

Suppose we have access to:

$$\begin{array}{ccccccc} x_1 & \hookrightarrow & y_{11}, \dots, y_{1m}, & f(y_{11}), \dots, f(y_{1m}) \\ \vdots & & \vdots & \vdots & \vdots \\ x_T & \hookrightarrow & y_{T1}, \dots, y_{Tm}, & f(y_{T1}), \dots, f(y_{Tm}) \end{array}$$

& are interested in the integrals:

$$\int f(y) p(y | X = x_1) dy$$

\vdots

$$\int f(y) p(y | X = x_T) dy$$

Or even $\int f(y) p(y | X = x) dy$ for arbitrary x !
 These need to be estimated simultaneously.

Note that:

$$\int f(y) p(y | X=x^*) dy$$

$$= \int \langle f, k(\cdot, y) \rangle_{\mathcal{H}_y} p(y | X=x^*) dy$$

$$= \langle f, \underbrace{\int k(\cdot, y) p(y | X=x^*) dy}_{p_{Y|X=x^*}} \rangle_{\mathcal{H}_f}$$

A reasonable strategy would therefore be to

estimate $p_{Y|X=x^*}$ from

samples, then use the

approximation in the

inner product above

(i.e. doing quadrature

is equivalent to approximating
a kernel mean).

Note that our data is
exactly what is needed for
the empirical versions of
conditional kernel mean
embeddings.

We could even estimate
the integral for

$$x^* \notin \{x_1, \dots, x_T\}$$

which is pretty cool!



The main difference between the conditional embedding setting & the quadrature setting is that we observe function values exactly!

$$\hat{\mu}_g^n(x)^{(\cdot)} = k_x(x, x_{1:n})^T \left(k_x(x_{1:n}, x_{1:n})^{-1} + n\sigma^2 I_n \right)^{-1} k_y(\cdot, y_{1:n})$$

$$\begin{aligned} \bullet \quad \mathbb{E}_{y|X=x^*} [f(y)] \\ = \langle f, \hat{\mu}_g^n(x^*) \rangle \end{aligned}$$

• If we look at WCE over \mathcal{H}_y we only get a difference of conditional kernel mean

embeddings.

- Can use Arthur's paper to get notes in noisy setting?
- Functional GP regression! with the same kernel as they do vv -regression.
- posterior variance should be MCMD^2 evaluated at x^* !

$$\prod_{\text{CMC}}^{\wedge} [f]$$

$$:= \underbrace{k(x, x_{1:m})^T (k_{xx}(x_{1:m}, x_{1:m})^{-1} + n\lambda I_m)^{-1}}_{\text{MCMD}^2}$$

$$f(y_{1:n})$$

$$= \sum w_i f(y_i)$$

$$\mathcal{L}(F) = \frac{1}{n} \sum_{i=1}^n \|F(x_i)(\cdot) - \mu_q(x_i)(\cdot)\|_{\mathcal{H}_Y}$$

$$+ \lambda \|F\|_{\mathcal{H}_{YX}}$$

$$\tilde{\mathcal{L}}(F) = \frac{1}{n} \sum_{i=1}^n \|F(x_i)(\cdot) - K_Y(y_i, \cdot)\|_{\mathcal{H}_Y}$$

$$+ \lambda \|F\|_{\mathcal{H}_{YX}}$$

K_Y : Matern Gaussian
 $\uparrow \rightarrow$ Gaussian

$$\mu_q(x_i)(\cdot) = \int K_Y(\cdot, y) q(y | X=x_i) dy$$

$$\tilde{z} \rightarrow \sum_{i=1}^n w_i^{\text{BQ}} k_y(\cdot, y_i)$$

$$\tilde{\mathcal{L}}(F) = \frac{1}{n} \sum_{i=1}^n \|F(x_i)(\cdot) - \frac{1}{n} \sum_{j=1}^n k_y(y_j, \cdot)\|_{\mathcal{H}_y}$$

$$\hat{\Pi}_{\text{BQ}}[f] = \sum w_i^{\text{BQ}} f(x_i)$$

$$\int k(x, x_i) \pi(dx)$$