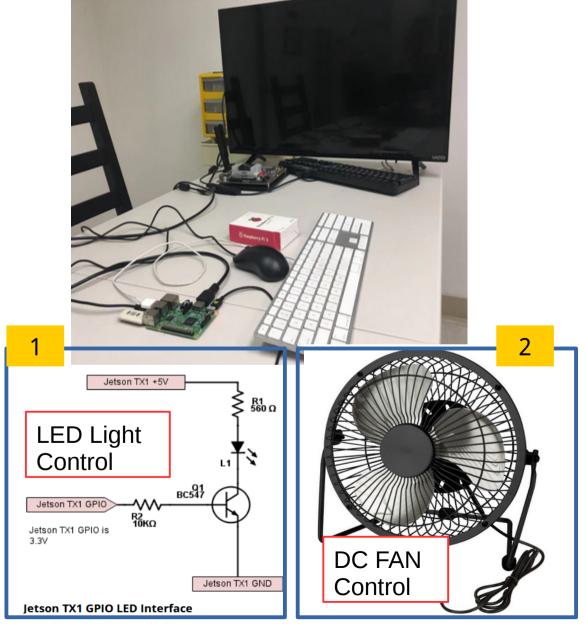
Python For Hands-on Lab 1A

СТІ

Sensor Interface, LED and Fan Control

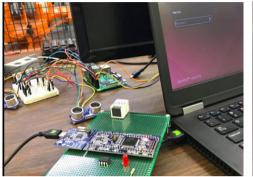
... Date: Feb 2019; Coded by: HL sample raspberry pie GPIO code #import the GPIO and time package import RPi.GPIO as GPIO import time print('-----') print(GPIO.RPI INFO) GPIO.setmode(GPIO.BOARD) **GPIO.cleanup()** Boardpin = 8 GPIO.setup(Boardpin, GPIO.OUT) # loop 5 times, on/off for 1 second for i in range(5): print('GPIO testing program',i) GPIO.output(Boardpin,GPIO.HIGH) time.sleep(1) GPIO.output(Boardpin,GPIO.LOW) time.sleep(1) GPIO.cleanup() print('End')



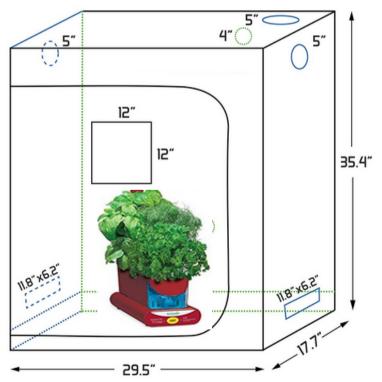


Python For Hands-on Lab 1B

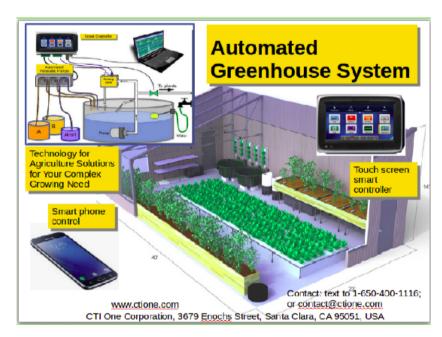
Program and Build Hydroponic System

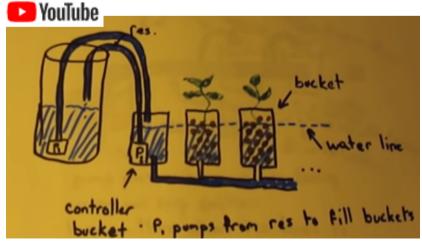






 $https://www.amazon.com/dp/B079DM1WCW/ref=sspa_dk_detail_5? \\ psc=1&pd_rd_i=B079DM1WCW&pd_rd_w=lesbr&pf_rd_p=8a8f3917-7900-4ce8-ad90-adf0d53c0985&pd_rd_wg=vJnEW&pf_rd_r=PBK6TB7X6QMNE226V53E&pd_rd_r=c3d1febb-7865-11e9-825e-f767610a7f33$





Python Hands-on Lab 2

Computer Vision and Digits Recognition

```
# capture frames from a camera

cap = cv2.VideoCapture(0)

while(1):

ret, frame = cap.read()

cv2.namedWindow("Original", cv2.WINDOW_NORMAL)

cv2.imshow('Original',frame)

gray_frame = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

edges = cv2.Canny(gray_frame,5,80)

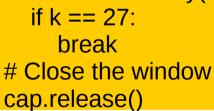
cv2.namedWindow("Edges", cv2.WINDOW_NORMAL)

cv2.imshow('Edges',edges)

# Wait for Esc key to stop

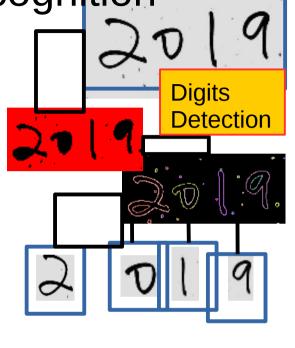
k = cv2.waitKey(5) & 0xFF

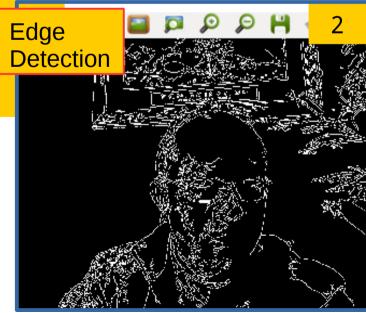
if k == 27:
```







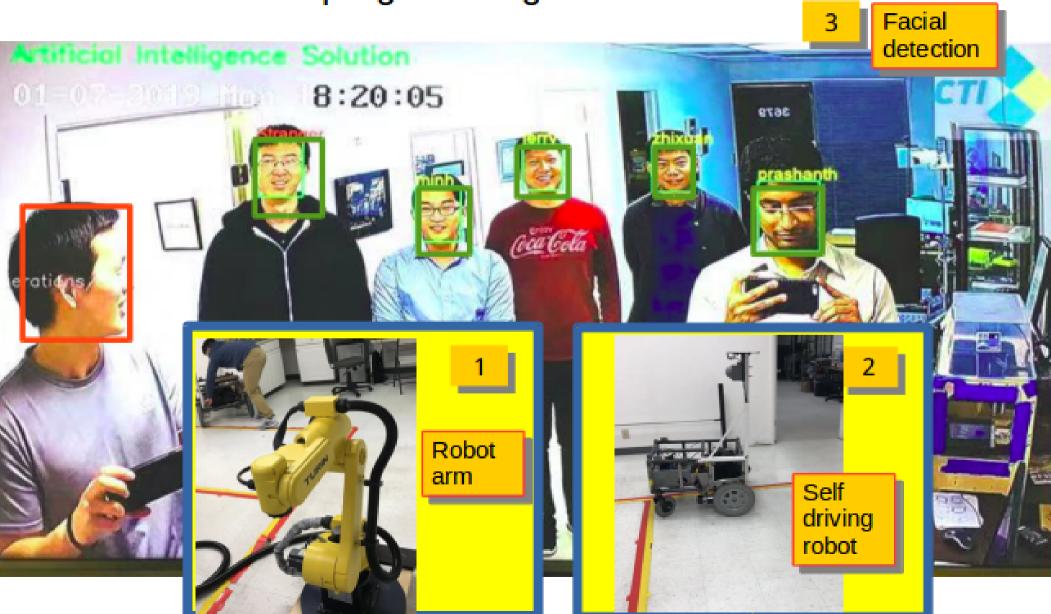




Programming Lab 3



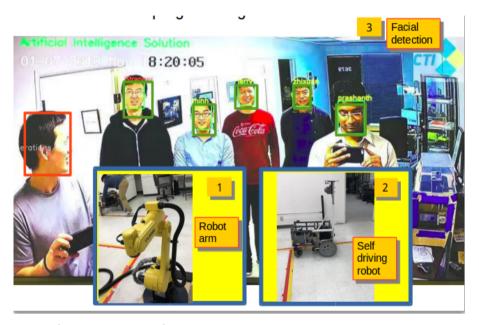
Chose one: Facial Recognition, Program Self Driving or programming robot arm



Programming Python and C++



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InT



Al and Tensor Flow



https://www.youtube.com/watch?v=XaFMGwP2rUw

Self Driving Robot



https://www.youtub e.com/watch? v=b3jGiEywa3w



https://www.youtube.com/watch?v=XRoqdKsWoAw



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