

# HUBERT KIM

12600 Foxridge Ln. Apt. L, Blacksburg VA 24060

☎ +1 (917) 834-0377   ✉ hk1540@vt.edu   🏠 hubertjkim.github.io/profile

## SUMMARY

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Ph.D. candidate trained for 4+ years in the start-up robotics laboratory, with hands-on experience of the robot development and ability to lead a project independently. Expertise in the following fields:

- Embedded Systems Programming
- Fast Prototyping Wearable Device
- Signal Processing
- Human Subject Research

## EDUCATION

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| <b>Virginia Polytechnic Institute and State University</b>   | <i>Blacksburg, VA</i> |
| <b>Ph.D.</b> , Mechanical Engineering  | Expected 2020         |
| <ul style="list-style-type: none"><li>• Dissertation: <i>Joint Torque Feedback for Arm Motion Training</i></li><li>• ICTAS Doctoral Scholarship (4-year graduate fellowship)</li></ul>                                     |                       |
| <b>New York University Tandon School of Engineering</b>  | <i>Brooklyn, NY</i>   |
| <b>B.S.</b> , <i>cum laude</i> , Mechanical Engineering (Minor in Mathematics)   | May 2015              |
| <ul style="list-style-type: none"><li>• Thesis: <i>Voltage attenuation along the electrodes of ionic polymer metal composites</i></li><li>• Awarded for Best Mechanical Engineering Experience for Undergraduate</li></ul> |                       |

## RESEARCH EXPERIENCE

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| <b>Ph.D. Researcher</b>   Virginia Polytechnic Institute and State University  | <i>Blacksburg, VA</i> |
| <ul style="list-style-type: none"><li>• Explore kinesthetic cue as a means of haptic information transfer</li><li>• Fabricated a direct-driving haptic exoskeleton</li><li>• Realized psychophysics tools in GUI and conducted human subject testing</li><li>• Supervised 3 senior design teams (including Cornell Cup Robotics) and trained 2 M.S. Students</li></ul> | May 2015 - Present    |
| <b>Undergraduate Researcher</b>   New York University Tandon School of Engineering   | <i>Brooklyn, NY</i>   |
| <ul style="list-style-type: none"><li>• Built various testbeds on signal processing applications for smart materials</li><li>• Analyzed transfer functions of the smart materials in oscillatory motion</li><li>• Published 5 journal papers (1 first-author, 1 co-author, 3 second-author)</li><li>• Passed NCEES: FE exam, NY</li></ul>                              | 2013 - 2015<br>2015   |
| <b>Undergraduate Student</b>   New York University Tandon School of Engineering  | <i>Brooklyn, NY</i>   |
| <i>Capstone Project</i> <ul style="list-style-type: none"><li>• Built a tendon-actuated manipulator to detect and grab the spinning object</li><li>• Developed an Arduino-based robotic arm with a flex sensor</li><li>• Presented at AerosPACE Epic Challenge Student Exposition, NASA Langley Research Center</li></ul>  | 2014 - 2015           |

## SKILLS

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| <b>Embedded systems programming</b>             | Code Composer Studio, C++, JavaScript           |
| <b>Data analysis &amp; Numerical simulation</b> | MATLAB  |
| <b>3D CAD</b>                                   | NX, Solidworks                                  |
| <b>Language</b>                                 | Korean, English (dual citizenship: ROK and USA) |

## PUBLICATIONS AND PRESENTATIONS

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- 2 first-author PUB: ICRA(2019, Accepted), J.of Intell Mater Syst Struct(2016)
- 1 poster PRESEN: IROS(2016)
- 4 co-author PUB: Renew. Energy(2015), Smart Mater Struct(2014, 2013), Mater(2014)