

# **HVDN Communicator**

Linux Distro Build Guide

Hudson Valley Digital Network

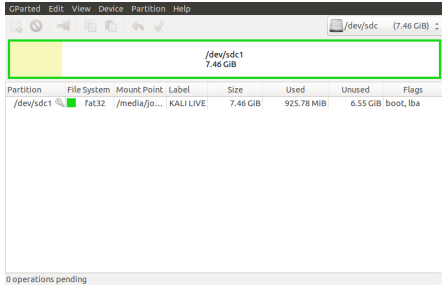
3 January 2020

v0.6

# Introduction

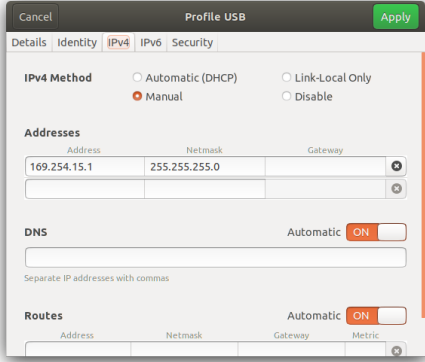
This is a guide on how to build the distribution image for the HVDN Communicator. All reference to “RPI” in this guide are an abbreviation for the Raspberry Pi Zero W hardware. The desktop operating system used in preparing the build is assumed to be a Debian or Debian derivative distribution. Ubuntu 18.04 was use din the preparation of this guide.

## Preparing Media

<ul style="list-style-type: none"><li>From your PC mount an 8GB SD Card</li><li>Run <b>sudo gparted</b> partitioning software</li><li>From <b>Gparted</b> menu select <b>Devices</b> and SD card inserted</li><li>Any existing partitions on the SD card right click and select <b>Delete</b></li><li>Right click on <b>unallocated</b>, select <b>new</b>, select <b>FAT32</b> as file system. Click <b>add</b></li><li>Click <b>check mark</b> to apply all operations</li><li>Note only up to 8GB of the SD Card will be formatted</li></ul>	 <pre>wget --max-redirect=3 https://downloads.raspberrypi.org/raspbian_lite_latest unzip raspbian_lite_latest sudo dd bs=4M if=2019-09-26-raspbian-buster-lite.img of=/dev/sdc conv=fsync</pre>
<ul style="list-style-type: none"><li>Download Raspbian and Extract from ZIP file</li><li>Install Raspbian on freshly formatted SD card</li></ul>	

## Connectivity

<b>Via connected keyboard, monitor and mouse</b>	
<ul style="list-style-type: none"><li>Change to your home directory, run <b>sync</b> as sudo, and unmount the SD card</li><li>Remove the SD card</li></ul>	<pre>cd ~ sudo sync umount /media/sd-card/root umount /media/sd-card/boot</pre>
<b>Via IP through Wireless Connection</b>	
<ul style="list-style-type: none"><li>You can use this method if you wish to access the RPi via an existing WiFi network</li><li>Change to the <b>boot</b> directory on the SD card</li><li>Enable <b>ssh</b> access by creating a blank file named <b>ssh</b></li></ul>	<pre>cd /media/sd-card/boot touch ssh</pre>
<ul style="list-style-type: none"><li>Within the boot directory, create a file called <b>wpa_supplicant.conf</b> and edit</li></ul>	<pre>vi wpa_supplicant.conf</pre>
<ul style="list-style-type: none"><li>When you have opened the new file, add the configuration at right and save</li><li>Be sure to replace <b>SSID</b> with your local wireless network SSID</li></ul>	<pre>country=US ctrl_interface=DIR=/var/run/wpa_supplicant GROUP=netdev update_config=1 network={     ssid="MyWiFiNetwork"     psk="aVeryStrongPassword"     key_mgmt=WPA-PSK }</pre>
<ul style="list-style-type: none"><li>Change to your home directory, run <b>sync</b> as sudo, and unmount the SD card</li><li>Remove the SD card</li></ul>	<pre>cd ~ sudo sync umount /media/sd-card/root umount /media/sd-card/boot</pre>

<p><b>Via IP through USB connection</b></p> <ul style="list-style-type: none"> <li>In this configuration you will be powering the RPi via the USB cable to your PC. Be sure to use the correct USB cable</li> <li>On your Linux host you need to add a USB Network Interface and a network with the Pi on the USB interface. Give it a static address (ie 169.254.15.1 )</li> </ul>	
<ul style="list-style-type: none"> <li>Change to the <b>boot</b> directory on the SD card</li> <li>Edit the <b>config.txt</b> file</li> </ul>	<pre>cd /media/sd-card/boot vi config.txt</pre> <p>Append the following line:</p> <pre>dtoverlay=dwc2</pre> <p>Then save the file.</p>
<ul style="list-style-type: none"> <li>While in the boot directory, edit the <b>cmdline.txt</b> file, replace a line, then save file.</li> </ul>	<pre>vi cmdline.txt</pre> <p>Replace with the following all as one continuous line:</p> <pre>dwc_otg.lpm_enable=0 console=serial0,115200 console=tty1 root=/dev/mmcblk0p2 rootfstype=ext4 elevator=deadline fsck.repair=yes rootwait modules-load=dwc2,g_ether quiet init=/usr/lib/raspi-config/init_resize.sh</pre> <p>Than save the file.</p>
<ul style="list-style-type: none"> <li>Remaining in the boot directory, enable <b>ssh</b> access by creating a blank file named <b>ssh</b></li> </ul>	<pre>touch ssh</pre>
<ul style="list-style-type: none"> <li>Change to the <b>rootfs</b> directory</li> <li>Edit the <b>interfaces</b> file</li> </ul>	<pre>cd /media/sd-card/rootfs/etc/network vi interfaces</pre> <p>Append the following lines:</p> <pre>allow-hotplug usb0 iface usb0 inet static     address 169.254.15.2     netmask 255.255.255.0     network 169.254.15.0     broadcast 169.254.15.255     gateway 169.254.15.1</pre> <p>Then save the file</p>
<ul style="list-style-type: none"> <li>Change to your home directory, run <b>sync</b> as <b>sudo</b>, and unmount the SD card</li> <li>Remove the SD card</li> </ul>	<pre>cd ~ sudo sync umount /media/sd-card/root umount /media/sd-card/boot</pre>

# Pi Setup

<ul style="list-style-type: none"><li>• Install Adafruit Radio Bonnet and Antenna</li><li>• Insert SD card</li><li>• Connect RPI and Power on</li><li>• Log in with default pi:raspberry</li></ul>	<p>If accessing via IP over USB, connect PC USB port to RPI USB Data port (next to mini-HDMI port)</p> <p>If connecting via SSH for first time click <b>yes</b> to <b>accept fingerprint</b></p>
<ul style="list-style-type: none"><li>• Run Configuration tool</li></ul>	<code>sudo raspi-config</code>
<ul style="list-style-type: none"><li>• Navigate through each menu making selections as noted then exit tool</li></ul>	<ol style="list-style-type: none"><li>1. Change User Password to <b>&lt;something&gt;</b></li><li>2. Network options N1 Change hostname to <b>your call + number [1-15]</b> <b>yourcall-5</b></li><li>3. Boot Options B1 Desktop/CLI choose <b>B1 Console</b></li><li>4. Localization I1 Change Local to <b>en_US.UTF-8</b> I2 Change Timezone</li><li>5. Interfacing options P2 <b>Enable SSH</b> P4 <b>Enable SPI</b> P5 <b>Enable I2C</b></li><li>7. Advanced Options A3 memory Split <b>Reduce GPU from 64 to 16</b></li><li>8. Update</li></ol>
<ul style="list-style-type: none"><li>• Run <b>sync</b> as sudo, and <b>reboot</b></li></ul>	<code>sudo sync</code> <code>sudo reboot</code>

# Install Packages, Libraries and Repository

## Packages

<ul style="list-style-type: none"><li>• Log back into the RPi.</li><li>• Ensure you are in the home directory</li><li>• Install the following packages<ul style="list-style-type: none"><li>◦ pip3 – Python Package Index</li><li>◦ Git – For cloning repositories</li></ul></li></ul>	<code>cd ~</code> <code>sudo apt-get install python3-pip</code> <code>sudo apt-get install git</code>
--	---

## Python Libraries

<ul style="list-style-type: none"><li>• Install the following Python libraries<ul style="list-style-type: none"><li>◦ Python Image Library</li><li>◦ APRS and APRSlib</li><li>◦ Adafruit Radio Bonnet Libraries</li></ul></li></ul>	<code>sudo apt-get install python3-pil</code> <code>sudo pip3 install aprs</code> <code>sudo pip3 install aprslib</code> <code>sudo pip3 install adafruit-circuitpython-rfm69</code> <code>sudo pip3 install adafruit-circuitpython-rfm9x</code> <code>sudo pip3 install adafruit-circuitpython-ssd1306</code> <code>sudo pip3 install adafruit-circuitpython-framebuf</code>
---	---

## HVDN Repository

<ul style="list-style-type: none"><li>• Ensure you are in the home directory</li><li>• Make two new directories called <b>hvdn-comm</b> and <b>hvdn-repo</b></li><li>• Change directory to hvdn-repo and clone the HASViolet repo from Github</li><li>• Copy the HASviolet stable directory to <b>hvdn-comm</b></li></ul>	<code>cd ~</code> <code>mkdir hvdn-comm</code> <code>mkdir hvdn-repo</code> <code>cd hvdn-repo</code> <code>git clone https://github.com/hudsonvalleydigitalnetwork/hasviolet.git</code> <code>cp /home/pi/hvdn-repo/hasviolet/stable /home/pi/hvdn-comm</code>
---	--

# Using HVDN Communicator

HVDN Communicator is data only currently designed to be used on local LoRa networks. It is installed in ***/home/pi/hvdn-comm***

HVDN Communicator is built with Python. Applications include;

- **hvdn\_lora-beacon.py** sends a repeating broadcast message
- **hvdn\_lora-chat.py** is a half-duplex messaging app
- **hvdn\_lora-tx.py** sends a message to another LoRa station
- **hvdn\_lora-rx.py** listens for messages from other LoRa stations

Three files dependend by all applications are;

- **hvdn-comm.ini** is a configuration file
- **rf95.py** is a Python Library for the HOPE RFM95 modules on the Raspberry Radio Bonnet
- **font5x8.bin** used by the OLED on the Adafruit Radio Bonnet

## hvdn\_lora-beacon.py

Beacon a LoRa message

Usage: hvdn\_lora-beacon.py -c COUNT -t DELAY "message"

### OPTIONS

- c Number of times to repeat MESSAGE
- t NUmber of seconds before repeat MESSAGE
- MESSAGE is message to be send within double quotes

## hvdn\_lora-chat.py

Half-duplex LoRa messaging app

Usage: ./hvdn\_lora-chat [-r] [-s]

### OPTIONS

- h, --help show this help message and exit
- r, --raw\_data Receive raw data
- s, --signal Signal Strength

- Starts and loops in Listening Mode
- CTRL-Z to send a message, CTRL-C to exit program
- When in send mode
  - Recipient is node id (255 = broadcast address)
  - Message is whatever message followed by enter
  - Message is sent, return to listening mode

## hvdn\_lora-tx.py

Send a LoRa message

Usage: hvdn\_lora-tx.py -d DESTINATION "message"

### OPTIONS

-d Destination ID

MESSAGE is message to be send within double quotes

## hvdn\_lora-rx.py

Listens for messages from other LoRa stations

Usage: ./hvdn\_lora-rx.py -r -s

### OPTIONS

-h, --help show this help message and exit

-r, --raw\_data Receive raw data

-s, --signal Signal Strength