



OpenMP part 2

Parallel Computing

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- Until OpenMP 3.1, parallel execution cannot be aborted
 - Parallel regions must always run to completion
 - Alternatively, the region does not start at all
- OpenMP 4.0 introduces cancellation
 - Best effort: does not guarantee to trigger termination immediately
- Useful for divide-and-conquer algorithms (e.g., stop searching when you find the element) and to handle errors

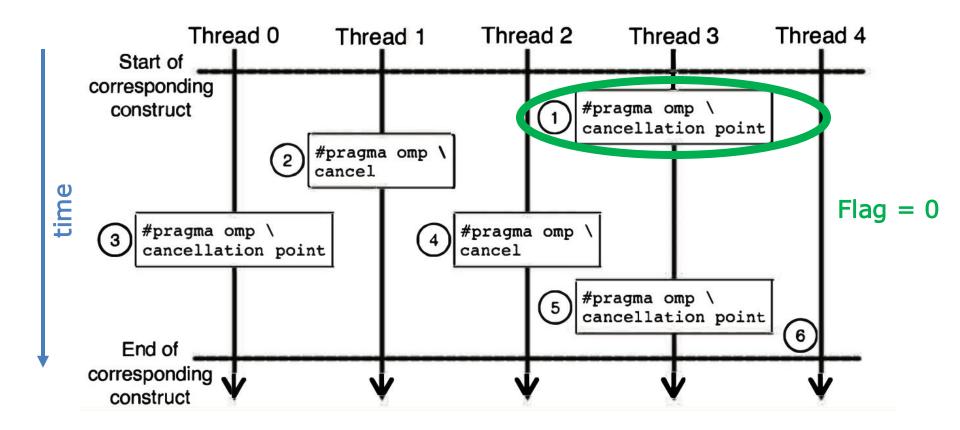
```
#pragma omp cancel <construct-type>
```

Cancel current thread

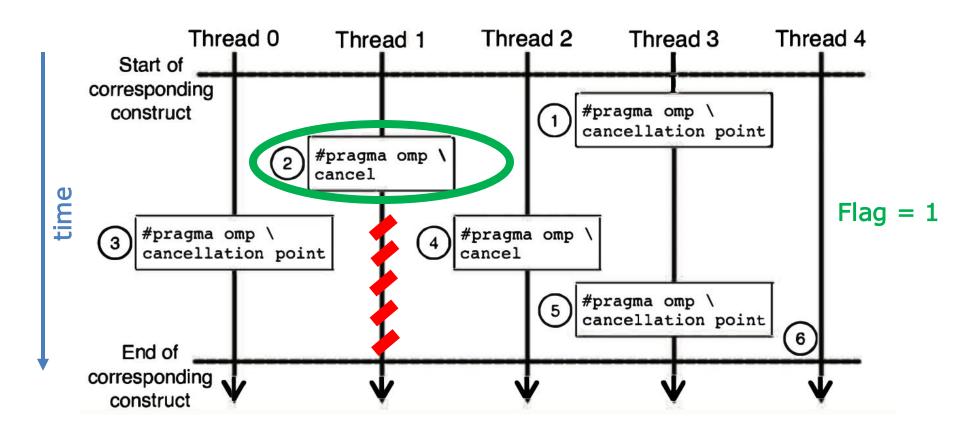
```
#pragma omp cancellation point
```

- Check if any thread requested cancellation
- □ A thread that wishes to terminate the execution must have cancel in its execution path
- ☐ The cancel directive raises a flag
- When a thread encounters cancellation point, it checks the cancellation flag

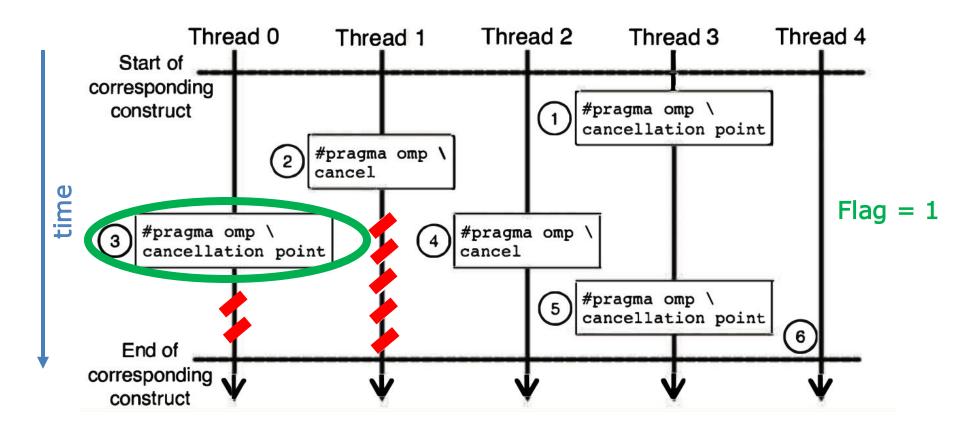
- The status of cancellation is also checked
 - At another cancel region
 - At a barrier (implicit or explicit)
- □ The user is responsible of setting cancellation points to ensure timely cancellation
- □ There is an overhead in checking for cancellation, so OMP_CANCELLATION is disabled by default



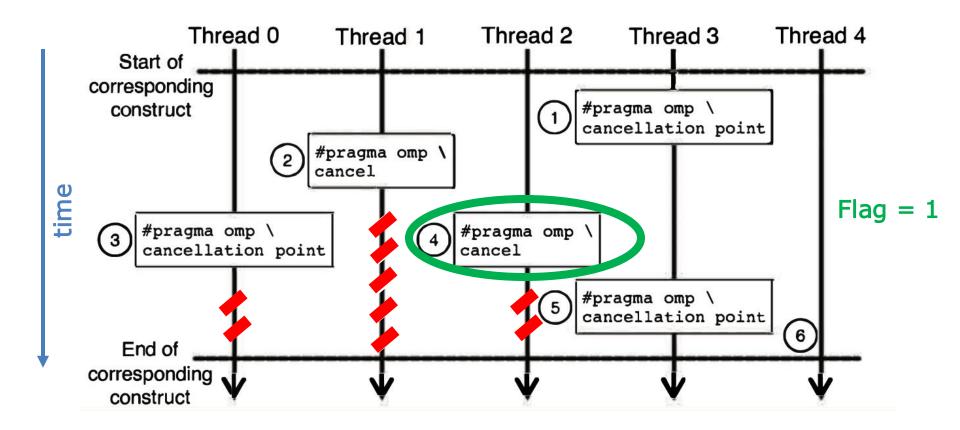
Thread 3 encounters a cancellation point, nothing happens



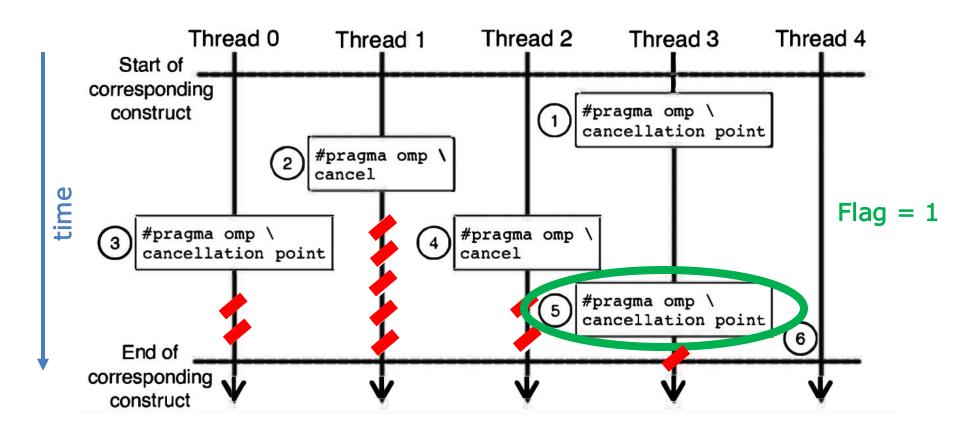
□ Thread 1 requests cancellation and waits at the next synchronization point



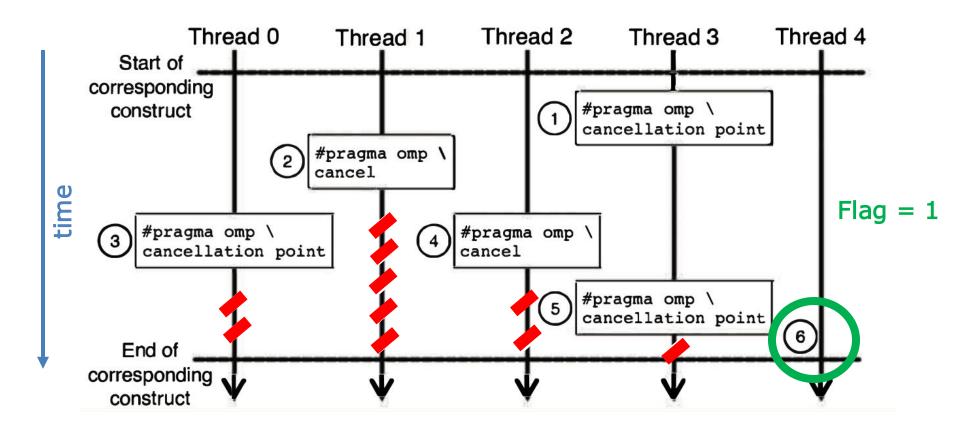
■ Thread 0 checks for cancellation and terminates



A cancel directive first checks for the cancellation flag, thread 2 terminates



☐ This time, thread 3 terminates



□ Thread 4 never encounters any cancellation points and it finishes execution normally

- Tasks are useful to parallelize algorithm with irregular and runtime-dependent execution flow
- ☐ Simplest example: while loop
- Queuing system that dynamically assigns work to threads
- Simplest definition: an OpenMP task is a block of code contained in a parallel region that can be executed simultaneously with other tasks in the same region
- □ Tasks are not guaranteed to be executed where they are defined in the source code

■ Without tasks: → highly inefficient!

```
while (p != NULL)
           p = p - next;
   count++;
p = head;
for(i=0; i<count; i++)
           parr[i] = p;
    p = p - next;
#pragma omp parallel for
for(i=0; i<count; i++)
           processwork(parr[i]);
```

1. Measure how long is the list

Most of the work is done here!

2. Put the content into an array

3. Process array elements in parallel

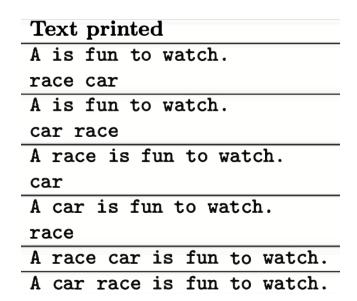
Linked list traversal in OpenMP

```
#pragma omp parallel
   #pragma omp master
   printf("Threads: %d\n", omp get num threads());
   #pragma omp single
         p=head;
         while (p)
             #pragma omp task firstprivate(p)
                  processwork(p);
                  printf("I am thread %d\n", omp get thread num());
          = p->next;
```

- ☐ How many threads create the tasks?
- Which thread executes which tasks?
- ☐ Why do we need firstprivate?

Printing a sentence

```
#pragma omp parallel
{
    #pragma omp single
    {
        printf("A ");
        #pragma omp task
            {printf("race ");} // Task #1
        #pragma omp task
            {printf("car ");} // Task #2
        printf("is fun to watch.\n");
    } // End of single region
} // End of parallel region
```



Threads start picking up work from the queue when they get here!

Printing a sentence

Correction: use the taskwait construct to force the pending child tasks to complete before resuming execution

- Note that you could use master instead of single, but there is no barrier on exit!
- ☐ Same concern if nowait is used

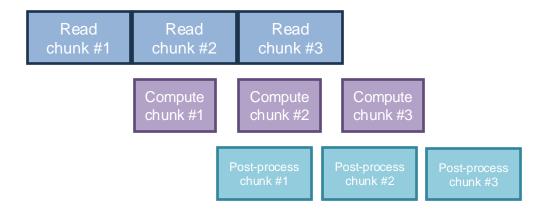
- When a thread encounters a task construct, the task is created but not immediately executed
- Tasks are guaranteed to be completed
 - At a barrier (implicit or explicit)
 - At task synchronization points

```
#pragma omp taskwait
```

#pragma omp taskgroup

□ taskwait forces completion of child tasks only, taskgroup synchronizes also their descendants

□ Tasks can be used to overlap computation and I/O (pipeline parallelism)



- ☐ After start-up, the three activities can be run at the same time on different chunks of data
- □ The pipeline can be implemented through sections, but communication and load imbalance are a problem

- By creating tasks instead of sections, each thread can execute any task as long as its inputs are ready
- ☐ The depend clause indicates a dependence between tasks

```
Read chunk #1

#pragma omp task depend(out: variable)

{read;}

#pragma omp task depend(in: variable)

{compute chunk #1
```

■ The priority clause can be used to hint that more important tasks should be executed more frequently

```
#pragma omp parallel default(none) \
                  shared(fp_read, n_io_chunks, n_work_chunks) \
                  shared(a, b, c) \
                  shared(status_read, status_processing) \
                  shared(status_postprocessing)
  #pragma omp single nowait
    for (int64_t i=0; i<n_io_chunks; i++) {</pre>
      #pragma omp ta/* Create tasks */cessing[i]) \
    } // End of for-loop
  } // End of single region
} // End of parallel region
```

The parallel region is a single region creating tasks for the other threads

```
#pragma omp parallel default(none) \
                  shared(fp_read, n_io_chunks, n_work_chunks) \
                  shared(a, b, c) \
                  shared(status_read, status_processing) \
                  shared(status_postprocessing)
  #pragma omp single nowait
    for (int64_t i=0; i<n_io_chunks; i++) {
     #pragma omp ta/* Create tasks */cessing[i]) \
   } // End of for-loop
 } // End of single region
} // End of parallel region
```

Data environment is not trivial when using tasks

Assumption: we are going to process n_io_chunks of data

Task synchronization point: barrier at the end of the parallel region

```
#pragma omp task depend(out: status_read[i]) \
               priority(20)
{
   (void) read_input(fp_read, i, a, b, &status_read[i]);
} // End of task reading in a chunk of data
#pragma omp task depend(in: status_read[i]) \
                 depend(out: status_processing[i]) \
                 priority(10)
{
   (void) compute_results(i, n_work_chunks, a, b, c,
                          &status_processing[i]);
} // End of task performing the computations
#pragma omp task depend(in: status_processing[i]) \
                 priority(5)
{
   (void) postprocess_results(i, n_work_chunks, c,
                              &status_postprocessing[i]);
} // End of task postprocessing the results
```

Read -> compute dependence

Compute -> postprocess dependence

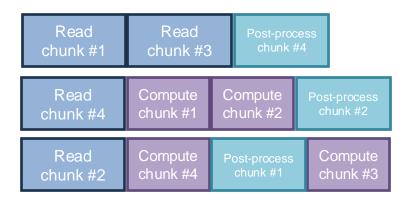
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                              &status_postprocessing[i]);
} // End of task postprocessing the results
```

Before running the program,

OMP_MAX_TASK_
PRIORITY has to be set (default is 0)

Numbers are relative, the execution must not depend on them

Possible execution order with 3 threads



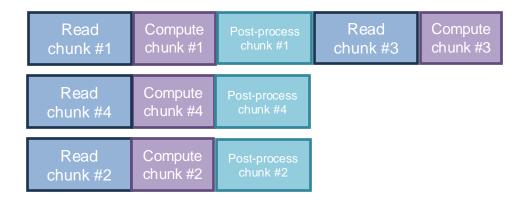
- □ As long as dependences are respected, the loop iterations can be executed in an arbitrary order
- No explicit flush required (it is implied before and after every task)
- ☐ Task scheduling overhead might be a problem

□ Covenience construct to simplify using tasks when there is a loop in the code

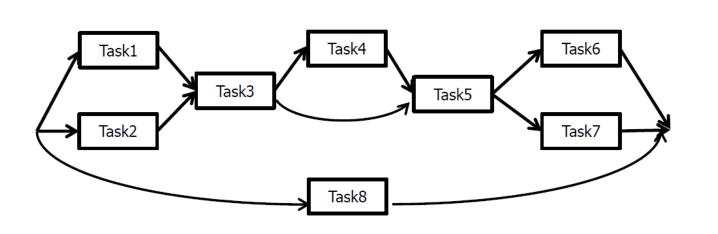
```
#pragma omp taskloop num_tasks(n_io_chunks/10) grainsize(50)
for (int64_t i=0; i<n_io_chunks; i++) {
        (void) read_input(fp_read, i, a, b);
        (void) compute_results(i, n_work_chunks, a, b, c);
        (void) postprocess_results(i, n_work_chunks, c);
} // End of for-loop</pre>
```

- □ To keep the number of created tasks low, num_tasks sets the number of tasks that the runtime system can generate
- □ Each task gets assigned a number of iterations which is the minimum between grainsize and the total number of iterations

- ☐ Each iteration became a task
- Dependences are no longer needed

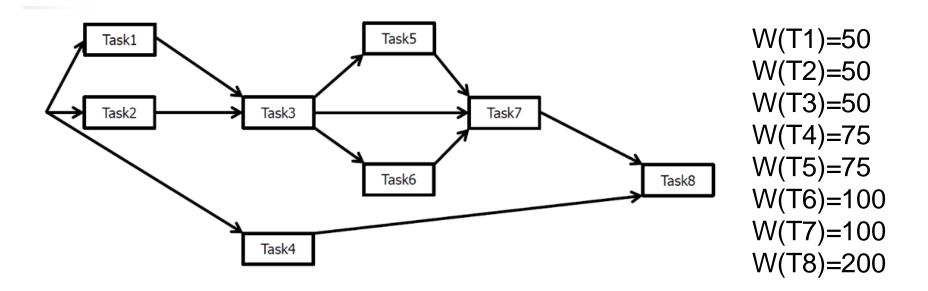


□ Larger units of work are scheduled, lower overhead, but less flexibility to handle load imbalance



\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
W(T1)=100
W(T2)=100
W(T3)=75
W(T4)=50
W(T5)=75
W(T6)=100
W(T7)=100
W(T8)=200

- Calculate work and span.
- Write an OpenMP implementation reflecting the structure of the task graph.
- How many threads are needed to achieve the maximum theoretical parallelism?

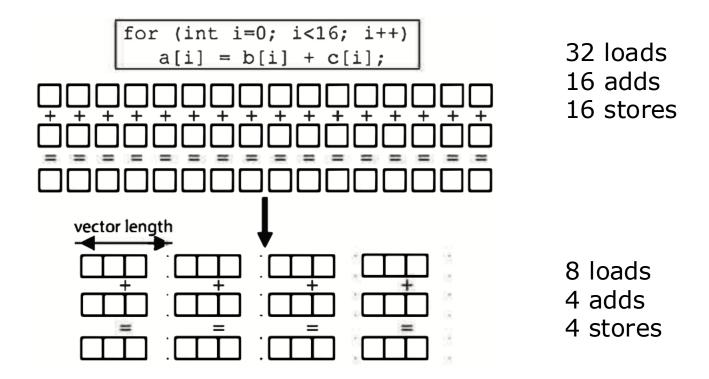


- Calculate work and span.
- Write an OpenMP implementation reflecting the structure of the task graph.
- How many threads are active during the execution of Task 3? How many during Task 5?

- A SIMD processor exploits data parallelism by providing instructions that operate on blocks of data (vectors)
- □ SIMD provides data parallelism at the *instruction* level, it can be combined with other OpenMP constructs to achieve multi-level parallelism

Scalar operations

SIMD operations



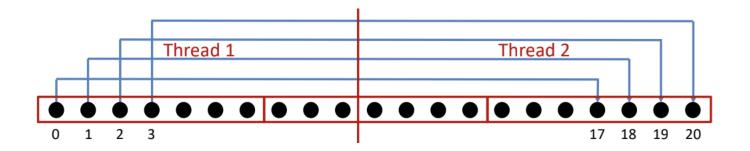
- SIMD instructions use SIMD registers
- Width of the register → vector length
- Similar latency as scalar instructions

- Compilers deal with multiple issues to identify whether a loop can be vectorized through SIMD instructions
 - analysis of dependences across iterations
 - alias analysis of pointers
 - data layout/alignment issues
 - conditional execution
 - loop bounds not multiple of vector length
- Loop iterations at the beginning and end may not be vectorized (loop *peeling*, *tail*)

Loop-Carried dependencies

```
void lcd_ex(float* a, float* b, size_t n,
float c1, float c2) {
  for (int i = 0; i < n; i++) {
    a[i] = c1 * a[i + 17] + c2 * b[i];
  }
}</pre>
```

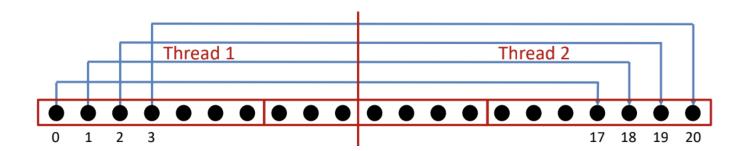
- □ Can this loop be parallelized?
 - Test: can you reverse the loop and still get correct results?



Loop-Carried dependencies

```
void lcd_ex(float* a, float* b, size_t n,
float c1, float c2) {
  for (int i = 0; i < n; i++) {
    a[i] = c1 * a[i + 17] + c2 * b[i];
  }
}</pre>
```

- □ Can this loop be vectorized?
 - Yes, only if vector length < distance length



```
#pragma omp simd
   /* for loop */
```

- The loop is divided into chunks, all iterations are executed by a single thread with SIMD vector instructions
 - Chunks should fit a vector register for performance
 - Each iteration is executed by a SIMD lane
- □ The compiler will generate SIMD instructions, it is up to the user to ensure this maintains correct behavior

- □ Data scope clauses (private, firstprivate, reduction, etc.) can be used in a simd directive
- A collapse clause can be used to fuse two perfectly nested loops (watch out for complexity!)
- ☐ The simdlen(size) clause suggests a preferred vector length
 - Maybe the code will work better with a specific vector length
 - The compiler is free to ignore it
 - It can hurt performance but the results remain correct

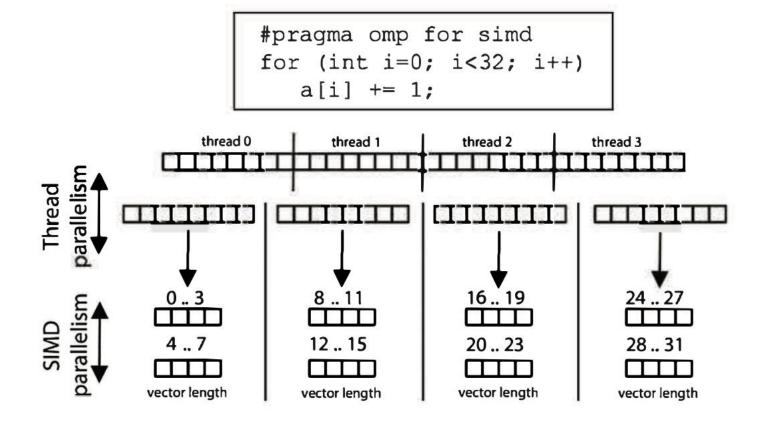
- In the case of loop-carried dependencies, the vector length must be smaller than the smallest dependence distance in the loop
- ☐ The safelen clause sets an upper limit to the vector length that the compiler cannot exceed

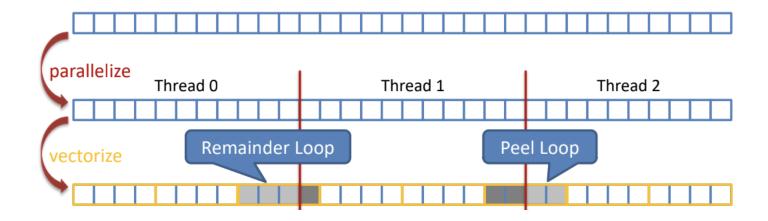
Composite loop-SIMD work-sharing construct:

```
#pragma omp for simd
   /* for loop */
```

- Portable implementation
- Number of threads and scheduling policy greatly affect performance
 - If the number of threads increases, work for each thread is smaller
 - Each thread should work with a chunk corresponding to the vector length

□ Distribute iterations among threads in a team, then each thread uses SIMD instructions

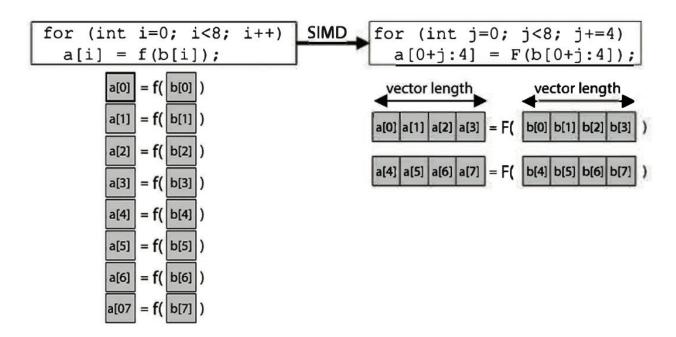




■ To avoid performance degradation, the simd: modifier can be added to the scheduling directive

Declare a function to be compiled for calls within a SIMD loop

```
#pragma omp declare simd
    /* function definition */
```



Multiple directives can be added to generate multiple compiled versions

```
value changes linearly same value
from one call to the other for all calls

#pragma omp declare simd linear(pixel) uniform(mask) inbranch
#pragma omp declare simd linear(pixel) notinbranch
#pragma omp declare simd extern void compute_pixel(char *pixel, char mask);

is always/never called within a branch
```

- OpenMP Tutorial by Blaise Barney, Lawrence Livermore National Laboratory https://hpc.llnl.gov/training/tutorials
- UC Berkeley CS267: Applications of Parallel Computers https://sites.google.com/lbl.gov/cs267-spr2020
- □ Video series from Tim Mattson (Intel) <u>Introduction</u> <u>to OpenMP</u>
- □ Ruud van der Pas, Eric Stotzer, and Christian Terboven, "Using OpenMP-The Next Step. Affinity, Accelerators, Tasking, and SIMD", MIT Press 2017