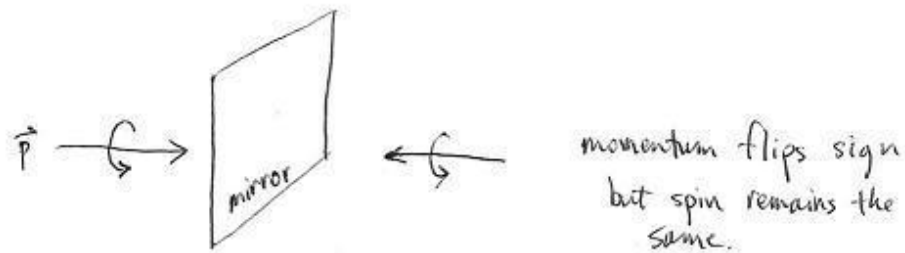


Discrete symmetries

Parity (P) flips the direction of spatial vectors

$$P: (t, \vec{x}) \rightarrow (t, -\vec{x})$$



As an operator on the creation and annihilation operators, we want

$$P^\dagger a_{\vec{p}}^s P = a_{-\vec{p}}^s$$

$$P^\dagger b_{\vec{p}}^s P = b_{-\vec{p}}^s$$

where P is some unitary operator, $P^\dagger P = P P^\dagger = 1$.

Taking the Hermitian conjugate, we also have

$$P^\dagger a_{\vec{p}}^{s\dagger} P = a_{-\vec{p}}^{s\dagger}$$

$$P^\dagger b_{\vec{p}}^{s\dagger} P = b_{-\vec{p}}^{s\dagger}$$

Actually this is a little too restrictive.

We could have

$$P^\dagger a_{\vec{p}}^s P = \eta_a a_{-\vec{p}}^s$$

$$P^\dagger b_{\vec{p}}^s P = \eta_b b_{-\vec{p}}^s$$

So long as $|\eta_a|^2 = |\eta_b|^2 = 1$. This is because all observables will have fermion operators in pairs and the phases η_a and η_b are not present in

those:

$$P^\dagger a_{\vec{p}}^{s\dagger} a_{\vec{p}}^s P = a_{-\vec{p}}^{s\dagger} a_{-\vec{p}}^s$$

$$P^\dagger b_{\vec{p}}^{s\dagger} b_{\vec{p}}^s P = b_{-\vec{p}}^{s\dagger} b_{-\vec{p}}^s$$

Let us implement parity on $\psi(x)$:

$$P^\dagger \psi(x) P = \int \frac{d^3\vec{p}}{(2\pi)^3 \sqrt{2E_{\vec{p}}}} \sum_{s=1,2} \left(\eta_a a_{-\vec{p}}^s u^s(\vec{p}) e^{-ip \cdot x} + \eta_b^* b_{-\vec{p}}^{s\dagger} v^s(\vec{p}) e^{ip \cdot x} \right)$$

Let us define $\tilde{p} = (E_{\vec{p}}, -\vec{p})$

$\tilde{x} = (t, -\vec{x})$

Note that

$$u^s(\vec{p}) = \begin{pmatrix} \sqrt{p \cdot \vec{\epsilon}} \xi^s \\ \sqrt{p \cdot \vec{\bar{\epsilon}}} \xi^s \end{pmatrix} \quad \begin{aligned} \vec{\epsilon} &= (1, \vec{\epsilon}) \\ \vec{\bar{\epsilon}} &= (1, -\vec{\epsilon}) \end{aligned}$$

$$= \begin{pmatrix} \sqrt{\vec{p} \cdot \vec{\bar{\epsilon}}} \xi^s \\ \sqrt{\vec{p} \cdot \vec{\epsilon}} \xi^s \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} u^s(-\vec{p}) = \gamma^0 u^s(-\vec{p})$$

$$\begin{aligned} v^s(\vec{p}) &= \begin{pmatrix} \sqrt{p \cdot \vec{\epsilon}} \xi^s \\ -\sqrt{p \cdot \vec{\bar{\epsilon}}} \xi^s \end{pmatrix} = \begin{pmatrix} \sqrt{\vec{p} \cdot \vec{\bar{\epsilon}}} \xi^s \\ -\sqrt{\vec{p} \cdot \vec{\epsilon}} \xi^s \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} v^s(-\vec{p}) \\ &= -\gamma^0 v^s(-\vec{p}) \end{aligned}$$

So therefore

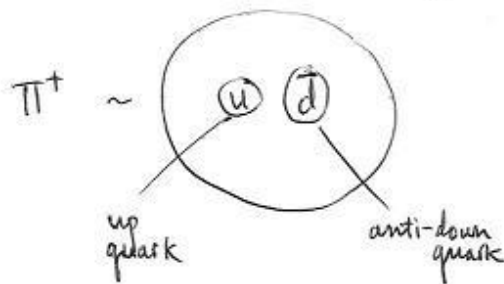
$$P^\dagger \psi(x) P = \gamma^0 \int \frac{d^3 \vec{p}}{(2\pi)^3 \sqrt{2E_{\vec{p}}}} \sum_{s=1,2} \left(\eta_a a_{-\vec{p}}^s u^s(-\vec{p}) e^{-i\vec{p} \cdot \vec{x}} - \eta_b^* b_{-\vec{p}}^{s\dagger} v^s(-\vec{p}) e^{i\vec{p} \cdot \vec{x}} \right) \quad (\vec{p} \cdot \vec{x} = p \cdot x)$$

We see that if $\eta_a = -\eta_b^*$ then

$$P^\dagger \psi(x) P = \eta_a \gamma^0 \psi(\vec{x})$$

Typically one chooses $\eta_a = +1$, $\eta_b = -1$. The choice is up to you. The relative minus sign

between fermion and anti-fermion is the reason that pi-mesons have odd parity.



$$\begin{aligned}
 P^\dagger \bar{\psi}(x) P &= P^\dagger \psi^\dagger(x) P \gamma^0 = (P^\dagger \psi(x) P)^\dagger \gamma^0 \\
 &= \eta_a^* (\gamma^0 \psi(x))^\dagger \gamma^0 = \eta_a^* \psi^\dagger(x) \gamma^0 \gamma^0 = \eta_a^* \bar{\psi}(x) \gamma^0 \\
 &\quad (\gamma^{0\dagger} = \gamma^0)
 \end{aligned}$$

$$\begin{aligned}
 \text{Therefore } P^\dagger \bar{\psi}(x) \psi(x) P &= P^\dagger \bar{\psi}(x) P P^\dagger \psi(x) P \\
 &= |\eta_a|^2 \bar{\psi}(x) \psi(x)
 \end{aligned}$$

Can also show

$$P^\dagger \bar{\psi} \gamma^0 \psi P = \bar{\psi} \gamma^0 \psi(x)$$

$$P^\dagger \bar{\psi} \gamma^i \psi P = -\bar{\psi}(x) \gamma^0 \gamma^i \gamma^0 \psi(x) = -\bar{\psi} \gamma^i \psi(x)$$

$$P^\dagger (i \bar{\psi} \gamma^5 \psi) P = i \bar{\psi}(x) \gamma^0 \gamma^5 \gamma^0 \psi(x) = -i \bar{\psi} \gamma^5 \psi$$

$$P^\dagger \bar{\psi} \gamma^\mu \gamma^5 \psi P = \bar{\psi}(x) \gamma^0 \gamma^\mu \gamma^5 \gamma^0 \psi(x) = \begin{cases} -\bar{\psi} \gamma^\mu \gamma^5 \psi(x) & \mu=0 \\ \bar{\psi} \gamma^\mu \gamma^5 \psi(x) & \mu=1,2,3 \end{cases}$$

$\bar{\psi}\psi$ scalar
 $i\bar{\psi}\gamma^5\psi$ pseudoscalar
 $\bar{\psi}\gamma^\mu\psi$ vector (+ for $\mu=0$, - for $\mu=1,2,3$)
 $\bar{\psi}\gamma^\mu\gamma^5\psi$ axial vector (- for $\mu=0$, + for $\mu=1,2,3$)

Time Reversal

Suppose there exists a linear unitary operator T for time reversal. Then if $[T, H] = 0$

$$\Rightarrow T^\dagger e^{-iHt} T = e^{-iHt}$$

No good! We want direction of time reversed.

Another possibility...

$$T^\dagger H T = -H$$

or $\{T, H\} = 0$

No good either since this implies that the eigenvalues of H and $-H$ are the same. This would mean H is unbounded below.

We instead assume something a little weird...
time reversal is conjugate-linear or "anti-linear."

$$T^\dagger c T = c^*$$

↑
complex number

We assume that $[T, H] = 0$ and $T^\dagger T = T T^\dagger = 1$.

Then we get $T^\dagger e^{-iHt} T = e^{+iHt}$.

Time reversal is like watching a movie backwards.
Momentum reverses and spin reverses.

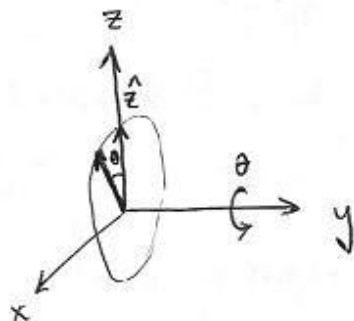
"Reversing" the spin is a bit complicated. Let us study it in detail.

$$\xi^1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \xi^2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

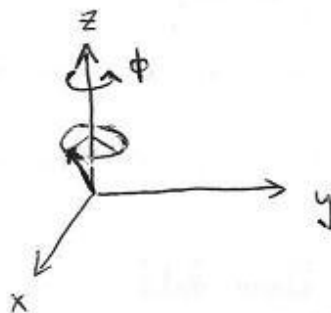
spin-up spin-down
z-axis z-axis

We can find spin-up and spin down along the

(θ, ϕ) direction by rotating by angle θ



about the y axis and then rotating by angle ϕ



The transformation is

$$M(\theta, \phi) = \exp\left[-i\phi \frac{\sigma^3}{2}\right] \exp\left[-i\theta \frac{\sigma^2}{2}\right]$$

We can compute exp using a Taylor series

$$\exp\left[-i\theta \frac{\sigma^2}{2}\right] = 1 - i\frac{\theta}{2} \sigma^2 - \frac{(\frac{\theta}{2})^2}{2!} + i\frac{(\frac{\theta}{2})^3}{3!} \sigma^2 + \dots$$

odd terms give $-i \sin \frac{\theta}{2} \sigma^2$
even terms give $\cos \frac{\theta}{2}$

$$\begin{aligned}\exp\left[-i\theta\frac{\sigma^2}{2}\right] &= \cos\frac{\theta}{2} - i\sin\frac{\theta}{2}\sigma^2 \\ &= \begin{bmatrix} \cos\frac{\theta}{2} & -i\sin\frac{\theta}{2} \\ i\sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{bmatrix}\end{aligned}$$

$$\begin{aligned}\exp\left[-i\phi\frac{\sigma^3}{2}\right] &= \cos\frac{\phi}{2} - i\sin\frac{\phi}{2}\sigma^3 \\ &= \begin{bmatrix} e^{-i\frac{\phi}{2}} & 0 \\ 0 & e^{i\frac{\phi}{2}} \end{bmatrix}\end{aligned}$$

$$\text{So } M(\theta, \phi) = \begin{bmatrix} e^{-i\frac{\phi}{2}}\cos\frac{\theta}{2} & -e^{-i\frac{\phi}{2}}\sin\frac{\theta}{2} \\ e^{i\frac{\phi}{2}}\sin\frac{\theta}{2} & e^{i\frac{\phi}{2}}\cos\frac{\theta}{2} \end{bmatrix}$$

Therefore spin-up in the (θ, ϕ) direction is

$$\chi^1 = M \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} e^{-i\frac{\phi}{2}}\cos\frac{\theta}{2} \\ e^{i\frac{\phi}{2}}\sin\frac{\theta}{2} \end{pmatrix}$$

spin down in the (θ, ϕ) direction is

$$\chi^2 = M \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -e^{-i\frac{\phi}{2}}\sin\frac{\theta}{2} \\ e^{i\frac{\phi}{2}}\cos\frac{\theta}{2} \end{pmatrix}$$

Interesting bit of trivia...

A 360° rotation for a spin- $\frac{1}{2}$ particles gives an overall minus sign...

$$\text{set } \phi = 0, \theta = 2\pi$$

This gives a 2π rotation about the y-axis

$$M\left(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) = \begin{pmatrix} \cos \pi \\ \sin \pi \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \quad M\left(\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right) = \begin{pmatrix} \sin \pi \\ \cos \pi \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

Similarly $\phi = 2\pi$, $\theta = 0$ gives a 2π rotation about the z-axis

$$M\left(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) = \begin{pmatrix} e^{-i\pi} \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \quad M\left(\begin{smallmatrix} 0 \\ 1 \end{smallmatrix}\right) = \begin{pmatrix} 0 \\ e^{i\pi} \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

In order to do a spin flip we reverse the direction by taking $(\theta + \pi, \phi)$ (note that taking $(\theta - \pi, \phi)$ gives an overall minus sign difference)

$$\xi^1(\theta + \pi, \phi) = \begin{pmatrix} e^{-i\frac{\phi}{2}} \cos(\frac{\theta}{2} + \frac{\pi}{2}) \\ e^{i\frac{\phi}{2}} \sin(\frac{\theta}{2} + \frac{\pi}{2}) \end{pmatrix} = \begin{pmatrix} -e^{-i\frac{\phi}{2}} \sin \frac{\theta}{2} \\ e^{i\frac{\phi}{2}} \cos \frac{\theta}{2} \end{pmatrix}$$

$$\xi^2(\theta + \pi, \phi) = \begin{pmatrix} -e^{-i\frac{\phi}{2}} \sin(\frac{\theta}{2} + \frac{\pi}{2}) \\ e^{i\frac{\phi}{2}} \cos(\frac{\theta}{2} + \frac{\pi}{2}) \end{pmatrix} = \begin{pmatrix} -e^{-i\frac{\phi}{2}} \cos \frac{\theta}{2} \\ -e^{i\frac{\phi}{2}} \sin \frac{\theta}{2} \end{pmatrix}$$

So if $\xi^s = (\xi^\uparrow, \xi^\downarrow)$ then $\xi^{-s} = (\xi^\downarrow, -\xi^\uparrow)$
(spin-reversed)

You may also notice that

$$\xi^2 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \xi^{1*}$$

$$\xi^1 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \xi^{2*}$$

So we can write ξ^{-s} in a fancy way

$$\begin{aligned} \xi^{-s} &= \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \xi^{s*} \\ &= -i\sigma^2 \xi^{s*} \end{aligned} \quad s=1,2$$

This is convenient since our time reversal operator involves complex conjugation.

We can show

$$u^{-s}(-\vec{p}) = \begin{pmatrix} \sqrt{\vec{p} \cdot \vec{\sigma}} (-i\sigma^2 \xi^{s*}) \\ \sqrt{\vec{p} \cdot \vec{\sigma}} (-i\sigma^2 \xi^{s*}) \end{pmatrix} \quad \tilde{p} = (E_{\vec{p}}, -\vec{p})$$

If we use the identity

$$\sqrt{\vec{p} \cdot \vec{\sigma}} \sigma^2 = \sigma^2 \sqrt{\vec{p} \cdot \vec{\sigma}^*}$$

(takes a few steps)
to prove
use $\sigma^2 \vec{\sigma} = -\vec{\sigma}^* \sigma^2$

$$u^{-s}(-\vec{p}) = -i \begin{pmatrix} \sigma^2 & 0 \\ 0 & \sigma^2 \end{pmatrix} [u^s(\vec{p})]^* \\ = -\gamma^1 \gamma^3 [u^s(\vec{p})]^*$$

$$\text{Similarly } v^{-s}(-\vec{p}) = -\gamma^1 \gamma^3 [v^s(\vec{p})]^*$$

Now can define the time reversal operation on the creation and annihilation operators

$$T^\dagger a_{\vec{p}}^s T = a_{-\vec{p}}^{-s}$$

$$T^\dagger b_{\vec{p}}^s T = b_{-\vec{p}}^{-s}$$

$$\text{where } a_{-\vec{p}}^{-s} = (a_{-\vec{p}}^\downarrow, -a_{-\vec{p}}^\uparrow) \\ b_{-\vec{p}}^{-s} = (b_{-\vec{p}}^\downarrow, -b_{-\vec{p}}^\uparrow)$$

$$\text{So } T^\dagger \psi(x) T =$$

$$\int \frac{d^3\vec{p}}{(2\pi)^3 \sqrt{2E_{\vec{p}}}} \sum_s T^\dagger (a_{\vec{p}}^s u^s(\vec{p}) e^{-ip \cdot x} + b_{\vec{p}}^{s\dagger} v^s(\vec{p}) e^{ip \cdot x}) T \\ = \int \frac{d^3\vec{p}}{(2\pi)^3 \sqrt{2E_{\vec{p}}}} \sum_s (a_{-\vec{p}}^{-s} \underbrace{[u^s(\vec{p})]^*}_{\gamma^1 \gamma^3 u^{-s}(-\vec{p})} e^{ip \cdot x} + b_{-\vec{p}}^{-s\dagger} \underbrace{[v^s(\vec{p})]^*}_{\gamma^1 \gamma^3 v^{-s}(-\vec{p})} e^{-ip \cdot x})$$

$$[\gamma^1 \gamma^3 \text{ is the inverse of } -\gamma^1 \gamma^3]$$

$$= \gamma^1 \gamma^3 \psi(x_T) \quad \text{where } x_T = (-t, \vec{x})$$