

In the Weyl representation we found

$$S^{0i} = -\frac{i}{2} \begin{pmatrix} \sigma^i & 0 \\ 0 & -\sigma^i \end{pmatrix}$$

$$S^{ij} = \frac{1}{2} \varepsilon^{ijk} \begin{pmatrix} \sigma^k & 0 \\ 0 & \sigma^k \end{pmatrix}$$

This is a reducible representation (meaning that the transformations have a block diagonal structure)

Let $\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$ $\left\{ \begin{array}{l} \text{two-component "left" Weyl spinor} \\ \text{two-component "right" Weyl spinor} \end{array} \right.$

Using the forms above for S^{0i} and S^{ij} ,

under an infinitesimal rotation $\vec{\theta}$ and infinitesimal boost $\vec{\beta}$ ($\tanh|\vec{\beta}| = \frac{|\vec{v}|}{c}$ relative velocity between frames)

$$\psi_L \rightarrow (1 - i\vec{\theta} \cdot \frac{\vec{\sigma}}{2} - \vec{\beta} \cdot \frac{\vec{\sigma}}{2}) \psi_L$$

$$\psi_R \rightarrow (1 - i\vec{\theta} \cdot \frac{\vec{\sigma}}{2} + \vec{\beta} \cdot \frac{\vec{\sigma}}{2}) \psi_R$$

The transformation of ψ_R is equivalent to the transformation of ψ_L^* ...

$$\psi_L^* \rightarrow (1 + i\vec{\theta} \cdot \frac{\vec{\sigma}}{2} - \vec{\beta} \cdot \frac{\vec{\sigma}}{2}) \psi_L^*$$

noting that $\sigma^2 \vec{\sigma}^* = -\vec{\sigma} \sigma^2$
 \uparrow
 $\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

we see that

$$\begin{aligned} \sigma^2 \psi_L^* &\rightarrow \sigma^2 (1 + i\vec{\theta} \cdot \frac{\vec{\sigma}}{2} - \vec{\beta} \cdot \frac{\vec{\sigma}}{2}) \psi_L^* \\ &= (1 - i\vec{\theta} \cdot \frac{\vec{\sigma}}{2} + \vec{\beta} \cdot \frac{\vec{\sigma}}{2}) \sigma^2 \psi_L^* \end{aligned}$$

just like ψ_R transformation

The Dirac equation has the form

$$(i\gamma^\mu \partial_\mu - m)\psi = 0$$

or

$$\begin{pmatrix} -m & i(\partial_0 + \vec{\sigma} \cdot \vec{\nabla}) \\ i(\partial_0 - \vec{\sigma} \cdot \vec{\nabla}) & -m \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = 0$$

When $m=0$ there is no coupling of $\psi_L + \psi_R$

$$i(\partial_0 - \vec{\sigma} \cdot \vec{\nabla})\psi_L = 0$$

$$i(\partial_0 + \vec{\sigma} \cdot \vec{\nabla})\psi_R = 0$$

Weyl equations

For later convenience let us define

$$\sigma^\mu = \underset{\substack{\uparrow \\ \text{2x2 identity}}}{(1, \vec{\sigma})}, \quad \bar{\sigma}^\mu = (1, -\vec{\sigma})$$

$$\text{Then } \gamma^\mu = \begin{pmatrix} 0 & \sigma^\mu \\ \bar{\sigma}^\mu & 0 \end{pmatrix}$$

The Dirac equation is

$$\begin{pmatrix} -m & i\bar{\sigma} \cdot \partial \\ i\bar{\sigma} \cdot \partial & -m \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = 0$$

and the Weyl equations are

$$i\bar{\sigma} \cdot \partial \psi_L = 0$$

$$i\bar{\sigma} \cdot \partial \psi_R = 0$$

We found that solutions of Dirac equation are solutions of the Klein-Gordon equation.

Try the form...

$$\psi(x) = u(p) e^{-ip \cdot x} \quad \text{where } p^0 = \sqrt{\vec{p}^2 + m^2} = E_{\vec{p}}$$

These are positive frequency solutions ($e^{-i\omega t}$)

$$(i \gamma^\mu \partial_\mu - m) u(p) e^{-ip \cdot x} = (\gamma^\mu p_\mu - m) u(p) e^{-ip \cdot x}$$

and so $(\gamma^\mu p_\mu - m) u(p) = 0$

Let's assume $m \neq 0$ and go to the rest frame where $p^0 = m$, $\vec{p} = 0$.

Then we have

$$(m \gamma^0 - m) u(p) = 0$$

$$\Rightarrow m \begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix} u(p) = 0$$

So $u(p) = \begin{pmatrix} a \\ b \\ a \\ b \end{pmatrix}$ for any a, b

or $u(p) = \sqrt{m} \begin{pmatrix} \xi \\ \xi \end{pmatrix}$ where $\xi = \begin{pmatrix} a \\ b \end{pmatrix}$
with $|a|^2 + |b|^2 = 1$

Our choice of normalization will be convenient later.

Our rotation generators are

$$S^{ij} = \frac{1}{2} \varepsilon^{ijk} \begin{pmatrix} \sigma^k & 0 \\ 0 & \sigma^k \end{pmatrix}$$

In particular $S_z = S^{12} = \frac{1}{2} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

So $\xi = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ gives $\text{spin-}z = +\frac{1}{2}$

$\xi = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ gives $\text{spin-}z = -\frac{1}{2}$

Since we are in the rest frame

$$p^\mu = \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix} \begin{matrix} \leftarrow p^0 \\ \leftarrow p^1 \\ \leftarrow p^2 \\ \leftarrow p^3 \end{matrix}$$

Suppose we boost to the frame where the particle has velocity $\vec{v} = v \cdot \hat{z}$. Let $\tanh \eta = \frac{v}{c}$. η is called the rapidity. Then

$$p^\mu = \begin{pmatrix} \cosh \eta & 0 & 0 & \sinh \eta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sinh \eta & 0 & 0 & \cosh \eta \end{pmatrix} \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} m \cosh \eta \\ 0 \\ 0 \\ m \sinh \eta \end{pmatrix}$$

In this frame $E = m \cosh \eta$, $p^3 = m \sinh \eta$

Let us now see how our $u(p)$ looks when we boost it by rapidity η in the $+z$ direction.

$$S^{03} = -\frac{i}{2} \begin{pmatrix} \sigma^3 & 0 \\ 0 & -\sigma^3 \end{pmatrix}$$

The boost transformation is

$$M = \exp[-i\eta S^{03}] = \exp\left[-\frac{\eta}{2} \begin{pmatrix} \sigma^3 & 0 \\ 0 & -\sigma^3 \end{pmatrix}\right]$$

Since $\sigma^3 \sigma^3 = 1$,

$$\begin{aligned} \exp[a \cdot \sigma^3] &= 1 + a\sigma^3 + \frac{a^2}{2!}1 + \frac{a^3}{3!}\sigma^3 + \frac{a^4}{4!}1 + \dots \\ &= \cosh a \cdot 1 + \sinh a \sigma^3 \end{aligned}$$

$$\text{So } M = \begin{pmatrix} \cosh \frac{\eta}{2} - \sinh \frac{\eta}{2} \sigma^3 & 0 \\ 0 & \cosh \frac{\eta}{2} + \sinh \frac{\eta}{2} \sigma^3 \end{pmatrix}$$

$$\text{Thus } M_{u(p)} = \sqrt{m} \begin{pmatrix} (\cosh \frac{\eta}{2} - \sinh \frac{\eta}{2} \sigma^3) \xi \\ (\cosh \frac{\eta}{2} + \sinh \frac{\eta}{2} \sigma^3) \xi \end{pmatrix}$$

This looks complicated. Notice that

$$\begin{aligned} (\cosh \frac{\eta}{2} - \sinh \frac{\eta}{2} \sigma^3)^2 &= \cosh^2 \frac{\eta}{2} + \sinh^2 \frac{\eta}{2} - 2 \cosh \frac{\eta}{2} \sinh \frac{\eta}{2} \sigma^3 \\ &= \cosh \eta - \sinh \eta \sigma^3 \\ &= \frac{E}{m} - \frac{p^3}{m} \sigma^3 = \frac{p \cdot \sigma}{m} \quad (\sigma^M = (1, \vec{\sigma})) \end{aligned}$$

$$\text{So } \sqrt{m} (\cosh \frac{\eta}{2} - \sinh \frac{\eta}{2} \delta^3) = \sqrt{p \cdot \bar{\delta}}$$

17

$$\text{Similarly } \sqrt{m} (\cosh \frac{\eta}{2} + \sinh \frac{\eta}{2} \delta^3) = \sqrt{p \cdot \bar{\delta}} \\ (\text{recall } \bar{\delta}^\mu = (1, -\vec{\delta}))$$

$$\text{So } u(p) = \begin{pmatrix} \sqrt{p \cdot \bar{\delta}} \xi \\ \sqrt{p \cdot \bar{\delta}} \xi \end{pmatrix} \quad \text{this is the general form} \\ \text{for arbitrary } p$$

$$\text{Useful fact: } (\vec{p} \cdot \vec{\delta})^2 = \vec{p}^2 \text{ and so} \\ (p \cdot \bar{\delta})(p \cdot \bar{\delta}) = (p^0)^2 - \vec{p}^2 = p^2 = m^2$$

Back to our specific example with momentum

$$p = (E, 0, 0, p^3)$$

$$p \cdot \bar{\delta} = \begin{pmatrix} E - p^3 & 0 \\ 0 & E + p^3 \end{pmatrix}$$

$$\text{And so } \sqrt{p \cdot \bar{\delta}} = \begin{pmatrix} \sqrt{E - p^3} & 0 \\ 0 & \sqrt{E + p^3} \end{pmatrix}$$

$$\text{Similarly } \sqrt{p \cdot \bar{\delta}} = \begin{pmatrix} \sqrt{E + p^3} & 0 \\ 0 & \sqrt{E - p^3} \end{pmatrix}$$

For $\text{spin}-z = +\frac{1}{2}$

$$u(p) = \begin{pmatrix} \sqrt{E-p^3} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ \sqrt{E+p^3} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{pmatrix}$$

For $\text{spin}-z = -\frac{1}{2}$

$$u(p) = \begin{pmatrix} \sqrt{E+p^3} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \sqrt{E-p^3} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{pmatrix}$$

Notice that in the massless limit $E \rightarrow p^3$ and so

$$u(p) = \begin{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \sqrt{2E} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{pmatrix} \quad \text{for } \text{spin}-z = +\frac{1}{2}$$

$$u(p) = \begin{pmatrix} \sqrt{2E} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{pmatrix} \quad \text{for } \text{spin}-z = -\frac{1}{2}$$

The helicity operator

$$h \equiv \hat{p} \cdot \vec{S} \quad (\text{where } \begin{aligned} S^1 &\equiv S^{23} \\ S^2 &\equiv S^{31} \\ S^3 &\equiv S^{12} \end{aligned})$$

is the component of spin

in the direction of motion

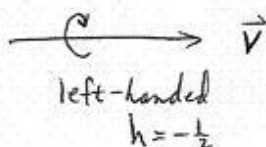
$$h = \frac{1}{2} \hat{p} \cdot \begin{pmatrix} \vec{\sigma} & 0 \\ 0 & -\vec{\sigma} \end{pmatrix}$$

When $h = +\frac{1}{2}$ we call it right-handed

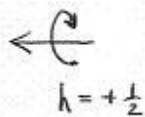
$h = -\frac{1}{2}$ we call it left-handed

Helicity is frame dependent

Suppose we have a particle in our reference frame



If we now boost to velocity $\vec{v}' > \vec{v}$ along the direction of \vec{v} then the particle now looks right-handed



For massless particles h is not changeable...

you can't catch up to a massless particle since it goes at the speed of light.

Let's return to the Weyl equations.

$$i(\partial_0 - \vec{\sigma} \cdot \vec{\nabla}) \psi_L = 0$$

$$i(\partial_0 + \vec{\sigma} \cdot \vec{\nabla}) \psi_R = 0$$

The ∂_0 on $e^{-i\vec{p} \cdot \vec{x}}$ gives $-iE$
 $\vec{\nabla}$ on $e^{-i\vec{p} \cdot \vec{x}}$ gives $i\vec{p}$

For a massless particle $\vec{p} = |\vec{p}| \hat{p} = E \hat{p}$

So the Weyl equations read

$$(E + E \hat{p} \cdot \vec{\sigma}) \psi_L = 0 \Rightarrow E(1 + 2h) \psi_L = 0$$

$$(E - E \hat{p} \cdot \vec{\sigma}) \psi_R = 0 \Rightarrow E(1 - 2h) \psi_R = 0$$

So ψ_L has $h = -\frac{1}{2}$

ψ_R has $h = +\frac{1}{2}$