

# **Bayesian Networks**

# **Knowledge Representation**

- Andreas Sauter
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- (Content adapted from Erman Acar)



### Overview

#### 1. Foundations

Degrees of Belief, Belief Dynamics, Independence, Bayes Theorem, Marginalization

### 2. Bayesian Networks

Graphs and their Independencies, Bayesian Networks, d-Separation

#### 3. Tools for Inference

Factors, Variable Elimination, Elimination Order, Interaction Graphs, Graph pruning

### 4. Exact Inference in Bayesian Networks

Posterior Marginal, Maximum – A-Posteriori, Most Probable Explanation



Lecture 4: Exact Inference in Bayesian Networks

# **Lecture Overview**

# **Posterior Marginals**

Joint Marginal, Normalization, Computation

# **More About Factors**

Maximizing-Out, Extended Factors

# Most Likely Instantiations

Maximum A-Posteriori, Most Probable Explanation, Computation



**Computing Posterior Marginals** 

### Definition

We already saw how we can compute the prior marginal Pr(Q) with  $Q \subseteq V$  via variable elimination.

Now we want to compute the distribution over Q given some evidence e via variable elimination

This is called the posterior marginal Pr(Q|e).

E.g.:  $Pr(Alarm = true \mid Earthquake = True)$ 

Note that the prior marginal is just a special case of the posterior marginal where the evidence is empty.



# Approach

Recall that  $\Pr(A|B) = \frac{\Pr(A \land B)}{\Pr(B)}$ , hence we can compute the posterior marginal through normalizing the joint marginal.

So for query variables Q and evidence e we compute  $Pr(Q|e) = \frac{Pr(Q \land e)}{Pr(e)}$ 

### The overall approach is then as follows:

- Reduce all factors w.r.t. e
- Compute the joint marginal  $Pr(Q \land e)$
- Sum-out Q to obtain Pr(e)
- Compute  $Pr(Q|e) = \frac{Pr(Q \land e)}{Pr(e)}$

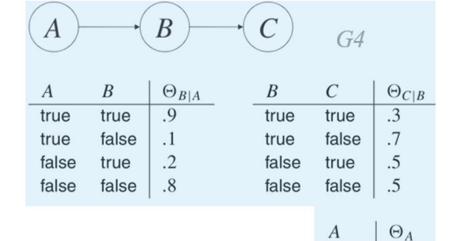


# Example

$$Q = \{C\}, e = \{A = true\}$$

$$Pr(Q \land e) = \Sigma_{A,B} (\Theta_A \Theta_{B|A} \Theta_{C|B})^e$$

$$= \Sigma_{A,B} \Theta_A^e \Theta_{B|A}^e \Theta_{C|B}^e$$



First, reduce all factors w.r.t. A = true:

				B	C	$\Theta_{C B}^{\mathbf{e}}$
$A \mid \Theta_{A}^{\mathbf{e}}$	A	B	$\Theta_{B A}^{\mathbf{e}}$	true	true	.3
I A	true	true	.9	true	false	.7
true   .6	true	false	.1	false	true	.5
			,	false	false	.5

Then we pick an ordering, say, first A then B resulting in  $\Pr(Q \land e) = \Sigma_B \Theta_{C|B}^e \Sigma_A \Theta_A^e \Theta_{B|A}^e$ 



.6

true

false

# Example – Continued

## So given

					В	C	$\Theta_{C B}^{\mathbf{e}}$
Δ	$\Theta^{\mathbf{e}}$	A	B	$\Theta_{B A}^{\mathbf{e}}$	true	true	.3
true	A	true	true	.9	true	false	.7
true	.6	true	false	.1	false	true	.5
					false	false	.5

We can compute  $\Pr(Q \land e) = \Sigma_B \Theta_{C|B}^e \Sigma_A \Theta_A^e \Theta_{B|A}^e$  via variable elimination.

A	B	$\Theta_A^{\mathbf{e}} \Theta_{B A}^{\mathbf{e}}$	B	$\sum_{A} \Theta_{A}^{\mathbf{e}} \Theta_{B A}^{\mathbf{e}}$	B	C	$\Theta_{C B}^{\mathbf{e}} \sum_{A} \Theta_{A}^{\mathbf{e}} \Theta_{B A}^{\mathbf{e}}$		
true	true	.54	true	.54	true	true	.162	C	$\sum_{B} \Theta_{C B}^{\mathbf{e}} \sum_{A} \Theta_{A}^{\mathbf{e}} \Theta_{B A}^{\mathbf{e}}$
true	false	.06	false	.06	true	false	.378	true	.192
					false	true	.030	false	.408
					false	false	.030		

Now, we can sum-out C to obtain Pr(e), for normalizing to obtain  $Pr(Q \mid e)$ :

$$Pr(a) = 0.6, Pr(c|a) = \frac{Pr(c \land a)}{Pr(a)} = \frac{0.192}{0.6} = 0.32, Pr(\neg c|a) = \frac{Pr(\neg c \land a)}{Pr(a)} = \frac{0.408}{0.6} = 0.68$$



# **More About Factors**

# Maximising-Out – Introduction

# Before we saw how to eliminate a variable by summing it out:

В	C	D	$f_1$				
true	true	true	.95				
true	true	false	.05		B	C	$\sum_{D} f_1$
true	false	true	.9	Sum-out D	true	true	1
true	false	false	.1		true	false	1
false	true	true	.8		false	true	1
false	true	false	.2		false	false	1
false	false	true	0				
false	false	false	1				

For some applications, we want to only keep the instantiation with the maximum

probability:

B	C	D	$f_1$				
true	true	true	.95				
true	true	false	.05		B	C	$\max_{D} f_1$
true	false	true	.9	max-out D	true	true	.95
true	false	false	.1		true	false	.9
false	true	true	.8		false	true	.8
false	true	false	.2		false	false	1
false	false	true	0				
false	false	false	1				



# Maximizing-Out – Formalization

Given a factor f over variables X maximizing-out  $X \in X$  results in a new factor  $(\max_X f)(Y) \stackrel{\text{def}}{=} \max_X f(X, Y)$  over variables  $Y = X \setminus X$ .

For an instantiation 
$$y$$
 of  $Y$ ,  $(\max_{X} f)(y) \stackrel{\text{def}}{=} \max(f(x,y), f(\neg x,y))$ 

Maximizing out is commutative:

$$\max_{X} \max_{Y} f = \max_{Y} \max_{X} f$$

If  $f_1$ ,  $f_2$  are factors and if variable X only appears in factor  $f_2$  then:

$$\max_{X} f_1 f_2 = f_1 \max_{X} f_2$$



### **Extended Factors**

When we maximize-out on normal factors, we lose the information on which instantiation maximized the probability.

With extended factors, we can keep this information which is necessary for certain queries.

For every maxed-out instantiation, the extended factor assigns a probability and the instantiation which led to the maximization:

B	C	D	$f_1$
true	true	true	.95
true	true	false	.05
true	false	true	.9
true	false	false	.1
false	true	true	.8
false	true	false	.2
false	false	true	0
false	false	false	1

max-out D

В	C	$\max_{D} f_1$
true	true	.95, D=true
true	false	.9, D=true
false	true	.8, D=true
false	false	1, D=false



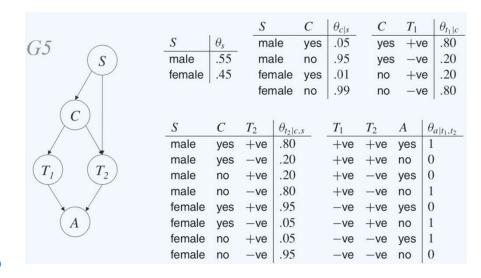
Most Likely Instantiations

### Introduction

Example: S=sex, C=has condition,  $T_1$ ,  $T_2$ = Test results 1 and 2, A= tests agree.

We want to investigate 4 groups: Female\male that have the condition or not.

Query: Given we only know that the the tests agree for a person (A=true), which group does this person belong to?



In other words: what is the most likely instantiation of S and C given A=true?



### Maximum A-Posteriori Query

Given a BN over variables V query variables  $Q \subseteq V$ , and an evidence e the maximum a-posteriori query (MAP) gives us the instantiation  $argmax_Q \Pr(Q, e)$  with a probability of  $\max_Q \Pr(Q, e)$ .

We can do this by first computing Pr(Q, e) with variable elimination as before and then maximizing-out Q using extended factors.

In our example with  $Q = \{S, C\}, e = \{A = true\}$ , we get a MAP with S=male, C=no with a probability of 0.49.



# Most Probable Explanation

Often we are interested in the MAP of all variables except the evidence.

We call a MAP a most probable explanation (MPE), if  $Q = V \setminus E$ , where E is the set of variables of the evidence.

We can compute it by maximizing-out all variables with extended factors.

In general, MPE is easier to compute that MAP. Hence, MPE is sometimes used to approximate MAP, but they might disagree.



# Example 1 – MPE

I	$\Theta_I$	J	$\Theta_J$
true	.5	true	.5
false	.5	false	.5

J	Y	$\Theta_{Y J}$
true	true	.01
true	false	.99
false	true	.99
false	false	.01

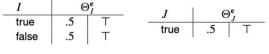
What is the MPE given J=true, O=false.

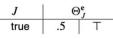
So we have to compute  $MPE(e) = \max_{v} (\Theta_I^e \Theta_J^e \Theta_{Y|J}^e \Theta_{X|I,J}^e \Theta_{O|X,Y}^e)$ 

I	J	$\boldsymbol{X}$	$\Theta_{X IJ}$
true	true	true	.95
true	true	false	.05
true	false	true	.05
true	false	false	.95
false	true	true	.05
false	true	false	.95
false	false	true	.05
false	false	false	.95

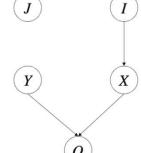
$\boldsymbol{X}$	Y	0	$\Theta_{O XY}$
true	true	true	.98
true	true	false	.02
true	false	true	.98
true	false	false	.02
false	true	true	.98
false	true	false	.02
false	false	true	.02
false	false	false	.98

We start by doing network pruning, resulting in:

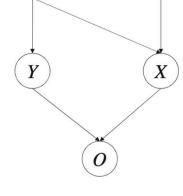




Y	$\Theta_Y^{\mathbf{e}}$			
true	.01	Т		
false	.99	T		



I	$\boldsymbol{X}$	$\Theta_{\lambda}^{e}$		$\boldsymbol{X}$	Y	0	$\Theta_O^e$	XY
true	true	.95	T	true	true	false	.02	Т
true	false	.05	Т	true	false	false	.02	T
false	true	.05	Т	false	true	false	.02	T
false	false	.95	Т	false	false	false	.98	T





# Example 1 - Continued

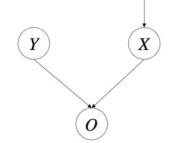
$$\begin{array}{c|c|c} I & \Theta_I^e \\ \hline \text{true} & .5 & \top \\ \text{false} & .5 & \top \\ \end{array}$$

$$\begin{array}{c|c|c} J & \Theta_J^{\rm e} \\ \hline {\rm true} & .5 & \top \\ \end{array}$$

$$\begin{tabular}{|c|c|c|c|c|} \hline $Y$ & $\Theta_Y^e$ \\ \hline true & .01 & \top \\ false & .99 & \top \\ \hline \end{tabular}$$



Assuming elimination order J,I,X,Y,O:



$$\max_{V}(\Theta_{I}^{e}\Theta_{J}^{e}\Theta_{Y}^{e}\Theta_{X|I}^{e}\Theta_{O|X,Y}^{e}) = \max_{O}\left(\max_{Y}\left(\max_{X}\left(\max_{I}(\Theta_{I}^{e}\Theta_{X|I}^{e})\Theta_{O|X,Y}\right)\Theta_{Y}^{e}\right)\right)\max_{J}(\Theta_{J}^{e})$$

I	X	$\Theta_I^{\mathbf{e}}\Theta$	e <i>X</i>   <i>I</i>	X	Y	0	max 6	$\Theta_I^{\mathbf{e}} \Theta_{X I}^{\mathbf{e}} \bigg) \Theta_{O XY}^{\mathbf{e}}$
true	true	.475	T	true	true	false	.0095	I=true
true	false	.025	Т	true	false	false	0002002002	I = true
false	true	.025	T	false	true	false	.0095	I = false
false	false	.475	T	false	false	false	.4655	I = false

0	(	max Y	$\left(\max_{X}\left(\max_{I}\Theta_{I}^{\mathbf{e}}\Theta_{X I}^{\mathbf{e}}\right)\Theta_{O XY}^{\mathbf{e}}\right)\Theta_{Y}^{\mathbf{e}}$
fal	se	.4608	45 $I = $ false, $X = $ false, $Y = $ false
	r	$\max_{O} \left( \mathbf{m} \right)$	$\max_{Y} \left( \max_{X} \left( \max_{I} \Theta_{I}^{\mathbf{e}} \Theta_{X I}^{\mathbf{e}} \right) \Theta_{O XY}^{\mathbf{e}} \right) \Theta_{Y}^{\mathbf{e}} \right)$
Т	.40	50845	I = false, $X = $ false, $Y = $ false, $O = $ false

$$\frac{\max\limits_{O}\left(\max\limits_{Y}\left(\max\limits_{X}\left(\max\limits_{I}\Theta_{I}^{\mathbf{e}}\Theta_{X|I}^{\mathbf{e}}\right)\Theta_{O|XY}^{\mathbf{e}}\right)\Theta_{Y}^{\mathbf{e}}\right)\left(\max\limits_{J}\Theta_{J}^{\mathbf{e}}\right)}{\top \quad .2304225 \quad | \ J = \mathsf{true}, \ I = \mathsf{false}, \ X = \mathsf{false}, \ Y = \mathsf{false}, \ O = \mathsf{false}}$$



# Example 2 – Compute MAP

I	$\Theta_I$	J	$\Theta_J$
true	.5	true	.5
false	.5	false	.5

$\boldsymbol{J}$	Y	$\Theta_{Y J}$
true	true	.01
true	false	.99
false	true	.99
false	false	.01

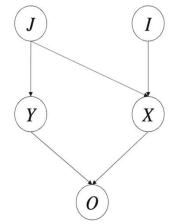
We want to	know the i	most likel	y instar	ntiation
of $Q = \{I, J\}$	given $O =$	$= true, \pi$	= 0, Y	, X, I, J

true true	true false	.95 .05
true	false	05
		.03
false	true	.05
false	false	.95
true	true	.05
true	false	.95
false	true	.05
false	false	.95
	false true true false	false true false true true false false true

$\boldsymbol{X}$	$\boldsymbol{Y}$	0	$\Theta_{O XY}$
true	true	true	.98
true	true	false	.02
true	false	true	.98
true	false	false	.02
false	true	true	.98
false	true	false	.02
false	false	true	.02
false	false	false	.98

We compute 
$$MAP(Q, e) = \max_{Q} \left( \sum_{V \setminus Q} \Theta_{I}^{e} \Theta_{J}^{e} \Theta_{Y|J}^{e} \Theta_{X|IJ}^{e} \Theta_{O|X,Y}^{e} \right)$$
  
=  $\max_{Q} \Pr(Q, e)$ 

"First sum-out  $V \setminus Q$ , then maximize-out Q"



# We can compute the marginal Pr(I, J, e) as before resulting in:

I	J	$f_1$	
true	true	.93248	Т
true	false	.97088	T
false	true	.07712	Τ
false	false	.97088	T

I	$\int$	2
true	.5	T
false	.5	T

$$egin{array}{c|c|c|c} J & f_3 & \\ \hline true & .5 & \top \\ \hline false & .5 & \top \\ \hline \end{array}$$



# Example 2 – Continued

I	$\boldsymbol{J}$	$f_1$							
true	true	.93248	Т	I	j j	$f_2$	J	j	$f_3$
true	false	.97088	Т	true	.5	T	true	.5	T
false	true	.07712	Т	false	.5	T	false	.5	T
false	false	.97088	Т						

### Now we are left with computing

$$\max_{I,J} \Pr(I,J,e) = \max_{I,J} f_1 f_2 f_3 = \max_{J} (\max_{I} f_1 f_2) f_3$$

I	J	$f_1 f_2$	
true	true	.466240	Т
true	false	.485440	Т
false	true	.038560	Т
false	false	.485440	Т

J	$\max_{I} f_1 f_2$	
true	.466240	I = true
false	.485440	I = true

The MAP of I and J given O=true is: I=true, J=false



# Lecture 4 – Summary

- We introduced extended factors and how to maximize them out.
- We saw how to compute posterior marginals.
   "What is the probability of an earthquake when the alarm is ringing."
- We saw how to compute maximum a-posteriori queries.

  "What is the most likely state of the alarm given someone is calling the police."
- We saw how to compute most probable explanations.
   "What is the most probable explanation of a ringing alarm."

