# Contents

# 1 1. Abschnitt

Blabla filltext foobar [**?**]...

```
int voyager = 0;
```

**Listing 1: Python-Code**

```python
while True:
    if (sonic.getDistance() < 60):
        print "Proximity alert!"
        # act.sendCommand(act.STOP)
        # sleep(5)
        # act.sendCommand(act.FWD)
    else:
        command = cam.getCommand()
        # send to motor control
        message = act.sendCommand(command)
        if message == act.ERROR:
            # raise Exception('modAct returned ERROR')
            print ('modAct Error: ' + str(message))
            cam.cv.waitKey(0)
        # print ("Command received: " + outputCommand(command) + ' (Code: ' + str(command) + ')')
        outputVideo(command)
```
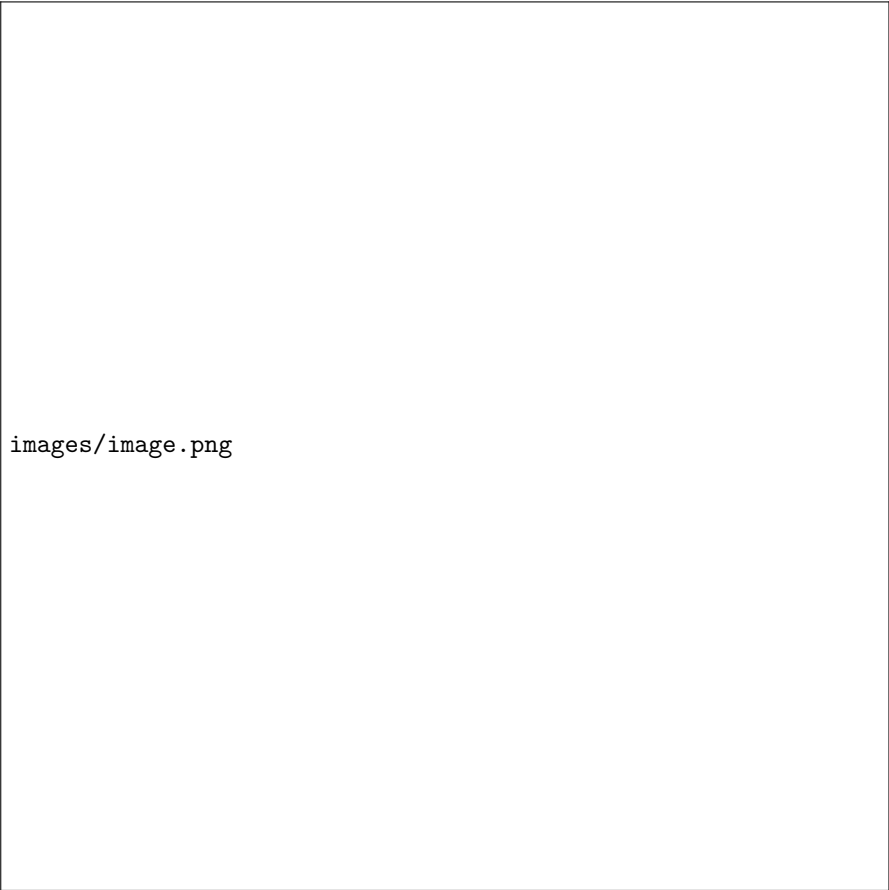
images/image.png

Figure 1: Text underneath the image

| a | b |
|---|---|
| 1 | 2 |

Table 1: Messergebnisse

- a) erstes Stichwort

- zweites Stichwort

## 2 2. Abschnitt

Blabla filltext ...