Spike: Task 16

Title: Goal-Oriented Action Planning
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Goals / Deliverables

 Basic deliverable: a simulation for agent control demonstrating the effectiveness of goaloriented action planning in considering long-term outcomes (e.g. side-effects, time delays) of actions, and can plan and act intelligently.

Technologies, Tools, and Resources Used

- SublimeText (for editing, executing and testing the code)
- Learning materials on Canvas (for instructions and sample code)

Tasks Undertaken

- I started by copying the project from Task 15: Soldier on Patrol into the Task 16: Goal-Oriented Action Planning folder, stripping the spike report down to what was needed for this task.
- Next, I consulted my lecture notes and the task instructions document to plan out what I wanted to do for this task, as how students implemented goal-oriented action planning was left up to us. The planned goals I put together for this task were:
 - The agent will have to contend with hunger, which will be increased with each step it takes, and each shot it fires. When its hunger reaches a threshold, it must consider whether to continue its current actions, or return to the food station and eat if it would not compromise its current attack against the target. When its hunger reaches a high enough level that if it continued its current actions it would not have the stamina to return to a food station to reduce its hunger (based on the maximum possible distance between itself and the food station), it must return to the food station and eat.
 - The soldier has two weapons at a time, with a limited number of magazines. When patrolling, they must consider if their ammo remaining, between the two weapons, will theoretically be sufficient to reduce the target's HP to 0. If it is not, the agent must return to an ammunition station to get new weapons. When attacking, if the soldier runs out of ammo, they must return to the ammo station to exchange their weapons. The choice of weapons should be random, and all weapons, including the ones just handed back, will be available.
 - When aiming its shot, the agent will consider whether staying with its current weapon
 or its secondary weapon will be more conducive or sufficient in reducing the target's
 HP to 0, in terms of shot impact, speed, rounds per minute. For example, if the target
 has less than full health, the soldier shouldn't use two rifle rounds to take out the
 target if another weapon would also reduce the target's health to 0 in one shot.
- First, I took the code outlining what each weapon was, as well as the code for pooling projectiles, and created a weapon class that could hold the appropriate variables and be passed from world to soldier and back.
- Created points for ammo station and food station.

- Added logic for considering when to swap to the next weapon, and to go to the ammo station
 if attacking and out of ammo, or patrolling and ammo would be insufficient to kill the target
 when encountered.
- Added logic for handling explosive weapons, for not firing one if too close to the target, and for avoiding existing explosive projectiles so as not to get caught in the blast radius.
- Added logic for checking if the soldier will starve if they don't go and get food now, and for sending them to the food station to satiate its hunger.
- Looking at canvas instructions and instructions pdf again after the lecture and having done all this, not sure it meets the requirements for this task, so submitting a draft to get feedback and moving on to the next task in the meantime.

Instructions for Operating the Code

- A: toggle the display of agents' collision avoidance range.
- I: toggle the display of agents' force, velocity and net desired change in position.
- P: pause or un-pause the game.
- S: re-spawn a dead soldier.
- T: re-spawn a dead target.
- W: scroll through soldier weapons.
- Escape: exit the simulation.

Code Snippets

```
class Weapon (object):
    def __init__(self, world=None, owner=None, name='', cooldown=1, effective_range=100, damage=25, reload_time=1,
        self.world = world
        self.world = world
        self.cooldown = cooldown
        self.effective_range = effective_range
        self.speed = speed
        self.speed = speed
        self.damage = damage
        self.neload_time = reload_time
        self.reload_time = reload_time
        self.magazine_size = magazine_size
        self.magazines_left = magazines
        self.magazines_left = magazines
        self.accuracy_modifier = accuracy_modifier
        self.explosive = explosive
        self.explosive = explosive
        self.explosion_radius = explosion_radius

        self.projectile_pool = []
        i = 0

while i < 200:
        self.projectile_pool.append(Projectile(world=self.world, weapon=self))
        i += 1</pre>
```

```
def undate shocker(self, delta);
    self.see.target = False
    self.update_Tov(self.world.obstacles, self.world.agents)

if not self.hungry() and self.choose_weapon();
    if self.see.target or (self.world.target is not None and self.distance(self.world.target.pos) < self.hunt_dist + self.world.target.radius);
    self.movement_mode = 'Attack'
else:
    self.movement_mode = 'Patrol'

if self.weapons[0].rounds_left in magazine == 0 and (datetime.now() - self.last_shot).total_seconds() <= self.weapons[0].rounds_left.in magazine == 0;
    self.weapons[0].rounds_left.in magazine == 0;
    self.weapons[0].rounds_left.in magazine == 0;
    self.weapons[0].magazines_left == self.weapons[0].magazine_size
    self.weapons[0].magazines_left == 1

if (datetime.now() - self.last_shot).total_seconds() <= self.weapons[0].cooldown:
    self.combat_mode = "Attack":
    self.combat_mode = "Attack":
    self.combat_mode == 'Attack':
    self.combat_mode =
```

```
def calculate_shooter(self, delta):
    if self.movement_mode == 'Exchange Weapons':
        return self.arrive(self.world.ammo_station, 'slow')
    elif self.movement_mode == 'Get Food':
        return self.arrive(self.world.food_station, 'slow')
    elif self.movement_mode == 'Patrol':
        return self.follow_path()
    elif self.movement_mode == 'Attack':
        if self.world.obstacles_enabled:
            return self.hunt(self.world.target, delta)
        else:
            return self.seek(self.world.target.pos)

return Vector2D(0,0)
```

```
def hungry(self):
     if self.hunger >= 50:
          self.world.destroy_agent(self)
     if self.last_hunger_ping == None:
          self.last_hunger_ping = datetime.now()
     if (datetime.now() - self.last_hunger_ping).total_seconds() >= 1:
          self.last_hunger_ping = datetime.now()
          self.hunger += 1
     if self.movement mode == 'Get Food':
     return True
elif self.movement_mode == 'Patrol':
           \max_{i} \text{distance} = (\text{Vector2D}(\emptyset,\emptyset) - \text{Vector2D}(\textit{self}.\text{world.cx}, \textit{self}.\text{world.cy})). \\ \text{length}() \\ \max_{i} \text{time} = \max_{i} \text{distance} / \textit{self}.\text{max\_speed} 
          if (self.hunger + max_time) * 1.1 >= 50:
               self.movement mode = 'Get Food'
                return True
     elif self.movement_mode == 'Attack':
          current_distance = self.distance(self.world.food_station)
          current_time = current_distance / self.max_speed
          if (self.hunger + current_time) * 1.1 >= 50:
    self.movement_mode = 'Get Food'
```

In-Simulation Screenshots

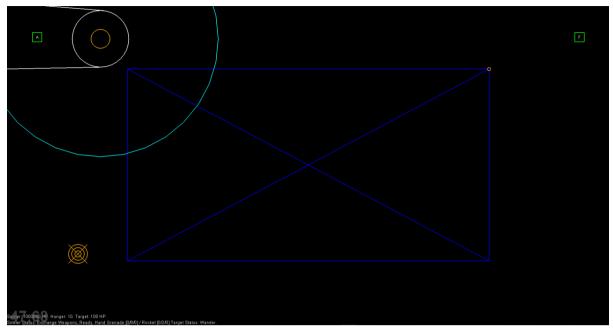


Figure 2: soldier agent is out of ammo and needs to swap its weapons.

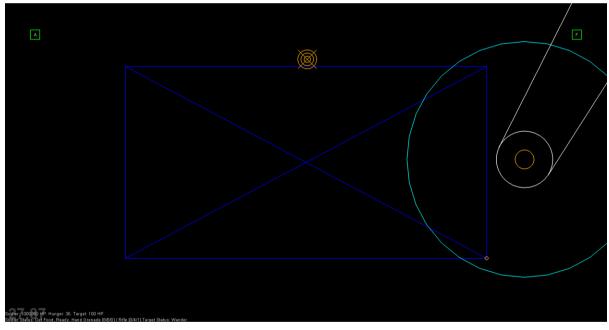


Figure 1: soldier agent is hungry and needs to eat.

What I Found Out

TBD