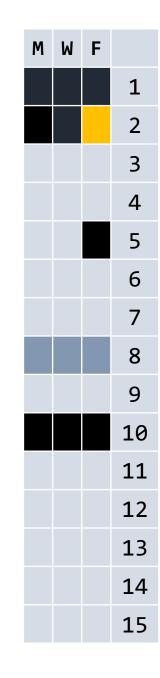
CMOR 421/521: Complexity and Efficiency



Topics

What is performance?

- Complexity: Big O, Ω , Θ
 - Up-front constants
 - Lower order terms
 - Combinations of algorithms
 - Interdependence of time and memory complexity
- Implementation details
 - (joined by caching and stride from earlier)
 - Function overhead, inline functions, macros, and recursion

Algorithm Complexity

You may have heard people say:

- This algorithm is O(n*log(n))
- This program runs in polynomial time
- The problem is NP-hard/NP-complete
- This problem scales linearly
- This problem scales exponentially
- etc

Why Care about Complexity?

Complexity tells us how the cost of a program scales asymptotically (i.e. if you go far enough out)

- t = \$: Computing time on a computer is often bought
- t = t: Solutions be needed by a deadline
- m = \$: Space/memory on a computer is often bought
- m = m: You can run out of memory

Knowing the complexity of a program can help us estimate whether a run can complete a given dataset in a given amount of time and memory

Big O Mathematically

A given function f(X) is said to be O(g(X)) if there exists two constants k and C such that:

$$f(X) \leq C*g(X)$$
 for all $X > k$

- Big O states an upper bound on a function
- Notice, by this definition n is $O(n^2)$, $O(n^3)$, etc
- We also require the upper bound to be asymptotically tight, i.e., as close as possible

Big O Practically

Example:

$$f(n) = 2*n^2 + 2*log(n) + n + 8$$

$$f(n) = \frac{2*n^2}{2} + \frac{2*log(n)}{2} + n + 8$$

- Ignore lower order terms
- Ignore coefficients

Big O Cheat Sheet

• Constant:	0(1)
• Logarithmic:	O(log(n))
• Log-linear/linearithmic:	O(n*log(n))
• Polynomial:	0(n^c)
• Exponential:	0(a^n)
• Factorial:	O(n!)
 Tetration/combinatorial: 	0(n^n)

Program:

For a square (n x n) 2D array:

- 1. Normalize the array by it's maximum element
 - 1. Find the max
 - 2. Divide every element by the max
- 2. Search for an element in a given row, print the result
- 3. Print the max element and the normalized array

Example code: 1) Normalizing the array: 2*n^2

```
// Assume we're given: double A[n][n] = {...};
// Find the maximum element
double max = A[0][0];
for(i=0; i < n; i++)
    for(j=0; j < n; j++)
        if( A[i][j] > max)
            max = A[i][j];
// Normalize
for(i=0; i < n; i++)
    for(j=0; j < n; j++)
        A[i][j] /= max;
```

Example code: 2) Search for elements: n + 6

```
int i_search, j_query;
printf("Enter the number to search for: ");
scanf("%lf", query) )
printf("Enter the row to be searched: ");
scanf("%d", i search);
j_query = -1;
for(j = 0; j < n && j_query < 0; j++)
    if A[i_search][j] == query
       j query = j;
printf("Query returned column %d\n");
```

Example code: 3) Print results: n^2 + n + 1

```
// Print the max
printf("Max: %lf\n", max);

// Print the normalized array
for(i=0; i < n; i++) {
    for(j=0; j < n; j++)
        printf(" %.4lf", A[i][j]);
    printf("\n");
}</pre>
```

Program:

For a square (n x n) 2D array:

- 1. Normalizing: 2*n^2
- 2. Search: n + 6
- 3. Print results: $n^2 + n + 1$

$$=> f(n) = 3*n^2 + 2*n + 7 => 0(n^2)$$

Note: Because we drop lower-order terms and coefficients, we typically don't count single actions (e.g. printing)

Big O Practically

Programs can rely on several variables/parameters

- The final Big O reported needs to include this
 - Previous example: What if we wanted to do multiple (q) searches? n->q*n, =>f would be $O(n^2+q*n)$, because q is unknown

Programs have both time and memory costs

- We can describe both using Big O notation
 - Previous example: Memory was O(n^2)
 - The memory costs do not (necessarily) go up if we do multiple searches

Big Ω : Big O's Opposite

A given function f(X) is said to be $\Omega(g(X))$ if there exists two constants k and C such that:

$$f(X) \ge C*g(X)$$
 for all $X > k$

- ullet Big Ω states an $oldsymbol{lower}$ bound on a function
- Notice, by this definition n^3 is $\Omega(n^2)$, $\Omega(n)$, ...
- ullet Big Ω must also be asymptotically tight
- \bullet For some functions, Ω is different than O

Complexity != Efficiency

Big O Isn't Everything

Big O is a tool that helps us understand how a program will scale, but it neglects many things

- Algorithms behavior may vary on different datasets
 - Big O vs Big Ω
- What if two algorithms have the same complexity? Are they truly equal?
 - Their coefficients and lower order terms may be different
- Big O doesn't know about architecture
 - Caching, stride, and fastest dimension/axis

Up-Front Constants

"Up-front constants" refers to the "C" in the mathematical statement: $f(X) \leq C*g(X)$ for X > k

- Example: suppose we want max, min, and average of an array
 - Can be calculate in one pass through O(n), or 3 separate passes O(3*n)
- Large up-front constants can make an algorithm with better complexity perform more poorly than an algorithm with more costly complexity for *smaller* datasets
- Remember Big O is asymptotic; *eventually* the better complexity algorithm will beat the other
 - What if you're never encounter the cross-over point?
 - => You choose the algorithm with higher (worse) complexity

Combinations of Algorithms

- Sometimes a given task can be made more efficient by doing another task first
 - Example: Sorting before searching
 - Searching on unsorted data: O(n)
 - Searching on sorted data: $O(\log(n))$, $\Omega(1)$
 - Sorting, comparison based: O(n*log(n))
- Previous example: multiple (linear) queries was O(q*n)
 - If we sort the data first: O(q*log(n) + n*log(n))
 - Is that worth it? O(n*log(n)) is worse than O(n)...
 - Is q > n? If so, $q*n > n^2 > n*log(n) => O(q*log(n))$
 - For large number of queries (q > n), sorting will improve the runtime

Time and Memory Interdependency

- Big O can be used to describe an algorithm's time complexity (how does runtime scale) and its memory complexity (how do memory needs scale)
- For some applications, we can trade time and memory complexity:
 - Faster algorithm, but more memory
 - Slower algorithm, but less memory
- We'd like both complexities to be small, but often one is more constraining
 - Examples: sparse matrices (prioritize memory), dynamic programming (prioritize time)

Big O and Architecture

Big O doesn't know about architecture

- It also doesn't know about the compiler and stack
- Recall: the amount of stack memory is "small"
 - But again, because the OS controls it, it doesn't need to be big to be robust
- Every time a function is called, memory gets allocated on the stack
 - That process takes time that has nothing to do with runtime
 - Function calls come with overhead costs

Function Overhead

- On the one hand: We love functions
 - Functions make code more readable, debuggable, maintainable, reusable
- On the other: Functions come with overhead due to stack allocation and initialization
 - This is felt with recursive functions and in parallel
- Readability/debuggability/maintainability, speed, and memory usage are all performance metrics
 - "High Performance" is relative to the resources you have
- There are two methods for improving function overhead when it is an issue

Improving Function Overhead

Method 1: Macros

```
#define cartesian2flat(i,j,n2) = i*n2 + j
```

Method 2: Inline functions

```
inline int cartesian2flat(int I, int j, int n2) {...}
```

- Both behave like functions but macros can have type issues as they are precompiler commands
- These are used for functions that are: 1) very simple, and
 2) called very often
- Example: indexing a mD array allocated as a 1D array

Next Up: Memory and architecture

Recursive Functions

```
Recursive Functions: A function that calls itself Example: a_n = 2*a_{n-1}, a_0 = 1 \Rightarrow a_n = 2^n
```

```
// This is a horrible excuse for recursion
void sequence(int n) {
    // Check if we're at the base case
    if( n == 0 )
        return 1;
    return(2*sequence(n-1));
}

// Better way for this example: iteratively
int result = 1;
for(i = 0; i < n; i++)
    result *= 2;</pre>
```

Recursion and Overhead

- Recursive functions are the typical culprits for stack overflow from a single program because they can be called many, many times (infinitely many if your base case is bad)
- This means they also incur greater overhead costs
- Mathematical recursion does not imply programmatic recursion
- Many mathematically recursive things can be programmed iteratively (i.e. with loops)
- Prefer iterative implementations to recursive ones
 - Sometimes recursion is the elegant solution! Use it then!

Performance

Program performance is dependent on several things

Performance depends on the quality of:

- Your resources=> Computing resources
- Your solution to the problem => Algorithm complexity
- Your utilization of your resources => Implementation details

HPC != Supercomputer * bad solution * bad implementation

HPC is about making the most of your computing resources, not having more resources

Performance Checklist

- Algorithm complexity: How do you choose/design an algorithm?
 - Priority: What constraints do you have on time and memory? Is one more important/tightly constrained than the other?
 - Parameters: Are there competing parameters (q vs n in the prev. example) that need to be balanced?
 - **Domain:** Are your datasets big enough to justify the up-front constants of your choice?
- Implementation details: How did you implement the algorithm?
 - Access patterns: Is/can your algorithm/code friendly to caching?
 - Function calls: Do you minimize excessive function overhead?
 - Efficiency: Can you consolidate memory and traversals?
 - Code quality: Is your code as friendly as is needed?

Next Up: Non-Communicating Parallelism

- This is the end of the Pre-Parallelism section of the course
 - We now have tools for/exposure to writing C++ code and evaluating a program's performance
 - HW1 will be posted tonight
- Next week: Non-communicating Parallelism (OpenMP)