-109-semantic-seg-part1-HL-2022- ← Ref: PPT.

pp52 Fig.3



Deep Convolutional Neural Network:

Encoder:

Feature Extraction — Convolutions

Classification — Feedforward NN

Decoder: Target Pixel by pixel Recognition of Object

May 2nd (Tue)

Example: Super Sampling. A Technique to project Lower Resolution Feature Map/Image to A Higher Resolution Feature/Image.

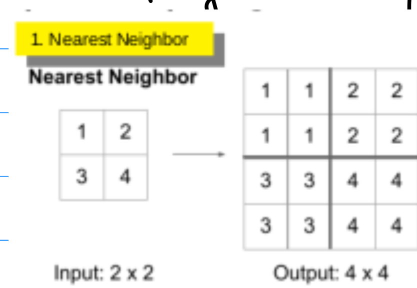
Ref: PPT. pp3.

2022F-109-semantic-seg-part1-HL-2022-11-10.pdf

Notes & Examples. pp53

2022F-101-cmpe258-note-part2-2022-12-6.pdf

Techniques 1° Nearest Neighbor Technique



Bi-Linear Interpolation Technique

Step 1. Project "Anchor" Points

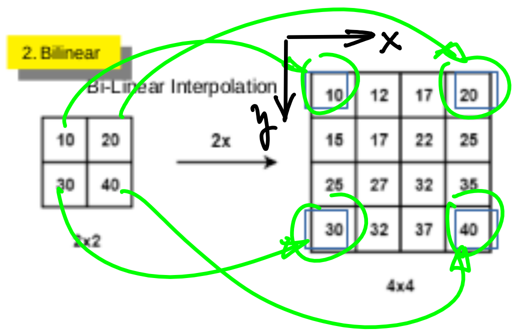


Fig. 1

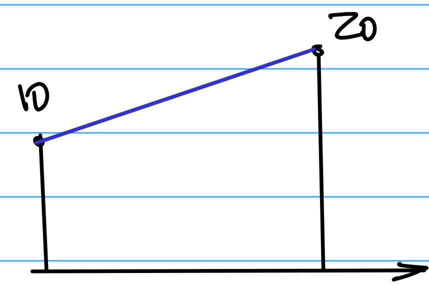


Fig. 2-c

Step 2. Bi-Linear Interpolation with 4 Anchor Points to fill up the rest of the feature points.

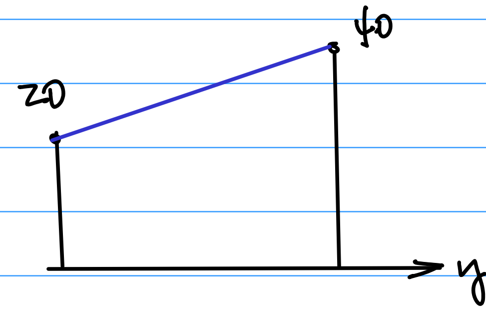


Fig. 2-d

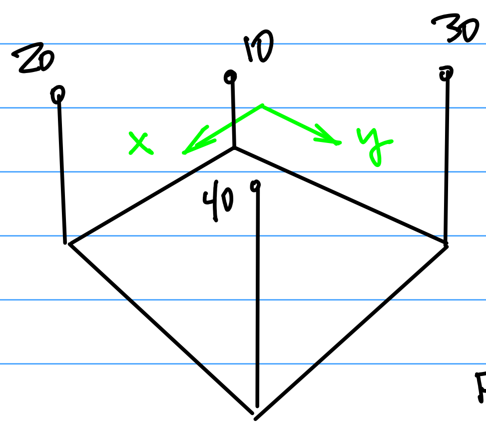


Fig. 2-a

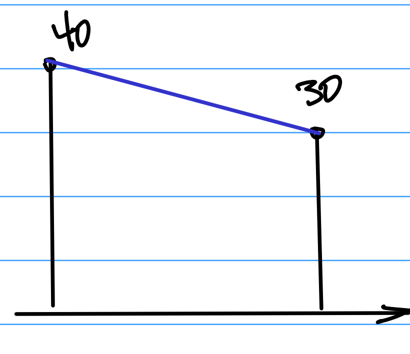
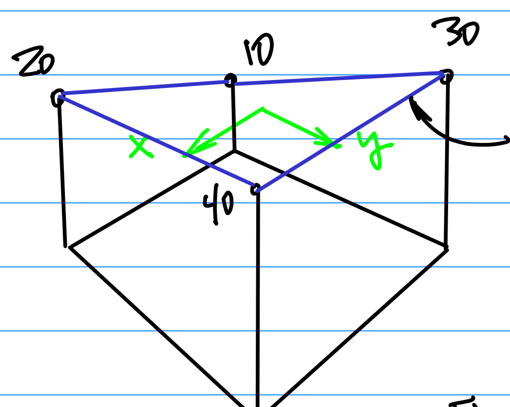


Fig. 2-e

"Right Hand" System



Straight Line

↓

Linear

↓

$y = ax + b$ ... (1)

Fig. 2-b

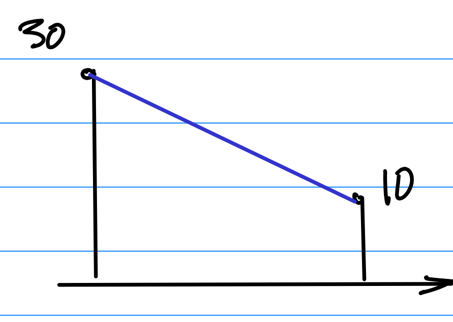


Fig. 2-f

From Fig. 2-C ~ Fig. 2-e,

The Interpolation is performed Linear W.r.t. x Variable; that is the 1st Linear Interpolation;

From Fig 2d ~ 2f,

The Interpolation is performed Linear W.r.t. y Variable; that is the 2nd Linear Interpolation;

Hen[ce] ... we ... ion.

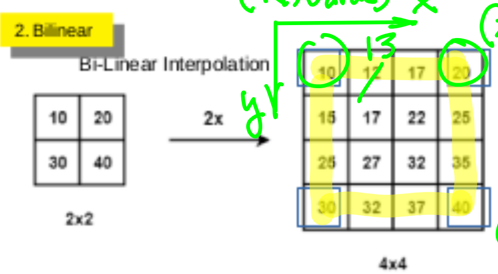


Fig.3
pp53

Background: Given (x_1, y_1), (x_2, y_2) and x_3, Find $y_3 = ?$

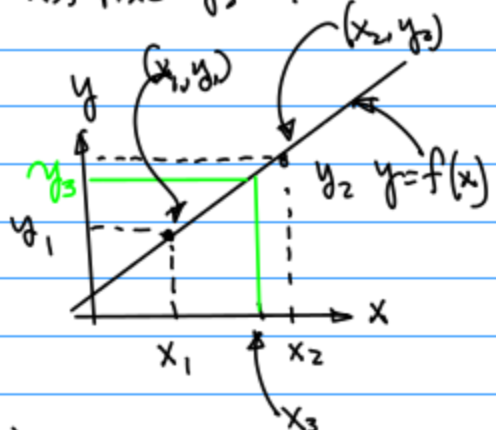


Fig.7

$y = f(x)$, $y = ax + b$ ... (1)

which is a linear function, (since x is Not in 2nd, 3rd, or higher order).

$$\frac{y_2 - y_1}{x_2 - x_1} = \frac{y - y_1}{x - x_1} \quad \text{... (2)}$$

Solve for a and b in the Above equation

$$y - y_1 = \frac{y_2 - y_1}{x_2 - x_1}(x - x_1)$$

$$y = \underbrace{\frac{y_2 - y_1}{x_2 - x_1}}_{a} x \underbrace{- \frac{y_2 - y_1}{x_2 - x_1} x_1 + y_1}_{b} \quad \text{... (3)}$$

$$a = \frac{y_2 - y_1}{x_2 - x_1} \quad \text{... (3-b)}$$

$$b = -\frac{y_2 - y_1}{x_2 - x_1} x_1 + y_1 \quad \text{... (3-c)}$$

Note: $y = ax + b$. whose a & b are derived in Eqn (3), (3-b) (3-c).

Example: Hand Calculation, pp55

From the given Condition

Coordinate, Feature Value

$(x_1, y_1) = (0, 10)$ See Fig.5-b.

$(x_2, y_2) = (3, 20)$

Hence $a = \frac{y_2 - y_1}{x_2 - x_1} = \frac{20 - 10}{3 - 0} = 10/3$

and

$$b = -\frac{y_2 - y_1}{x_2 - x_1} x_1 + y_1$$

$$= -\frac{20 - 10}{3 - 0} \cdot 0 + 10 = 10$$

Therefore, from Eqn (3), we have

$$y = ax + b = \frac{10}{3} \cdot x + 10 \Big|_{x=1} = \frac{10}{3} + 10$$

$$\cong 3.3 + 10 = 13.$$

Please Carry out the Calculation for the Next Feature Value using the Same Linear interpolation w.r.t. x.

Now, consider the 2nd Linear Interpolation w.r.t y.

From Ref. pp 55

$(x_1, y_1) = (0, 10)$

$(x_2, y_2) = (\cancel{0}\ 3, 30)$

Feature Value (Function) from the feature map.

Independent Variable → "y"

Along the y-axis of the feature map.

Then use Eqn (3-b) & (3-c) to find slope a and offset b; as follows

$$a = \frac{30-10}{3-0} = 20/3$$

From Ref. pp.55

y_2' y_1'

$$b = -\frac{y_2-y_1}{x_2-x_1}x_1 + y_1$$

$$= -\frac{30-10}{3-0}\cdot y_1' + 10 \Big|_{y_1'=0}$$

$$= 10$$

Therefore, we have

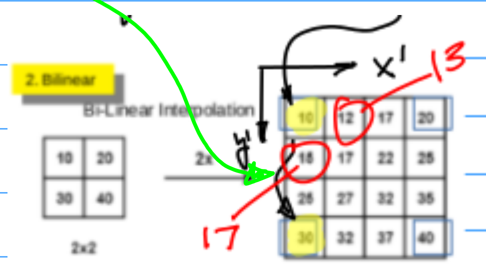
pp55

$$y = ax + b$$

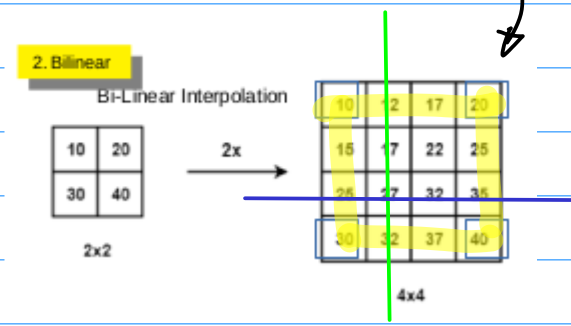
$$= 20/3 \cdot x + 10 = 20/3 \cdot y' + 10$$

$$\simeq 17$$

see the illustration below.



Carry out the calculations, we can have all boundary points fixed as illustrated below



then, for the interior