

# CAP 5619 - Deep and Reinforcement Learning

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## 1 Problem 1

(1)

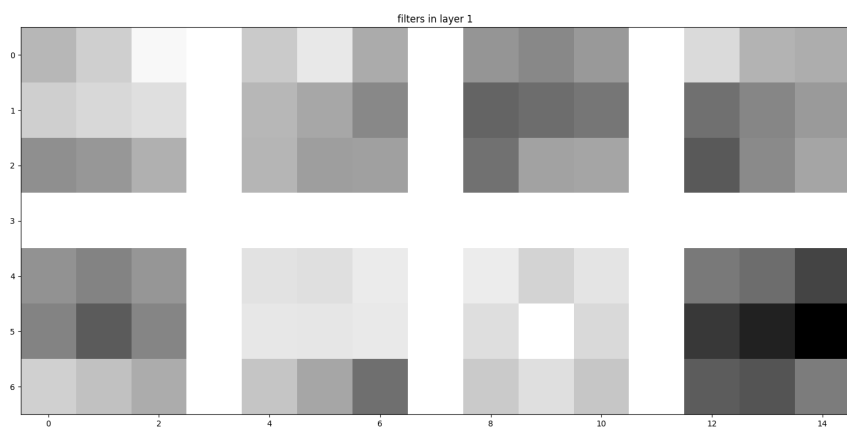


Figure 1: filters at layer 1

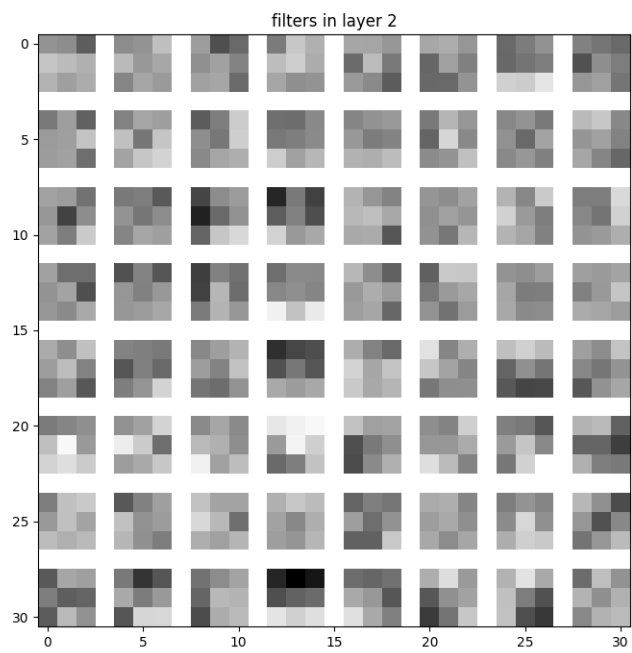


Figure 2: filters at layer 2

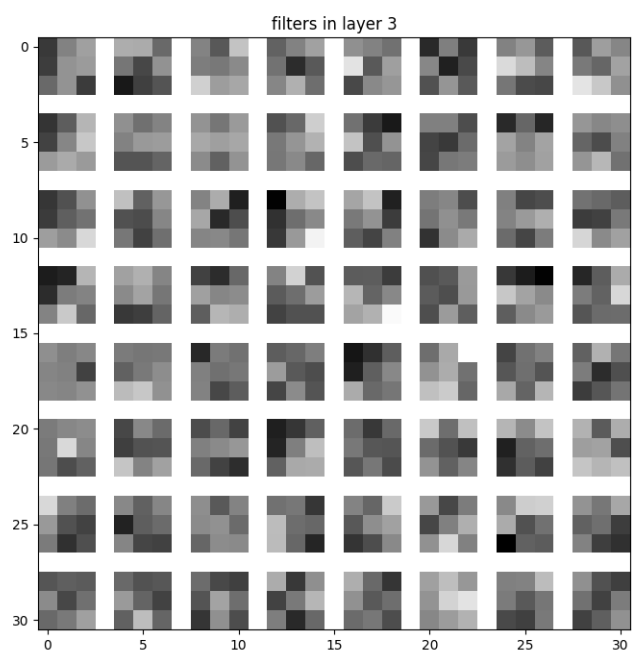


Figure 3: filters at layer 3

(2) Yes, we can still see clearly they are basically 0 and 8.

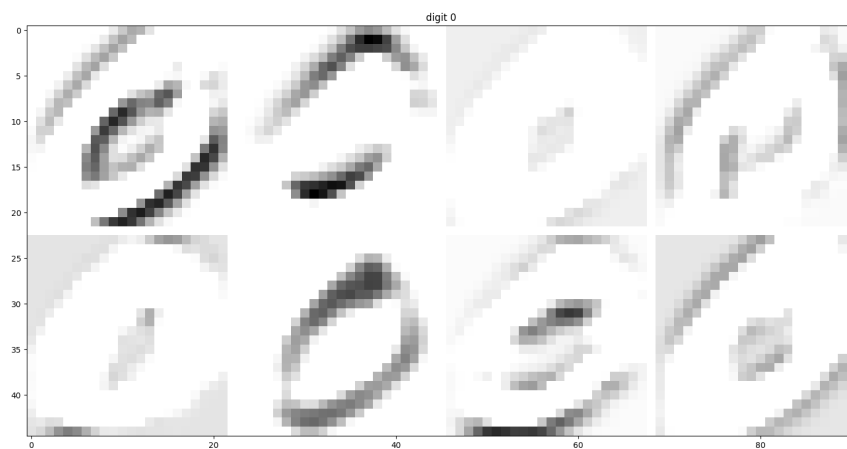


Figure 4: feature map for digit 0

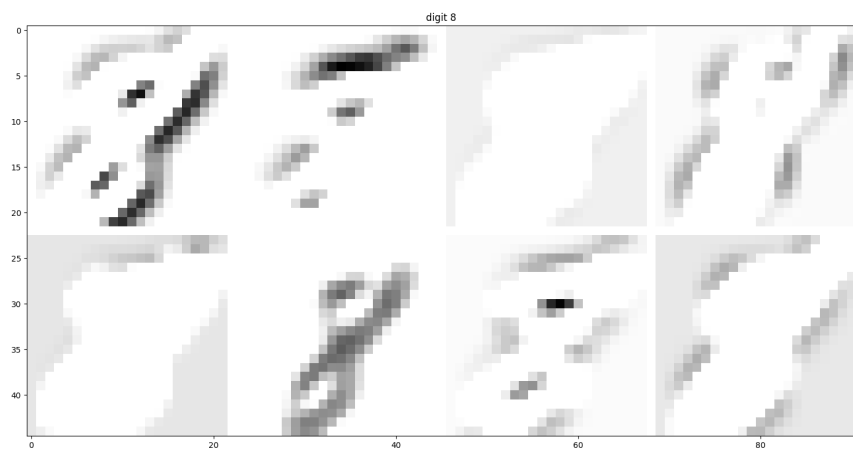
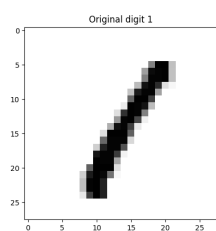
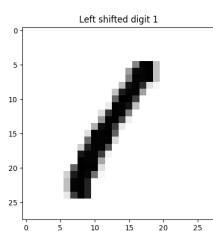


Figure 5: feature map for digit 8

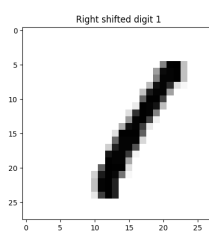
(3) The predictions do not change, they are still correctly labeled as 1.



(a) original



(b) left shifted



(c) right shifted

Figure 6: digit 1

## 2 Problem 2

(1)

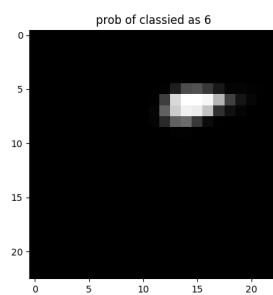


Figure 7: probability as 6

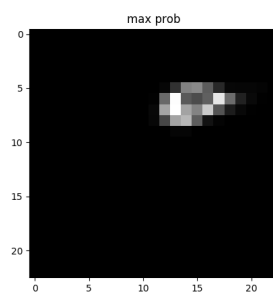


Figure 8: maximum probability

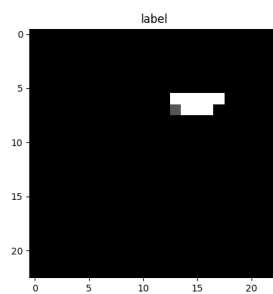


Figure 9: label



(2) By analyse the hot spot, we can see most sensitive part is the head of 6, namely uper-right corner of the figure. It's the most important part for recogination.

(3) theoretically it can be done. Through the example in step 1, we can see one black patch at the right location will lead to a recogination of 4 or 0. It's presumed we can at least cut a black patch from some digits and patch is at the hot spot, it might lead to a 4 or 0. While I tried many times, and even increased the patch size, It is still classied as 6 somehow.

### 3 Problem 3

(1)

$$\hat{y}^{(1)} = \begin{bmatrix} 0.94921601 \\ 0.05078399 \end{bmatrix}, \quad \hat{y}^{(2)} = \begin{bmatrix} 0.95221995 \\ 0.04778005 \end{bmatrix}, \quad \hat{y}^{(3)} = \begin{bmatrix} 0.94001124 \\ 0.05998876 \end{bmatrix} \quad (1)$$

loss: 9.434827012614068

(2)

$$L(b_1 - \epsilon) = 9.434835467223774, \quad L(b_1 + \epsilon) = 9.43481855635174 \quad (2)$$

$$\frac{dL}{db_1} \approx -0.08455436017129614 \quad (3)$$

$$L(b_2 - \epsilon) = 9.434775274858213, \quad L(b_2 + \epsilon) = 9.434878741709078 \quad (4)$$

$$\frac{dL}{db_2} \approx 0.5173342543240977 \quad (5)$$

(3) The backpropogation is calculated as:

$$\frac{dl}{d\hat{y}} = \begin{bmatrix} \frac{dl}{d\hat{y}_1} \\ \frac{dl}{d\hat{y}_2} \end{bmatrix} = \begin{bmatrix} 2\hat{y}_1 - 1 \\ -\frac{1}{\hat{y}_2} \end{bmatrix} \quad (6)$$

$$\frac{dl}{do} = (\frac{d\hat{y}}{do})^T .dot(\frac{dl}{d\hat{y}}) \quad (7)$$

in which

$$\frac{d\hat{y}}{do} = \hat{y}_1 \hat{y}_2 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad (8)$$

$$\frac{dl}{dh} = (\frac{do}{dh})^T .dot(\frac{dl}{do}) = V^T .dot(\frac{dl}{do}) \quad (9)$$

$$\frac{dl}{da} = \frac{dh}{da} * \frac{dl}{dh} = (1 - h^2) * \frac{dl}{dh} \quad (10)$$

$$\frac{dl}{db} = (\frac{da}{db})^T .dot(\frac{dl}{da}) \quad (11)$$

in which

$$\frac{da}{db} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + W .dot(\frac{dh^{t-1}}{db}) \quad (12)$$

in which

$$\frac{dh^{t-1}}{db} = ((\frac{da^{t-1}}{db})^T * \frac{dh^{t-1}}{da^{t-1}})^T \quad (13)$$

All these notations follow the Python standards, in which \* stands for element-wise multiplication. Results:

For  $t = 0$ :

$$\begin{aligned} \frac{dl}{dy} &= \begin{bmatrix} 0.89843201 \\ -19.691243652 \end{bmatrix} \\ \frac{dy}{do} &= \begin{bmatrix} 0.04820498 & -0.04820498 \\ -0.04820498 & 0.04820498 \end{bmatrix} \\ \frac{dl}{do} &= \begin{bmatrix} 0.9925249 \\ -0.9925249 \end{bmatrix} \\ \frac{do}{dh} &= \begin{bmatrix} -2 & 1 \\ -1 & 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}\frac{dl}{dh} &= \begin{bmatrix} -0.9925249 \\ 0.9925249 \end{bmatrix} \\ \frac{dl}{da} &= \begin{bmatrix} -0.0701227 \\ 0.0701227 \end{bmatrix} \\ \frac{da}{db} &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ \frac{dl}{db} &= \begin{bmatrix} -0.0701227 \\ 0.0701227 \end{bmatrix}\end{aligned}$$

For  $t = 1$ :

$$\begin{aligned}\frac{dl}{dy} &= \begin{bmatrix} 0.9044399 \\ -20.9292368 \end{bmatrix} \\ \frac{dy}{do} &= \begin{bmatrix} 0.04549712 & -0.04549712 \\ -0.04549712 & 0.04549712 \end{bmatrix} \\ \frac{dl}{do} &= \begin{bmatrix} 0.99336936 \\ -0.99336936 \end{bmatrix} \\ \frac{do}{dh} &= \begin{bmatrix} -2 & 1 \\ -1 & 0 \end{bmatrix} \\ \frac{dl}{dh} &= \begin{bmatrix} -0.99336936 \\ 0.99336936 \end{bmatrix} \\ \frac{dh}{da} &= \begin{bmatrix} 0.00420315 \\ 0.01138416 \end{bmatrix} \\ \frac{dl}{da} &= \begin{bmatrix} -0.00417528 \\ 0.01130867 \end{bmatrix} \\ \frac{dh}{db} &= \begin{bmatrix} 0.07065082 & 0. \\ 0. & 0.07065082 \end{bmatrix} \\ \frac{da}{db} &= \begin{bmatrix} 1.07065082 & -0.07065082 \\ 0. & 1.14130165 \end{bmatrix} \\ \frac{dl}{db} &= \begin{bmatrix} -0.00447027 \\ 0.0132016 \end{bmatrix}\end{aligned}$$

For  $t = 2$ :

$$\begin{aligned}\frac{dl}{dy} &= \begin{bmatrix} 0.88002248 \\ -16.66978991 \end{bmatrix} \\ \frac{dy}{do} &= \begin{bmatrix} 0.05639011 & -0.05639011 \\ -0.05639011 & 0.05639011 \end{bmatrix}\end{aligned}$$

$$\begin{aligned}
\frac{dl}{do} &= \begin{bmatrix} 0.9896358 \\ -0.9896358 \end{bmatrix} \\
\frac{do}{dh} &= \begin{bmatrix} -2 & 1 \\ -1 & 0 \end{bmatrix} \\
\frac{dl}{dh} &= \begin{bmatrix} -0.9896358 \\ 0.9896358 \end{bmatrix} \\
\frac{dh}{da} &= \begin{bmatrix} 0.01002062 \\ 0.42731798 \end{bmatrix} \\
\frac{dl}{da} &= \begin{bmatrix} -0.00991676 \\ 0.42288917 \end{bmatrix} \\
\frac{dh}{db} &= \begin{bmatrix} 0.00450011 & -0.00029696 \\ 0. & 0.01299276 \end{bmatrix} \\
\frac{da}{db} &= \begin{bmatrix} 1.00450011 & -0.01328971 \\ 0. & 1.02598552 \end{bmatrix} \\
\frac{dl}{db} &= \begin{bmatrix} -0.00996139 \\ 0.43400995 \end{bmatrix}
\end{aligned}$$

Add these 3  $\frac{dl}{db}$ , we get

$$\frac{dl}{db} = \begin{bmatrix} -0.08455436 \\ 0.51733425 \end{bmatrix} \quad (14)$$

which is almost the same with the central difference results.

(4) new  $b$ :

$$b = \begin{bmatrix} -1.00084554 \\ 1.00517334 \end{bmatrix} \quad (15)$$

(5) new loss with new  $b$  9.437563229688841

## 4 Problem 4

(1) The most difficult part should be  $W$  and  $U$ , if we unfold the graph, we can see  $W$  connects the hidden states for different time steps, we need to do a backpropagation for  $W$  and  $U$  for all preceding time step. Long-time dependence is very difficult to train.

(2) echo state network fixes  $W$  and  $U$ . Only  $V$  is learned.

(3) By adding forget gates and input gates, vanish gradient introduced by long-time dependence can be alleviated.