An analogous adiabatic following is also what we count on in magnetic trapping. Take a quadrapole magnetic trap: MA F(t), trajectory of atom At the location of adom,

B-fill is $B(F(t)) \equiv B_{gg}(t)$ We want the magnetic moment of the atom

to follow tightly the local magnetic field

direction. Otherwise it would no longer be trapped. B-fill is B(=(+)) = Bg(+) So we need that the rate of change of the direction of \vec{B} , $\vec{J} \approx \frac{\vec{B}}{\vec{B}} = \frac{\vec{B}'\vec{V}}{\vec{B}} = \frac{\vec{V}}{\vec{V}}$ is much smaller Han the precession period $\Omega_{L} = \gamma B = \gamma B' r$ $\Rightarrow = \frac{1}{2} \ll \gamma B' r \Rightarrow r = \sqrt{\frac{V}{\gamma B'}} \quad \text{if } de$ radius of the "Ma forma hole" within which the particles will be lost from the trap Solutions: 1. Plug the hole! Kettale et al. PRL 75,3969 (1995) Enables 2. TOP trap: Rotate the magnetic field SEC Zero rapidly on a large circle. Comble group, PRL 74, 3352 (1995)

Quantized Sph in a magnetic field: $\ddot{H} = -\hat{\beta} \cdot \vec{B} = -\chi \hat{L}_z B_0$ Ly is the operator associated with augular momentum along 2. Heisenberg equations of motion $\frac{d}{dt} \hat{O} = \frac{i}{t} [\hat{H}, \hat{O}] + \frac{\partial \hat{O}}{\partial t}$ => de fin = if [H, Ch] using [Li, Li] = it Eigh Lk we see $\frac{d}{dt} \hat{p}_{u} = \gamma \vec{p} \times \vec{B} \quad exact!$ and in particular $\frac{d}{dt} < \hat{p}_{k} > = \gamma < \vec{p} > \times \vec{B}$ expectation values =) Same equation of motion as for a classical magnetic moment for any value of angular momentum!

Comments:

· this is valid for any angular momentum operator, so also for Spn 1/2.

- and therefore for any two-level system that can be mapped onto spin precession

· valid for the case of several angular momenta within an atom complet to a total angular momentum F (as long as B is not large enough to "break" the coupling).

· valid also for a system of N two-level systems symmetrically coupled to an extend field. In this case, we have an effective angular momentum $L = \frac{N}{2}$

Spin precession -> Diche superrationee constructive interference of N'aliquel' particles.

Two-level system, spin $\frac{1}{2}$ — les — IT — $m = +\frac{1}{2}$ — Ig — $M = -\frac{1}{2}$ with (n - n) y to (n - n)

=> = 2t (P1 - P1) = 2t (2Pe-1)

Start at
$$t=0$$
 with $P_g(t=0)=1$.

$$P_e(t) = \frac{1}{hy} \langle p_2 \rangle + \frac{1}{2}$$
use classical solution
$$= \frac{1}{2} - \frac{1}{7} \left(1 - 2 \frac{\omega R^2}{\Omega_{12}^2} \sin^2\left(\frac{\Omega_R t}{2}\right)\right)$$

$$P_{e}(t) = \frac{\omega_{n}^{2}}{\Omega_{n}^{2}} \sin^{2}\left(\frac{\Omega_{n}t}{2}\right)$$

$$Rabi + ranibian probability$$

$$\frac{Spin \frac{1}{2} \quad Hamiltonian}{1e \rangle = \binom{1}{0}}{|g\rangle} = \binom{0}{1}$$

$$B_o = B_o \hat{z}$$

$$H_o = -\vec{p} \cdot \vec{B} = -\gamma \hat{s}_z B_o$$

$$= \frac{\hbar \omega_o}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\sigma_z \quad Panli \quad madrix$$

=> Eigenstates are le>, lg>, with eigenenegits = two

Take a spin initially aligned along
$$\hat{x}$$

$$|Y(t=0)\rangle = \frac{1}{VZ}(le) + lg\lambda$$

$$|Y(t)\rangle = \frac{1}{VZ}(e^{-i\frac{\omega_t}{2}}le) + e^{+i\frac{\omega_t}{2}}lg\lambda$$

$$= \frac{1}{VZ}e^{-i\frac{\omega_t}{2}}(le) + e^{i\omega_t}lg\lambda$$

$$precession in the xy plane of frequency $\omega_0$$$

Spin
$$\frac{7}{2}$$
 in a rotating magnetic field

 $H_0 = -\tilde{p} \cdot \tilde{B}_0 = -\tilde{p} \tilde{B}_0 \cdot \hat{S} \cdot \hat{z}$
 $= \frac{t \omega_0}{2} \sigma_2 = \frac{t \omega_0}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$
 $\omega_0 = -\frac{3}{2} \frac{B_0}{C}$

Eigenstates $|\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

Eigensenergies $\pm \frac{t \omega_0}{2}$
 $H_1 = -\tilde{p} \cdot \tilde{B}_1 = -\tilde{p} \cdot \frac{\omega_R}{2} \left(-\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t) \right)$
 $= \omega_R \left(\hat{S}_x \cos(\omega t) + \hat{S}_y \sin(\omega t) \right)$
 $= \frac{t \omega_R}{2} \left(\sigma_x \cos(\omega t) + \sigma_y \sin(\omega t) \right)$
 $= \frac{t \omega_R}{2} \left(\sigma_x \cos(\omega t) + \sigma_y \sin(\omega t) \right)$
 $= \frac{t \omega_R}{2} \left(\frac{0}{e^{i\omega t}} \cdot \frac{1}{\omega_R} \right)$

This is exact.

Transform to robering from

Robation about
$$\hat{z}$$
 by angle \hat{z} :

 $e^{-i\hat{S}_{\hat{z}}\cdot\hat{y}} = e^{-i\frac{\omega t}{2}}\sigma$:

 $= \left(e^{i\frac{\omega t}{2}} = 0\right)$
 $= \left(e^{i\frac{\omega t}{2}} = 0\right)$

=>
$$\widetilde{H} = \frac{t}{2} \begin{pmatrix} -\delta & \omega_R \\ \omega_R & \delta \end{pmatrix}$$
 $\delta = \omega - \omega_R$

= $-\frac{t}{2} \sigma_{\tau} + \frac{t}{2} \sigma_{\chi}$

= $\frac{1}{2} \widetilde{h} \cdot \widetilde{\sigma}$ with $\widetilde{h} = \begin{pmatrix} t \omega_R \\ -t \sigma \end{pmatrix}$

=> $\frac{t}{2} \widetilde{h} \cdot \widetilde{\sigma}$ with $\widetilde{h} = \begin{pmatrix} t \omega_R \\ -t \sigma \end{pmatrix}$

=> $\frac{t}{2} \widetilde{h} \cdot \widetilde{\sigma}$ with $\widetilde{h} = \begin{pmatrix} t \omega_R \\ -t \sigma \end{pmatrix}$

=> $\frac{t}{2} \widetilde{h} \cdot \widetilde{\sigma}$ with $\widetilde{h} = \begin{pmatrix} t \omega_R \\ -t \sigma \end{pmatrix}$ with $\widetilde{h} = \frac{t}{2} \widetilde{h} = \frac{$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \\ -t \sigma \end{pmatrix} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \\ -t \sigma \end{pmatrix} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \\ -t \sigma \end{pmatrix} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \\ -t \sigma \end{pmatrix} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

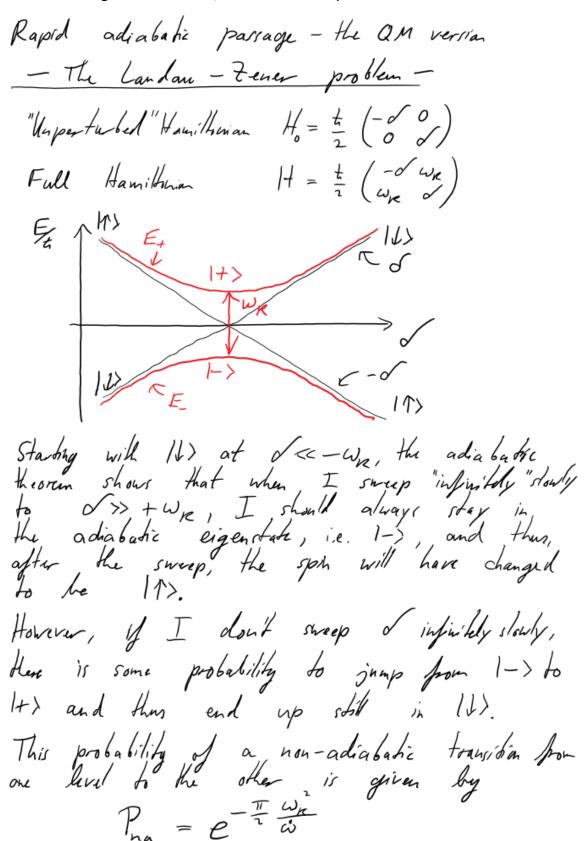
$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \end{pmatrix} = \frac{\omega_{R}}{-\sigma}$$

$$\hat{z} \times \vec{h} = \begin{pmatrix} 0 \\ t \omega_{R} \\ 0 \end{pmatrix} \times \begin{pmatrix} t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_{R} \\ t \omega_{R} \\ 0 \end{pmatrix} = \begin{pmatrix} t \omega_{R} \\ t \omega_$$

To remember: The hamiltonian

$$\widetilde{H} = \frac{1}{2} \begin{pmatrix} -\sigma & \omega_{R} \\ \omega_{R} & \sigma' \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \sin \varphi \\ \sin \varphi & -\cos \varphi \end{pmatrix}$$
with $\cos \varphi = \frac{\sigma}{\Omega_{R}} = \frac{1}{2} \begin{pmatrix} \Omega_{R} & 0 \\ 0 & -\Omega_{R} \end{pmatrix}$

$$\widetilde{H}^{\dagger} = R^{\dagger} \widetilde{H} R = \frac{1}{2} \begin{pmatrix} \Omega_{R} & 0 \\ 0 & -\Omega_{R} \end{pmatrix}$$
Check $\widetilde{H} R | T \rangle = \widetilde{H} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} = \frac{1}{2} \Omega_{R} \begin{pmatrix} \cos \varphi & \varphi \\ \sin \varphi & \varphi \end{pmatrix} =$



Note that this implies a criterion identical to the che we had found classically to have a successful rapid adiabatic panage: $\omega \ll \omega_R \implies P_{na} \ll 1$ = evolution is to good approximation adiabatic. For faster sweeps, we have is >> WR : I only small probability for sph flip. Plis = 1 - Pha will then he small. - Calculate Pip perturbatively, assuming with win $H = \frac{t_1}{2} \begin{pmatrix} \omega_0 & \omega_R e^{-i\varphi(t)} \\ \omega_R e^{i\varphi(t)} & -\omega_0 \end{pmatrix}$ in Lub france Hamiltonian: g(+) - phase of my driving field In frame rotating $\overline{H} = \frac{t}{2} \begin{pmatrix} 0 & \omega_{R} e^{-i(\rho(H) - \omega_{o}t)} \\ \omega_{R} e^{-i(\rho(H) - \omega_{o}t)} \end{pmatrix}$

Easiest is to use \overline{H} , the ham, bouran in the prame obtaining at ω_0 .

Take $|Y(t)\rangle = \alpha(t)|1\rangle + b(t)|1\rangle$ $\dot{\alpha} = -i\frac{\omega_R}{2}e^{-i(\varphi(t)-\omega_0 t)}t$ $\dot{b} = -i\frac{\omega_R}{2}e^{+i(\varphi(t)-\omega_0 t)}\alpha$ Let's assume a linear sweep $S(t) = \dot{\varphi} - \omega_0 = \Delta t$ $\Rightarrow \rho(t) = \omega_0 t + \frac{1}{2}\Delta t^2 \qquad (\Delta = \dot{\omega} = cond.)$ $\dot{\alpha} = -i\frac{\omega_R}{2}e^{-i\frac{1}{2}\Delta t^2}t$

 $\dot{a} = -i \frac{\omega_R}{2} e^{-i\frac{1}{2}\lambda t^2} b$ $\dot{b} = -i \frac{\omega_R}{2} e^{+i\frac{1}{2}\lambda t^2} a$

Perturbative calculation: Let's orsume we start in $|1\rangle$, and we have weak coupling so $b\approx 1$ throughout. Then

 $\dot{\alpha} \approx -i \frac{\omega_R}{2} e^{-i\frac{1}{2}\lambda t^2}$

We see that a will only grow significantly for times such that $2tt^2 \le 1$, so in a range $\Delta t \sim \frac{1}{\sqrt{2}} = \frac{1}{160}$ around t = 0 where we are on resonance. Outside this time interval a oscillator rapidly and a no longer accumulates amplitude.

We can thus estimate $\alpha \approx \omega_R \cdot \Delta t \approx \frac{\omega_R}{\sqrt{\omega}}$. Then $P_{lin} = |a|^2 \sim \frac{\omega_R}{i}$, which is correct. Let's do it with prefactors: $\dot{\alpha} = -i \frac{\omega_R}{2} e^{-i\frac{1}{2}\lambda t^2}$ $=) \quad \alpha(t) = -i \frac{\omega_R}{2} \int dt \ e^{-i\frac{1}{2}\lambda t^2} = -i \omega_R \int dt \ e^{-i\frac{1}{2}\lambda t^2}$ change of variables $\tau^2 = it^2 =$ $\tau = e^{i\frac{\pi}{4}}t$ $e^{i\frac{\pi}{4}\infty}$ $d\tau = e^{i\frac{\pi}{4}}dt$ $e^{i\frac{\pi}{4}}\omega_R \int d\tau e^{-\frac{1}{2}L\tau^2} \int_{0}^{\ln t} \int_{0}^{\pi} dt$ $= -ie^{-i\frac{\pi}{4}}\omega_R \sqrt{\frac{\pi}{2L}}$ $=) P_{\text{slip}} = |a|^2 = \frac{\pi}{2} \frac{\omega_R^2}{\dot{\omega}}$ exact limit of $1 - e^{-\frac{\pi}{2} \frac{\omega_R^2}{\dot{\omega}}}$ (the non-perturbative result!) Non-perturbative calculation

First, let's point out that since we are after the probability of being in 17% or 16%, we know that our problem is classical at heart. We can map the question on the spin-flip probability to the problem of a classical spin precessing in a time-varying unagreetic field where B_{x} is static but B_{z} is varied from large and negative to large and positive. We saw the solutions in the last bestone. Mathematically, we could thus aftempt solving the equation $L = L \times y B(t)$ and read of the answer from $P_e = \frac{1}{2} \left(\frac{L_2}{L} + 1 \right)$ The equations are however even less transparent than what we derived for the spin & case, so let's proceed with those: Start again with the two coupled equations $\dot{\alpha} = -i \frac{\omega_R}{2} e^{-i\frac{1}{2}\lambda t^2} b \quad \text{with boundary candidate}$ $\dot{l} = -i \frac{\omega_R}{2} e^{+i\frac{1}{2}\lambda t^2} \alpha \quad \alpha(-\infty) = 0; \quad b(-\infty) = 1$ $\Rightarrow \alpha = -i \frac{\omega_e}{2} e^{-\frac{1}{2}\lambda t^2} \dot{b} -i\lambda t \dot{a}$ 22t = 1/2-2/7EL $\alpha = -\frac{\omega_R^2}{4} \alpha - i \lambda t \alpha$ Substituting $\alpha = e^{-\frac{i}{4}\lambda t^2}C \Rightarrow \dot{\alpha} = e^{-\frac{i}{4}\lambda t^2}\dot{c} - \frac{1}{2}\lambda t e^{-\frac{i}{4}\lambda t^2}\dot{c}$ $\dot{\alpha} = e^{-\frac{i}{4}\lambda t^2}\dot{c} - i\lambda t e^{-\frac{i}{4}\lambda t^2}\dot{c} - \left(\frac{1}{4}\lambda^2 t^2 + i\frac{\lambda}{2}\right)e^{-\frac{i}{4}\lambda t^2}\dot{c}$ => c -iatc - 1/2 tc-12c = - we'c -ixtc - 1/2t'c $\ddot{C} + \left(\frac{\omega_{R}^{2}}{4} - i\frac{\alpha}{2} + \frac{\alpha^{2}}{4}t^{2}\right)C = 0$ We ber equation

We can introduce a scaled time 7 = 12 p-14 + We old a similar change of variables for the perhabsine calculation: $\Delta t = \frac{1}{12}$ was the characteristic time spent near resonance ($\mathcal{L} \approx 0$) where the phase $\mathcal{L}(t)$ old not change much and the amplitude a was able to grow apprecially. The $e^{i\frac{\pi}{4}}$ factor was used to turn $e^{-i\frac{\pi}{2}\Delta t}$ into a real gamman $e^{-i\frac{\pi}{2}\Delta t}$ =) $dz = \sqrt{2} e^{-i\frac{\pi}{4}} dt$ $\frac{d^2C}{dt^2} = \frac{d^2C}{dz^2} de^{-i\frac{\pi}{2}} = -\left(\frac{\omega_R^2}{4} - \frac{i\lambda}{2} + \frac{\lambda^2}{4}z^2\right)C$ = - di(-i \overline \frac{\pi^2}{4d} - \frac{1}{2} + \frac{2^2}{11}) C $\Rightarrow \left(\frac{d^2C}{dz^2} + \left(i\frac{\omega_R^2}{4\omega} + \frac{1}{2} - \frac{z^2}{4}\right)C = 0\right)$ Compare to hamour oscillator: - to Y" + 1 mw2x2 Y = EY or $\frac{d^2 f}{dx^2} + \left(n + \frac{1}{2} - \frac{x}{4}\right) \psi = 0$ with $E = \frac{t}{u} \left(n + \frac{1}{2}\right)$ \Rightarrow here $N = i \frac{\omega_R^2}{4\lambda}$ imaginary. Boundary conditions $\alpha = e^{-i\frac{\pi}{4}\pm t^2}C = 0$ at $t = -\infty$ Mo: $L(-\infty) = 1 \Rightarrow \alpha = -i\frac{\omega_R}{2}e^{-\frac{1}{2}iAt^2} = -i\frac{\omega_R}{2}e^{\frac{3^2}{2}}$ of $t = -\infty$ $= e^{-\frac{i\pi}{2}At^2}c = e^{\frac{3^2}{2}iAt^2} = -i\frac{\omega_R}{2}e^{\frac{3^2}{2}}$ $= e^{-\frac{i\pi}{2}At^2}c = e^{\frac{3^2}{2}iAt^2}e^{\frac{3^2}{2}}$ $= e^{-\frac{i\pi}{2}At^2}c = e^{\frac{3^2}{2}iAt^2}e^{-\frac{i\pi}{2}iAt^2}$ $= \frac{dc}{dt}(-\infty)e^{-\frac{i\pi}{2}}e^{-\frac{i\pi}{2}iAt^2}e^{-\frac{i\pi$ Solution: Porabolic cylinder functions $c(z) = \frac{\omega_R}{2\sqrt{\lambda}} e^{-\frac{\pi}{2} \frac{\omega_R}{4\lambda}} D_{-1-i\frac{\omega_R}{2\lambda}} (iz)$ (anum, 2 > 1) With there are finds $|\alpha(\infty)|^2 = 1 - e^{-\frac{\pi}{2} \frac{\omega n}{\alpha}}$