

Lab 8 Documentation

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EE 104

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Abstract

This lab uses Python to build a CNN in order to classify different animals and objects. To practice GUI programming another game was made.

Objective

The objective of this lab is to apply neural network modeling concepts and Python methods learned in lecture to increase the accuracy of a CNN classifying animals and objects. Another fun objective of the lab is to continue practicing GUI programming with the creation of another game, Balloon Flight!

References

Dr. Christopher Pham's Module 8 Lectures & Code

Coding Games In Python

& its Python Games Resource Pack: Chapter 8 Balloon Flight

Instructions/Documentation

Do ensure that the following python modules are installed and imported:

For CNN

(Was ran on Colab, not needed to install anything, but in case you need to install:)

```
import tensorflow as tf
```

```
from tensorflow import keras
```

```
from tensorflow.keras import datasets, layers, models
```

```
import matplotlib.pyplot as plt
```

```
import numpy as np
```

For the game, Balloon Flight!

```
pip install pgzero on command line
```

```
import pgzrun

from pgzero.builtins import Actor

from random import randint
```

CNN Classifier

Added data augmentation layers, multitude of other layers and dropout layer of 30%

```
4 # augmentation
data_augmentation = keras.Sequential(
    [
        layers.RandomFlip("horizontal",
                           input_shape=(32,
                                         32,
                                         3)),
        layers.RandomRotation(0.1),
    ]
)

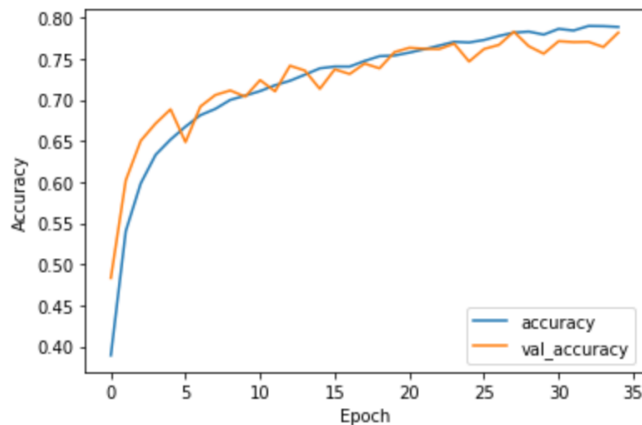
model = models.Sequential()
model.add(data_augmentation)
model.add(layers.Conv2D(64, (3, 3), input_shape=(32, 32, 3)))
model.add(layers.Conv2D(64, (3, 3)))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(128, (3, 3), activation='relu'))
model.add(layers.Conv2D(128, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(256, (3, 3), activation='relu'))
model.add(layers.Conv2D(256, (3, 3), activation='relu'))
```

```
▶ model.add(layers.Dropout(0.3))
model.add(layers.Flatten())
model.add(layers.Dense(128, activation='relu'))
model.add(layers.Dense(10))
```

▼ Evaluate the model

```
✓ [13] plt.plot(history.history['accuracy'], label='accuracy')  
2s    plt.plot(history.history['val_accuracy'], label = 'val_accuracy')  
      plt.xlabel('Epoch')  
      plt.ylabel('Accuracy')  
      plt.legend(loc='lower right')  
  
      test_loss, test_acc = model.evaluate(test_images, test_labels, verbose=2)
```

313/313 - 1s - loss: 1.3372 - accuracy: 0.6215 - 1s/epoch - 3ms/step



val_accuracy: 0.7903

```
▶ airplane_url = "https://upload.wikimedia.org/wikipedia/commons/thumb/f/f0/Another_Airplane%21_%28467  
airplane_path = tf.keras.utils.get_file('Blue_airplane', origin=airplane_url)  
  
img = tf.keras.utils.load_img(  
    airplane_path, target_size=(32, 32)  
)  
img_array = tf.keras.utils.img_to_array(img)  
img_array = tf.expand_dims(img_array, 0) # Create a batch  
  
predictions = model.predict(img_array)  
score = tf.nn.softmax(predictions[0])  
  
print(  
    "This image most likely belongs to {} with a {:.2f} percent confidence."  
    .format(class_names[np.argmax(score)], 100 * np.max(score))  
)
```

▶ This image most likely belongs to airplane with a 100.00 percent confidence.

```

▶ automobile_url = "https://sniteartmuseum.nd.edu/assets/166204/original/ferrari.jpg"
  automobile_path = tf.keras.utils.get_file('Red_automobile', origin=automobile_url)

  img = tf.keras.utils.load_img(
      automobile_path, target_size=(32, 32)
  )
  img_array = tf.keras.utils.img_to_array(img)
  img_array = tf.expand_dims(img_array, 0) # Create a batch

  predictions = model.predict(img_array)
  score = tf.nn.softmax(predictions[0])

  print(
      "This image most likely belongs to {} with a {:.2f} percent confidence."
      .format(class_names[np.argmax(score)], 100 * np.max(score))
  )

```

Downloading data from <https://sniteartmuseum.nd.edu/assets/166204/original/ferrari.jpg>
 98304/96948 [=====] - 0s 2us/step
 106496/96948 [=====] - 0s 2us/step
 This image most likely belongs to automobile with a 100.00 percent confidence.

```

[22] horse_url = "https://upload.wikimedia.org/wikipedia/commons/0/03/American_quarter_horse.jpg"
  horse_path = tf.keras.utils.get_file('Brown_horse', origin=horse_url)

  img = tf.keras.utils.load_img(
      horse_path, target_size=(32, 32)
  )
  img_array = tf.keras.utils.img_to_array(img)
  img_array = tf.expand_dims(img_array, 0) # Create a batch

  predictions = model.predict(img_array)
  score = tf.nn.softmax(predictions[0])

  print(
      "This image most likely belongs to {} with a {:.2f} percent confidence."
      .format(class_names[np.argmax(score)], 100 * np.max(score))
  )

```

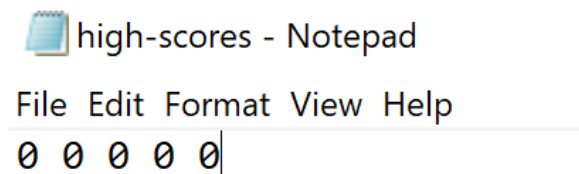
Downloading data from https://upload.wikimedia.org/wikipedia/commons/0/03/American_quarter_horse.jpg
 2547712/2543247 [=====] - 0s 0us/step
 2555904/2543247 [=====] - 0s 0us/step
 This image most likely belongs to horse with a 100.00 percent confidence.

Game Development – Balloon Flight!

It's a beautiful day for a balloon flight! Steer your hot air balloon to keep you and your passengers safe in this game. 5 new features were added to the initial sample code provided by Chapter 8 Balloon Flight tutorial from *Coding Games in Python*:

- More High Scores: Stats for high scores have been adjusted to allow top 5 high scores.
- Speed Up: The bird obstacle has been sped up by 2.
- Different Way to Score: Initial scoring process was inefficient. Once the user's balloon passes an obstacle, it immediately increments the score instead of waiting for the obstacle to leave the screen.
- Space Out: The tree obstacle and house obstacles are spaced out. The bird is already spaced out due to its much faster speed.
- A Little More Room: For more mobility, the balloon's top is now allowed to go off screen a little (but not too much).

To implement More High Scores, adjust the high-scores text file to 5 numbers instead of 3.



Don't forget to make sure the filename's pathway is correctly directed to the high-scores file in the folder.

```
39 def update_high_scores():
40     global score, scores
41     filename = (r'C:\Users\lingt\OneDrive\Documents\EE104\Lab 8\Chapter 8 Balloon Flight\high-scores.txt')
```

Additional flags to handle identifying when balloon passes the three different obstacles were added in line 34 through 37 of the code.

```

10
11 # define actors
12 balloon = Actor('balloon')
13 balloon.pos = 400, 300
14
15 bird = Actor('bird-up')
16 bird.pos = randint(800, 1600), randint(10, 200)
17
18 house = Actor('house')
19 house.pos = randint(800, 1600), 460
20
21 tree = Actor('tree')
22 tree.pos = randint(800, 1600), 450
23
24 # define flags
25 bird_up = True
26 up = False
27 game_over = False
28 score = 0
29 number_of_updates = 0
30
31 # for score keeping
32 scores = []
33
34 # to flag midpoints for incrementing score
35 birdPassedMidpoint = False
36 housePassedMidpoint = False
37 treePassedMidpoint = False
38

```

All other changes to sample code is in `update()`. The global variables are updated to include the added flags. The if statement starting in line 110 shows how an obstacle passing the balloon's flag is handled. If an obstacle passes the balloon without being hit (is less than 400), then it is marked True and the score is incremented. Line 113 shows that the bird is sped up by 2 (initially the variable was 4, now it is 6). When an obstacle gets off the screen, the flag is reset to False (example in line 120). The tree and house are spaced out with the if statement starting in line 145. The if statement checks if the tree has been assigned a value within ± 200 of the house. It spaces out the tree by 500 from the house if it is too close to the house. Lastly, line 149 was adjusted to allow some mobility room for the top of the balloon to go off the screen a little without making the player lose.

```

100
101 def update():
102     global game_over, score, number_of_updates
103     # flags for objects passing the balloon/midpoint
104     global birdPassedMidpoint, housePassedMidpoint, treePassedMidpoint
105     if not game_over:
106         if not up:
107             balloon.y += GRAVITY_STRENGTH # gravity
108         if bird.x > 0:
109             # case statement to increment score if balloon passes bird
110             if bird.x < 400 and birdPassedMidpoint == False:
111                 score += 1
112                 birdPassedMidpoint = True #flags midpoint
113             bird.x -= 6 # + 2 speed
114             if number_of_updates == 9:
115                 flap()
116                 number_of_updates = 0
117             else:
118                 number_of_updates += 1
119         else:
120             birdPassedMidpoint = False #resets midpoint flag
121             bird.x = randint(800, 1600)
122             bird.y = randint(10, 200)
123             number_of_updates = 0
124
125         if house.right > 0:
126             # case statement to increment score if balloon passes house
127             if house.x < 400 and housePassedMidpoint == False:
128                 score += 1
129                 housePassedMidpoint = True #flags midpoint
130             house.x -= 2
131         else:
132             housePassedMidpoint = False #resets midpoint flag
133             house.x = randint(800, 1600)
134
135         if tree.right > 0:
136             # case statement to increment score if balloon passes tree
137             if tree.x < 400 and treePassedMidpoint == False:
138                 score += 1
139                 treePassedMidpoint = True #flags midpoint
140             tree.x -= 2
141         else:
142             treePassedMidpoint = False #resets midpoint flag
143             tree.x = randint(800, 1600)
144             # if tree is within 200 from house
145             if tree.x < house.x + 200 and tree.x > house.x - 200:
146                 tree.x = house.x + 500 # space out tree from house by 500
147
148         #adjusted so top of balloon can go off screen a little for more mobility
149         if balloon.top < -100 or balloon.bottom > 560:
150             game_over = True
151             update_high_scores()
152
153         if (balloon.collidepoint(bird.x, bird.y) or
154             balloon.collidepoint(house.x, house.y) or
155             balloon.collidepoint(tree.x, tree.y)):
156             game_over = True
157             update_high_scores()
158

```