

# Test of the linear systems from the convection-diffusion equations

This package provides implementations of comparing BICGSTAB, GMRES, DQGMRES, FOM, DIOM, SCG, SWI, RGMRES, RFOM, RSCG, and DSWI for solving the linear systems from the convection-diffusion equations:

$$Ax = b,$$

where  $A \in \mathbb{R}^{n \times n}$  is unsymmetric positive definite.

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## BICGSTAB

Using Matlabs function “bicgstab” directly.

## REGMRES

REGMRES (Restarted GMRES): Algorithm 6.11 in Yousef Saad’s “Iterative Methods for Sparse Linear System (2nd Edition)”

```
function [x, k, res, resvec] = regmres(A, b, restart, tol, x0, maxit)
```

- `[x] = regmres(A, b)` attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- `[x] = regmres(A, b, restart)` specifies the restarted number. If `restart` is `[]` then `regmres` uses the default, `n`.
- `[x] = regmres(A, b, restart, tol)` specifies the tolerance of the method. If `tol` is `[]` then `regmres` uses the default, `1e-6`.
- `[x] = regmres(A, b, restart, tol, x0)` specifies the initial guess. If `x0` is `[]` then `regmres` uses the default, an all zero vector.
- `[x] = regmres(A, b, restart, tol, x0, maxit)` specifies the maximum number of iterations. If `maxit` is `[]` then `regmres` uses the default, `10000`.

- $[x, k] = \text{regmres}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{regmres}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{regmres}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

GMRES: set `restart = n` in the function “`regmres`”.

## DQGMRES

DQGMRES (Direct Quasi-GMRES): Algorithms 6.6 and 6.13 in Yousef Saad’s “Iterative Methods for Sparse Linear System (2nd Edition)”

```
function [x, k, res, resvec] = dqgmres(A, b, m, tol, x0, maxit)
```

- $[x] = \text{dqgmres}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- $[x] = \text{dqgmres}(A, b, m)$  specifies the number of the sliding window. If  $m$  is `[]` then `dqgmres` uses the default,  $n$ .
- $[x] = \text{dqgmres}(A, b, m, \text{tol})$  specifies the tolerance of the method. If  $\text{tol}$  is `[]` then `dqgmres` uses the default,  $1e-6$ .
- $[x] = \text{dqgmres}(A, b, m, \text{tol}, x0)$  specifies the initial guess. If  $x0$  is `[]` then `dqgmres` uses the default, an all zero vector.
- $[x] = \text{dqgmres}(A, b, m, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If  $\text{maxit}$  is `[]` then `dqgmres` uses the default, 10000.
- $[x, k] = \text{dqgmres}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{dqgmres}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{dqgmres}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

## REFOM

REFOM (Restarted FOM): Algorithm 6.5 in Yousef Saad’s “Iterative Methods for Sparse Linear System (2nd Edition)”

```
function [x, k, res, resvec] = refom(A, b, restart, tol, x0, maxit)
```

- $[x] = \text{refom}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .

- $[x] = \text{refom}(A, b, \text{restart})$  specifies the restarted number. If restart is  $[]$  then refom uses the default, n
- $[x] = \text{refom}(A, b, \text{restart}, \text{tol})$  specifies the tolerance of the method. If tol is  $[]$  then refom uses the default,  $1e-6$ .
- $[x] = \text{refom}(A, b, \text{restart}, \text{tol}, x0)$  specifies the initial guess. If x0 is  $[]$  then refom uses the default, an all zero vector.
- $[x] = \text{refom}(A, b, \text{restart}, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If maxit is  $[]$  then refom uses the default, 10000.
- $[x, k] = \text{refom}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{refom}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{refom}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

FOM: set restart= $n$  in the function “refom”.

## DIOM( $m$ )

DIOM (Direct Incomplete Orthogonalization Method): Algorithms 6.6 and 6.8 in Yousef Saad’s “Iterative Methods for Sparse Linear System (2nd Edition)”

```
function [x, k, res, resvec] = diom(A, b, mk, tol, x0, maxit)
```

- $[x] = \text{diom}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- $[x] = \text{diom}(A, b, m)$  specifies the number of the sliding window. If  $m$  is  $[]$  then diom uses the default, n.
- $[x] = \text{diom}(A, b, m, \text{tol})$  specifies the tolerance of the method. If tol is  $[]$  then diom uses the default,  $1e-6$ .
- $[x] = \text{diom}(A, b, m, \text{tol}, x0)$  specifies the initial guess. If x0 is  $[]$  then diom uses the default, an all zero vector.
- $[x] = \text{diom}(A, b, m, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If maxit is  $[]$  then diom uses the default, 10000.
- $[x, k] = \text{diom}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{diom}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{diom}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

## RESCG

RESCG (Restarted SCG): Restarted semi-conjugate gradient method

```
function [x, k, res, resvec] = rescg(A, b, restart, tol, x0, maxit)
```

- $[x] = \text{rescg}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- $[x] = \text{rescg}(A, b, \text{restart})$  specifies the restarted number. If  $\text{restart}$  is  $[]$  then  $\text{rescg}$  uses the default,  $n$ .
- $[x] = \text{rescg}(A, b, \text{restart}, \text{tol})$  specifies the tolerance of the method. If  $\text{tol}$  is  $[]$  then  $\text{rescg}$  uses the default,  $1e-6$ .
- $[x] = \text{rescg}(A, b, \text{restart}, \text{tol}, x0)$  specifies the initial guess. If  $x0$  is  $[]$  then  $\text{rescg}$  uses the default, an all zero vector.
- $[x] = \text{rescg}(A, b, \text{restart}, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If  $\text{maxit}$  is  $[]$  then  $\text{rescg}$  uses the default, 10000.
- $[x, k] = \text{rescg}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{rescg}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{rescg}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

SCG: set  $\text{restart}=n$  in the function “ $\text{rescg}$ ”.

## SWI( $m$ )

SWI: Sliding window implementation with pre-allocated memory

```
[x, k, res, resvec] = swi(A, b, m, tol, x0, maxit)
```

- $[x] = \text{swi}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- $[x] = \text{swi}(A, b, m)$  specifies the number of the sliding window. If  $m$  is  $[]$  then  $\text{swi}$  uses the default,  $n$ .
- $[x] = \text{swi}(A, b, m, \text{tol})$  specifies the tolerance of the method. If  $\text{tol}$  is  $[]$  then  $\text{swi}$  uses the default,  $1e-6$ .
- $[x] = \text{swi}(A, b, m, \text{tol}, x0)$  specifies the initial guess. If  $x0$  is  $[]$  then  $\text{swi}$  uses the default, an all zero vector.
- $[x] = \text{swi}(A, b, m, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If  $\text{maxit}$  is  $[]$  then  $\text{swi}$  uses the default, 10000.
- $[x, k] = \text{swi}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$ .
- $[x, k, \text{res}] = \text{swi}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{swi}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

## DYNSWIWP

DYNSWIWP: Sliding window implementation with choosing  $m$  dynamically

The approach to choose  $m$  dynamically is as follows:

$$m = \begin{cases} \max\{[0.8m], 2\}, & \text{if } \|r_k\| < 0.9\|r_{k-1}\|; \\ \min\{2m, n\}, & \text{if } \|r_k\| > 2\|r_{k-1}\|; \\ m, & \text{otherwise.} \end{cases}$$

```
[x, k, res, resvec] = dynswiwp(A, b, m, tol, x0, maxit)
```

- $[x] = \text{dynswiwp}(A, b)$  attempts to find a solution  $x$  to the system of linear equations  $Ax = b$ . The  $n$ -by- $n$  coefficient matrix  $A$  must be positive definite but need not be symmetric. The right hand side column vector  $b$  must have length  $n$ .
- $[x] = \text{dynswiwp}(A, b, m)$  specifies the number of the sliding window. If  $m$  is  $[]$  then `dynswiwp` uses the default,  $n$ .
- $[x] = \text{dynswiwp}(A, b, m, \text{tol})$  specifies the tolerance of the method. If  $\text{tol}$  is  $[]$  then `dynswiwp` uses the default,  $1e-6$ .
- $[x] = \text{dynswiwp}(A, b, m, \text{tol}, x0)$  specifies the initial guess. If  $x0$  is  $[]$  then `dynswiwp` uses the default, an all zero vector.
- $[x] = \text{dynswiwp}(A, b, m, \text{tol}, x0, \text{maxit})$  specifies the maximum number of iterations. If  $\text{maxit}$  is  $[]$  then `dynswiwp` uses the default, 10000.
- $[x, k] = \text{dynswiwp}(A, b, \dots)$  returns the iteration number at which  $x$  was computed:  $1 \leq k \leq \text{maxit}$
- $[x, k, \text{res}] = \text{dynswiwp}(A, b, \dots)$  also returns the last relative residual norm  $\|b - Ax\|/\|b\|$ .
- $[x, k, \text{res}, \text{resvec}] = \text{dynswiwp}(A, b, \dots)$  also returns a vector of estimates of the residual norms at each iteration, including  $\|b - Ax\|$ .

## BICGSTAB

Using Matlabs function “bicgstab” directly.

### Test

1. Download the files: `regmres.m`, `refom.m`, `rescg.m`, `dqgmres.m`, `diom.m`, `swi.m`, `dynswiwp.m`, `test_condiff.m`, `A.mat` and `b.mat`;
2. Run the function “test\_condiff” directly, i.e.,

```
>> test_condiff
```

BICGSTAB	130	0.0045	5.36e-08
GMRES	43	0.0114	4.17e-07
DQGMRES(36)	43	0.0132	5.81e-07
FOM	43	0.0232	4.47e-07
DIOM(2)	5751	0.2528	NaN
DIOM(5)	49	0.0119	8.25e-07
DIOM(10)	60	0.0226	2.33e-07
SCG	43	0.0052	4.47e-07
SWI(2)	71	0.0116	8.28e-07
SWI(5)	52	0.0090	1.58e-07
SWI(10)	63	0.0075	3.50e-07
RGMRES	123	0.0147	7.18e-07
RFOM	85	0.0190	9.29e-07
RSCG	84	0.0103	9.91e-07
DSWI	69	0.0158	6.37e-07