



105-1-Camsvr2-testing-hl-2020-2-26.odp

CTI One Corporation

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https://github.com/hualili/robotics-open_abb/tree/master/ai-embedded

/media/harry/easystore/backup-2020-2-15/CTI0/3proejcts/3-8-smart-tech/3-8-4-huaYuan/3-8-4-6-products/CAMSVR-3-8-4-6-1/manufacturing-camsvr3-8-4-6-1/camsvr-pack/105-testing\$

Company confidential



CAMSVR2 From the Packaging Box

华源智能



CAMSVR2



Power unit:
12V, 2 A

CAMSVR2 Testing Set Up

- 1 Set up CAMSVR2 and have its power cable and URAT/RS232 cable which is in CAT5 cable (ethernet cable) with RJ45 connector , we call this cable 1, this cable installed on CAMSVR2. CAMSVR2 now in the test is set as UART/RS232 client



- 2 Set up laptop computer (1) with putty or minicom for linux OS, hyperterminal for windows. (2) then have USB-to-serial cable, we call this cable2, and make this cable plug into laptop, which is then set as UART/RS232 host. (3) then perform loop back test of the UART/RS232 host as described in the following slides.



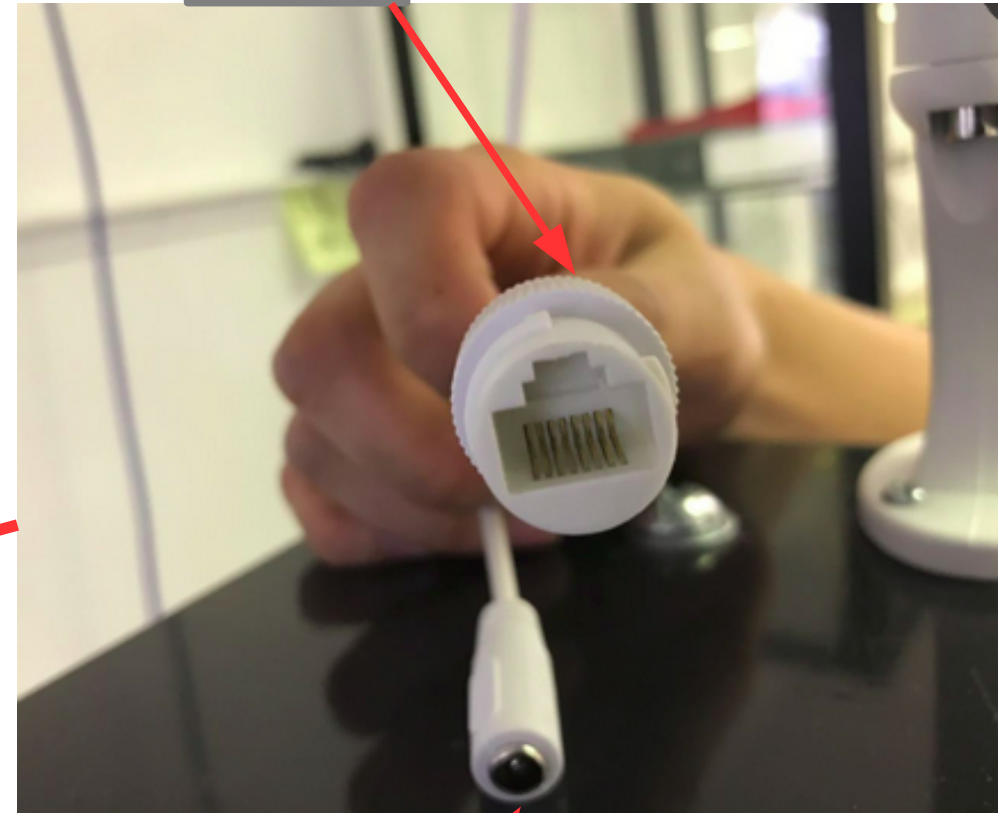
USB-to-serial cable



USB-to-serial cable

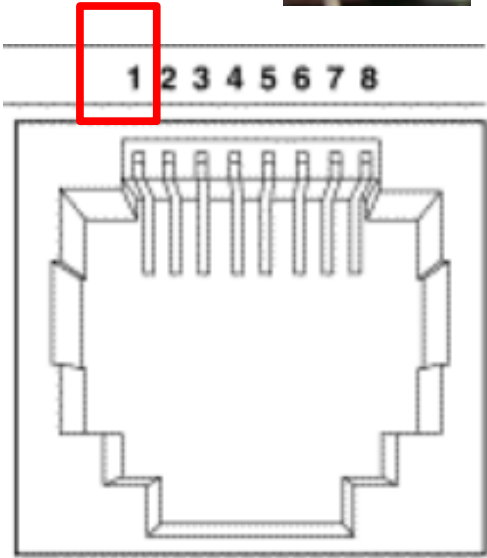
Cable 1 and 2

- 1 Set up CAMSVR2 URAT/RS232 cable is in CAT5 cable (ethernet cable) with RJ45 connector.
- 2 CAMSVR2 cable 2 is power cable see the figure to the right.



cable 2

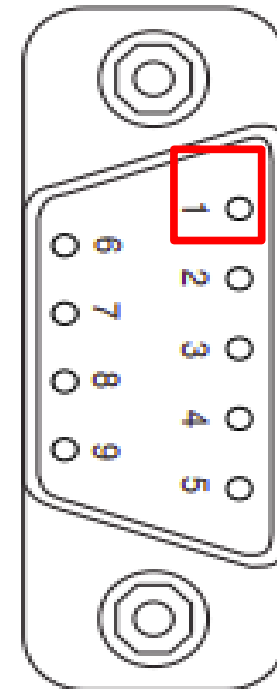
Pin Assignment



RJ45 Female Pin Connectivity

PIN
1
2
3 GND
4
5
6 TX (to Laptop Rx)
7
8 RX (from Laptop Tx)

DB9 Male Connector from USB-to-Serial Cable for Laptop connection



PIN
1
2 RX
3 TX
4
5 GND
6
7
8
9





Pin Connectivity for Communication Test



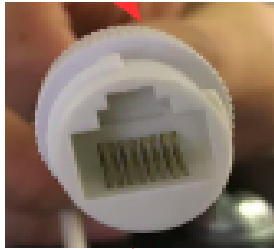
RJ45-CAMSVR2		DB9-Laptop
PIN		PIN
1	GND	5
2		
3		
4		
5	TX (to Laptop Rx)	2
6		
7	RX (from Laptop Tx)	3
8		





UART/RS232 Testing Set Up

CAMSVR-1



Laptop



RS232 Setting: (1) Start putty on the linux laptop, and set baud rate 115200, 8N1, no parity checking; (2) then run the program on linux laptop,



CAMSVR Intrusion Detection

Step 1: Connect the hardware as shown in the previous slide.

Step 2: Plug Power adapter to CAMSVR-2.

Step 3: Run the program “Illegal_Intrusion.py” on the laptop.

Step 4: Verify if the UART connection is set up. By those message shown on Figure 1 below.

Step 5: The “Illegal_Intrusion.py” program will send back a Image received from CAMSVR-2.

Step 6: Users use mouse click to click 2 points to select a Region of Interest.

Step 7: After the Region of Interest is set, whenever there is an illegal intrusion action occur inside that region, an Illegal Intrusion Image is sent from CAMSVR-2 to host/laptop to inform users about the intrusion (as shown in Figures 3)

```
Received: hello N10001 is here  
Sent: H001 copied N10001  
Received: N10001 copied, now sending image N10001-2020-02-20.jpg  
Sent: H001 copied N10001-2020-02-20.jpg
```

Fig1. UART Handshake Message



Fig2.
image_received.jpg
Illegal Intrusion



END