

## PH312: Physics of Fluids (Prof. McCoy) – Reflection

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1. Explain why particle paths, streamlines, and streaklines are identical for *steady flow*.

- (a) In steady flow, the velocity field is time-independent, i.e.,  $\mathbf{u}(\mathbf{r}, t) = \mathbf{u}(\mathbf{r})$ , and thus streamlines (which are just velocity field lines) are also time-independent. Let a particle  $p$  be moving instantaneously along some streamline  $S$ . Because  $S$  is unchanging and that the tangent of  $S$  at  $p$  is always along the velocity of  $p$ ,  $p$  must move along  $S$ .
- (b) Let  $p$  be moving along  $S$ . Suppose  $p$  moves onto some streamline  $S_1 \neq S$ . From (a), we know that  $S_1$  and  $S$  must cross, but this is impossible because  $p$  will then have velocities in two direction. Two streamlines cannot intersect except at a position of zero velocity.
- (c) Let particles  $\{p\}$  make up some streakline. By definition, each of  $\{p\}$  has passed through one point belonging to some streamline  $S$ . From (b), we know that none of  $\{p\}$  leaves  $S$ , and so all of  $\{p\}$  must follow  $S$ .

2. To transform the flow field in Figure 6.3(a) where flow is viewed from the bank to Figure 6.3(b) where flow is viewed from the ship, we add  $-\mathbf{U}$  (which points Left-Right) to each velocity vector  $\mathbf{u}'$  in (a). For example, the point  $p$  in (a) with  $\mathbf{u}'$  pointing Up-Left becomes  $\mathbf{u} = \text{Up-Left} + \text{Right} \approx \text{Up-Right}$ . The velocity may change direction in some cases depending on how  $\mathbf{U}$  compares to  $\mathbf{u}'$  in direction and amplitude. For example, the regions in (a) where the flow is Right-to-Left are where it was previously moving downstream in (b) **more slowly** than  $\mathbf{U}$ .

3.

(a)  $a = b_i c_{ij} d_j$  ✓

(b)  $a = b_i c_i + d_j$  ✗

The LHS has no free index, but the RHS does. So, this is not allowed according to the convention (p.28, K&C: the free index must appear on both sides). If we want to say that the component  $d_j$  is equal to the scalar  $a - b_i c_i$  for all  $j$  then we have to be explicit to avoid confusion.

(c)  $a_i = \delta_{ij} b_i + c_i$  ✗

The contraction  $\delta_{ij} b_i$  leaves  $b_j$  with free index  $j$ , which is incompatible with the free index  $i$  on  $a_i$  and  $c_i$ .

(d)  $a_k = b_k c + d_i e_{ik} = c b_k + d_i e_{ik}$  ✓

(e)  $a_i = b_i + c_{ij} d_{ij} e_i$  ✗

The index  $i$  appears 3 times in the second term on the RHS. This can cause confusion.

4. Let  $A$  be a second-order tensor and  $R$  be a rotation matrix. Because  $R^\top R = \mathbb{I}$ , i.e.,  $(R^\top R)_{mn} = \delta_{mn}$ , we have

$$A'_{ii} = R_{im} R_{in} A_{mn} = R_{mi}^\top R_{in} A_{mn} = (R^\top R)_{mn} A_{mn} = \delta_{mn} A_{mn} = A_{mm} = A_{ii}.$$

So,  $A_{ii}$ , or the trace of the matrix of  $A$ , is invariant under coordinate rotations.

5. Let  $R$  be a rotation matrix. Because  $R^\top R = \mathbb{I} = R R^\top$ , i.e.,  $(R R^\top)_{ij} = \delta_{ij}$ , we have

$$\delta'_{ij} = R_{im} R_{jn} \delta_{mn} = R_{im} R_{jm} = R_{im} R_{mj}^\top = (R R^\top)_{ij} = \delta_{ij}.$$

So,  $\delta_{ij}$  is an isotropic tensor.