

last_one 模板

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计算几何

几何公式

三角形:

1. 半周长 $P=(a+b+c)/2$

2. 面积

$$S=aHa/2=absin(C)/2=\sqrt{P(P-a)(P-b)(P-c)}$$

3. 中线

$$Ma=\sqrt{2(b^2+c^2)-a^2}/2=\sqrt{b^2+c^2+2bccos(A)}/2$$

4. 角平分线

$$Ta=\sqrt{bc((b+c)^2-a^2)}/(b+c)=2bccos(A/2)/(b+c)$$

5. 高线

$$Ha=bsin(C)=csin(B)=\sqrt{b^2-((a^2+b^2-c^2)/(2a))^2}$$

6. 内切圆半径

$$r=S/P=asin(B/2)sin(C/2)/sin((B+C)/2)=4Rsin(A/2)sin(B/2)sin(C/2)=\sqrt{(P-a)(P-b)(P-c)}/P=Ptan(A/2)tan(B/2)tan(C/2)$$

7. 外接圆半径

$$R=abc/(4S)=a/(2sin(A))=b/(2sin(B))=c/(2sin(C))$$

四边形:

D_1, D_2 为对角线, M 为对角线中点连线, A 为对角线夹角

$$1. a^2+b^2+c^2+d^2=D_1^2+D_2^2+4M^2$$

$$2. S=D_1D_2sin(A)/2$$

(以下对圆的内接四边形)

$$3. ac+bd=D_1D_2$$

$$4. S=\sqrt{(P-a)(P-b)(P-c)(P-d)}, P \text{ 为半周长}$$

正 n 边形:

R 为外接圆半径, r 为内切圆半径

$$1. \text{中心角 } A=2\pi/n$$

$$2. \text{内角 } C=(n-2)\pi/n$$

3. 边长

$$a=2\sqrt{R^2-r^2}=2Rsin(A/2)=2rtan(A/2)$$

4. 面积

$$S=nar/2=nr^2tan(A/2)=nR^2sin(A)/2=na^2/(4tan(A/2))$$

圆:

1. 弧长 $l=rA$

$$2. \text{弦长 } a=2\sqrt{2hr-h^2}=2rsin(A/2)$$

3. 弓形高

$$h=r-\sqrt{r^2-a^2/4}=r(1-cos(A/2))=atan(A/4)/2$$

$$4. \text{扇形面积 } S_1=rl/2=r^2A/2$$

$$5. \text{弓形面积 } S_2=(rl-a(r-h))/2=r^2(A-sin(A))/2$$

棱柱:

1. 体积 $V=Ah$, A 为底面积, h 为高

2. 侧面积 $S=lp$, l 为棱长, p 为直截面周长

3. 全面积 $T=S+2A$

棱锥:

1. 体积 $V=Ah/3$, A 为底面积, h 为高

(以下对正棱锥)

2. 侧面积 $S=lp/2$, l 为斜高, p 为底面周长

3. 全面积 $T=S+A$

棱台:

1. 体积 $V=(A_1+A_2+\sqrt{A_1A_2})h/3$, A_1, A_2 为上下底面积, h 为高

(以下为正棱台)

2. 侧面积 $S=(p_1+p_2)l/2$, p_1, p_2 为上下底面周长, l 为斜高

3. 全面积 $T=S+A_1+A_2$

圆柱:

1. 侧面积 $S=2\pi rh$

2. 全面积 $T=2\pi r(h+r)$

3. 体积 $V=\pi r^2h$

圆锥:

1. 母线 $l=\sqrt{h^2+r^2}$

2. 侧面积 $S=\pi rl$

3. 全面积 $T=\pi r(l+r)$

4. 体积 $V=\pi r^2h/3$

圆台:

1. 母线 $l=\sqrt{h^2+(r_1-r_2)^2}$

2. 侧面积 $S=\pi(r_1+r_2)l$

3. 全面积 $T=\pi r_1(l+r_1)+\pi r_2(l+r_2)$

4. 体积 $V = \pi(r_1^2 + r_2^2 + r_1 r_2)h/3$

球:

1. 全面积 $T = 4\pi r^2$

2. 体积 $V = 4\pi r^3/3$

球台:

1. 侧面积 $S = 2\pi r h$

2. 全面积 $T = \pi(2rh + r_1^2 + r_2^2)$

3. 体积 $V = \pi h(3(r_1^2 + r_2^2) + h^2)/6$

球扇形:

1. 全面积 $T = \pi r(2h + r_0)$, h 为球冠高, r_0 为球冠底面半径

2. 体积 $V = 2\pi r^2 h/3$

凸包

凸包

/*时间复杂度 $n \log(n)$ */

```
struct point{
    double x, y;
    double dis;
}pnt[10010], res[10010];
//pnt 存输入点, res 存凸包点
int n;//点的个数
bool mult(point sp, point ep, point op){
    return (sp.x - op.x) * (ep.y - op.y) >=
           (ep.x - op.x) * (sp.y - op.y);
}
bool operator < (const point &l, const point &r){
    return l.y < r.y ||
           (l.y == r.y && l.x < r.x);
}
double dist(point a, point b){
    return sqrt((a.y - b.y) * (a.y - b.y) +
               (a.x - b.x) * (a.x - b.x));
}
int graham(){
    int i, len, k = 0, top = 1;
    sort(pnt, pnt + n);
    if (n == 0) return 0;
    res[0] = pnt[0];
    if (n == 1) return 1;
    res[1] = pnt[1];
```

```
    if (n == 2) return 2;
    res[2] = pnt[2];
    for (i = 2; i < n; i++) {
        while (top &&
               mult(pnt[i], res[top], res[top-1]))
            top--;
        res[++top] = pnt[i];
    }
    len = top;
    res[++top] = pnt[n - 2];
    for (i = n - 3; i >= 0; i--) {
        while (top != len &&
               mult(pnt[i], res[top], res[top-1]))
            top--;
        res[++top] = pnt[i];
    }
    return top; // 返回凸包中点的个数
}
int main()
{
    int top;
    double ans;
    while(scanf("%d", &n), n){
        for(int i = 0; i < n; i++)

            scanf("%lf%lf", &pnt[i].x, &pnt[i].y);
        if(n==1)
            printf("0.00\n");
        else if(n==2)

            printf("%.2lf\n", dist(pnt[0], pnt[1]));
        else{
            top = graham();
            //ans 为凸包周长
            ans = 0;
            for(int i = 0; i < top - 1; i++)
                ans += dist(res[i], res[i +
1]);
            ans += dist(res[0], res[top - 1]);
            printf("%.2lf\n", ans);
        }
    }
    return 0;
}
```

三维凸包

```

#define PR 1e-8
#define N 510
struct TPoint{
    double x,y,z;
    TPoint(){}
    TPoint(double _x,double _y,double
_z):x(_x),y(_y),z(_z){}
    TPoint operator-(const TPoint p) {
        return TPoint(x-p.x,y-p.y,z-p.z);}
    TPoint operator*(const TPoint p) { //叉积
        return
TPoint(y*p.z-z*p.y,z*p.x-x*p.z,x*p.y-y*p.x);}
    double operator^(const TPoint p) { //点积
        return x*p.x+y*p.y+z*p.z;}
};
struct fac{
    int a,b,c; //凸包一个面上的三个点的编号
    bool ok; //该面是否是最终凸包中的面
};
struct T3dhull{
    int n; //初始点数
    TPoint ply[N]; //初始点
    int trianglecnt; //凸包上三角形数
    fac tri[N]; //凸包三角形
    int vis[N][N]; //点i到点j是属于哪个面
    double dist(TPoint a){ //两点长度
        return sqrt(a.x*a.x+a.y*a.y+a.z*a.z);}
    double area(TPoint a,TPoint b,TPoint c) { //三
        角形面积*2
        return dist((b-a)*(c-a));}
    double volume(TPoint a,TPoint b,TPoint
c,TPoint d){
        return (b-a)*(c-a)*(d-a); //四面体有向体
        积*6
    double ptoplane(TPoint &p,fac &f){ //正: 点在
        面同向
        TPoint
m=ply[f.b]-ply[f.a],n=ply[f.c]-ply[f.a],t=p-ply[f.a];
        return (m*n)^t;
    }
    void deal(int p,int a,int b){
        int f=vis[a][b];
        fac add;
        if(tri[f].ok){
            if((ptoplane(ply[p],tri[f]))>PR)
dfs(p,f);
            else{
add.a=b,add.b=a,add.c=p,add.ok=1;
vis[p][b]=vis[a][p]=vis[b][a]=trianglecnt;
            tri[trianglecnt++]=add;
            }
        }
    }
    void dfs(int p,int cnt){
        //维护凸包, 如果点p在凸包外更新凸包
        tri[cnt].ok=0;
        deal(p,tri[cnt].b,tri[cnt].a);
        deal(p,tri[cnt].c,tri[cnt].b);
        deal(p,tri[cnt].a,tri[cnt].c);
    }
    bool same(int s,int e){
        //判断两个面是否为同一面
        TPoint a=ply[tri[s].a];
        TPoint b=ply[tri[s].b];
        TPoint c=ply[tri[s].c];
        return
fabs(volume(a,b,c,ply[tri[e].a]))<PR
&&fabs(volume(a,b,c,ply[tri[e].b]))<PR
&&fabs(volume(a,b,c,ply[tri[e].c]))<PR;
    }
    void construct(){ //构建凸包
        int i,j;
        trianglecnt=0;
        if(n<4) return ;
        bool tmp=true;
        for(i=1;i<n;i++){ //前两点不共点
            if((dist(ply[0]-ply[i]))>PR){
                swap(ply[1],ply[i]);
                tmp=false; break;
            }
        }
    }

```

```

        if(tmp) return;
        tmp=true;
        for(i=2;i<n;i++){//前三点不共线
            if((dist((ply[0]-ply[1])*(ply[1]-ply[i])))>PR){
                swap(ply[2],ply[i]);
                tmp=false; break;
            }
        }
        if(tmp) return ;
        tmp=true;
        for(i=3;i<n;i++){//前四点不共面
            if(fabs((ply[0]-ply[1])*(ply[1]-ply[2])^(ply[0]-ply[i]
            数))>PR){
                swap(ply[3],ply[i]);
                tmp=false; break;
            }
        }
        if(tmp) return ;
        fac add;
        for(i=0;i<4;i++){//构建初始四面体
            add.a=(i+1)%4,add.b=(i+2)%4;
            add.c=(i+3)%4,add.ok=1;
            if((ptoplane(ply[i],add))>0)
                swap(add.b,add.c);

            vis[add.a][add.b]=vis[add.b][add.c]=vis[add.c][add
            .a]=trianglecnt;
            tri[trianglecnt++]=add;
        }
        for(i=4;i<n;i++){//构建更新凸包
            for(j=0;j<trianglecnt;j++){
                if(tri[j].ok&&(ptoplane(ply[i],tri[j]))>PR){
                    dfs(i,j); break;
                }
            }
        }
        int cnt=trianglecnt;
        trianglecnt=0;
        for(i=0;i<cnt;i++){
            if(tri[i].ok)
                tri[trianglecnt++]=tri[i];
        }
        double area(){//表面积
            double ret=0;
            for(int i=0;i<trianglecnt;i++)
                ret+=area(ply[tri[i].a],ply[tri[i].b],ply[tri[i].c]);
            return ret/2.0;
        }
        double volume(){//体积
            TPoint p(0,0,0);
            double ret=0;
            for(int i=0;i<trianglecnt;i++)
                ret+=volume(p,ply[tri[i].a],ply[tri[i].b],ply[tri[i].c]);
            return fabs(ret/6);
        }
        int facetri() {return trianglecnt;}//表面三角形数
        int facepolygon(){//表面多边形数
            int ans=0,i,j,k;
            for(i=0;i<trianglecnt;i++){
                for(j=0,k=1;j<i;j++){
                    if(same(i,j)) {
                        k=0;break;}
                }
                ans+=k;
            }
            return ans;
        }
        double res(){//三维凸包中的点到凸包的最短距离
            double _min=1e300;
            for(int i=0;i<trianglecnt;i++){
                double
                now=Dis(ply[tri[i].a],ply[tri[i].b],ply[tri[i].c],dd);
                if(_min>now) _min=now;
            }
            return _min;
        }
    }hull;
    int main(){

```



```

while(~scanf("%d",&hull.n)){
    int i;
    for(i=0;i<hull.n;i++)

scanf("%lf%lf%lf",&hull.ply[i].x,&hull.ply[i].y,&h
ull.ply[i].z);
    hull.construct();
    printf("%.3lf\n",hull.area());
}
return 0;
}

```

判断线段相交

```

const double eps=1e-10;
struct point{double x, y;};
double min(double a, double b){
    return a<b?a:b;}
double max(double a, double b){
    return a>b?a:b;}
bool inter(point a, point b, point c, point d){
    if (min(a.x, b.x)>max(c.x, d.x)||
        min(a.y, b.y)>max(c.y, d.y)||
        min(c.x, d.x)>max(a.x, b.x)||
        min(c.y, d.y)>max(a.y, b.y) )
        return 0;
    double h, i, j, k;
    h=(b.x-a.x)*(c.y-a.y)-(b.y-a.y)*(c.x-a.x);
    i=(b.x-a.x)*(d.y-a.y)-(b.y-a.y)*(d.x-a.x);
    j=(d.x-c.x)*(a.y-c.y)-(d.y-c.y)*(a.x-c.x);
    k=(d.x-c.x)*(b.y-c.y)-(d.y-c.y)*(b.x-c.x);
    return h * i <= eps && j * k <= eps;
}

```

三角形几个重要的点

```

struct point{double x,y;};
struct line{point a,b;};
double distance(point p1,point p2){
    return sqrt((p1.x-p2.x)*(p1.x-p2.x)+
        (p1.y-p2.y)*(p1.y-p2.y));
}
point intersection(line u,line v){

```

```

point ret=u.a;
double t=((u.a.x-v.a.x)*(v.a.y-v.b.y)-
    (u.a.y-v.a.y)*(v.a.x-v.b.x))
    /((u.a.x-u.b.x)*(v.a.y-v.b.y)-
    (u.a.y-u.b.y)*(v.a.x-v.b.x));
ret.x+=(u.b.x-u.a.x)*t;
ret.y+=(u.b.y-u.a.y)*t;
return ret;
}
//最小覆盖圆圆心
struct point circumcenter(struct point a,struct point
b,struct point c){
    struct line u,v;
    struct point o1,o2,o3,ans;
    double r1,r2,r3;
    bool p=0;
    o1.x=(b.x+c.x)/2;
    o1.y=(b.y+c.y)/2;
    r1=distance(b,c)/2;
    if(distance(o1,a)<=r1){
        ans=o1;
        p=1;
    }
    o2.x=(a.x+c.x)/2;
    o2.y=(a.y+c.y)/2;
    r2=distance(a,c)/2;
    if(distance(o2,b)<=r2){
        ans=o2;
        p=1;
    }
    o3.x=(b.x+a.x)/2;
    o3.y=(b.y+a.y)/2;
    r3=distance(b,a)/2;
    if(distance(o3,c)<=r3){
        ans=o3;
        p=1;
    }
    if(p==0){
        u.a.x=(a.x+b.x)/2;
        u.a.y=(a.y+b.y)/2;
        u.b.x=u.a.x-a.y+b.y;
        u.b.y=u.a.y+a.x-b.x;
        v.a.x=(a.x+c.x)/2;
        v.a.y=(a.y+c.y)/2;

```

```

        v.b.x=v.a.x-a.y+c.y;
        v.b.y=v.a.y+a.x-c.x;
        return intersection(u,v);
    }
    else return ans;
}
//外心
point circumcenter(point a,point b,point c){
    line u,v;
    u.a.x=(a.x+b.x)/2;
    u.a.y=(a.y+b.y)/2;
    u.b.x=u.a.x-a.y+b.y;
    u.b.y=u.a.y+a.x-b.x;
    v.a.x=(a.x+c.x)/2;
    v.a.y=(a.y+c.y)/2;
    v.b.x=v.a.x-a.y+c.y;
    v.b.y=v.a.y+a.x-c.x;
    return intersection(u,v);
}
//内心
point incenter(point a,point b,point c){
    line u,v;
    double m,n;
    u.a=a;
    m=atan2(b.y-a.y,b.x-a.x);
    n=atan2(c.y-a.y,c.x-a.x);
    u.b.x=u.a.x+cos((m+n)/2);
    u.b.y=u.a.y+sin((m+n)/2);
    v.a=b;
    m=atan2(a.y-b.y,a.x-b.x);
    n=atan2(c.y-b.y,c.x-b.x);
    v.b.x=v.a.x+cos((m+n)/2);
    v.b.y=v.a.y+sin((m+n)/2);
    return intersection(u,v);
}
//垂心
point perpcenter(point a,point b,point c){
    line u,v;
    u.a=c;
    u.b.x=u.a.x-a.y+b.y;
    u.b.y=u.a.y+a.x-b.x;
    v.a=b;
    v.b.x=v.a.x-a.y+c.y;
    v.b.y=v.a.y+a.x-c.x;

    return intersection(u,v);
}
//重心
//到三角形三顶点距离的平方和最小的点
//三角形内到三边距离之积最大的点
point barycenter(point a,point b,point c){
    line u,v;
    u.a.x=(a.x+b.x)/2;
    u.a.y=(a.y+b.y)/2;
    u.b=c;
    v.a.x=(a.x+c.x)/2;
    v.a.y=(a.y+c.y)/2;
    v.b=b;
    return intersection(u,v);
}
//费马点
//到三角形三顶点距离之和最小的点
point fermentpoint(point a,point b,point c){
    point u,v;
    double step=fabs(a.x)+fabs(a.y)+
                fabs(b.x)+fabs(b.y)+
                fabs(c.x)+fabs(c.y);
    int i,j,k;
    u.x=(a.x+b.x+c.x)/3;
    u.y=(a.y+b.y+c.y)/3;
    while (step>1e-10)
        for (k=0;k<10;step/=2,k++)
            for (i=-1;i<=1;i++)
                for (j=-1;j<=1;j++){
                    v.x=u.x+step*i;
                    v.y=u.y+step*j;
                    if (distance(u,a)+
                        distance(u,b)+
                        distance(u,c)>
                        distance(v,a)+
                        distance(v,b)+
                        distance(v,c))
                        u=v;
                }
    return u;
}

```

多边形面积

```

struct point{ double x; double
y;}map[100005];
int main() {
    int i, j, m, n;
    double x, y, x1, y1, x2, y2, ans, a, b, c, d;
    while (scanf("%d", &n) != EOF) {
        ans=0;
        for(i=1; i<=n; i++)

scanf("%lf%lf", &map[i].x, &map[i].y);
        x=map[1].x;
        y=map[1].y;
        for(i=2; i<=n-1; i++) {
            x1=map[i].x;
            y1=map[i].y;
            x2=map[i+1].x;
            y2=map[i+1].y;
            a=x-x1;
            b=y-y1;
            c=x-x2;
            d=y-y2;
            ans+=(a*d-b*c)/2;
        }
        ans=fabs(ans);
        printf("%.21f\n", ans);
    }
    return 0;
}

```

多边形重心

```

struct point{ double x; double
y;}map[100005];
int main() {
    int i, j, m, n;
    double x, y, ss, sx, sy, s;
    while (scanf("%d", &n) != EOF) {
        ss=0;
        sx=0;
        sy=0;
        for(i=1; i<=n; i++)

```

```

scanf("%lf%lf", &map[i].x, &map[i].y);
        for(i=2; i<=n-1; i++) {
            x=(map[1].x+map[i].x+map[i+1].x)/3;
            y=(map[1].y+map[i].y+map[i+1].y)/3;

            s=( (map[i].x-map[1].x)*(map[i+1].y-m
ap[1].y)-(map[i+1].x-map[1].x)*(map[i].y-
map[1].y) )/2;

            sx+=s*x;
            sy+=s*y;
            ss+=s;
        }

        printf("%.21f %.21f\n", sx/ss+0.000000
01, sy/ss+0.00000001);
    }
    return 0;
}

```

分治法求最小点对（二维）

```

/*分治算法求最小点对*/
#define MAXN 100005
struct Point{double x, y;};
struct Point
point[MAXN], *px[MAXN], *py[MAXN];
double get_dis(Point *p1, Point *p2) {
    return
sqrt((p1->x-p2->x)*(p1->x-p2->x)+(p1->y-p
2->y)*(p1->y-p2->y));
}
bool cmpx(Point *p1, Point *p2) {return
p1->x<p2->x;}
bool cmpy(Point *p1, Point *p2) {return
p1->y<p2->y;}
double min(double a, double b) {return
a<b?a:b;}
//-----核心代码-----//
double closest(int s, int e) {
    if(s+1==e)

```

```

        return get_dis(px[s], px[e]);
    if (s+2==e)
        return
min(get_dis(px[s], px[s+1]), min(get_dis(px
[s+1], px[e]), get_dis(px[s], px[e])));
    int mid=(s+e)>>1;
    double
ans=min(closest(s, mid), closest(mid+1, e));
//递归求解
    int i, j, cnt=0;
    for(i=s; i<=e; i++) { //把x坐标在
px[mid].x-ans~px[mid].x+ans范围内的点取出
来

        if(px[i]->x>=px[mid]->x-ans&&px[i]->x
<=px[mid]->x+ans)
            py[cnt++]=px[i];
    }
    sort(py, py+cnt, cmpy); //按y坐标排序
    for(i=0; i<cnt; i++) {
        for(j=i+1; j<cnt; j++) { //py数组中
的点是按照y坐标升序的
            if(py[j]->y-py[i]->y>=ans)
                break;

        ans=min(ans, get_dis(py[i], py[j]));
    }
}
return ans;
}

int main() {
    int i, n;
    while(scanf("%d", &n)!=EOF) {
        if(n==0)
            break;
        for(i=0; i<n; i++) {

            scanf("%lf%lf", &point[i].x, &point[i].
y);

            px[i]=&point[i];
        }
        sort(px, px+n, cmpx);
        double distance=closest(0, n-1);
        printf("%.2lf\n", distance);
    }
}

```

```

    }
    return 0;
}

分治法求最小点对（三维）

#define MAXN 100005
using namespace std;
struct Point {double x, y, z;};
struct Point
point[MAXN], *px[MAXN], *py[MAXN];
double get_dis(Point *p1, Point *p2) {
    return
sqrt((p1->x-p2->x)*(p1->x-p2->x)+(p1->y-p
2->y)*(p1->y-p2->y)+(p1->z-p2->z)*(p1->z-
p2->z));
}
bool cmpx(Point *p1, Point *p2) {return
p1->x<p2->x;}
bool cmpy(Point *p1, Point *p2) {return
p1->y<p2->y;}
double min(double a, double b) {return
a<b?a:b;}
//-----核心代码-----//
double closest(int s, int e) {
    if(s+1==e)
        return get_dis(px[s], px[e]);
    if(s+2==e)
        return
min(get_dis(px[s], px[s+1]), min(get_dis(px
[s+1], px[e]), get_dis(px[s], px[e])));
    int mid=(s+e)>>1;
    double
ans=min(closest(s, mid), closest(mid+1, e));
//递归求解
    int i, j, cnt=0;
    for(i=s; i<=e; i++) { //把x坐标在
px[mid].x-ans~px[mid].x+ans范围内的点取出
来

        if(px[i]->x>=px[mid]->x-ans&&px[i]->x
<=px[mid]->x+ans)
            py[cnt++]=px[i];
    }
}

```

```

    }
    sort(py, py+cnt, cmpy); //按y坐标排序
    for(i=0; i<cnt; i++) {
        for(j=i+1; j<cnt; j++) { //py数组中的
            //点是按照y坐标升序的
            if(py[j]->y-py[i]->y>=ans)
                break;

            ans=min(ans, get_dis(py[i], py[j]));
        }
    }
    return ans;
}

int main() {
    int i, n;
    while(scanf("%d", &n) != EOF) {
        if(n==0)
            break;
        for(i=0; i<n; i++) {

            scanf("%lf%lf%lf", &point[i].x, &point[
i].y, &point[i].z);
            px[i]=&point[i];
        }
        sort(px, px+n, cmpx);
        double distance=closest(0, n-1);
        printf("%.2lf\n", distance);
    }
    return 0;
}

```

最小覆盖圆

```

struct point { double x; double
y; } map[100005], o, o1, o2, o3;
struct line { struct point a, b; };
struct point intersection(struct line
u, struct line v) {
    struct point ret=u.a;
    double
t=((u.a.x-v.a.x)*(v.a.y-v.b.y)-(u.a.y-v.a
.y)*(v.a.x-v.b.x))
    /((u.a.x-u.b.x)*(v.a.y-v.b.y)-(u.a.y-
u.b.y)*(v.a.x-v.b.x));
    ret.x=(u.b.x-u.a.x)*t;
    ret.y=(u.b.y-u.a.y)*t;
    return ret;
}

double dis(struct point x, struct point y) {
    return
sqrt((x.x-y.x)*(x.x-y.x)+(x.y-y.y)*(x.y-
y.y));
}

struct point circumcenter(struct point
a, struct point b, struct point c) {
    struct line u, v;
    struct point o1, o2, o3, ans;
    double r1, r2, r3;
    bool p=0;
    o1.x=(b.x+c.x)/2;
    o1.y=(b.y+c.y)/2;
    r1=dis(b, c)/2;
    if(dis(o1, a)<=r1) {
        ans=o1;
        p=1;
    }
    o2.x=(a.x+c.x)/2;
    o2.y=(a.y+c.y)/2;
    r2=dis(a, c)/2;
    if(dis(o2, b)<=r2) {
        ans=o2;
        p=1;
    }
    o3.x=(b.x+a.x)/2;
    o3.y=(b.y+a.y)/2;
    r3=dis(b, a)/2;
    if(dis(o3, c)<=r3) {
        ans=o3;
        p=1;
    }
    if(p==0) {
        u.a.x=(a.x+b.x)/2;
        u.a.y=(a.y+b.y)/2;
        u.b.x=u.a.x-a.y+b.y;
        u.b.y=u.a.y+a.x-b.x;
        v.a.x=(a.x+c.x)/2;

```

```

v. a. y=(a. y+c. y)/2;
v. b. x=v. a. x-a. y+c. y;
v. b. y=v. a. y+a. x-c. x;
return intersection(u, v);
}
else return ans;
}
double maxzhi(double x, double y) {
    if(x>y) return x;
    else return y;
}
int main() {
    int i, j, m, n, p1, p2, p3, xuhao, xuanze;
    double maxdis, r, r1, r2, r3;
    while(scanf("%d", &n) != EOF && n) {
        for(i=1; i<=n; i++)

scanf("%lf%lf", &map[i]. x, &map[i]. y);
        if(n>2) {
            p1=1;
            p2=2;
            p3=3;

o=circumcenter(map[p1], map[p2], map[p3
]);

r=maxzhi(dis(o, map[p1]), dis(o, map[p2]
));

while(1) {
            maxdis=r;
            for(i=1; i<=n; i++) {

if(dis(o, map[i])>maxdis) {

maxdis=dis(o, map[i]);
                xuhao=i;
            }
        }
        xuanze=0;
        if(maxdis>r) {

o1=circumcenter(map[p2], map[p3], map[x
uhao]);

r1=maxzhi(dis(o1, map[p2]), dis(o1, map
[p3]));

if(dis(map[p1], o1)<=r1) {
                o=o1;
                r=r1;
                xuanze=1;

o2=circumcenter(map[p1], map[p3], map[x
uhao]);

r2=maxzhi(dis(o2, map[p1]), dis(o2, map
[p3]));

if(dis(map[p2], o2)<=r2 &&
(r2<r || xuanze==0)) {
                o=o2;
                r=r2;
                xuanze=2;

o3=circumcenter(map[p1], map[p2], map[x
uhao]);

r3=maxzhi(dis(o3, map[p1]), dis(o3, map
[p2]));

if(dis(map[p3], o3)<=r3 &&
(r3<r || xuanze==0)) {
                o=o3;
                r=r3;
                xuanze=3;

if(xuanze==1) p1=xuhao;
                else
if(xuanze==2) p2=xuhao;
                else p3=xuhao;
            }
            else break;
        }
    }
    else {

```

```

        r=dis(map[1],map[2])/2;
    }
    printf("%.21f\n",r);
}
}

```

最小覆盖矩阵

```

#include <iostream>
#include <cstdio>
#include <cmath>
#include <algorithm>
#include <vector>
using namespace std;
const double eps=1e-6;
const double inf=1e10;
int dcmp(double x)
{
    if(fabs(x)<eps) return 0;
    else return x<0?-1:1;
}
struct point
{
    double x,y;
    point(double x=0,double y=0):x(x),y(y){}
};
point operator-(point a,point b){return
point(a.x-b.x,a.y-b.y);}
point operator+(point a,point b){return
point(a.x+b.x,a.y+b.y);}
point operator*(point a,double p){return
point(a.x*p,a.y*p);}
bool operator<(const point& a,const point& b)
{
    return a.x<b.x||(a.x==b.x&&a.y<b.y);
}
bool operator==(const point& a,const point& b)
{
    return
dcmp(a.x-b.x)==0&&dcmp(a.y-b.y)==0;
}
double cross(point a,point b){return
a.x*b.y-a.y*b.x;}

```

```

double dot(point a,point b){return
a.x*b.x+a.y*b.y;}
double length(point a){return sqrt(dot(a,a));}
point normal(point a)
{
    double l=length(a);
    return point(a.x/l,a.y/l);
}
double distoline(point p,point a,point b)
{
    point v1=b-a,v2=p-a;
    return fabs(cross(v1,v2))/length(v1);
}
vector<point> p;
double mina,minp;
vector<point> convex(vector<point>& p)
{
    sort(p.begin(),p.end());
    int n=p.size();
    vector<point> ch(n+1);
    int m=0;
    for(int i=0;i<n;i++)
    {
        while(m>1&&cross(ch[m-1]-ch[m-2],p[i]-ch[m-2])
<=0) m--;
        ch[m++]=p[i];
    }
    int k=m;
    for(int i=n-2;i>=0;i--)
    {
        while(m>k&&cross(ch[m-1]-ch[m-2],p[i]-ch[m-2])
<=0) m--;
        ch[m++]=p[i];
    }
    if(n>1) m--;
    ch.resize(m);
    return ch;
}
void rotating_calipers(vector<point>& points)
{
    vector<point> p=convex(points);
    int n=p.size();

```

```

    p.push_back(p[0]);
    mina=inf;minp=inf;
    int l=1,r=1,u=1;
    for(int i=0;i<n;i++)
    {
        point edge=normal(p[(i+1)%n]-p[i]);

        while(dot(edge,p[r%n]-p[i])<dot(edge,p[(r+1)%n]-
p[i])) r++;

        while(u<r||cross(edge,p[u%n]-p[i])<cross(edge,p[(
u+1)%n]-p[i])) u++;

        while(l<u||dot(edge,p[l%n]-p[i])>dot(edge,p[(l+1)
%n]-p[i])) l++;

        double
w=dot(edge,p[r%n]-p[i])-dot(edge,p[l%n]-p[i]);
        double
h=distoline(p[u%n],p[i],p[(i+1)%n]);
        mina=min(mina,w*h);
        minp=min(minp,2*(w+h));
    }
}
int main()
{
    int n;
    while(~scanf("%d",&n))
    {
        p.clear();
        for(int i=0;i<n;i++)
        {
            double x,y;
            scanf("%lf%lf",&x,&y);
            p.push_back(point(x,y));
        }
        rotating_calipers(p);
        printf("%.6f\n",minp);
    }
    return 0;
}

```


数论

对于一个大于 1 正整数 n 可以分解质因数： $n=p_1^{a_1} \cdot p_2^{a_2} \cdot p_3^{a_3} \cdots p_k^{a_k}$,

则 n 的正约数的个数就是 $(a_1+1)(a_2+1)(a_3+1) \cdots (a_k+1)$.

斯特林公式： $n! = \sqrt{2 \cdot 3.14 \cdot n} \cdot (n/e)^n$

整数的唯一分解定理：任意正整数都有且只有一种方式写出其素因子的乘积表达式。

$A = (p_1^{a_1}) \cdot (p_2^{a_2}) \cdot (p_3^{a_3}) \cdots (p_n^{a_n})$
其中 p_i 均为素数

约数和公式：对于已经分解的整数
 $A = (p_1^{a_1}) \cdot (p_2^{a_2}) \cdot (p_3^{a_3}) \cdots (p_n^{a_n})$

有 A 的所有因子之和为： $S = (1+p_1+p_1^2+p_1^3+\cdots+p_1^{a_1}) \cdot (1+p_2+p_2^2+p_2^3+\cdots+p_2^{a_2}) \cdots (1+p_n+p_n^2+p_n^3+\cdots+p_n^{a_n})$ (展开理解)

同余模公式： $(a+b) \% m = (a \% m + b \% m) \% m$
 $(a \cdot b) \% m = (a \% m \cdot b \% m) \% m$

n 的环排列的个数与 $n-1$ 个元素的排列的个数相等。

组合数公式： $c[i][j] = c[i-1][j-1] + c[i-1][j]; (c[i][0] = 1, c[i][i] = 1)$

stirling 数 (将 n 个人分成 k 个组，每组内按特定方式围圈的分组方式) 公式： $s[i][j] = s[i-1][j-1] + (i-1) \cdot s[i-1][j]; (s[1][1] = 1, s[i][0] = 0)$

M 个小球放入 N 个盒子中
 $C[N+M-1][N-1]$

卡特兰数：

$C[i+1] = (2 \cdot (i+1) \cdot C[i]) / (i+2);$

$C[i] = \text{for}(j=0; j \leq i-1; j++)$

$C[i] += C[j] \cdot C[i-1-j];$

$A^B \bmod C = (A \bmod C)^{(B \bmod \text{Phi}(C))} \bmod C$

求 $A^B \bmod C$ (A, B 为高精度, C 为 int)

```
/*a,b为高精度, c为int. 公式: A^B%C =
A^(B%phi(C)+phi(C))%C*/
#define LL long long
#define nnum 1000005
#define nmax 31625
int flag[nmax], prime[nmax], plen;
char cha[nnum], chb[nnum];
void mkprime() {
    int i, j;
    memset(flag, -1, sizeof(flag));
    for (i = 2, plen = 0; i < nmax; i++) {
        if (flag[i]) prime[plen++] = i;
        for (j = 0; (j < plen) && (i * prime[j]
< nmax); j++) {
            flag[i * prime[j]] = 0;
            if (i % prime[j] == 0) break;
        }
    }
}
int getPhi(int n) {
    int i, te, phi;
    te = (int) sqrt(n * 1.0);
    for (i = 0, phi = n; (i < plen) &&
(prime[i] <= te); i++) {
        if (n % prime[i] == 0) {
            phi = phi / prime[i] * (prime[i]
- 1);
            while (n % prime[i] == 0) n /=
prime[i];
        }
    }
    if (n > 1) phi = phi / n * (n - 1);
    return phi;
}
int cmpBigNum(int p, char *ch)
{
    int i, len;
    LL res;
    len = strlen(ch);
    for (i = 0, res = 0; i < len; i++) {
        res = (res * 10 + (ch[i] - '0'));
```

```

        if (res > p) return 1;
    }
    return 0;
};

int getModBigNum(int p, char *ch) {
    int i, len;
    LL res;
    len = strlen(ch);
    for (i = 0, res = 0; i < len; i++)
        res = (res * 10 + (ch[i] - '0')) %
p;
    return (int) res;
};

int modular_exp(int a, int b, int c) {
    LL res, temp;
    res = 1 % c, temp = a % c;
    while (b) {
        if (b & 1)
            res = res * temp % c;
        temp = temp * temp % c;
        b >>= 1;
    }
    return (int) res;
};

void solve(int a, int c, char *ch) {
    int phi, res, b;
    phi = getPhi(c);
    if (cmpBigNum(phi, ch))
        b = getModBigNum(phi, ch) + phi;
    else
        b = atoi(ch);
    res = modular_exp(a, b, c);
    printf("%d\n", res);
};

int main() {
    int a, c;
    mkprime();
    while (~scanf("%s %s %d", cha, chb, &c))
    {
        a = getModBigNum(c, cha);
        solve(a, c, chb);
    }
    return 0;
}

```

求 $A^B \% C$ 2.0 (A, B, C 均为 long long)

```

//a, b, c 小于  $2^{63}$ 
// 二分求:  $(A*B) \% C$ 
unsigned long long Multi(unsigned long long
a, unsigned long long b, unsigned long long
n) {
    unsigned long long back=0, temp = a%n;
    while (b) {
        if ( (b&1) && ((back+=temp)>=n) )
            back -= n;
        if ((temp<<=1) >= n) temp -= n;
        b>>=1;
    }
    return back;
};

//二分求:  $A^B \% C$ 
unsigned long long Pow(unsigned long long a,
unsigned long long b, unsigned long long c) {
    unsigned long long ans = 1;
    while (b!=0) {
        if (b&1) ans = Multi(ans, a, c);
        a = Multi(a, a, c);
        b >>= 1;
    }
    return ans;
};

int main() {
    unsigned long long a, b, c;
    while (scanf("%llu%llu%llu", &a, &b,
&c)!=EOF)
        printf("%llu\n", Pow(a, b, c));
    return 0;
}

```

整数分解 (判断质数)

```

struct prime{
    unsigned __int64 num;
    int sum;
}no[10010];

```

```

int sum;
unsigned __int64 factor[10010];
unsigned __int64 mul_mod(unsigned __int64
a, unsigned __int64 b, unsigned __int64 n) {
    unsigned __int64 exp = a % n;
    unsigned __int64 res = 0;
    while(b) {
        if(b&1) {
            res += exp;
            if(res > n) res -= n;
        }
        exp <<= 1;
        if(exp>n) exp -= n;
        b >>= 1;
    }
    return res;
}

unsigned __int64 exp_mod(unsigned __int64
a, unsigned __int64 b, unsigned __int64 c) {
    unsigned __int64 k = 1;
    while(b) {
        if(b & 1) k = mul_mod(k, a, c);
        a = mul_mod(a, a, c);
        b >>= 1;
    }
    return k;
}

bool miller_rabbin(unsigned __int64 n,
unsigned __int64 times) {
    if(n == 2) return 1;
    if(n < 2 || !(n & 1)) return 0;
    unsigned __int64 a, u = n - 1, x, y;
    int t = 0;
    while((u&1) == 0) {
        ++ t;
        u >>= 1;
    }
    for(int i=0; i<times; i++) {
        a = rand() % (n-1) + 1;
        x = exp_mod(a, u, n);
        for(int j=0; j<t; j++) {
            y = mul_mod(x, x, n);
            if(y == 1 && x != 1 && x != n-1)
                return false;
            x = y;
        }
        if(y != 1) return false;
        return true;
    }
}

unsigned __int64 gcd(unsigned __int64
a, unsigned __int64 b) {
    unsigned __int64 t;
    while(b) {
        t = a % b;
        a = b;
        b = t;
    }
    return a;
};

unsigned __int64 Pollard_rho(unsigned
__int64 x, unsigned __int64 c) {
    unsigned __int64 i = 1, k = 2;
    unsigned __int64 x0 = rand() % (x - 1)
+ 1;
    unsigned __int64 y = x0;
    while(1) {
        i++;
        x0 = ( mul_mod(x0, x0, x) + c) % x;
        unsigned __int64 d = gcd((y - x0 +
x) % x, x);
        if(d > 1 && d < x) return d;
        if(y==x0) return x;
        if(i==k) {
            y = x0;
            k <<= 1;
        }
    }
};

void findfac(unsigned __int64 n, unsigned
__int64 c) {
    if(n==1) return;
    if(miller_rabbin(n, 6)) {
        factor[sum++] = n;
        return;
    }
}

```

```

unsigned __int64 p = n;
unsigned __int64 k = c;
while(p>=n)
    p = Pollard_rho(p, c--);
findfac(p, k);
findfac(n/p, k);
};
int main() {
    unsigned __int64 n, t;
    unsigned __int64 ans;
    scanf("%I64u", &t);
    while(t-->0) {
        scanf("%I64u", &n);
        sum = 0;
        findfac(n, 120);
        sort(factor, factor+sum);
        no[0].num = factor[0];
        no[0].sum = 1;
        int index = 0;
        for(int i = 1; i<sum; i++) {
            if(factor[i]!=factor[i-1]) {
                index++;
                no[index].num = factor[i];
                no[index].sum = 1;
            }
            else no[index].sum++;
        }
        if(sum==1)
            printf("Prime\n");
        else
            for(int i = 0; i<=index; i++)

            printf("%I64d %d\n", no[i].num, no[i].sum);
    }
    return 0;
}

```

求单个数的欧拉值

```

unsigned euler(unsigned x) { // 就是公式
    unsigned i, res=x;
    for (i = 2; i < (int)sqrt(x * 1.0) + 1;

```

```

        i++)
            if(x%i==0) {
                res = res / i * (i - 1);
                while (x % i == 0) x /= i; //
                保证i一定是素数
            }
            if (x > 1) res = res / x * (x - 1);
    return res;
}

```

快速 GCD

```

int gcd(int a, int b)
{
    while (b ^= a ^= b ^= a %= b);
    return a;
}

```

快速幂

```

long long quickpow(long long m, long long
n, long long k) {
    long long b = 1;
    while (n > 0) {
        if (n & 1)
            b = (b%k)*(m%k) % k;
        n = n >> 1;
        m = (m%k)*(m%k) % k;
    }
    return b;
}

```

错排公式

no[n]表示 n 个球放入 n 个盒子里, 相同号不放入相同号箱子的方法

```

no[0]=0;
no[1]=0;
no[2]=1;
for (int i = 3; i <= 100; i++)
{
    no[i] = (i - 1) * (no[i-1] + no[i-2]) % MOD;
}

```

```

}

while(m){
    if(m&1) ret = (ret * a) % n;
    a = (a * a) % n;
    m >>= 1;
}
return ret;
}

// calCmn(ll p, ll q){
    ll x = q, y = p - q;
    ll tmp = (factorial[p] % mod) *
    powmod(factorial[y]*factorial[x], mod-2,
    mod) % mod;
    return tmp;
}

0 到 n 相异或值

int xorUpToK(int k) {
    switch (k % 4) {
        case 0: return k;
        case 1: return 1;
        case 2: return k + 1;
        case 3: return 0;
    }
}

组合数公式

for(int i = 0; i <= x; i++)
{
    c[i][0] = c[i][i] = 1;
    for(int j = 1; j < i; j++)
    {
        c[i][j] = c[i-1][j] + c[i-1][j-1];
    }
}

线性筛素数

long long prime[N], flag[N];
long long count;//素数个数
void getprime(long long n){
    long long i,j;
    memset(flag,0,sizeof(flag));
    for(i=2;i<=n;i++){
        //未标记的就是素数了
        if(!flag[i]) prime[++count]=i;
        for(j = 1;j<=count&&i*prime[j]<=n;
j++){
            flag[i * prime[j]] = 1;//prime[j]
            都是素数
            if(i % prime[j]==0)
                break;
        }
    }
}

大组合数对素数取模

typedef __int64 ll;
const int maxn = 100005;
const ll mod = 1000000009;
ll factorial[2*maxn];

void init(){
    factorial[0] = 1;
    for(int i = 1; i < 2*maxn; i++)
        factorial[i] = (factorial[i-1] * i) %
mod;
}

容斥原理

#include<stdio.h>
#include<string.h>
int a[20], N, M, la ;
int hash[20];
__int64 gcd(__int64 a, __int64 b){
    ll ret = 1;
    a %= n;
}

```

```

    __int64 c ;
    while(b){
        c = a % b ;
        a = b ;
        b = c ;
    }
    return a ;
}
//当前点已经加入容斥的个数，记录容斥的
过程值结果
void dfs(int now, int count, __int64 lcm,
__int64 &sum){
    lcm = a[now] / gcd(lcm, a[now]) * lcm ;
    if(count & 1)
        sum += (N - 1) / lcm ;
    else sum -= (N - 1) / lcm ;
    for(int i = now + 1; i < M; i++){
        dfs(i, count + 1, lcm, sum);
    }
}
int main(){
    int b,i ;
    while(scanf("%d%d", &N, &M) != EOF){
        for(i = 0, la = 0; i < M; i++){
            scanf("%d", &b);
            if(b) a[la++] = b ;
        }
        M = la ;
        __int64 sum = 0 ;
        //memset(hash,0,sizeof(hash));
        for(i = 0; i < M; i++) //枚举起点
            dfs(i, 1, a[i], sum);
        printf("%I64d\n", sum);
    }
    return 0 ;
}

```

高斯消元

```
const int maxn = 105;
int equ, var; // 有 equ 个方程, var 个变元。增广阵行数为 equ, 分别为 0 到 equ - 1, 列数为
var + 1, 分别为 0 到 var.
int a[maxn][maxn];
int x[maxn]; // 解集.
bool free_x[maxn]; // 判断是否是不确定的变元.
int free_num;
void Debug(void)
{
    int i, j;
    for (i = 0; i < equ; i++)
    {
        for (j = 0; j < var + 1; j++)
        {
            cout << a[i][j] << " ";
        }
        cout << endl;
    }
    cout << endl;
}
inline int gcd(int a, int b)
{
    int t;
    while (b != 0)
    {
        t = b;
        b = a % b;
        a = t;
    }
    return a;
}
inline int lcm(int a, int b)
{
    return a * b / gcd(a, b);
}
// 高斯消元法解方程组(Gauss-Jordan elimination).(-2 表示有浮点数解, 但无整数解, -1 表示
无解, 0 表示唯一解, 大于 0 表示无穷解, 并返回自由变元的个数)
int Gauss(void)
{
    int i, j, k;
```

```

int max_r; // 当前这列绝对值最大的行.
int col; // 当前处理的列.
int ta, tb;
int LCM;
int temp;
int free_x_num;
int free_index;
// 转换为阶梯阵.
col = 0; // 当前处理的列.
for (k = 0; k < equ && col < var; k++, col++)
{ // 枚举当前处理的行.
    // 找到该 col 列元素绝对值最大的那行与第 k 行交换.(为了在除法时减小误差)
    max_r = k;
    for (i = k + 1; i < equ; i++)
    {
        if (abs(a[i][col]) > abs(a[max_r][col])) max_r = i;
    }
    if (max_r != k)
    { // 与第 k 行交换.
        for (j = k; j < var + 1; j++) swap(a[k][j], a[max_r][j]);
    }
    if (a[k][col] == 0)
    { // 说明该 col 列第 k 行以下全是 0 了, 则处理当前行的下一列.
        k--; continue;
    }
    for (i = k + 1; i < equ; i++)
    { // 枚举要删去的行.
        if (a[i][col] != 0)
        {
            LCM = lcm(abs(a[i][col]), abs(a[k][col]));
            ta = LCM / abs(a[i][col]), tb = LCM / abs(a[k][col]);
            if (a[i][col] * a[k][col] < 0) tb = -tb; // 异号的情况是两个数相加.
            for (j = col; j < var + 1; j++)
            {
                a[i][j] = a[i][j] * ta - a[k][j] * tb;
            }
        }
    }
}
Debug();
// 1. 无解的情况: 化简的增广阵中存在(0, 0, ..., a)这样的行(a != 0).
for (i = k; i < equ; i++)
{ // 对于无穷解来说, 如果要判断哪些是自由变元, 那么初等行变换中的交换就会影响,
    则要记录交换.

```



```

        if (a[i][col] != 0) return -1;
    }
    // 2. 无穷解的情况: 在 var * (var + 1) 的增广阵中出现 (0, 0, ..., 0) 这样的行, 即说明没有
    形成严格的上三角阵.
    // 且出现的行数即为自由变元的个数.
    if (k < var)
    {
        // 首先, 自由变元有 var - k 个, 即不确定的变元至少有 var - k 个.
        for (i = k - 1; i >= 0; i--)
        {
            // 第 i 行一定不会是 (0, 0, ..., 0) 的情况, 因为这样的行是在第 k 行到第 equ 行.
            // 同样, 第 i 行一定不会是 (0, 0, ..., a), a != 0 的情况, 这样的无解的.
            free_x_num = 0; // 用于判断该行中的不确定的变元的个数, 如果超过 1 个,
            则无法求解, 它们仍然为不确定的变元.
            for (j = 0; j < var; j++)
            {
                if (a[i][j] != 0 && free_x[j]) free_x_num++, free_index = j;
            }
            if (free_x_num > 1) continue; // 无法求解出确定的变元.
            // 说明就只有一个不确定的变元 free_index, 那么可以求解出该变元, 且该变
            元是确定的.
            temp = a[i][var];
            for (j = 0; j < var; j++)
            {
                if (a[i][j] != 0 && j != free_index) temp -= a[i][j] * x[j];
            }
            x[free_index] = temp / a[i][free_index]; // 求出该变元.
            free_x[free_index] = 0; // 该变元是确定的.
        }
        return var - k; // 自由变元有 var - k 个.
    }
    // 3. 唯一解的情况: 在 var * (var + 1) 的增广阵中形成严格的上三角阵.
    // 计算出 Xn-1, Xn-2 ... X0.
    for (i = var - 1; i >= 0; i--)
    {
        temp = a[i][var];
        for (j = i + 1; j < var; j++)
        {
            if (a[i][j] != 0) temp -= a[i][j] * x[j];
        }
        if (temp % a[i][i] != 0) return -2; // 说明有浮点数解, 但无整数解.
        x[i] = temp / a[i][i];
    }
    return 0;

```

```
}
int main(void)
{
    freopen("Input.txt", "r", stdin);
    int i, j;
    while (scanf("%d %d", &equ, &var) != EOF)
    {
        memset(a, 0, sizeof(a));
        memset(x, 0, sizeof(x));
        memset(free_x, 1, sizeof(free_x)); // 一开始全是不确定的变元.
        for (i = 0; i < equ; i++)
        {
            for (j = 0; j < var + 1; j++)
            {
                scanf("%d", &a[i][j]);
            }
        }
        // Debug();
        free_num = Gauss();
        if (free_num == -1) printf("无解!\n");
        else if (free_num == -2) printf("有浮点数解, 无整数解!\n");
        else if (free_num > 0)
        {
            printf("无穷多解! 自由变元个数为%d\n", free_num);
            for (i = 0; i < var; i++)
            {
                if (free_x[i]) printf("x%d 是不确定的\n", i + 1);
                else printf("x%d: %d\n", i + 1, x[i]);
            }
        }
        else
        {
            for (i = 0; i < var; i++)
            {
                printf("x%d: %d\n", i + 1, x[i]);
            }
        }
        printf("\n");
    }
    return 0;
}
```

求和公式

求和公式, $k = 1..n$

1. $\text{sum}(k) = n(n+1)/2$

2. $\text{sum}(2k-1) = n^2$

3. $\text{sum}(k^2) = n(n+1)(2n+1)/6$

4. $\text{sum}((2k-1)^2) = n(4n^2-1)/3$

5. $\text{sum}(k^3) = (n(n+1)/2)^2$

6. $\text{sum}((2k-1)^3) = n^2(2n^2-1)$

7. $\text{sum}(k^4) = n(n+1)(2n+1)(3n^2+3n-1)/30$

8. $\text{sum}(k^5) = n^2(n+1)^2(2n^2+2n-1)/12$

9. $\text{sum}(k(k+1)) = n(n+1)(n+2)/3$

10. $\text{sum}(k(k+1)(k+2)) = n(n+1)(n+2)(n+3)/4$

12. $\text{sum}(k(k+1)(k+2)(k+3)) =$
 $n(n+1)(n+2)(n+3)(n+4)/5$

图论

最短路

Dijkstra (带输出路径)

```
#define INF 100000000
#define maxn 1001
bool vis[maxn];
int
adj[maxn][maxn], dis[maxn], pre[maxn]; //pre
[] 记录前驱
int n, m;
void dijkstra(int v) {
    int i, j, u, min;
    for(i=0; i<=n; i++) {
        dis[i]=adj[v][i];
        vis[i]=0;
        //if(i!=v&&adj[v][i]!=INF) pre[i]
= v;
        // else pre[i] = -1;
    }
    vis[v]=1; dis[v]=0;
    for(i=1; i<n; i++) {
        min = INF;
        for(j=1; j<=n; j++)
            if(!vis[j]&&min > dis[j]) {
                min = dis[j];
                u = j;
            }
        if(min == INF) break;
        vis[u]=1;
        for(j=1; j<=n; j++)

if(!vis[j]&&adj[u][j]!=INF&&dis[u]+adj[u]
[j]<dis[j]) {
            dis[j] = adj[u][j] +
dis[u];
            // pre[j] = u;
        }
    }
```

```

}
int main()
{
    int i, j, x, y, w;
    while(~scanf("%d%d", &n, &m)&&n)
    {
        for(i=0; i<=n; i++)
        {
            for(j=0; j<=n; j++)
                if(i==j) adj[i][j]=0;
                else adj[i][j] = INF;
        }
        while(m--)
        {
            scanf("%d%d%d", &x, &y, &w);
            adj[x][y] = w;
            adj[y][x] = w;
        }
        dijkstra(0);
        printf("%d\n", dis[n]); //以下为
输出路径
        /*int p, len=0, ans[maxn];
        p = n-1;
        while(p!=0)
        {
            ans[len++] = p;
            p = pre[p];
        }
        printf("0->");
        for(i=len-1; i>=0; i--)
            printf("%d", ans[i]);
        puts(""); */
    }
    return 0;
}
```

Floyd

```
//floyd求出了各点之间的距离
for(k = 1; k<=n; k++) {
    for(i = 1; i<=n; i++) {
        for(j = 1; j<=n; j++) {
```

```

        if(dis[i][j]>dis[i][k] + dis[k][j]){
            dis[i][j] =
dis[i][k] + dis[k][j];
        }
    }
}

```

SPFA(邻接表)

```

#define INF 9999999
using namespace std;
struct EDGE{
    int v , w , next;
}edge[10010];
int head[10010] , k;
int n , m , s , e;
int dis[1010] , vis[1010] , cnt[1010];
void build_edge(int u , int v , int w) {//无
    edge[k].v = v;
    edge[k].w = w;
    edge[k].next = head[u];
    head[u] = k++;
    edge[k].v = u;
    edge[k].w = w;
    edge[k].next = head[v];
    head[v] = k++;
};
void build_edge1(int u , int v , int w) {//
    edge[k].v = v;
    edge[k].w = w;
    edge[k].next = head[u];
    head[u] = k++;
};
bool spfa(){
    memset(vis,0,sizeof(vis));
    memset(cnt,0,sizeof(cnt));
    for(int i = 0;i<=n;i++){
        dis[i] = INF;
        dis[s] = 0;

```

```

        priority_queue<pair<int ,int> > q;
        q.push(make_pair(0,s));
        vis[s] = 1;
        cnt[s]++;
        int temp;
        while(!q.empty()){
            temp = q.top().second;
            q.pop();
            vis[temp] = 0;
            for(int i = head[temp];i!=-1;i =
edge[i].next){
                if(dis[edge[i].v] - edge[i].w >
dis[temp]){
                    dis[edge[i].v] = edge[i].w +
dis[temp];
                    if(!vis[edge[i].v]){
                        q.push(make_pair(-dis[edge[i].v],edge[i].v));
                        vis[edge[i].v] = 1;
                        cnt[edge[i].v]++;
                        if(cnt[edge[i].v]>=n)
                            return true;//有负
                    }
                }
            }
        }
        return false;
    }
}

```

最小生成树

Kruskal

```

struct point{
    int u , v;
    int w;
}num[5008];
int p[102], n , i , sum , x , y;;
int cmp(const void *a , const void *b) {
    struct point *c , *d;
    c = (struct point *)a;

```

```

    d = (struct point *)b;
    return c->w - d->w;
};

int root(int x){
    if(x==p[x]) return x;
    return p[x]=root(p[x]);
};

int Kruskal(){
    int i;
    for(i=0;i<n;i++)p[i]=i;

    qsort(num,n*(n-1)/2,sizeof(num[0]),cmp);
    sum=0;
    for(i=0;i<n*(n-1)/2;i++){
        x = root(num[i].u);
        y = root(num[i].v);
        if(x!=y){
            sum+=num[i].w;
            p[x] = y;
        }
    }
    return sum;
}

int main(){
    while(scanf("%d",&n),n){
        for(i=0;i<n*(n-1)/2;i++)

scanf("%d%d%d",&num[i].u,&num[i].v,&num[i].w);

        Kruskal();
        printf("%d\n",sum);
    }
    return 0;
}

```

强连通分量

Tarjan

```

#define MAX 100010
vector<int> p[MAX];
stack<int> s;

```

```

int dfn[MAX],low[MAX],vis[MAX],no[MAX];
//no表示每个点在哪个强连通分量中
int index,flag,num;//num表示强连通分量的个数

void Tarjan(int x){
    dfn[x] = low[x] = ++index;
    vis[x] = 1;
    s.push(x);
    for(int i = 0;i < p[x].size();i++){
        if(!dfn[p[x][i]]){
            Tarjan(p[x][i]);
            low[x] = min(low[x],low[p[x][i]]);
        }
        else if(vis[p[x][i]])
            low[x] = min(dfn[p[x][i]],low[x]);
    }
    if(dfn[x]==low[x]){
        num++;
        int v;
        while(1){
            v = s.top();
            no[v] = num;
            vis[v] = 0;
            s.pop();
            if(v==x)
                break;
        }
    }
};

int main(){
    int n,m;
    while(scanf("%d",&n)!=EOF){
        scanf("%d",&m);
        for(int i = 0;i <= n;i++)
            p[i].clear();
        for(int i = 0;i < m;i++){
            int a,b;
            scanf("%d%d",&a,&b);
            p[a].push_back(b);
        }
        memset(dfn,0,sizeof(dfn));
        memset(low,0,sizeof(low));
        memset(vis,0,sizeof(vis));
        index = 0;
    }
}

```

```

    flag = 0;
    num = 0;
    for(int i = 1; i <= n; i++)
        if(!dfn[i])
            Tarjan(i);
    }
    return 0;
}

```

网络流

Dinic

```

#define MAX 200010
#define INF 999999999999999999
#define min(a, b) (a < b ? a : b)
struct Edge{
    int st, ed;
    int next;
    int flow;
} edge[MAX*10];
int head[MAX], out[MAX];
int stack[MAX], p[MAX];
int leve[MAX];
int Count, s, t;
void build_edge ( int u, int v, long long
flw ) {
    edge[Count].st = u;
    edge[Count].ed = v;
    edge[Count].flow = flw;
    edge[Count].next = head[u];
    head[u] = Count++;
    edge[Count].st = v;
    edge[Count].ed = u;
    edge[Count].flow = 0;
    edge[Count].next = head[v];
    head[v] = Count++;
};
bool BFS() {
    memset(leve, -1, sizeof(leve));
    int front, rear, u, v, i;
    front = rear = 0;

```

```

    p[rear++] = s;
    leve[s] = 0;
    while(front != rear) {
        u = p[front++];
        for (i = head[u]; i != -1; i =
edge[i].next ) {
            v = edge[i].ed;
            if(edge[i].flow >
0 && leve[v] == -1) {
                leve[v] = leve[u] + 1;
                p[rear++] = v;
            }
        }
    }
    return leve[t] != -1;
};
int Dinic () {
    int maxFlow = 0;
    while (BFS()) {
        int top = 0, u = s, i;
        for(i = s; i <= t; i++) //此处s为0,
t为n+1
            out[i] = head[i];
        while(out[s] != -1) {
            if(u == t) {
                long long dd = INF;
                for (i = top-1; i >= 0; i--)
                    dd = min
(edge[stack[i]].flow, dd);
                for (i = top-1; i >= 0; i--)
                    edge[stack[i]].flow
-= dd;

                edge[stack[i]^1].flow += dd;
                if
(edge[stack[i]].flow == 0)
                    top = i;
            }
            maxFlow += dd;
            u = edge[stack[top]].st;
        }
        else if
(out[u] != -1 && edge[out[u]].flow > 0 && leve[u]
+ 1 == leve[edge[out[u]].ed]) {

```

```

        stack[top++] = out[u];
        u = edge[out[u]].ed;
    }
    else{
        while
(top>0&&u!=s&&out[u]==-1)
            u =
edge[stack[--top]].st;
        out[u] =
edge[out[u]].next;
    }
}
return maxFlow;
};

int main() {
    int n, m, u, v, w, a, b;
    scanf("%d%d", &n, &m);
    s = 0;
    t = n + 1;
    Count = 0;
    memset(head, -1, sizeof(head));
    for(int i = 1; i <= n; i++) {
        scanf("%d%d", &a, &b);
        build_edge(s, i, a);
        build_edge(i, t, b);
    }
    while(m--) {
        scanf("%d%d%d", &u, &v, &w);
        build_edge(u, v, w);
        build_edge(v, u, w);
    }
    long long maxFlow = Dinic();
    printf("%lld\n", maxFlow);
    return 0;
}

```

//节点下标从 0 开始
//加边时运行 `add_edge(a,b,c,0,d)` 表示加一条 `a` 到 `b` 的流量为 `c` 花费为 `d` 的边（注意花费为单位流量花费）
//特别注意双向边，如果要加的是双向边的话，运行 `add_edge(a,b,c,0,d),add_edge(b,a,c,0,d)` 较好，不要只运行一次 `add_edge(a,b,c,c,d)`，费用会不对。
//求解时代入 `MCMF(s,t,n,v1,v2)`，表示起点为 `s`，终点为 `t`，点数为 `n` 的图中，最大流为 `v1`，最大花费为 `v2`
`#define INF 1000000000`
`const int M = 4 * 10010; //边`
`const int N = 1010; //点`
`struct Node{ //边，点f到点t，流量为c，费用为w`
`int st, ed;`
`int flow, cost;`
`int next;`
`}edge[M];`
`int head[N], dis[N], q[N], pre[N], cnt;`
//cnt为已添加的边数，head为邻接表，dis为花费，pre为父亲节点
`bool vis[N];`
`void init(){`
`memset(head, -1, sizeof(head));`
`cnt = 0;`
`}`
`void add_edge(int f, int t, int d1, int d2, int w){`
//f到t的一条边，流量为d1，反向流量d2，花费w，反向边花费-w（可以反悔）
`edge[cnt].st = f;`
`edge[cnt].ed = t;`
`edge[cnt].flow = d1;`
`edge[cnt].cost = w;`
`edge[cnt].next = head[f];`
`head[f] = cnt++;`

`edge[cnt].st = t;`
`edge[cnt].ed = f;`
`edge[cnt].flow = d2;`
`edge[cnt].cost = -w;`
`edge[cnt].next = head[t];`

费用流

最小费用最大流 MCMF

//建图前运行 `init()`


```

    head[t] = cnt++;
}

bool spfa(int s, int t, int n){
    int i, tmp, l, r;
    memset(pre, -1, sizeof(pre));
    for(i = 0; i < n; ++i) dis[i] = INF;
    dis[s] = 0;
    q[0] = s;
    l = 0, r = 1;
    vis[s] = true;
    while(l != r){
        tmp = q[l];
        l = (l + 1) % (n + 1);
        vis[tmp] = false;
        for(i = head[tmp]; i != -1; i =
edge[i].next){
            if(edge[i].flow && dis[edge[i].ed] >
dis[tmp] + edge[i].cost){
                dis[edge[i].ed] = dis[tmp] +
edge[i].cost;

                pre[edge[i].ed] = i;
                if(!vis[edge[i].ed]){
                    vis[edge[i].ed] = true;
                    q[r] = edge[i].ed;
                    r = (r + 1) % (n + 1);
                }
            }
        }
        if(pre[t] == -1) return false;
        return true;
    }

void MCMF(int s, int t, int n, int &flow, int
&cost){
    //起点s, 终点t, 点数n, 最大流flow, 最小
花费cost

    int tmp, arg;
    flow = cost = 0;
    while(spfa(s, t, n)){
        arg = INF;
        tmp = t;
        while(tmp != s){

```

```

            arg = min(arg,
edge[pre[tmp]].flow);
            tmp = edge[pre[tmp]].st;
        }
        tmp = t;
        while(tmp != s){
            edge[pre[tmp]].flow -= arg;
            edge[pre[tmp] ^ 1].flow += arg;
            tmp = edge[pre[tmp]].st;
        }
        flow += arg;
        cost += arg * dis[t];
    }
}

```

最大费用流

```

const int E = 50010;//边数
const int INF = 0x7fffffff;
const int N = 210;//点数

struct edge
{
    int next,v,flow,cost;
}e[E];
int head[N],cnt;
queue<int> q;
int S,T;//起点、终点
int dis[N],cc[N],visit[N],pre[N],dd[N];

void addedge(int u,int v,int flow,int cost){
    e[cnt].v = v;
    e[cnt].flow = flow;
    e[cnt].cost = cost;
    e[cnt].next = head[u];
    head[u] = cnt++;
}

void addEdge(int u,int v,int flow,int cost){
    addedge(u,v,flow,cost);
    addedge(v,u,0,-cost);
}

```

```

void init(){
    cnt = 0;
    memset(head,-1,sizeof(head));
}

int spfa(){
    fill(dis,dis + T + 1, -INF);
    dis[S] = 0;
    pre[S] = -1;
    while(!q.empty()) q.pop();
    q.push(S);
    while(!q.empty()) {
        int u = q.front();
        q.pop();
        visit[u] = 0;
        for(int i = head[u]; i != -1; i =
e[i].next) {
            if(e[i].flow > 0 && dis[e[i].v] <
dis[u] + e[i].cost) {
                dis[e[i].v] = dis[u] +
e[i].cost;

                pre[e[i].v] = u;
                cc[e[i].v] = i;
                dd[e[i].v] = e[i].cost;
                if(!visit[e[i].v]) {
                    q.push(e[i].v);
                    visit[e[i].v] = 1;
                }
            }
        }
    }
    return dis[T] >= 0;
}

int argument(){
    int aug = INF;
    int u,v;
    int ans = 0;
    for(u = pre[v = T]; v != S; v = u, u = pre[v])
        if(e[cc[v]].flow < aug) aug =
e[cc[v]].flow;
    for(u = pre[v = T]; v != S; v = u, u = pre[v])
    {
        e[cc[v]].flow -= aug;
        e[cc[v] ^ 1].flow += aug;
        ans += dd[v] * aug;
    }
    return ans;
}

void mcmf(){
    memset(visit,0,sizeof(visit));
    while(spfa()) {
        int cost = argument();
        if(ans < 0) break;
        ans -= cost;
    }
    printf("%d\n",ans);
}

```

树的直径

```

struct NODE{
    int v ,w;
    int next;
}nodes[1000010];
int head[1000010] ,cnt;
int n ,m ,maxnode;
long long ans;
int flag[1000010];
int dir[4][2] = {{1,0},{-1,0},{0,-1},{0,1}};
void addedge(int u ,int v ,int w){
    nodes[cnt].v = v;
    nodes[cnt].w = w;
    nodes[cnt].next = head[u];
    head[u] = cnt;
    cnt++;

    nodes[cnt].v = u;
    nodes[cnt].w = w;
    nodes[cnt].next = head[v];
    head[v] = cnt;
    cnt++;
}

void DFS(int x ,int sum){

```

```

if(sum > ans)
{
    ans = sum;
    maxnode = x;
}
int re;
flag[x] = 1;
for(int i = head[x]; i != -1; i = nodes[i].next)
{
    re = nodes[i].v;
    if(!flag[re])
    {
        DFS(re, sum + nodes[i].w);
    }
}
}

int main(){
    int u, v, w;
    while(~scanf("%d", &n)){
        memset(head, -1, sizeof(head));
        memset(flag, 0, sizeof(flag));
        ans = 0;
        cnt = 0;
        for(int i = 1; i < n; i++) {
            scanf("%d%d%d", &u, &v, &w);
            addedge(u, v, w);
        }
        DFS(1, 0);
        ans = 0;
        memset(flag, 0, sizeof(flag));
        DFS(maxnode, 0);
        printf("%lld\n", ans);
    }
    return 0;
}

```

LCA(Tarjan)

```

#include<cstdio>
#include<cstring>
#include<algorithm>
#include<vector>

```

```

#include<cmath>
#include<queue>
#define mem(a,b) memset(a,b,sizeof(a))
#define MAX 40010
using namespace std;
struct NODE
{
    int v, w;
    int to;
}edges[2*MAX];
int head[MAX], cnt; //邻接表存边
struct QUERY
{
    int v;
    int to, no;
}queries[MAX];
int he[MAX], cntq; //邻接表存询问
int n, m;
bool flag[MAX]; //是否遍历
int ancestor[MAX], pa[MAX], cntpa[MAX];
//祖先，并查集，集合中元素个数
int ans[MAX];
int dist[MAX], num[MAX][2];
void addedge(int u, int v, int w){
    edges[cnt].v = v;
    edges[cnt].w = w;
    edges[cnt].to = head[u];
    head[u] = cnt++;
    edges[cnt].v = u;
    edges[cnt].w = w;
    edges[cnt].to = head[v];
    head[v] = cnt++;
}

void addquery(int u, int v, int no){
    queries[cntq].no = no;
    queries[cntq].v = v;
    queries[cntq].to = he[u];
    he[u] = cntq++;
    queries[cntq].no = no;
    queries[cntq].v = u;
    queries[cntq].to = he[v];
    he[v] = cntq++;
}

```

```

int find(int x){
    if(pa[x]==x) return x;
    return pa[x] = find(pa[x]);
}
void merge(int x ,int y){
    int xx = find(x);
    int yy = find(y);
    if(xx != yy){
        if(cntpa[xx] <= cntpa[yy]){
            pa[xx] = yy;
            cntpa[yy] += cntpa[xx];
        }
        else{
            pa[yy] = xx;
            cntpa[xx] += cntpa[yy];
        }
    }
}
void LCA(int u){
    flag[u] = 1;
    ancestor[u] = u;
    for(int i = head[u]; i != -1; i = edges[i].to){
        int re = edges[i].v;
        if(flag[re]) continue;
        dist[re] = dist[u] + edges[i].w;
        LCA(re);
        merge(u, re);
        ancestor[find(u)] = u;
    }
    for(int i = he[u]; i != -1; i = querys[i].to){
        int re = querys[i].v;
        if(flag[re])
            ans[querys[i].no] =
ancestor[find(re)];
    }
}

int main(){
    int t ,x ,y ,w;
    scanf("%d",&t);
    while(t--){
        mem(head,-1);
        mem(he,-1);
        cnt = cntq = 0;

        mem(flag,0);
        for(int i = 1; i <= n; i ++){
            pa[i] = i;
            cntpa[i] = 1;
        }
        scanf("%d%d",&n,&m);
        for(int i = 1; i < n; i ++){
            scanf("%d%d%d",&x,&y,&w);
            addedge(x,y,w);
        }
        for(int i = 1; i <= m;i++){
            scanf("%d%d",&x,&y);
            num[i][0] = x;
            num[i][1] = y;
            addquery(x,y,i);
        }
        dist[1] = 0;
        LCA(1);
        for(int i = 1; i <= m; i ++){
            printf("%d\n",dist[num[i][0]] +
dist[num[i][1]] - 2 * dist[ans[i]]);
        }
        return 0;
    }
}

LCA(RMQ)

#include<cstdio>
#include<cstring>
#include<algorithm>
#include<vector>
#include<cmath>
#define mem(a,b) memset(a,b,sizeof(a))
#define MAX 100010
using namespace std;
struct NODE
{
    int v, w;
    int to ,no;
}edges[2*MAX];
int head[MAX] ,cnt;//邻接表
bool vis[MAX];//是否到达
int first[MAX],last[MAX],times;

```

```

//每个点第一次访问时间，最后访问时间，
记录时间
int pos[MAX];//访问的编号
int dep[2*MAX];//每个点的深度
int que[2*MAX],cou;//dfs 访问顺序
int n, s, q;
int val[MAX],path[MAX];
int no[30];
int dp[2*MAX][20];//rmq
void addedge(int u,int v,int w,int no){
    edges[cnt].no = no;
    edges[cnt].v = v;
    edges[cnt].w = w;
    edges[cnt].to = head[u];
    head[u] = cnt;
    cnt++;
    edges[cnt].no = no;
    edges[cnt].v = u;
    edges[cnt].w = w;
    edges[cnt].to = head[v];
    head[v] = cnt;
    cnt++;
}

int _min(int i,int j){
    if(dep[i] < dep[j])
        return i;
    return j;
}

void rmq(){
    int sta;
    for(int i = 0; i <= 20; i++){
        if(cou <= no[i]){
            sta = i;
            break;
        }
    }
    for(int j = 1; j <= sta; j++){
        int re = 1<<(j - 1);
        //此处如果写 i <= cou, 开 2 倍会
RE
        for(int i = 1; i + re <= cou; i++){
            dp[i][j] = _min(dp[i][j - 1], dp[i
+ re][j - 1]);
        }
    }
}

int query(int x,int y){
    int xx = pos[x];
    int yy = pos[y];
    if(xx > yy)
        swap(xx, yy);
    int len = yy - xx + 1;
    int k = log(len * 1.0) / log(2.0);
    return _min(dp[xx][k], dp[yy - (1<<k) +
1][k]);
}

void DFS(int u,int depth){
    vis[u] = 1;
    que[++cou] = u;
    dep[cou] = depth;
    dp[cou][0] = pos[u] = cou;
    first[u] = ++times;
    for(int i = head[u]; i!= -1; i = edges[i].to){
        int re = edges[i].v;
        if(vis[re]) continue;
        path[edges[i].no] = re;
        DFS(re, depth + 1);
        que[++cou] = u;
        dep[cou] = depth;
        dp[cou][0] = cou;
    }
    last[u] = times;
}

int sum[MAX];
int lowbit(int x){
    return (x)&(-x);
}

void update(int pos, int x){
    while(pos <= times){
        sum[pos] += x;
        pos += lowbit(pos);
    }
}

int query1(int pos){
    int s = 0;
    while(pos > 0){
        s += sum[pos];
    }
}

```

```

        pos -= lowbit(pos);
    }
    return s;
}
int main(){
    int x ,y ,w;
    no[0] = 1;
    for(int i = 1; i <= 20; i ++){
        no[i] = no[i - 1] * 2;
    }
    while(~scanf("%d%d%d",&n,&q,&s)){
        mem(head,-1);
        mem(vis,0);
        mem(sum,0);
        cnt = 0;
        cou = 0;
        times = 0;
        for(int i = 1; i < n; i++){
            scanf("%d%d%d",&x,&y,&w);
            addedge(x, y, w, i);
            val[i] = w;
        }
        DFS(s,1);
        rmq();
        for(int i = 1; i < n; i++){
            update(first[path[i]], val[i]);
            update(last[path[i]] + 1, -val[i]);
        }
        int op;
        for(int i = 1; i <= q; i ++){
            scanf("%d",&op);
            if(op == 1){
                scanf("%d%d",&x,&w);
                update(first[path[x]], w -
val[x]);
                update(last[path[x]] + 1,
val[x] - w);
                val[x] = w;
            }
            else if(op == 0){
                scanf("%d",&x);
                int d1 ,d2 ,d3;
                d1 = query1(first[s]);
                d2 = query1(first[x]);

```

```

                d3 =
query1(first[que[query(s,x)]]);
                s = x;
                printf("%d\n", d1 + d2 - 2
* d3);
            }
        }
    }
    return 0;
}

```

哈密顿回路

/*保证有哈密顿回路的情况下，才能这样求。

Dirac 定理： 设一个无向图中有 N 个节点，若所有节点的度数都大于等于 $N/2$ ，则汉密尔顿回路一定存在。

注意，“ $N/2$ ” 中的除法不是整除，而是实数除法。*/

```

void reverse(int s ,int t){
    int temp;
    while(s < t){
        temp = ans[s];
        ans[s] = ans[t];
        ans[t] = temp;
        s++;
        t--;
    }
}

void hamilton(){
    int s = 1 ,t;//s表示起点
    int cnt = 0;
    bool vis[410];
    mem(vis);
    for(int i = 1; i <= n; i++){
        if(map[s][i]){
            t = i;
            break;
        }
    }
    vis[s] = vis[t] = true;
    ans[cnt++] = s;
    ans[cnt++] = t;
}

```

```

while(true){
    while(true){
        int i;
        for(i = 1;i <= n;i++){
            if(map[t][i] && !vis[i]){
                ans[cnt++] = i;
                vis[i] = true;
                t = i;
                break;
            }
        }
        if(i > n)
            break;
    }
    reverse(0,cnt-1);
    swap(s,t);
    while(true){
        int i;
        for(i = 1;i <= n;i++){
            if(map[t][i] && !vis[i]){
                ans[cnt++] = i;
                vis[i] = true;
                t = i;
                break;
            }
        }
        if(i > n)
            break;
    }
    if(!map[s][t]){
        int i;
        for(i = 1;i < cnt - 2;i++){
            if(map[ans[i]][t] &&
map[s][ans[i+1]])
                break;
            i++;
            t = ans[i];
            reverse(i,cnt - 1);
        }
        if(cnt==n) return;
        int j,i;
        for(j = 1;j <= n;j++){
            if(vis[j]) continue;
            for(i = 1;i < cnt - 2;i++){
                if(map[ans[i]][j])
                    break;

```

```

        if(map[ans[i]][j])
            break;
    }
    s = ans[i-1];
    t = j;
    reverse(0,i-1);
    reverse(i,cnt - 1);
    ans[cnt++] = j;
    vis[j] = true;
}
}

```

最小树形图（朱刘算法）

poj 3164 验

```

double map[110][110];
int flag[110],pre[110],vis[110];
int n;//点数
double zhu_liu(int s)//朱刘算法,s为树根节点
{
    int i,j,k;
    pre[s] = s;
    for(i = 0;i < n;i++){
        map[i][i] = INF;
        flag[i] = 0;
    }
    double sum = 0;
    while(1){
        //求最短弧集合E
        for(i = 0;i < n;i++){
            if(flag[i] || i==s) continue;
            pre[i] = i;
            for(j = 0;j < n;j++){
                if(!flag[j] && map[j][i] <
map[pre[i]][i]) pre[i] = j;
            }
            if(pre[i]==i) return -1.0;//不能建
成树形图
        }
        //检查E
        for(i = 0;i < n;i++){
            {
                if(flag[i] || i==s) continue;
                //从当前点开始找环

```

```

mem(vis,0);
vis[s] = 1;
j = i;
do{
    vis[j] = 1;
    j = pre[j];
}while(!vis[j]);
//没有找到环
if(j==s) continue;
//收缩G中的有向环
i = j;
//将整个环的权值保存, 累计入原
图的最小树形图
do{
    sum += map[pre[j]][j];
    j = pre[j];
}while(j!=i);
j = i;
//对与环上的点有关的边, 修改边
权
do{
    for(k = 0; k < n; k++){
        if(!flag[k] && map[k][j]
< INF && k!=pre[j])
            map[k][j] -=
map[pre[j]][j];
        j = pre[j];
    }while(j!=i);
    //缩点, 将整个环缩成i号点, 所
有与环上的点有关的边转移到点i
    for(j = 0; j < n; j++){
        if(j==i) continue;
        for(k = pre[i]; k!=i; k =
pre[k]){
            if(map[k][j] < map[i][j])
map[i][j] = map[k][j];
            if(map[j][k] < map[j][i])
map[j][i] = map[j][k];
        }
    }
    //标记环上其他的点为被缩掉
    for(j = pre[i]; j!=i; j = pre[j]) flag[j]
= 1;
    //当前环缩点结束, 形成新的图

```

```

G1, 跳出继续求G1的最小树形图
break;
}
if(i==n){
    for(i = 0; i < n; i++){
        if(!flag[i] && i!=s) sum +=
map[pre[i]][i];
        break;
    }
}
return sum;
}

```

无向图求割边 (含重边, 邻接表)

```

#define MAX 10010//点
#define MAXN 100010//边
struct EDGE{
    int v;
    int next;
    int id;
}edges[2*MAXN];
int head[MAX], cnt;
int n, m;
void addedge(int u, int v, int id){
    edges[cnt].v = v;
    edges[cnt].next = head[u];
    edges[cnt].id = id;
    head[u] = cnt++;
    edges[cnt].v = u;
    edges[cnt].next = head[v];
    edges[cnt].id = id;
    head[v] = cnt++;
}
bool vis[MAX];
int low[MAX], dfn[MAX], index1;
int ans[MAXN], cou;//割边的编号和个数
void tarjan(int u, int id){
    low[u] = dfn[u] = ++index1;
    vis[u] = 1;
    for(int i = head[u]; i != -1; i =
edges[i].next){
        int re = edges[i].v;

```



```

        if(!vis[re]){
            tarjan(re, edges[i].id);
            low[u] = min(low[u], low[re]);
            if(low[re] > dfn[u])
                ans[cou++] = edges[i].id;
        }
        else if(edges[i].id != id && vis[re] ==
1)
            low[u] = min(low[u], dfn[re]);
    }
}
int main(){
    int t, u, v;
    scanf("%d", &t);
    while(t--){
        memset(head, -1, sizeof(head));
        cnt = 0;
        scanf("%d%d", &n, &m);
        for(int i = 1; i <= m; i++){
            scanf("%d%d", &u, &v);
            if(u == v) continue;
            addedge(u, v, i);
        }
        memset(vis, 0, sizeof(vis));
        memset(dfn, 0, sizeof(dfn));
        memset(low, 0, sizeof(low));
        index1 = 0;
        cou = 0;
        tarjan(1, -1);
    }
    return 0;
}

```

无向图求割点

- 1) 如果 u 该点是根节点并且有两个或者两个以上儿子，那么 u 是一个割点
- 2) 如果 u 不是根节点并且存在它的一个儿子 v , 使得 $low[v] \geq dfn[u]$, 那么 u 是割点

数据结构

线段树

线段树（一段数进行加减）

```
#define MAX 1000010
struct Tree{
    int left ,right;
    __int64 sum;
    __int64 lnc;
}tree[MAX];
__int64 num[100010];
void build_tree(int id,int l,int r){
    tree[id].left = l;
    tree[id].right = r;
    tree[id].lnc = 0;
    if (l==r){
        tree[id].sum = num[l];
        return;
    }
    int mid = (l + r)>>1;
    build_tree(id<<1,l,mid);
    build_tree(id<<1+1,mid+1,r);
    tree[id].sum = tree[id<<1].sum +
tree[id<<1+1].sum;
};
void update(int id,int l,int r, __int64
val){
    if
    (tree[id].left==l&&tree[id].right==r){
        tree[id].lnc += val;
        return;
    }
    tree[id].sum += ((r - l + 1) * val);
    int mid = (tree[id].left +
tree[id].right)>>1;
    if (r<=mid){
        update(id<<1,l,r,val);
    }
    else if(l>mid){

```

```
        update(id<<1+1,l,r,val);
    }
    else{
        update(id<<1,l,mid,val);
        update(id<<1+1,mid+1,r,val);
    }
};
__int64 query(int id,int l,int r){
    if
    (tree[id].left==l&&tree[id].right==r){
        return tree[id].sum + (r - l + 1)
* tree[id].lnc;//询问总和
    }
    else{
        tree[id<<1].lnc += tree[id].lnc;
        tree[id<<1+1].lnc +=
tree[id].lnc;
        tree[id].sum += (tree[id].lnc *
(tree[id].right - tree[id].left + 1));
        tree[id].lnc = 0;
    }
    int mid =
(tree[id].left+tree[id].right)>>1;
    if (r<=mid)return query(id<<1,l,r);
    else if(l>mid)return
query(id<<1+1,l,r);
    else return query(id<<1,l,mid) +
query(id<<1+1,mid+1,r);
};
int main(){
    int n ,m ,q;
    while(scanf("%d%d",&n,&m)!=EOF){//有n
个数，进行m次操作
        memset(num,0,sizeof(num));
        memset(tree,0,sizeof(tree));
        for(int i = 1;i<=n;i++){
            scanf("%I64d",&num[i]);
        }
        build_tree(1,1,n);
        for(int i = 0;i<m;i++){
            char c;
            getchar();
            scanf("%c",&c);
            if(c=='C'){//C表示增加
```

```

        int l, r;
        __int64 val;

        scanf("%d %d %I64d", &l, &r, &val);
        update(1, l, r, val);
    }
    if(c=='Q') { //Q表示询问
        int l, r;
        scanf("%d%d", &l, &r);

        printf("%I64d\n", query(1, l, r)); //询问
        1到r区间内的总和
    }
}
return 0;
}

```

线段树求逆序数

(将一个数放在最后, 逆序数改变量 $n-2*a[i]-1$ (从0开始且 n 个数连续))

```

struct Tree{
    int lson, rson;
    int no;
}tree[5010*3];
int num[5010];
void build_tree(int id, int left, int
right){
    tree[id].lson = left;
    tree[id].rson = right;
    tree[id].no = 0;
    if(left==right)
        return;
    int mid = (left + right) / 2;
    build_tree(2*id, left, mid);
    build_tree(2*id+1, mid+1, right);
};
void update(int id, int pos){
    if(tree[id].lson==tree[id].rson){
        tree[id].no++;
        return;
    }

```

```

        int mid = (tree[id].lson +
tree[id].rson) / 2;
        if(pos <= mid) update(2*id, pos);
        else update(2*id+1, pos);
        tree[id].no = tree[2*id].no +
tree[2*id+1].no;
    };
    int query(int id, int left, int right){
        if(tree[id].lson==left &&
tree[id].rson==right)
            return tree[id].no;
        int mid = (tree[id].lson +
tree[id].rson) / 2;
        if(right<=mid)
            return query(2*id, left, right);
        else if(left > mid)
            return query(2*id+1, left, right);
        else
            return query(2*id, left, mid) +
query(2*id+1, mid+1, right);
    };
    int main(){
        int n;
        long long ans, min;
        while(~scanf("%d", &n)){
            build_tree(1, 0, n-1);
            ans = 0;
            for(int i = 0; i<n; i++){
                scanf("%d", &num[i]);
                ans += query(1, num[i], n-1);
                update(1, num[i]);
            }
            //求以此将最前面的数放到最后面,
            逆序数最小值
            min = ans;
            for(int i = 0; i<n-1; i++){
                ans = ans + (n - 2 * num[i] -
1);

                if(ans < min)min = ans;
            }
            printf("%lld\n", min);
        }
        return 0;
    }
}

```

归并求逆序数

```

long long num[500010];
long long c[500010];
long long cnt;
void Mergesort(int l, int r) {
    int mid, i, j, tmp;
    if (r > l + 1) {
        mid = (l + r) / 2;
        Mergesort(l, mid);
        Mergesort(mid, r);
        tmp = 1;
        for (i = l, j = mid; i < mid && j < r;) {
            if (num[i] > num[j]) {
                c[tmp++] = num[j++];
                cnt += mid - i;
            }
            else c[tmp++] = num[i++];
        }
        if (j < r)
            for (; j < r; j++) c[tmp++] = num[j];
        else
            for (; i < mid; i++) c[tmp++] = num[i];
        for (i = l; i < r; i++) num[i] = c[i];
    }
};
int main() {
    int n;
    while (scanf("%d", &n), n) {
        cnt = 0;
        for (int i = 0; i < n; i++)
            scanf("%lld", &num[i]);
        Mergesort(0, n);
        printf("%lld\n", cnt);
    }
    return 0;
}

i <= n; i++) aa[in[i].order] = i;
//树状数组求逆序
memset(c, 0, sizeof(c));

```

树状数组

树状数组求逆序数

```

const int maxn = 500005;
int n, aa[maxn]; //离散化后的数组
int c[maxn]; //树状数组
struct Node {
    int v;
    int order;
} in[maxn];
int lowbit(int x) {
    return x & (-x);
}
void update(int t, int value) {
    int i;
    for (i = t; i <= n; i += lowbit(i))
        c[i] += value;
}
int getsum(int x) {
    int i;
    int temp = 0;
    for (i = x; i >= 1; i -= lowbit(i))
        temp += c[i];
    return temp;
}
bool cmp(Node a, Node b) {
    return a.v < b.v;
}
int main() {
    int i, j;
    while (scanf("%d", &n) == 1 && n) {
        //离散化
        for (i = 1; i <= n; i++) {
            scanf("%d", &in[i].v);
            in[i].order = i;
        }
        sort(in + 1, in + n + 1, cmp);
        for (i = 1;
            long long ans = 0;
            for (i = 1; i <= n; i++) {
                update(aa[i], 1);
            }
        }
    }
}

```

```

        ans+=i-getsum(aa[i]);
    }
    cout<<ans<<endl;
}
return 0;
}

```

二维树状数组

```

#define MAX 100005
int N=1005,c[1005][1005];
int lowbit( int x ){
    return x & (-x);
}
void modify( int x, int y, int delta ){//a[x][y]增加
delta
    int i, j;
    for(i=x; i<=N; i+=lowbit(i)){
        for(j=y; j<=N; j+=lowbit(j)){
            c[i][j] += delta;
        }
    }
}
int sum( int x, int y ){
    int res = 0, i, j;
    for(i=x; i>0; i-=lowbit(i)){
        for(j=y; j>0; j-=lowbit(j)){
            res += c[i][j];
        }
    }
    return res;
}

```

扫描线

```

#define MAX 10010//点数
struct NODE{
    int lx ,rx ,y;
    int flag;
}nodes[2*MAX];
int n;//点数
int xx[2*MAX];

```

```

int cnt;//去重之后的个数
void deal(){
    cnt = 0;
    int cou = 2 * n;
    for(int i = 1;i < cou;i++){
        if(xx[cnt] != xx[i]){
            cou++;
            xx[cou] = xx[i];
        }
    }
}
int cmp(struct NODE a,struct NODE b){
    if(a.y == b.y)
        return a.flag > b.flag;
    return a.y < b.y;
}
int get_id(int no){
    int left ,right = cnt;
    while(left <= right){
        int mid = (left + right) >> 1;
        if(xx[mid] > no) right = mid + 1;
        else if(xx[mid] < no) left = mid + 1;
        else return mid;
    }
}
struct TREE{
    int left ,right;
    int sum;
}tree[8*MAX];
void build_tree(int id ,int left ,int right){
    tree[id].left = left;
    tree[id].right = right;
    tree[id].sum = 0;
    if(left == right)
        return ;
    int mid = (left + right) >> 1;
    build_tree(id<<1,left,mid);
    build_tree((id<<1) | 1,mid + 1,right);
}
void update(int id ,int left ,int right ,int flag){
int main(){
    int lx ,rx ,dy ,uy;
    while(~scanf("%d",&n)){
        for(int i = 0;i < n;i++){

```

```
scanf("%d%d%d%d",&lx,&dy,&rx,&uy);
    xx[2*i] = nodes[2*i].lx =
nodes[2*i+1].lx = lx;
    xx[2*i+1] = nodes[2*i].rx =
nodes[2*i+1].rx = rx;
    nodes[2*i].y = dy;
    nodes[2*i].flag = 1;
    nodes[2*i+1].y = uy;
    nodes[2*i+1].flag = -1;
}
int cou = 2 * n;
sort(xx,xx+cou);
deal();
sort(nodes,nodes+cou,cmp);
build_tree(1,0,cnt - 1);
for(int i = 0;i < cou - 1;i++){
    int left = get_id(nodes[i].lx);
    int right = get_id(nodes[i].rx);

update(1,left,right,nodes[i].flag);
    ans += tree[1].sum *
(nodes[i+1].y - nodes[i].y);
}
}
return 0;
}
```

哈希函数

// JS Hash Function

```
unsigned int JSHash(char *str){
    unsigned int hash = 1315423911;
    while (*str){
        hash ^= ((hash << 5) + (*str++) + (hash >>
2));
    }
    return (hash & 0x7FFFFFFF);
}
```

// BKDR Hash Function

```
unsigned int BKDRHash(char *str){
    unsigned int seed = 131;
```

// 31 131 1313 13131 131313 etc..

```
unsigned int hash = 0;
while (*str)
    hash = hash * seed + (*str++);
return (hash & 0x7FFFFFFF);
}

// AP Hash Function
unsigned int APHash(char *str){
    unsigned int hash = 0;
    int i;
    for (i=0; *str; i++){
        if ((i & 1) == 0)
            hash ^= ((hash << 7) ^ (*str++) ^
(hash >> 3));
        else
            hash ^= (~((hash << 11) ^ (*str++) ^
(hash >> 5)));
    }
    return (hash & 0x7FFFFFFF);
}
```

树链剖分

```
#pragma comment(linker,
"/STACK:200000000")
#define MAX 500010//点数
using namespace std;
struct EDGE{
    int v;
    int next;
}edges[2 * MAX];
int head[MAX],cou;//邻接表

int n,m,p;
int num[MAX];

void addedge(int x,int y){
    edges[cou].v = y;
    edges[cou].next = head[x];
    head[x] = cou++;
    edges[cou].v = x;
    edges[cou].next = head[y];
    head[y] = cou++;
```

```

}
int size[MAX],son[MAX],fa[MAX],dep[MAX];
//儿子个数,重儿子编号,父亲节点编号,
深度
int top[MAX],pos[MAX],no,ppos[MAX];
/*所在链的顶点,与父亲所在边在线段树中的
位置,
线段树大小,线段树编号对应的点*/
//第一次求出 fa,dep,size,son
int dfs1(int u,int pre,int depth){
    fa[u] = pre;
    dep[u] = depth;
    size[u] = 1;
    son[u] = -1;
    for(int i = head[u]; i != -1; i =
edges[i].next){
        int re = edges[i].v;
        if(re == pre) continue;
        cnt = dfs1(re, u, depth + 1);
        if(son[u] == -1 || size[son[u]] <
size[re])
            son[u] = re;
        size[u] += cnt;
    }
    return size[u];
}
//第二次求 top 和 pos
void dfs2(int u,int tops){
    top[u] = tops;
    pos[u] = no;
    ppos[no] = u;
    no++;
    if(son[u] == -1)
        return;
    dfs2(son[u], tops);
    for(int i = head[u]; i != -1; i = 1;
edges[i].next){
        int re = edges[i].v;
        if(re == fa[u] || re == son[u])
            continue;
        dfs2(re, re);
    }
}
struct TREE{
    int sum;
    int left ,right;
    int lazy;
}tree[4*MAX];

void push_down(int id){
    if(tree[id].lazy != 0){
        tree[id<<1].lazy += tree[id].lazy;
        tree[(id<<1)+1].lazy += tree[id].lazy;
        tree[id].lazy = 0;
    }
}

void build_tree(int id ,int left ,int right){
    tree[id].left = left;
    tree[id].right = right;
    tree[id].sum = tree[id].lazy = 0;
    if(left == right){
        tree[id].sum = num[ppos[left]];
        return;
    }
    int mid = (left + right) >> 1;
    build_tree(id<<1, left, mid);
    build_tree((id<<1) | 1, mid + 1,right);
}

void update(int id ,int le ,int ri ,int val){
    if(tree[id].left == le && tree[id].right ==
ri){
        if(le == ri){
            tree[id].sum += val;
            return;
        }
        tree[id].lazy += val;
        return;
    }
    int mid = (tree[id].left + tree[id].right) >>
push_down(id);
    if(ri <= mid)
        update(id<<1, le, ri ,val);
    else if(le > mid)
        update((id<<1) | 1, le, ri, val);
    else{
        update(id<<1, le, mid ,val);
        update((id<<1) | 1, mid + 1, ri, val);
    }
}

```

```

    }
}
int query(int id ,int pos){
    if(tree[id].left == tree[id].right){
        tree[id].sum += tree[id].lazy;
        tree[id].lazy = 0;
        return tree[id].sum;
    }
    int mid = (tree[id].left + tree[id].right) >>
1;
    push_down(id);
    if(pos <= mid)
        return query(id<<1, pos);
    else
        return query((id<<1)|1, pos);
}

void in_de(int x ,int y ,int val){
    int f1 = top[x] ,f2 = top[y];
    while(f1 != f2){
        if(dep[f1] < dep[f2]){
            swap(f1, f2);
            swap(x, y);
        }
        update(1, pos[f1], pos[x], val);
        x = fa[f1];
        f1 = top[x];
    }
    /*对边权更新
    if(x == y)
        return;
    if(dep[x] < dep[y])
        swap(x,y);
    update(1,pos[son[y]],pos[x],val);
    */
    对点权更新
    if(dep[x] < dep[y])
        swap(x, y);
    update(1, pos[y], pos[x], val);
}

int find_num(int x){
    int ans = pos[x];
    return query(1, ans);
}

```

```

int main(){
    int x ,y ,w;
    char str[10];
    while(~scanf("%d%d%d", &n, &m, &p)){
        mem(head,-1);
        no = cou = 0;
        for(int i = 1;i <= n; i ++){
            scanf("%d", &num[i]);
        }
        for(int i = 1;i <= m; i ++){
            scanf("%d%d", &x, &y);
            addedge(x, y);
        }
        addedge(n + 1,1);
        dfs1(n + 1, 0, 1);
        dfs2(n + 1, n + 1);
        build_tree(1,0,no - 1);
        for(int i = 0; i < p; i ++){
            scanf("%s",str);
            if(str[0] == 'Q'){
                scanf("%d", &x);

                printf("%d\n",find_num(x));
            }
            else if(str[0] == 'D'){
                scanf("%d%d%d", &x, &y,
&w);
                in_de(x, y, -w);
            }
            else
            {
                scanf("%d%d%d", &x, &y,
&w);
                in_de(x, y , w);
            }
        }
    }
    return 0;
}

```

splay

```

#define KEY_VALUE ch[ch[root][1]][0]
#define MAX 200010

```



```

using namespace std;

int num[MAX];
int n;
int min1[MAX],val[MAX];
int add[MAX],flag[MAX];

int pre[MAX];//表示父亲节点
int ch[MAX][2];//表示左右儿子节点
int root;//根节点
int tot;//节点数
int size[MAX];//子树规模
int s[MAX],tot1;//内存池
void update_add(int r,int ADD){
    if(!r) return;
    add[r] += ADD;
    min1[r] += ADD;
    val[r] += ADD;
}
void update_re(int r,int fl){
    if(!r) return;
    swap(ch[r][0],ch[r][1]);
    flag[r] ^= fl;
}
//一般不会使用 push_down，只有在使用
// lazy 标记的时候需要添加
void push_down(int u){
    if(add[u]){
        update_add(ch[u][0],add[u]);
        update_add(ch[u][1],add[u]);
        add[u] = 0;
    }
    if(flag[u]){
        update_re(ch[u][0],flag[u]);
        update_re(ch[u][1],flag[u]);
        flag[u] = 0;
    }
}
//将子树信息更新到父亲节点
void push_up(int u){
    size[u] = size[ch[u][0]] + size[ch[u][1]] +
1;
    //根据题目修改一下
    min1[u] = min(min1[ch[u][0]],min1[ch[u][1]]),val[u]
);
}
//建立新节点
void newnode(int &r,int father,int k){
    if(tot1) r = s[tot1--];
    else r = ++tot;
    pre[r] = father;
    ch[r][0] = ch[r][1] = 0;
    size[r] = 1;
    //以下内容根据题目修改
    val[r] = k;
    min1[r] = k;
    flag[r] = 0;
    add[r] = 0;
}
//旋转操作
void rotate(int u,int kind){//kind 为 1 是右旋，
为 0 是左旋
    int y = pre[u];
    push_down(y);
    push_down(u);
    ch[y][!kind] = ch[u][kind];
    pre[ch[u][kind]] = y;
    if(pre[y])
        ch[pre[y]][ch[pre[y]][1]==y] = u;
    pre[u] = pre[y];
    pre[y] = u;
    ch[u][kind] = y;
    push_up(y);
}
void splay(int r,int goal){
    push_down(r);
    while(pre[r] != goal){
        if(pre[pre[r]]==goal)
            rotate(r,ch[pre[r]][0]==r);
        else{
            int y = pre[r];
            int kind = ch[pre[y]][0]==y;//如
果 y 是父亲节点的左子树为 1，否则为 0
            //判断两个方向是否相同,方
            向不同
            if(ch[y][kind]==r){
                rotate(r,!kind);
            }
        }
    }
}

```

```

        rotate(r,kind);
    }
    else{
        rotate(y,kind);
        rotate(r,kind);
    }
}
}
push_up(r);
if(goal==0) root = r;
}
//把第 k 位的数移动到 goal 下面
void rotateto(int k,int goal){
    int r = root;
    push_down(r);
    while(size[ch[r][0]] != k){
        if(k < size[ch[r][0]])
            r = ch[r][0];
        else{
            k -= (size[ch[r][0]] + 1);
            r = ch[r][1];
        }
        push_down(r);
    }
    splay(r,goal);
}
void adds(int left ,int right ,int x){
    rotateto(left-1,0);
    rotateto(right+1,root);
    update_add(KEY_VALUE,x);
    push_up(ch[root][1]);
    push_up(root);
}
int query(int left ,int right){
    rotateto(left-1,0);
    rotateto(right+1,root);
    return min1[KEY_VALUE];
}
//建树
void build_tree(int &x ,int left ,int right ,int
father){
    if(left > right) return;
    int mid = (left + right) >> 1;
    newnode(x,father,num[mid]);
    build_tree(ch[x][0],left,mid-1,x);
    build_tree(ch[x][1],mid+1,right,x);
    push_up(x);
}
//初始化
void init(){
    ch[0][0] = ch[0][1] = size[0] = pre[0] = 0;
    min1[0] = INF;
    root = tot = tot1 = 0;
    newnode(root,0,INF);
    newnode(ch[root][1],root,INF);
    size[root] = 2;
    build_tree(KEY_VALUE,0,n-1,ch[root][1]);
    push_up(ch[root][1]);
    push_up(root);
}
//插入操作
void insert(int k ,int x){
    rotateto(k,0);
    rotateto(k+1,root);
    newnode(KEY_VALUE,ch[root][1],x);
    push_up(ch[root][1]);
    push_up(root);
}
//删除操作，将第 k 位的数删除
void erase(int k){
    rotateto(k-1,0);
    rotateto(k+1,root);
    s[++tot1] = KEY_VALUE;
    KEY_VALUE = 0;
    push_up(ch[root][1]);
    push_up(root);
}
void reverse(int left ,int right){
    rotateto(left-1,0);
    rotateto(right+1,root);
    update_re(KEY_VALUE,1);
}
void revolve(int left ,int right ,int t){
    if(!t) return;
    rotateto(right-t,0);
    rotateto(right+1,root);
    push_down(KEY_VALUE);
    int re = KEY_VALUE;

```

```

        KEY_VALUE = 0;
        push_up(ch[root][1]);
        push_up(root);
        rotateto(left-1,0);
        rotateto(left,root);
        KEY_VALUE = re;
        if(re) pre[re] = ch[root][1];
        push_up(ch[root][1]);
        push_up(root);
    }
    char str[110];

int main()
{
    int m ,a ,b ,c;
    while(~scanf("%d",&n))
    {
        for(int i = 0;i < n;i++)
            scanf("%d",&num[i]);
        init();
        scanf("%d",&m);
        while(m--){
            scanf("%s",str);
            if(str[0]=='M'){
                scanf("%d%d",&a,&b);
                printf("%d\n",query(a,b));
            }
            else if(str[0]=='A'){
                scanf("%d%d%d",&a,&b,&c);
                adds(a,b,c);
            }
            else if(str[0]=='D'){
                scanf("%d",&a);
                erase(a);
            }
            else if(str[0]=='I'){
                scanf("%d%d",&a,&b);
                insert(a,b);
            }
            else if(str[3]=='E'){
                scanf("%d%d",&a,&b);
                reverse(a,b);
            }
        }
    }
}

```

字符串

KMP

KMP

```
int nextval[1000010];
vector<int> v;
void get_nextval(int len ,char ptrn[]){
    int i = 0 , j = -1;
    nextval[i] = -1;
    while(i < len-1) {
        if(j == -1 || ptrn[i]==ptrn[j]) {
            ++i;
            ++j;

            if(ptrn[i]!=ptrn[j])nextval[i] = j;
            else nextval[i] = nextval[j];
        }
        else j = nextval[j];
    }
};
```

```
void kmp_search(char str1[] ,char
str2[] ,int len1 ,int len2) {
    int i = 0, j = 0;
    while(i <= len1) {
        if(j==len2) {
            v.push_back(i - len2);
            j = nextval[j];
            if(i==len1)break;
        }
        else{
            if(j==-1 ||
str1[i]==str2[j]) {
                i++;
                j++;
            }
            else j = nextval[j];
        }
    }
};
```

```
};
```

```
int main() {
    char str1[1000010] , str2[1000010];
    int len1 , len2;
    scanf("%s%s", str1, str2);
    len1 = strlen(str1);
    len2 = strlen(str2);
    //当需要处理如: 在abababab中abab的个数
    时, 加上下两行
    str2[len2] = '*';
    len2++;
    str2[len2] = '\0';
    get_nextval(len2 , str2);
    len2--; //对应上面的注释
    kmp_search(str1, str2, len1, len2);
    printf("%d", v.size());
    for(int i = 0; i < v.size(); i++)
        printf(" %d", v[i]);
    printf("\n");
    return 0;
}
```

后缀数组

```
int
wa[MAX], wb[MAX], wv[MAX], ws1[MAX], sa[
MAX];
int rank1[MAX], height[MAX];
int cmp(int *r, int a, int b, int l)
    return r[a]==r[b] && r[a+l]==r[b+l];

void da(int *r, int *sa, int n, int m){
    int i, j, p, *x=wa, *y=wb, *t;
    for(i=0; i<m; i++) ws1[i]=0;
    for(i=0; i<n; i++) ws1[x[i]=r[i]]++;
    for(i=1; i<m; i++) ws1[i]+=ws1[i-1];
    for(i=n-1; i>=0; i--) sa[--ws1[x[i]]]=i;
    for(j=1, p=1; p<n; j*=2, m=p){
        for(p=0, i=n-j; i<n; i++) y[p++]=i;
        for(i=0; i<n; i++) if(sa[i]>=j)
y[p++]=sa[i]-j;
        for(i=0; i<n; i++) wv[i]=x[y[i]];
```

```
    for(i=0;i<m;i++) ws1[i]=0;
    for(i=0;i<n;i++) ws1[wv[i]]++;
    for(i=1;i<m;i++) ws1[i]+=ws1[i-1];
    for(i=n-1;i>=0;i--)
sa[--ws1[wv[i]]]=y[i];

    for(t=x,x=y,y=t,p=1,x[sa[0]]=0,i=1;i<n;i++)

    x[sa[i]]=cmp(y,sa[i-1],sa[i],j)?p-1:p++;
    }
    return;
}
void calheight(int *r,int *sa,int n){
    int i,j,k=0;
    for(i=1;i<=n;i++)
        rank1[sa[i]]=i;
    for(i=0;i<n;height[rank1[i++]]=k)

        for(k?k--:0,j=sa[rank1[i]-1];r[i+k]==r[j+k];k+
+);
    return;
}
num[1...n-1];
num[n] = 0;
da(num,sa,n+1,1000001);
calheight(num,sa,n);
```

动态规划

最长非上升子序列

//时间复杂度 $O(n \log n)$

```
int LDesS(int a[], int n) {
    int i, r, l, len, m, order[1010];
    memset(order, 0, sizeof(order));
    len = 1;
    for (i = 0; i < n; ++i) {
        l = 1;
        r = len;
        while (l <= r) {
            m = (l + r) >> 1;
            if (order[m] >= a[i]) //改为>,
            则是最长下降子序列
                l = m + 1;
            else r = m - 1;
        }
        if (order[l] < a[i]) order[l] =
a[i];
        len = max(len, l);
    }
    return len;
};
```

```
int main() {
    int n, num[1010], Max;
    scanf("%d", &n); //n个数
    for (int i = 0; i < n; ++i)
        scanf("%d", &num[i]);
    Max = LDesS(num, n);
    printf("%d\n", Max);
}
```

最长非下降子序列

//时间复杂度 $O(n \log n)$

```
#define MAX 1010
int a[MAX], k;
void find(int x, int y, int b) {
```

```
int mid;
int f;
while(x < y) {
    mid = (x + y) / 2;
    if(a[mid] >= b) {
        f = mid;
        y = mid;
    }
    else x = mid + 1;
}
if(a[x] >= b) f = x;
a[f] = b;
}

int main() {
    int i, n, b;
    while (scanf("%d", &n) != -1) {
        memset(a, 0, sizeof(a));
        k = 0;
        for (i = 1; i <= n; ++i) {
            scanf("%d", &b);
            if (b >= a[k]) //改为>, 则是最长
            上升子序列
                a[++k] = b;
            else find(1, k, b);
        }
        printf("%d\n", k);
    }
    return 0;
}
```

最长公共子序列

```
vector<char> common;
int lcs(string A, string B) {
    vector<vector<int>> len;
    len.resize(A.size()+1);
    for (int i = 0; i <= A.size(); ++i)
        len[i].resize(B.size()+1, 0);
    for (int i = 1; i <= A.size(); ++i) {
        for (int j = 1; j <= B.size(); ++j) {
            if (A[i-1] == B[j-1])
                len[i][j] = len[i-1][j-1]
+ 1;
```

```

        else if (len[i-1][j] >=
len[i][j-1])
            len[i][j] = len[i-1][j];
        else
            len[i][j] = len[i][j-1];
    }
}
int apos = A.size();
int bpos = B.size();
int commonlen = len[apos][bpos];
int k = commonlen;
common.resize(commonlen);
while(apos && bpos){
    if(len[apos][bpos] ==
len[apos-1][bpos] + 1){
        common[--k] = A[--apos];
        --bpos;
    }
    else if (len[apos-1][bpos] >=
len[apos][bpos-1])
        --apos;
    else
        --bpos;
}
for(int i = 0; i < commonlen; i++)
    cout<<common[i];
cout<<endl;
return commonlen;
}
int main()
{
    string A = "abcdss";
    string B = "asbda";
    cout<<lcs(A,B);
    return 0;
}

char *str2 , int len2 , char *&lcs){
    if(NULL == str1 || NULL == str2)
        return -1;    //空参数
    // 压缩后的最长子串记录向量
    int *c = new int[len2+1];
    for(int i = 0 ; i < len2 ; ++i)
        c[i] = 0;
    int max_len = 0;    //匹配的长度
    int pos = 0;        //在str2上的匹配最
                        末位置
    for(int i = 0 ; i < len1 ; ++i){
        for(int j = len2 ; j > 0 ; --j){//
更新时从后往前遍历
            if(str1[i] == str2[j-1]){
                c[j] = c[j-1] + 1;
                if(c[j] > max_len){
                    max_len = c[j];
                    pos = j-1;
                }
            }
            else
                c[j] = 0;
        }
    }
    if(0 == max_len)
        return 0;
    // 得到公共子串
    lcs = new char[max_len];
    for(int i = 0 ; i < max_len ; ++i)
        lcs[i] = str2[pos-max_len+1+i];
    cout<<"pos = "<<pos<<endl;
    delete [] c;
    return max_len;
}
// test
int main(){
    const char *str1 = "abacaba";
    const char *str2 = "caba";
    int len1 = strlen(str1);
    int len2 = strlen(str2);
    char *lcs;
    int len = LCS(str1 , len1 , str2 , len2 ,
lcs);
    cout<<"max length = "<<len<<endl;
}

```

最长公共子串

```

// 查找公共子串
// lcs记录公共子串
// return 公共子串长度
int LCS(const char *str1 , int len1 , const

```

```

for(int i = 0 ; i < len ; ++i)
    cout<<lcs[i]<<" ";
}

```

多重背包

```

struct Cash{
    int n, d;
};
typedef struct Cash C;
C num[11];
int f[100010];
int main(){
    int N, cash;
    int i, j, k;
    scanf("%d",&cash);
    scanf("%d",&N);
    for(i = 0;i<N;i++){
        scanf("%d%d",&num[i].n,&num[i].d);
    }
    int min = 100000, all = 0;
    for(i = 0;i<N;i++){
        if(min>num[i].d)
            min = num[i].d;
        all += num[i].d * num[i].n;
    }
    if(min > cash){
        printf("0\n");
        continue;
    }
    if(all < cash){
        printf("%d\n",all);
        continue;
    }

    memset(f,0,sizeof(f));
    for(i = 0;i<N;i++){
        if(num[i].d * num[i].n==cash)
            f[cash] = cash;
        else if(num[i].d*num[i].n>cash)
            for (k=num[i].d;k<=cash;k++)
                if (f[k-num[i].d]+ num[i].d>f[k])
                    f[k]=f[k-num[i].d]+num[i].d;
        else{
            int m = num[i].n;
            for(j=1;j<=num[i].n/2;j*=2){
                for( k=cash;k>=j*num[i].d;k--){
                    if (f[k-j*num[i].d]+
                        j*num[i].d>f[k])
                        f[k]=f[k-j*num[i].d]+j*num[i].d;
                    m -= j;
                }
                for (k=cash;k>=m*num[i].d;k--){
                    if(f[k-m*num[i].d]+
                        m*num[i].d>f[k])
                        f[k]=f[k-m*num[i].d]+m*num[i].d;
                }
            }
        }
        printf("%d\n",f[cash]);
    }
    return 0;
}

```


泛化背包

```

int n, dp[510][10010], max1;
int c[100010], u[100010];
vector<int> v[100010];
void solve(int x, int spend){
    int re;
    for(int i = 0; i < v[x].size(); i++){
        re = v[x][i];
        //对于子节点为叶子节点的点，直接进行dp操作合并。
        if(v[re].empty()){
            for(int j = spend; j >= c[re]; j--){
                dp[x][j] = max(dp[x][j],
                    dp[x][j - c[re]] + u[re]);
                if(dp[x][j] > max1)
                    max1 = dp[x][j];
            }
        }
        else{
            for(int j = 0; j <= spend - c[re]; j++){
                dp[re][j] = dp[x][j];
                //对dp[re][0~spend-c[re]]更行，
                //算出其子树的一个泛化背包。即花费
                //j=1~spend-c[re]能获得的最大战斗力
                solve(re, spend - c[re]);
            }
            for(int j = spend; j >= c[re]; j--){
                dp[x][j] = max(dp[x][j],
                    dp[re][j - c[re]] + u[re]);
                if(dp[x][j] > max1)
                    max1 = dp[x][j];
            }
        }
    }
}

```

}

双调 TSP

```

for(int i = 1; i <= n; i++){
    {
        for(int j = 1; j <= i; j++){
            {
                dp[i][j] = dp[j][i] = 999999999;
            }
        }
    }

    dp[2][1] = dp[1][2] = dist[1][2];
    for(int j = 3; j <= n; j++){
        {
            dp[j][1] = dp[1][j] = dp[1][j-1] +
                dist[j-1][j];
        }
    }

    for(int i = 2; i <= n; i++){
        {
            double ans = 999999999;
            for(int k = 1; k < i; k++){
                {
                    f(ans > dp[i][k] + dist[k][i+1])
                    {
                        ans = dp[i][k] + dist[k][i+1];
                    }
                }
            }
            dp[i+1][i] = dp[i][i+1] = ans;
            for(int j = i + 2; j <= n; j++){
                {
                    dp[j][i] = dp[i][j] = dp[i][j-1] +
                        dist[j-1][j];
                }
            }
        }
    }

    dp[n][n] = dp[n][n-1] + dist[n-1][n];
}

```

高精度

C 语言实现

```
#define maxsize 100
struct hp{
    int len;
    int s[maxsize+1];
};
//输入
void input(hp &a, string str) {
    int i;
    while(str[0]!='0' && str.size()!=1)
        str.erase(0, 1);
    a.len=(int)str.size();
    for(i=1; i<=a.len; ++i)
        a.s[i]=str[a.len-i]-48;
    for (i=a.len+1; i<=maxsize; ++i)
        a.s[i]=0;
}
//输出
void print(const hp &y)
{
    int i;
    for(i=y.len; i>=1; i--)
        cout<<y.s[i];
    cout<<endl;
}
//比较函数 a > b返回正数, a==b返回0, a < b
返回负数
int compare(const hp &a, const hp &b) {
    int len;
    if(a.len>b.len)
        len=a.len;
    else
        len=b.len;
    while(len>0 && a.s[len]==b.s[len])
        len--;
    if(len==0)
        return 0;
    else
```

```
        return a.s[len]-b.s[len];
}
//加法, 结果保存在c中
void plus(const hp &a, const hp &b, hp &c)
{
    int i, len;
    for(i=1; i<=maxsize; i++) c.s[i]=0;
    if(a.len>b.len) len=a.len;
    else len=b.len;
    for(i=1; i<=len; i++)
    {
        c.s[i]+=a.s[i]+b.s[i];
        if(c.s[i]>=10)
        {
            c.s[i]-=10;
            c.s[i+1]++;
        }
    }
    if(c.s[len+1]>0) len++;
    c.len=len;
}
//减法 结果保存在c中, a是被减数, b是减数,
不支持负数运算
void subtract(const hp &a, const hp &b, hp &c)
{
    int i, len;
    for(i=1; i<=maxsize; i++) c.s[i]=0;
    if(a.len>b.len) len=a.len;
    else len=b.len;
    for(i=1; i<=len; i++)
    {
        c.s[i]+=a.s[i]-b.s[i];
        if(c.s[i]<0)
        {
            c.s[i]+=10;
            c.s[i+1]--;
        }
    }
    while(len>1&&c.s[len]==0) len--;
    c.len=len;
}
//高精度乘10
void multiply10(hp &a)
{

```

```

    int i;
    for(i=a.len;i>=1;i--)
        a.s[i+1]=a.s[i];
    a.s[1]=0;
    a.len++;
    while(a.len>1&&a.s[a.len]==0)
a.len--;
}
//高精度乘单精度, a是高精度, b是单精度
void multiply(const hp &a, int b, hp &c) {
    int i, len;
    for(i=1;i<=maxsize;i++) c.s[i]=0;
    len=a.len;
    for(i=1;i<=len;i++) {
        c.s[i]+=a.s[i]*b;
        c.s[i+1]+=c.s[i]/10;
        c.s[i]%=10;
    }
    len++;
    while(c.s[len]>=10) {
        c.s[len+1]+=c.s[len]/10;
        c.s[len]%=10;
        len++;
    }
    while(len>1&&c.s[len]==0) len--;
    c.len=len;
}
//高精度乘高精度
void multiplyh(const hp &a, const hp &b, hp
&c)
{
    int i, j, len;
    for(i=1;i<=maxsize;i++) c.s[i]=0;
    for(i=1;i<=a.len;i++)
        for(j=1;j<=b.len;j++)
        {
            c.s[i+j-1]+=a.s[i]*b.s[j];
            c.s[i+j]+=c.s[i+j-1]/10;
            c.s[i+j-1]%=10;
        }
    d.s[1]=a.s[i];
    while(compare(d, b)>=0)
    {
        subtract(d, b, e);
        d=e;
    }
}
    len=a.len+b.len+1;
    while(len>1&&c.s[len]==0) len--;
    c.len=len;
}
//高精度除单精度, a是高精度, c为商, d为余数
void divide(const hp &a, int b, hp &c, int &d)
{
    int i, len;
    for(i=1;i<=maxsize;i++) c.s[i]=0;
    len=a.len;
    d=0;
    for(i=len;i>=1;i--)
    {
        d=d*10+a.s[i];
        c.s[i]=d/b;
        d%=b;
    }
    while(len>1&&c.s[len]==0) len--;
    c.len=len;
}
//高精度除高精度
void divideh(const hp &a, const hp &b, hp
&c, hp &d)
{
    hp e;
    int i, len;
    for(i=1;i<=maxsize;i++)
    {
        c.s[i]=0;
        d.s[i]=0;
    }
    len=a.len;
    d.len=1;
    for(i=len;i>=1;i--)
    {
        multiply10(d);
        c.s[i]++;
    }
    while(len>1&&c.s[len]==0) len--;
    c.len=len;
}

```

JAVA 实现

```

package Animal;

import java.util.*;
import java.math.*;

class order{
    int num ,id;
    static class orderComparator implements
Comparator{
        public int compare(Object o1,Object
o2){
            order s1 = (order)o1;
            order s2 = (order)o2;
            if(s1.num==s2.num)
            {
                return s1.id > s2.id ? 1 :
-1;
            }
            return s1.num > s2.num ? 1 :
-1;
        }
    }
    order(int num ,int id){
        this.num = num;
        this.id = id;
    }
}

class orderComparator implements Comparator
{//从小到大排序
    public final int compare(Object pFirst,
Object pSecond) {
        order a = (order) pFirst;
        order b = (order) pSecond;
        if(a.num==b.num){
            return a.id > b.id ? 1 : -1;
        }
        return a.num > b.num ? 1 : -1;
    }
}

```

```

public class Cat {
    static int n;
    public static void main(String[] args){
        BigInteger[] ans = new
BigInteger[1010];
        order[] no = new order[1010];
        BigInteger a ,b ,c;
        Scanner cin = new Scanner(System.in);
        while(cin.hasNext()){
            n = cin.nextInt();
            for(int i = 0;i < n;i++){
                no[i] = new
order(cin.nextInt(),i);
            }
            Arrays.sort(no,0,n,new
orderComparator());
            a = BigInteger.ONE;
            b = BigInteger.ONE;
            int s = 2 ,cnt = 0;
            while(cnt < n){

                while(s < no[cnt].num){
                    c = a;
                    a = a.add(b);
                    b = c;
                    s++;
                }
                ans[no[cnt].id] = a;
                cnt++;
            }
            for(int i = 0;i < n;i++){
                System.out.println(ans[i]);
            }
        }
    }
}

```

BigInteger a ,b,c;
 BigInteger[] d = new BigInteger[40];
 Int x;
 a = BigInteger.valueOf(3232);将一个 int 型赋值给一个大数。

```
d = a. divideAndRemainder(b);除法并取余，返回一个  
数组，第一个为商，第二个为余数  
c = a.pow(x);a 的 x 次方，x 为 int 型  
//10 进制->2 进制  
String a = "121";//输入数值  
BigInteger src = new BigInteger(a);//转换为 BigInteger  
类型  
System.out.println(src.toString(2));//转换为 2 进制并  
输出  
//2 进制->10 进制  
String b = "1111001";//输入数值  
BigInteger src1= new BigInteger(b,2);//转换为  
BigInteger 类型  
System.out.println(src1.toString());//转换为 10 进制并  
输出结果
```

杂

去重

```
v.erase(unique(v.begin(),v.end()),v.end());
struct NODE{
    int x,y;
    bool operator < (const struct NODE &a) const {
        if(x==a.x)
            return y > a.y;
        return x > a.x;
    }
};//按 x 从大到小排序，优先队列时按 x 从小到大
```

手动扩栈

```
#pragma comment(linker,
"/STACK:102400000,102400000")
```

输入加速

```
void read(int &x) {
    char c;
    while((c=getchar())<'0' || c>'9');
    x=c-'0';
    while((c=getchar())>='0' && c<='9')
        x=(x<<3)+(x<<1)+c-'0';
}
```