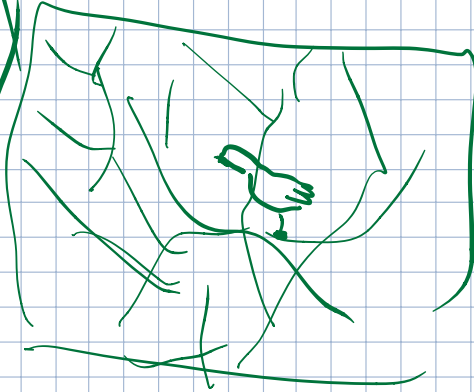
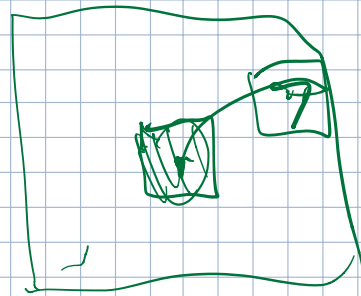
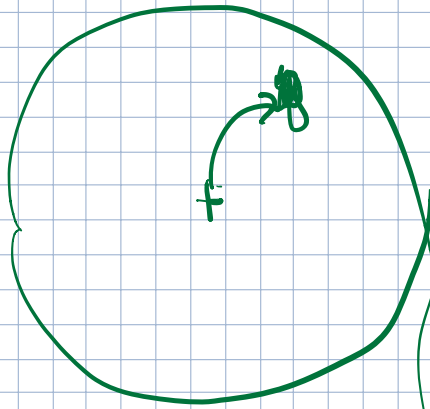
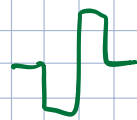
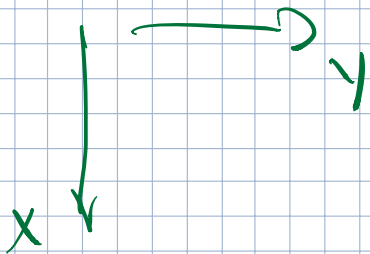


YOLO



$$M_c = \sum_{i=0}^p a_i \left(\psi_i + \delta_{x_i, y_i} \right)$$

$$\psi_i(\cdot - x_i, \cdot - y_i)$$



Planning ?

① : des SSH :

- python ch
- Motion Clouds
- Log Gabon

②

CHAMP

prise en main

③

CHAMP

extension binance

④

saccades

Where

OBV₁

⑤

stream

⑥

stream

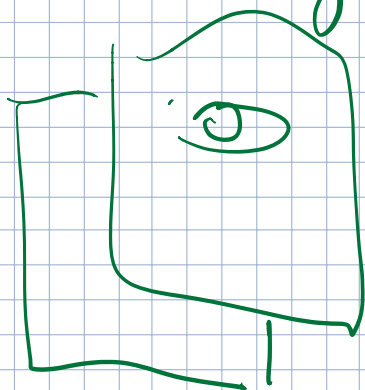
continuer

OBV₁

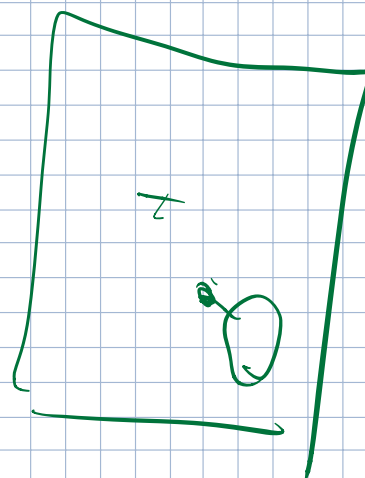
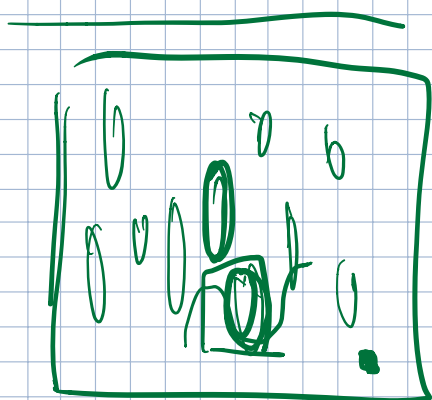
ψ

pip install git + <https://github.com/...>

Le Cheap Eye Tracker

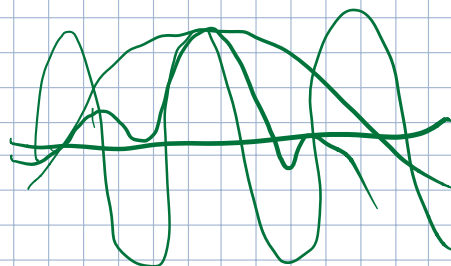
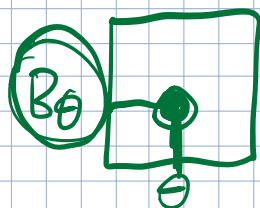
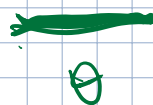
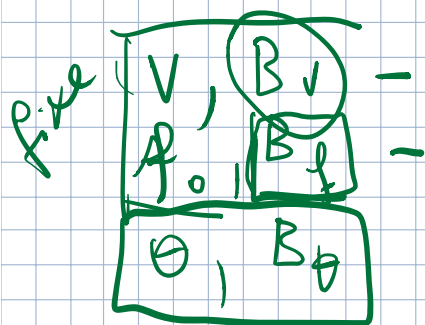


Motion Vectors



cycle / pixel

$$\frac{1}{20}$$



W_1

installer MC + gèneses B_0 / θ

- Log Gabon sur base
- copier collea depuis

• sachant θ, B_0 apprendre le réseau de classif
- avec les pixels

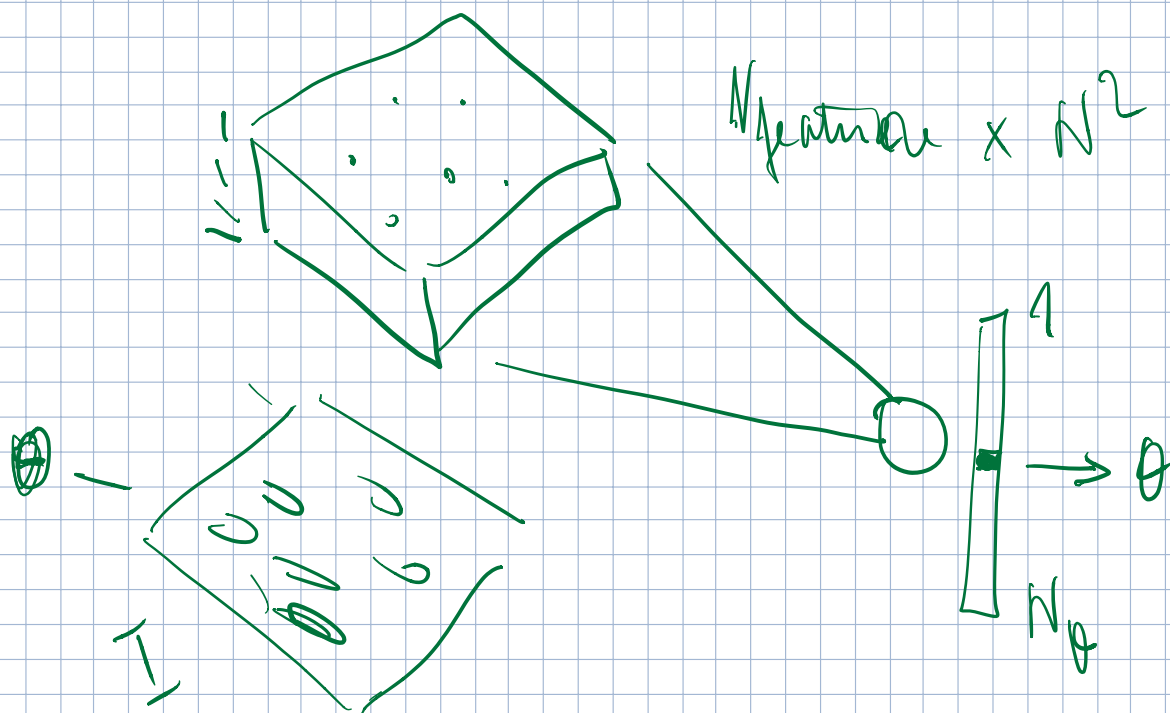


apprendre sur les voffs Log Gabon
- en connaissant les
paramètres f_0, B_f ~~et~~ B_0

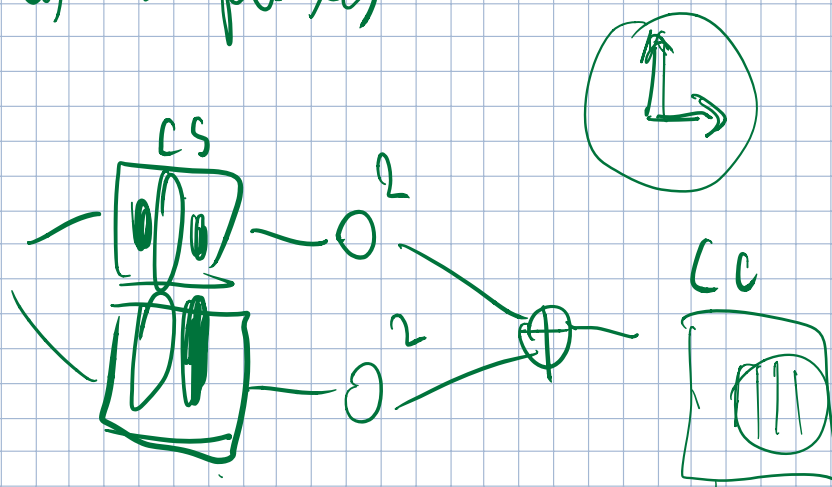
apprendre sans connaître B_0

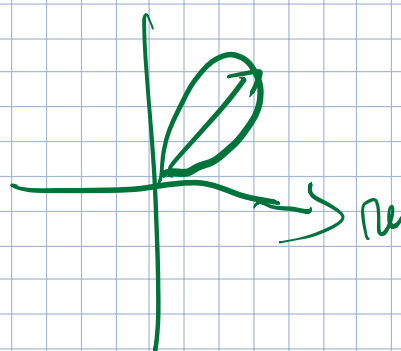
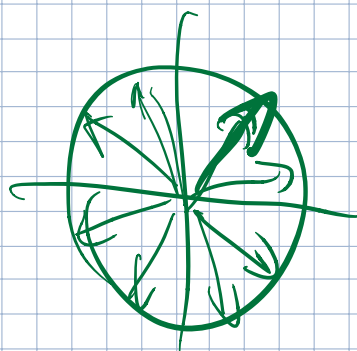
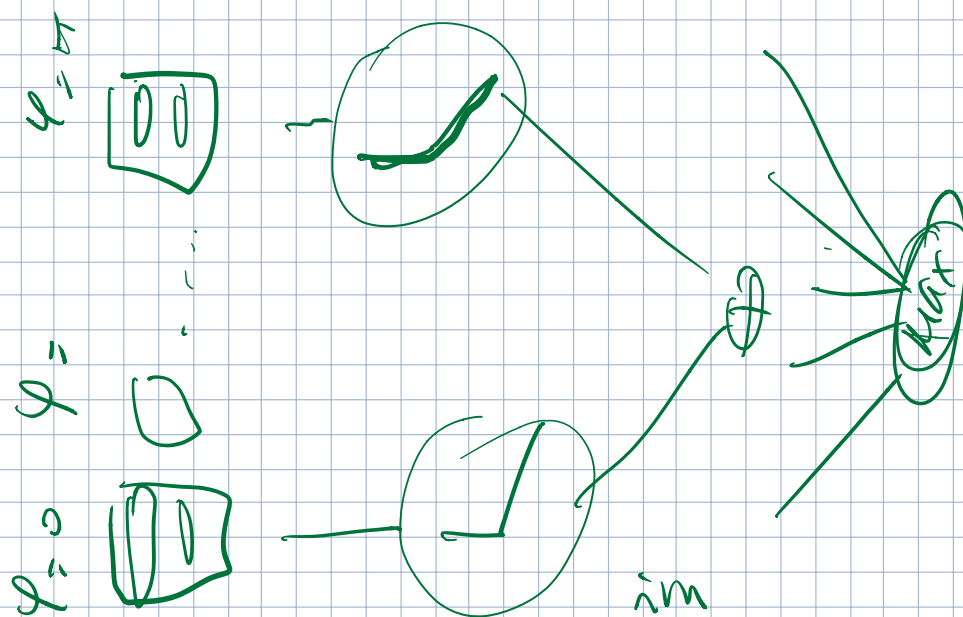
tester avec un B_f incorrect

Logistic Regression

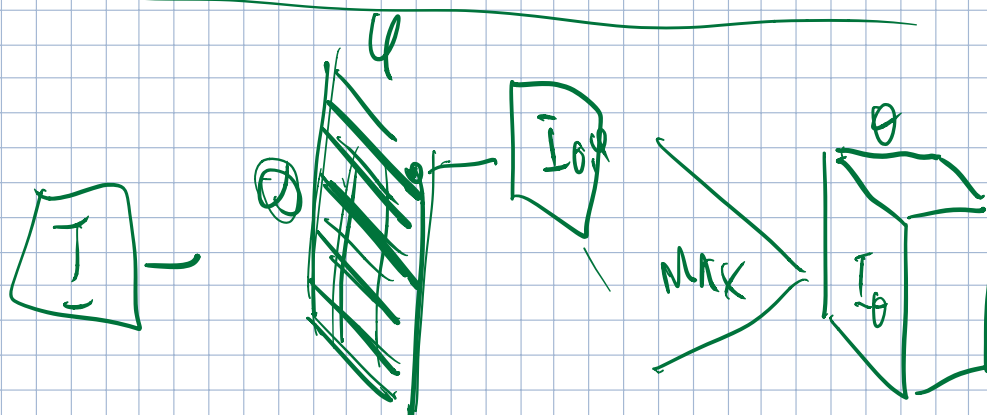


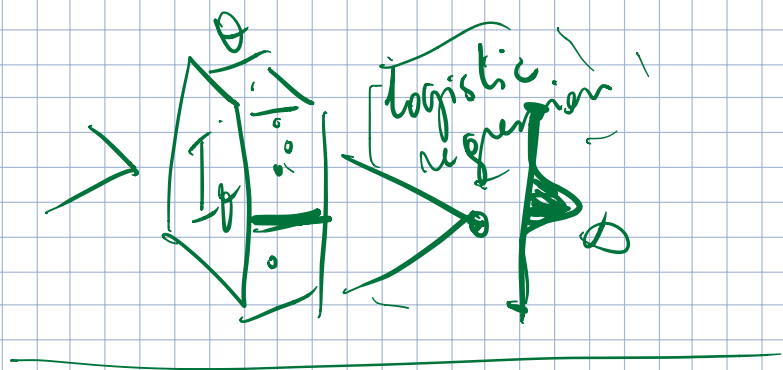
cellular complexes



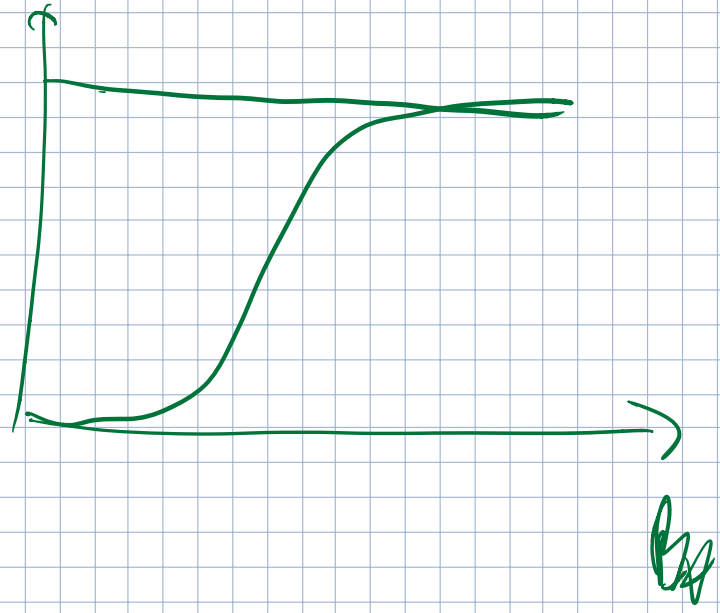


$$r^2 = x^2 + y^2$$

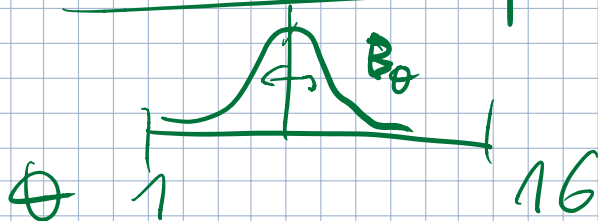




accuracy



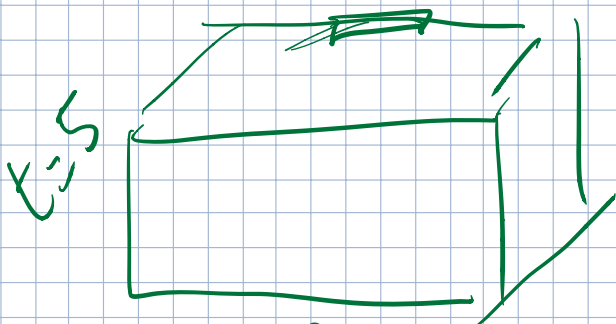
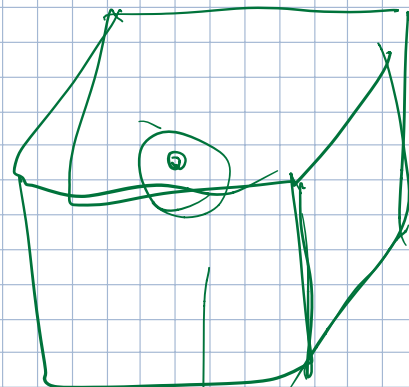
Time unwarping



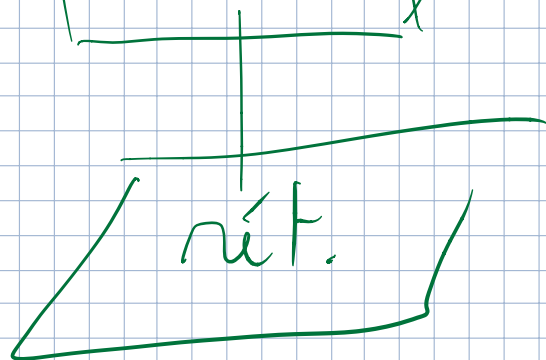
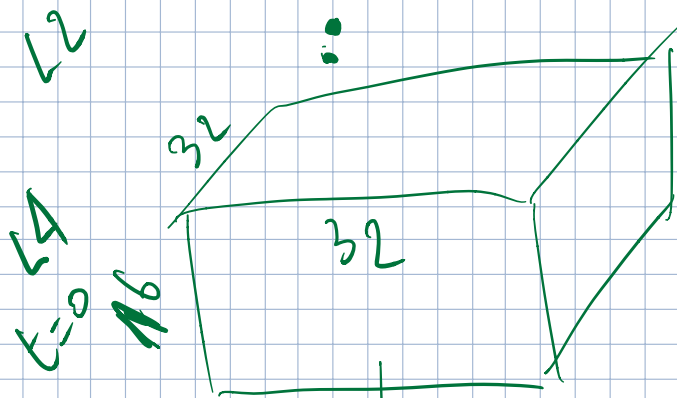
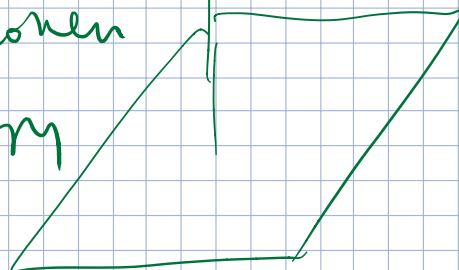
200

200

cross entropy



Kohonen
SOM



16

