

Towards Production-Run Heisenbugs Reproduction on Commercial Hardware

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*What's a coder's worst
nightmare?*

*The bug only occurs in production
but cannot be replicated locally.*

Heisenbug

When you trace them, they disappear!



Heisenbug

When you trace them, they disappear!

- Localization is hard



Heisenbug

When you trace them, they disappear!

- Localization is hard
- reproduction is hard



Heisenbug

When you trace them, they disappear!

- Localization is hard
- reproduction is hard
- never know if it is fixed...



A motivating example

Init: $x=1, y=2$

T1

```
1: T2.start()
2: z=0
3: x++
4: y++
5: z=1
6: T2.join()
```

T2

```
7: if (z==1)
8:     assert(x+1==y)
```

$z=1$

$x=2, y=3$

$x+1==y$

contradiction!



A motivating example

Init: $x=1, y=2$

T1

```
1: T2.start()  
2: z=0  
3: x++  
4: y++ |  
5: z=1 | PSO  
6: T2.join()
```

T2

```
7: if (z==1)  
8:     assert(x+1==y) X
```

$z=1$

$x=2, y=3$

$x+1==y$

contradiction!



A motivating example

Init: $x=1, y=2$

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\$12 million loss of equipment!



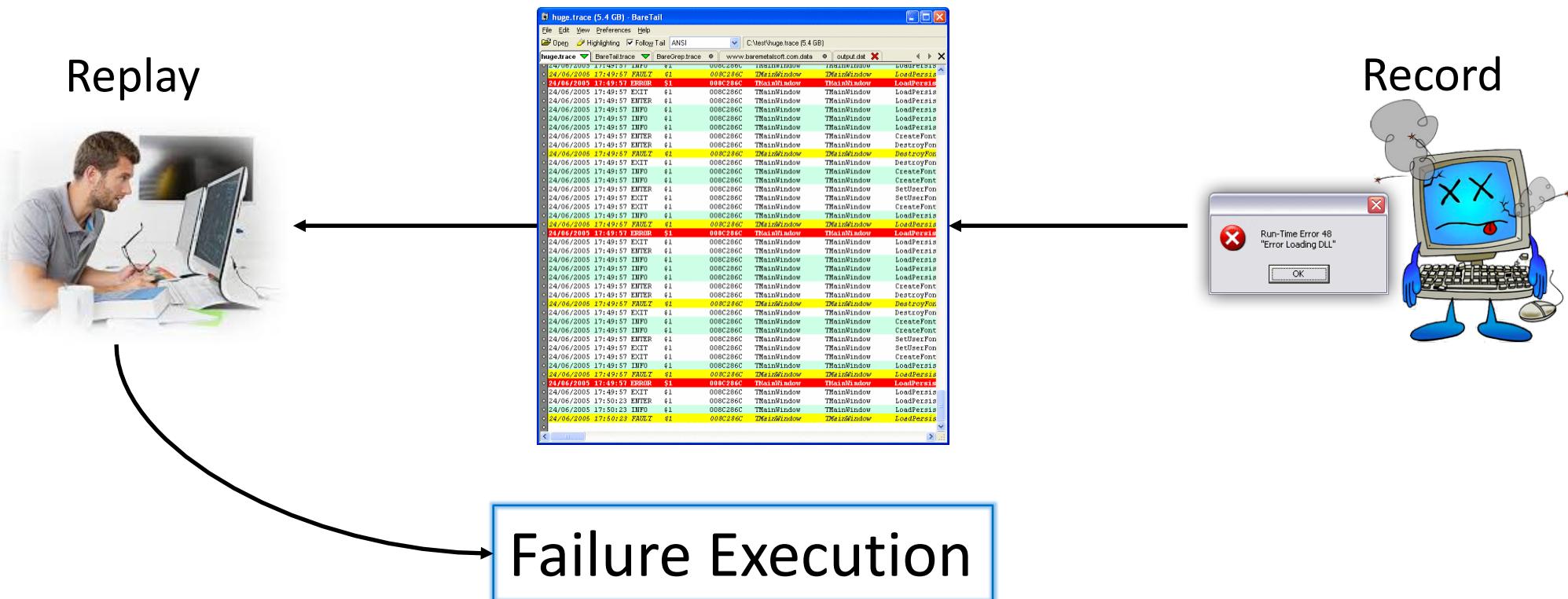
contradiction!

$x=2, y=3$

$x+1==y$

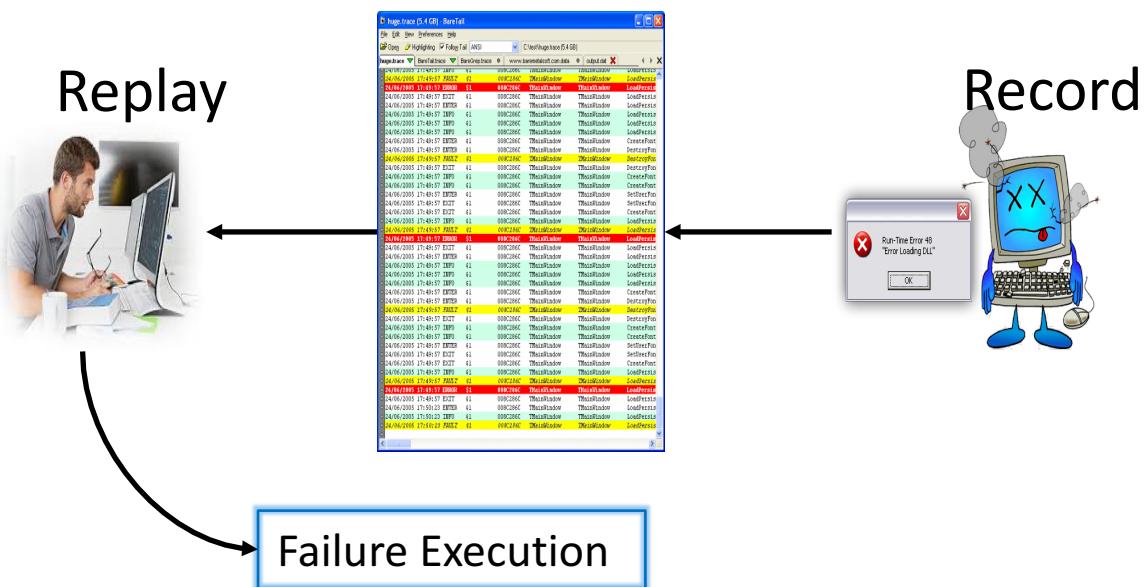
Record & Replay (RnR)

Goal: record the non-determinism at runtime and reproduce the failure



Record & Replay (RnR)

Goal: **record** the non-determinism at runtime and **reproduce** the failure



- runtime overhead
- the ability to reproduce failures

Related Work

- Software-based approach
 - **order-based**: fully record shared memory dependencies at runtime
 - LEAP[FSE'10], Order[USENIX ATC'11], Chimera[PLDI'12], Light[PLDI'15] RR[USENIX ATC'17]...
 - Chimera: > 2.4x
 - **search-based**: partially record the dependencies at runtime and use offline analysis (e.g. SMT solvers) to reason the dependencies
 - ODR[SOSP'09], Lee et al. [MICRO'09], Weeratunge et al.[ASPLOS'10], CLAP[PLDI'13]...
 - CLAP: 0.9x – 3x
- Hardware-based approach
 - Rerun[ISCA'08], Delorean[ISCA'08], Coreracer[MICRO'11], PBI[ASPLOS'13]...
 - rely on special hardware that are not deployed

Reality of RnR



In production

- high overheads
- failing to reproduce failures
- lack of commodity hardware support

Contributions

Goal: record the execution at runtime with low overhead and faithfully reproduce it offline

- RnR based on *control flow tracing* on commercial hardware (Intel PT)
- core-based **constraints reduction** to reduce the offline computation
- H3, evaluated on popular benchmarks and real-world applications,
overhead: 1.4%-23.4%

Intel Processor Trace (PT)

PT: Program control flow tracing, supported on 5th and 6th generation *Intel* core

- Low overhead, as low as 5%¹
- Highly compacted packets, <1 bit per retired instruction
- One bit (1/0) for branch taken indication
- Compressed branch target address

1: <https://sites.google.com/site/intelptmicrtutorial>.

PT Tracing Overhead

Program	Native time (s)	PT time (s)	PT OH(%)	trace
bodytrack	0.557	0.573	2.9%	94M
x264	1.086	1.145	5.4%	88M
vips	1.431	1.642	14.7%	98M
blackscholes	1.51	1.56	9.9%	289M
ferret	1.699	1.769	4.1%	145M
swaptions	2.81	2.98	6.0%	897M
raytrace	3.818	4.036	5.7%	102M
facesim	5.048	5.145	1.9%	110M
fluidanimate	14.8	15.1	1.4%	1240M
freqmine	15.9	17.1	7.5%	2468M
Avg.	4.866	5.105	4.9%	553M

4.9% overhead on executions of PARSEC 3.0 on average

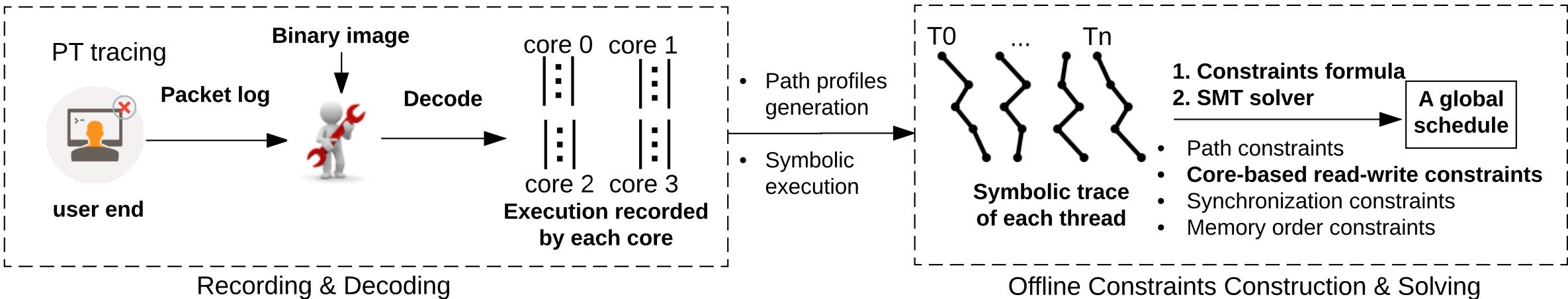
Challenges

- PT trace: low-level representation (assembly instruction)
- Absence of the thread information
- No data values of memory accesses

Solutions

- PT trace: low-level representation & no data values
 - Idea: extract the path profiles from PT trace and re-execute the program by KLEE to generate symbol values
- Absence of the thread information
 - Idea: use thread context switch information by Perf

H3 Overview



Phase 1: Control-flow tracing

Reconstruct the execution on each core by decoding the packets generated by PT and thread information from Perf

Phase 2: Offline analysis

- Path profiles of each thread
- Symbolic trace of each thread
- SMT constraints over the trace

Example

Init: $x=1, y=2$

T1

1: T2.start()

2: z=0

3: x++

4: y++

5: z=1

6: T2.join()

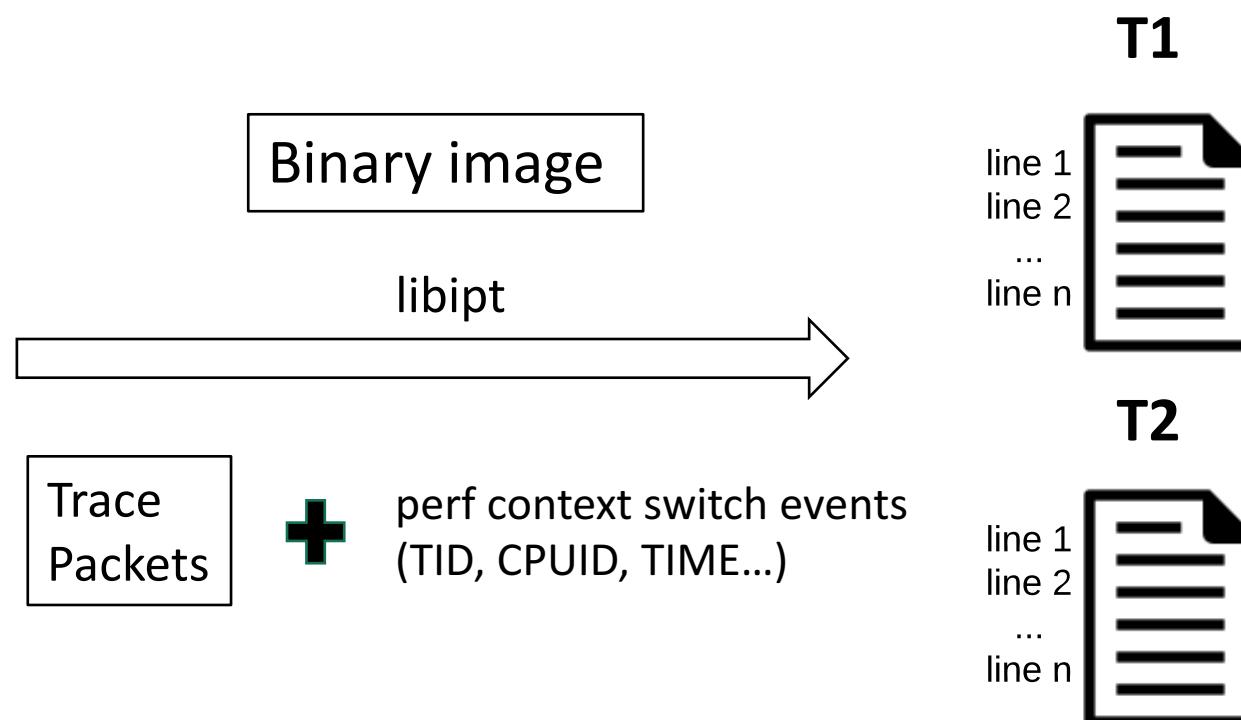
T2

7: if ($z==1$)

8: ~~assert($x+1==y$)~~

Step1: Collecting path profiles of each thread

PT: tracing control-flow of the program's execution



Example

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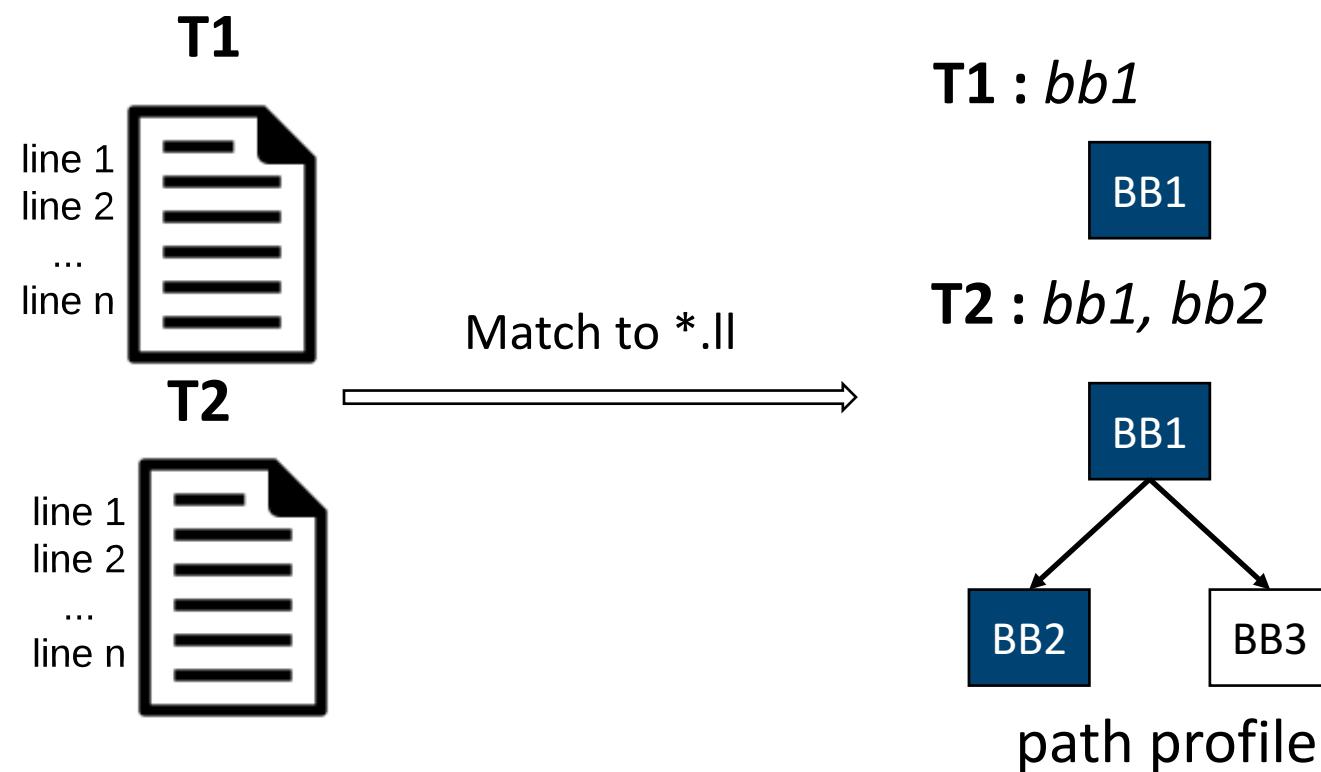
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Step1: Collecting path profiles of each thread

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6: T2.join()

T2

7: if ($z==1$)

8: ~~assert(x+1==y)~~

Step2: symbolic trace generation

KLEE[OSDI'08]: execute the thread along the path profile

T1

$$W_z^2 = 0$$

$$R_x^3, W_x^3 = R_x^3 + 1$$

$$R_y^4, W_y^4 = R_y^4 + 1$$

$$W_z^5 = 1$$

Using symbol values to represent concrete values, e.g.,

W_z^2 : value written to z at line 2

R_x^3 : value read from z at line 3

T2

$$True \equiv R_z^7 == 1$$

$$R_x^8 + 1 \neq R_y^8$$

Example

Init: $x=1, y=2$

T1

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2: $z=0$

3: $x++$

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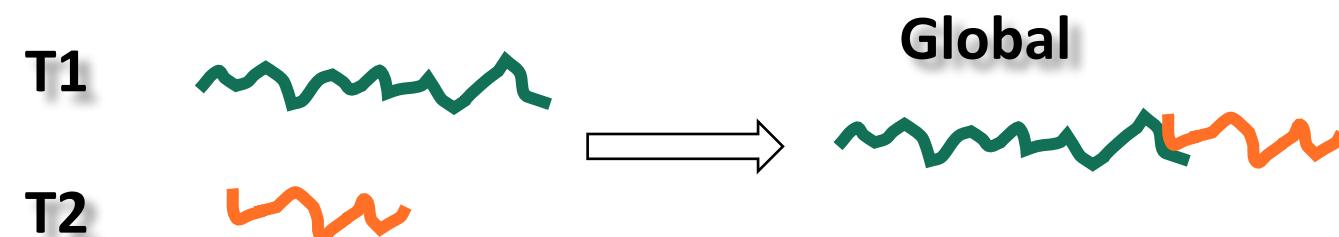
T2

7: if ($z==1$)

8: ~~X~~ assert($x+1==y$)

Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses



Order variable O represents the order of a statement, e.g.,

$$O_2 < O_3$$

means 2: $z=0$ happen before 3: $x++$

Example

Init: $x=1, y=2$

T1

1: T2.start()

2: $z=0$

3: $x++$

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6: T2.join()

T2

7: if ($z==1$)

8: ~~assert~~($x+1==y$)

Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses

Read-Write Constraints

$$(R_z^7 = 0 \wedge O_7 < O_2) \vee (R_z^7 = W_z^5 \wedge O_5 < O_7 \wedge (O_2 < O_5 \vee O_7 < O_2))$$

match a read to a write

Memory Order Constraints

SC

$$\begin{aligned} O_1 &< O_2 < O_3^{R_x} < O_3^{W_x} < O_4^{R_x} \\ &< O_4^{W_x} < O_5 < O_6 \\ O_7 &< O_8^x < O_8^y \end{aligned}$$

PSO

$$\begin{aligned} O_1 &< O_2 & O_5 &< O_6 \\ O_3^{R_x} &< O_3^{W_x} & O_4^{R_x} &< O_4^{W_x} \\ O_7 &< O_8^x &< O_8^y \end{aligned}$$

Path Constraints

$$R_z^7 = 1$$

Failure Constraints

$$R_x^8 + 1! = R_y^8$$

Example

Init: $x=1, y=2$

T1

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T2

7: if ($z==1$)

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Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses

Read-Write Constraints

$$(R_z^7 = 0 \wedge O_7 \leq O_2) \vee (R_z^7 = W_z^5 \wedge O_5 < O_7 \wedge (O_2 < O_5 \vee O_7 < O_2))$$

match a read to a write

Memory Order Constraints

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$$O_1 < O_2 < O_3^{R_x} < O_3^{W_x} < O_4^{R_x} \\ < O_4^{W_x} < O_5 < O_6 \\ O_7 < O_8^x < O_8^y$$

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$$O_1 < O_2 \quad O_5 < O_6 \\ O_3^{R_x} < O_3^{W_x} \quad O_4^{R_x} < O_4^{W_x} \\ O_7 < O_8^x < O_8^y$$

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Example

Init: $x=1, y=2$

T1

1: T2.start()

2: $z=0$

3: $x++$

4: $y++$

5: $z=1$

HA

6: T2.join()

T2

rf

7: if ($z==1$)

8: ~~assert($x+1==y$)~~

Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses

Read-Write Constraints

$$(R_z^7 = 0 \wedge O_7 \leq O_2) \vee (R_z^7 = W_z^5 \wedge O_5 < O_7 \wedge (O_2 < O_5 \vee O_7 < O_2))$$

Memory Order Constraints

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$$\begin{aligned} O_1 &< O_2 < O_3^{R_x} < O_3^{W_x} < O_4^{R_x} \\ &< O_4^{W_x} < O_5 < O_6 \\ O_7 &< O_8^x < O_8^y \end{aligned}$$

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$$\begin{aligned} O_1 &< O_2 & O_5 &< O_6 \\ O_3^{R_x} &< O_3^{W_x} & O_4^{R_x} &< O_4^{W_x} \\ O_7 &< O_8^x & O_8^y & \end{aligned}$$

Path Constraints

$$R_z^7 = 1$$

Failure Constraints

$$R_x^8 + 1! = R_y^8$$

Example

Init: $x=1, y=2$

T1

1: T2.start()

2: $z=0$  **reordering**
3: $x++$  **PSO**

4: $y++$

5: $z=1$

6: T2.join()

T2

7: if ($z==1$)

8:  assert($x+1==y$)

Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses

Read-Write Constraints

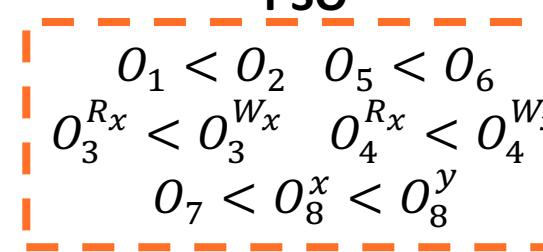
$$(R_z^7 = 0 \wedge O_7 < O_2) \vee \\ (R_z^7 = W_z^5 \wedge O_5 < O_7 \wedge (O_2 < O_5 \vee O_7 < O_2))$$

Memory Order Constraints

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$$O_1 < O_2 < O_3^{R_x} < O_3^{W_x} < O_4^{R_x} \\ < O_4^{W_x} < O_5 < O_6 \\ O_7 < O_8^x < O_8^y$$

PSO



execution should
be allowed by the
memory model

Path Constraints

$$R_z^7 = 1$$

Failure Constraints

$$R_x^8 + 1! = R_y^8$$

Example

Init: $x=1, y=2$

T1

1: T2.start()

2: $z=0$

3: $x++$

4: $y++$

5: $z=1$

6: T2.join()

T2

7: if ($z==1$)

8: assert($x+1==y$)

True

Step 3: computing global failure schedule

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$$O_1 < O_2 \quad O_5 < O_6 \\ O_3^{R_x} < O_3^{W_x} \quad O_4^{R_x} < O_4^{W_x} \\ O_7 < O_8^x < O_8^y$$

Path Constraints

$$R_z^7 = 1$$

Failure Constraints

$$R_x^8 + 1! = R_y^8$$

make the failure happen

Example

Init: $x=1, y=2$

T1

1: T2.start()

2: $z=0$

3: $x++$

4: $y++$

5: $z=1$

6: T2.join()

T2

7: if ($z==1$)

8: ~~assert($x+1==y$)~~ *Violation*

Step 3: computing global failure schedule

CLAP[PLDI'13]: Reason dependencies of memory accesses

Read-Write Constraints

$$(R_z^7 = 0 \wedge O_7 < O_2) \vee \\ (R_z^7 = W_z^5 \wedge O_5 < O_7 \wedge (O_2 < O_5 \vee O_7 < O_2))$$

Memory Order Constraints

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Example

Init: $x=1, y=2$

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3: $x++$

4: $y++$ ↗
5: $z=1$ ↘ **reordering**

6: T2.join()

T2

7: if ($z==1$)

8: ~~X~~ assert($x+1==y$)

Step 3: computing global failure schedule

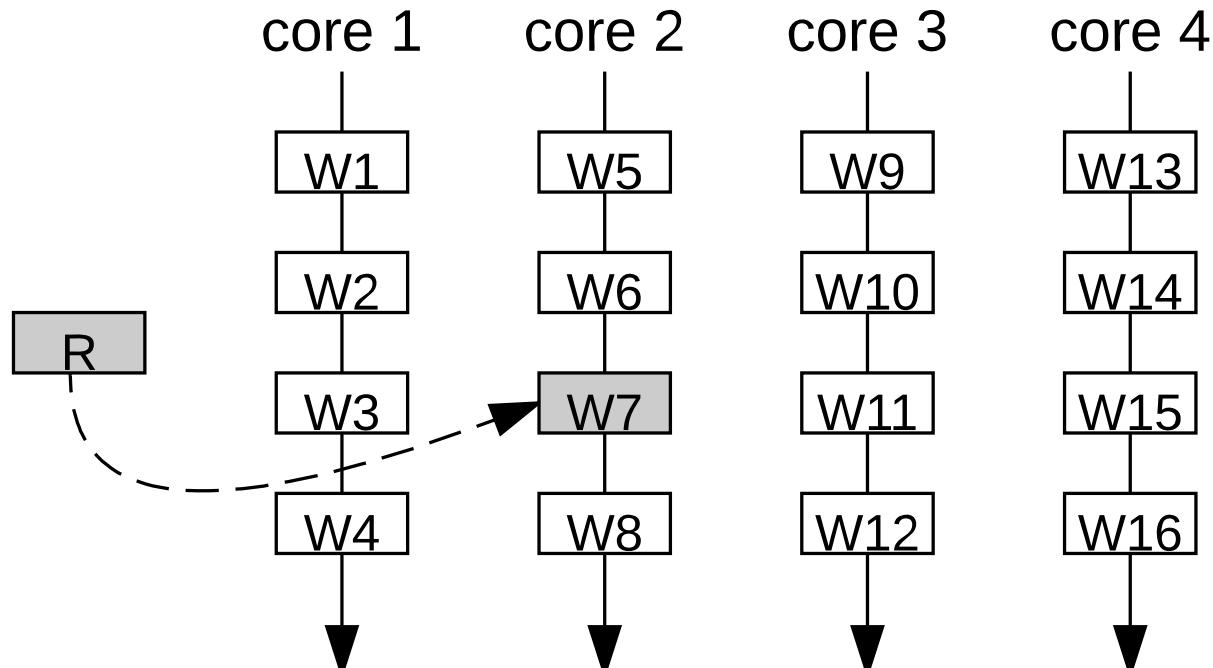
$O_1=1, O_2=2, O_3=3, O_5=4, O_7=5, O_8=6,$
 $O_4=7$

Schedule:

1-2-3-5-7-8-4



Core-based constraints reduction

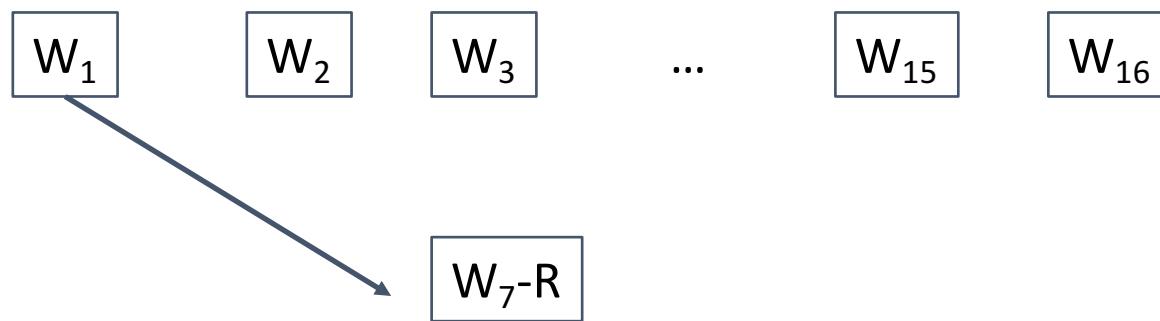


Match R to the write W_7

- All the writes write a different value to the same memory location

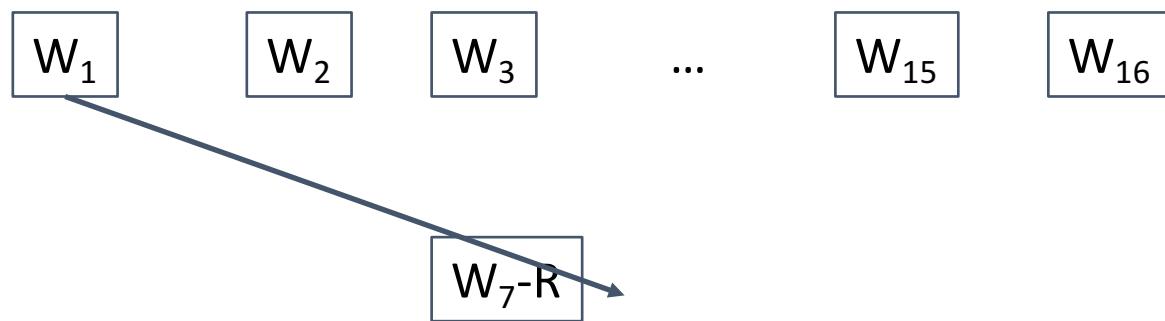
Core-based constraints reduction

Without the partial order on each core



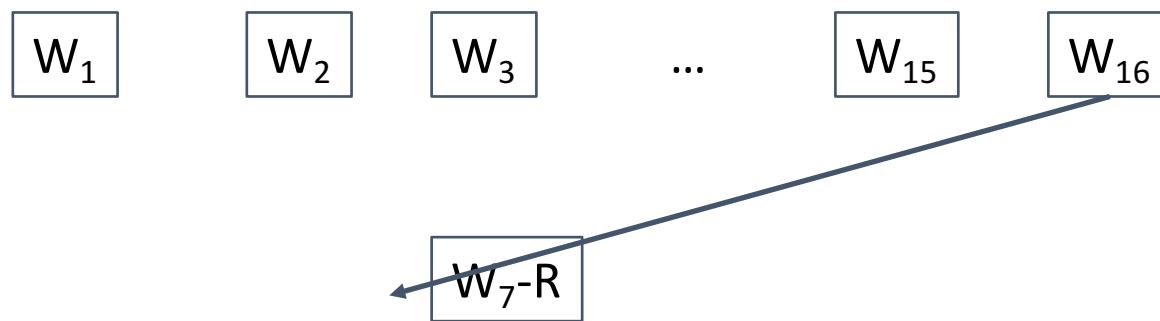
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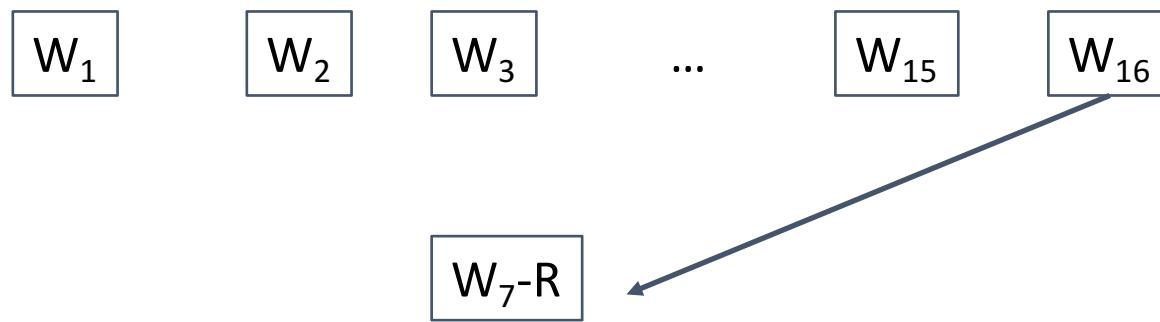
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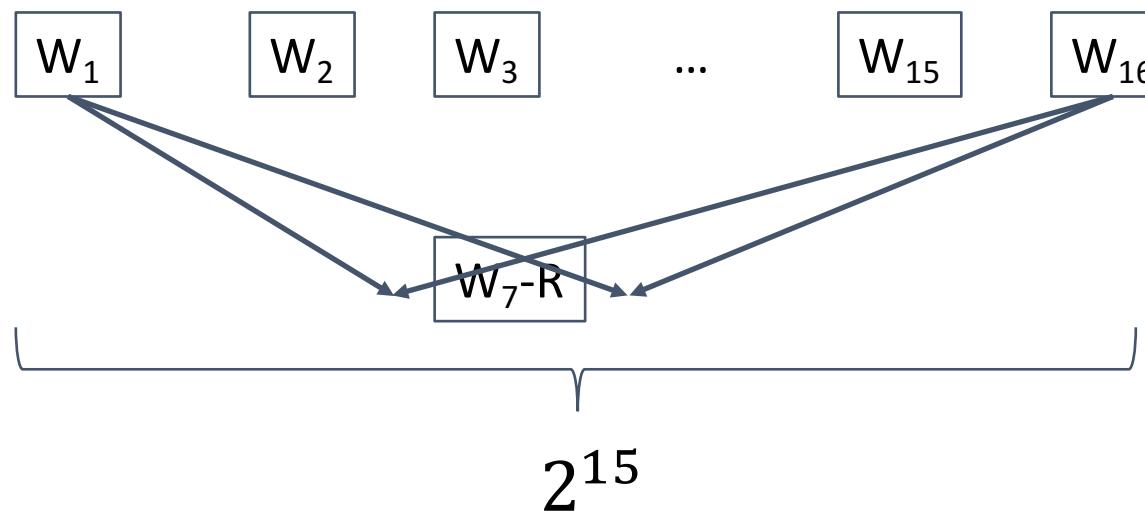
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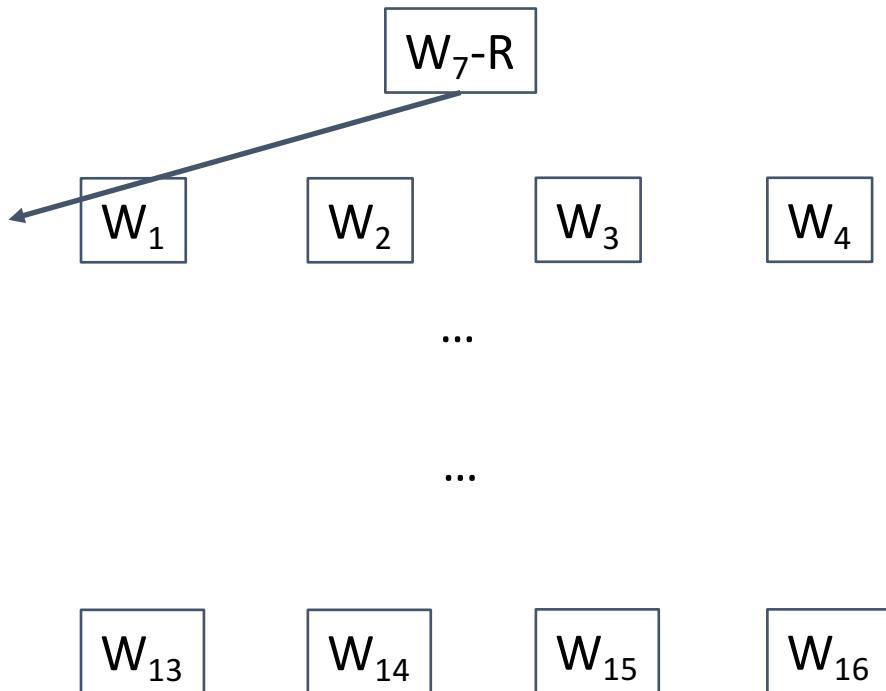
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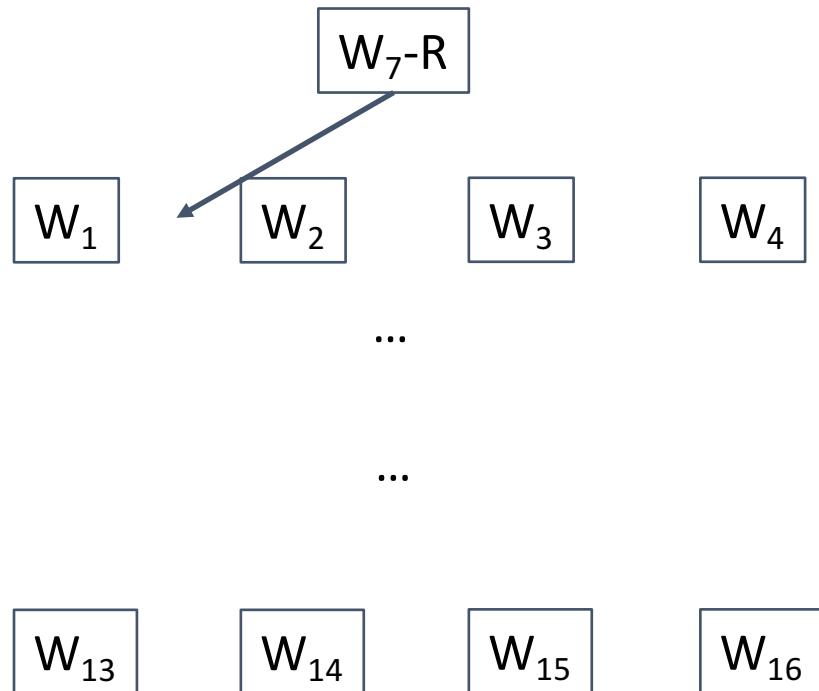
Core-based constraints reduction

Knowing the partial order on each core



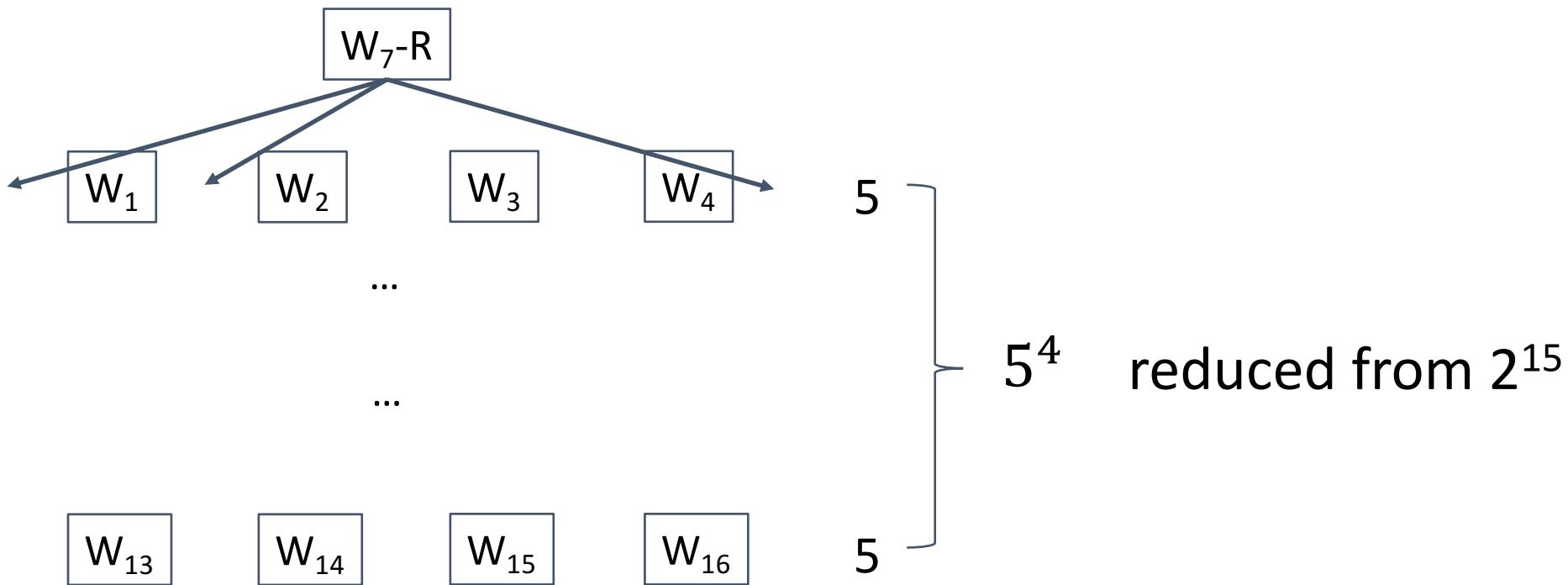
Core-based constraints reduction

Knowing the partial order on each core



Core-based constraints reduction

Knowing the partial order on each core



H3 Implementation

- Control-flow tracing
 - PT decoding library & Linux Perf tool
- Path profiles generation
 - Python scripts to extract the path profiles from PT trace
- Symbolic trace collecting
 - Modified KLEE[OSDI'08] for symbolic execution along the path profiles
- Constraints construction
 - Modified CLAP[PLDI'13] to implement the core-based constraints reduction
 - Z3 for solving the constraints

Evaluation

- Environment
 - 4 core 3.5GHz Intel i7 6700HQ Skylake with 16 GB RAM
 - Ubuntu 14.04, Linux kernel 4.7
- Three sets of experiments
 - runtime overhead
 - how effective to reproduce bugs
 - how effective is the core-based constraints reduction

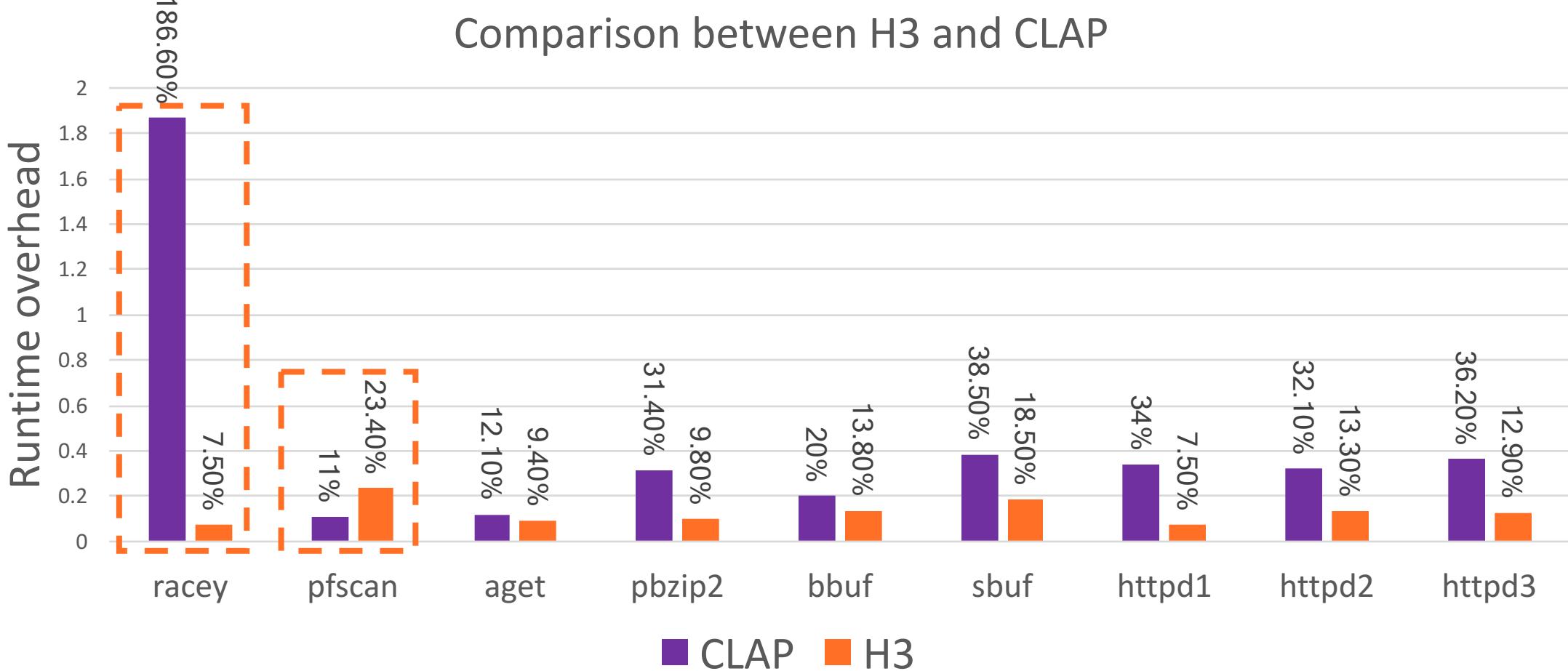
Benchmarks

Program	LOC	#Threads	#SV	#insnns (executed)	#branches (total)	#branches (app)	Ratio app/total	Symb. time
racey	192	4	3	1,229,632	78,117	77,994	99.8%	107s
pfscan	1026	3	13	1,287	237	43	18.1%	2.5s
aget-0.4.1	942	4	30	3,748	313	5	1.6%	117s
pbzip2-0.9.4	1942	5	18	1,844,445	272,453	5	0.0018%	8.7s
bbuf	371	5	11	1,235	257	3	1.2%	5.5s
sbuf	151	2	5	64,993	11,170	290	2.6%	1.6s
httpd-2.2.9	643K	10	22	366,665	63,653	12,916	20.3%	712s
httpd-2.0.48	643K	10	22	366,379	63,809	13,074	20.5%	698s
httpd-2.0.46	643K	10	22	366,271	63,794	12,874	20.2%	643s

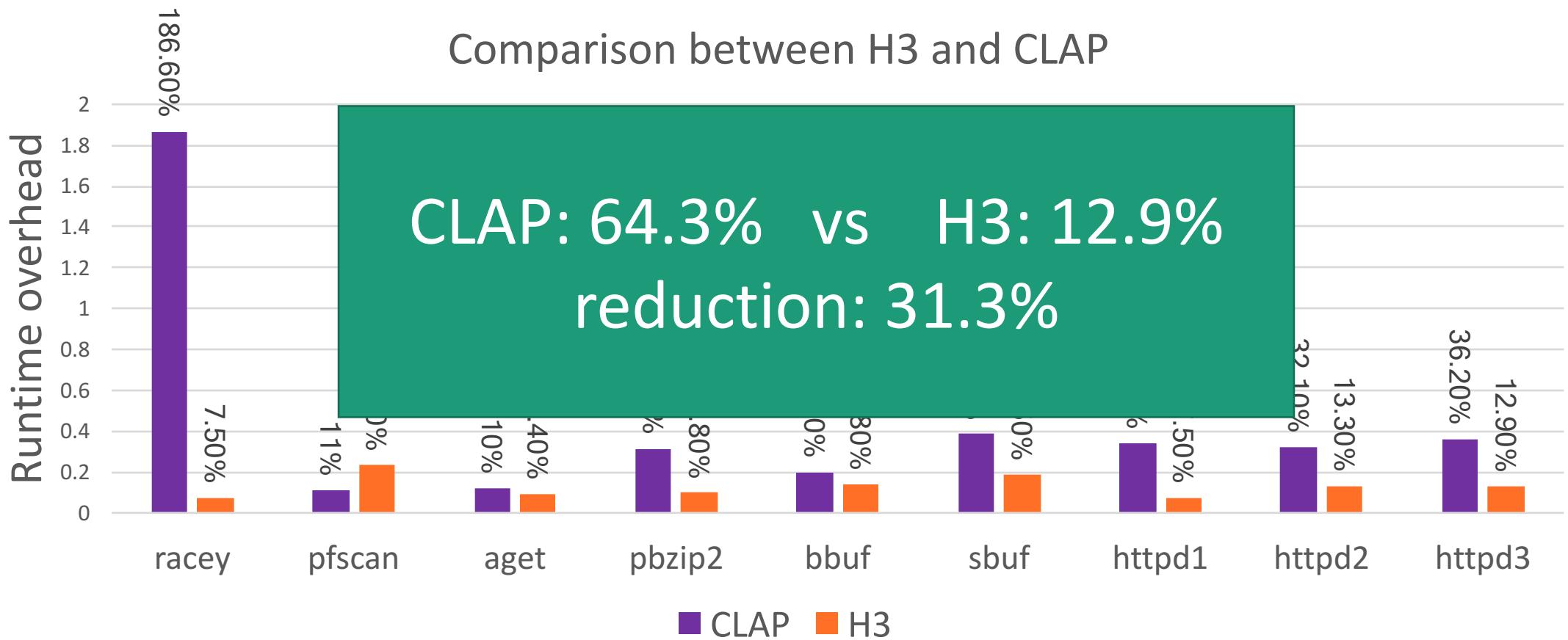
<http://pages.cs.wisc.edu/~markhill/racey.html>

<https://github.com/jieyu/concurrency-bugs>

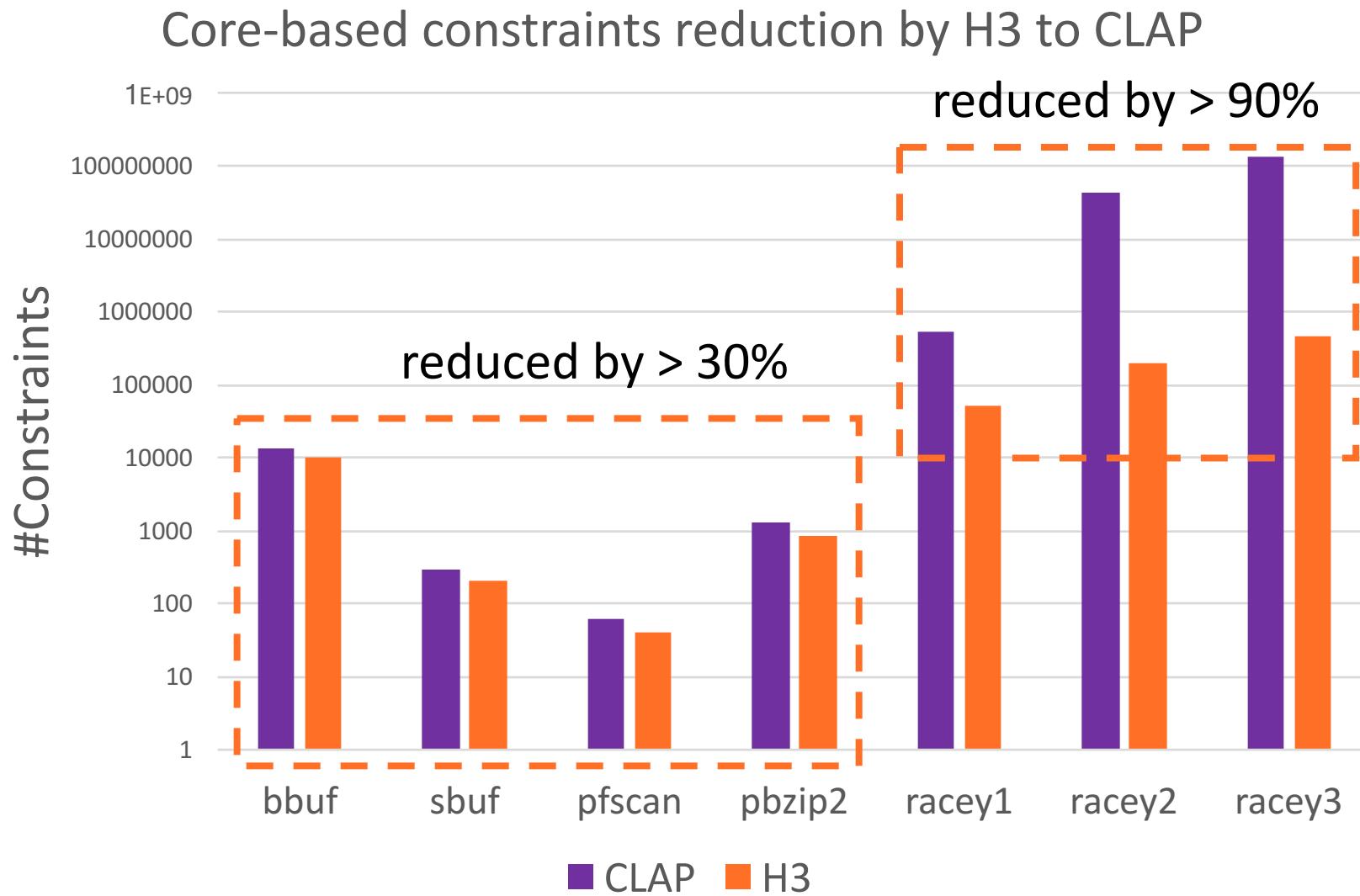
Runtime overhead



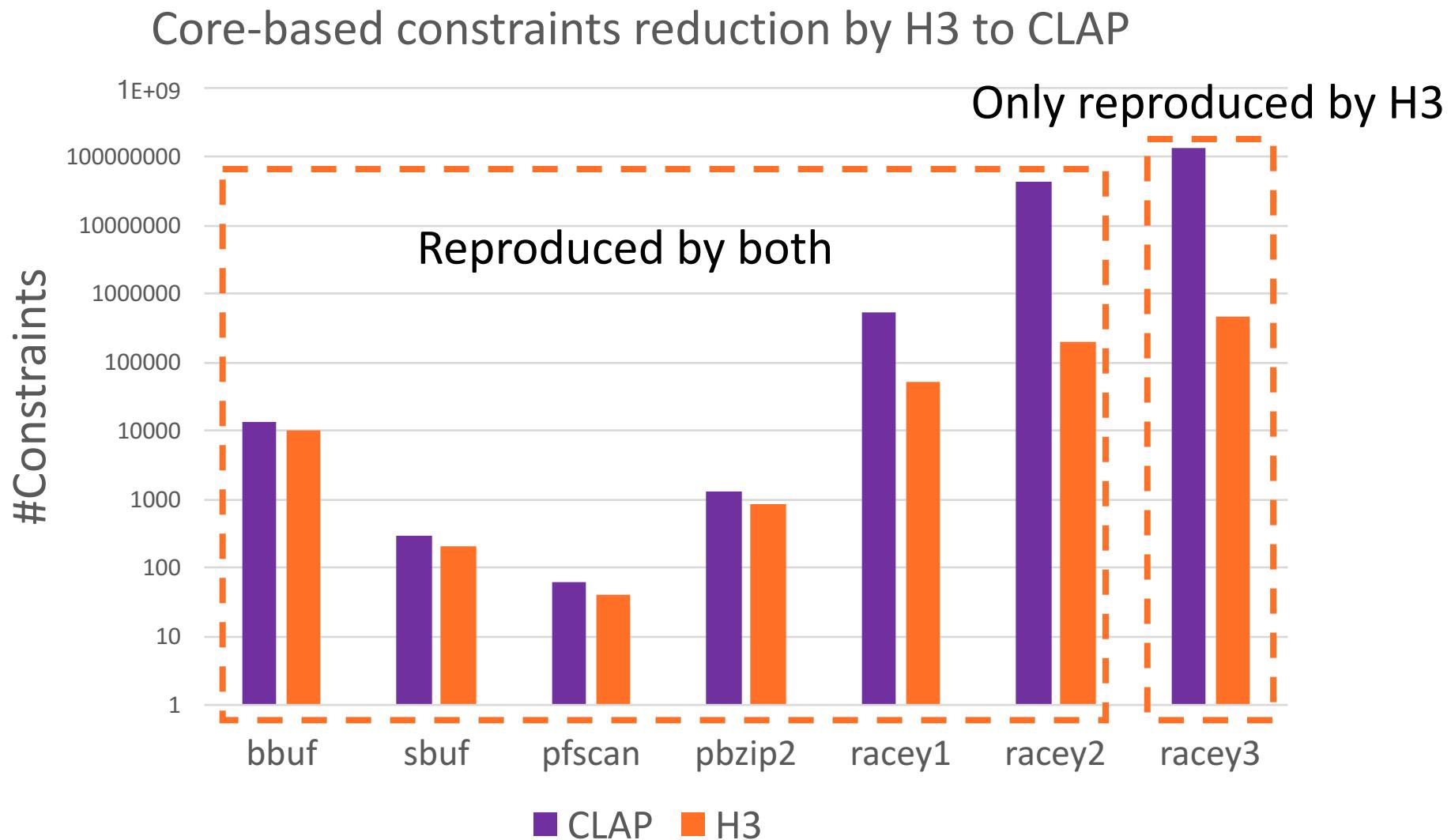
Runtime overhead



Constraints reduction



Bug reproduction



Conclusion

H3: Reproducing Heisenbugs based on *control flow tracing* on commercial hardware (Intel PT)

- Runtime Overhead
 - PARSEC 3.0 : ~4.9%
 - Real application: ~12.9% vs CLAP[PLDI'13] ~64.3%
- Bug reproduction
 - reproduces one more bug than CLAP

Discussion

- Symbolic execution is slow
 - Eliminate symbolic execution: use hardware watchpoints to catch values and memory locations
- Constraints for long traces
 - Use checkpoints and periodic global synchronization
- Non-deterministic program inputs (e.g., syscall results)
 - Integrate with Mozilla RR [USENIX ATC'17]
 - Key insight: use H3 to handle schedules, and RR to handle inputs

Thank you

