

Taller 1: Problemas inversos

Y un poco de programación

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Gracias a mis colaboradores,
Romain Brossier, Ludovic Métivier

Gracias al IGP por recibirme

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- What is inversion? When do we meet this class of problem (inversion is everywhere in physical, sociological, health, ...)
- Provide recipes to solve linear inverse problems
- Give simple examples
- Two useful books on the subject, and main credits:
 - 1 Geophysical Data Analysis: Discrete Inverse Theory (Revised Edition) William Menke (1989), Academic Press
 - 2 Parameter Estimation and Inverse Problems (Second Edition) Richard C. Aster, Brian Borchers & Clifford H. Thurber (2013), Academic Press

Mathematical background

Inverse problem (and/or optimization) specific notions

The linear case

Mathematical background

Forward problem:

Model parameters \rightarrow Forward modeling \rightarrow Predicted data

Inverse problem:

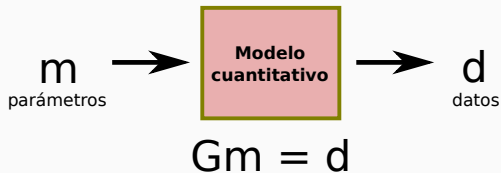
Observed data \rightarrow Inverse modeling \rightarrow Parameter estimation

We are interested in the relationships between physical (or chemical, economic, ...) model parameters m and a set of data d .

- We assume a good knowledge of the laws governing the investigated phenomena (underlying physics), in the form of a function G such that

$$d = G(m) \tag{1}$$

- In the mathematical model $d = G(m)$, the forward modeling operator G can be defined as
 - a linear or nonlinear system of algebraic equations
 - the solution of an ODE or PDE
- Forward problem: find d given m
- Inverse problem: find m given d_c
- Model identification problem: find G knowing some values of d and m



Modelo → línea recta

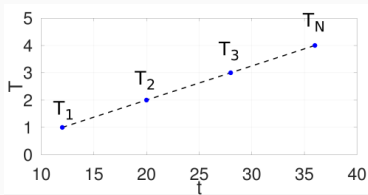
ejemplo:

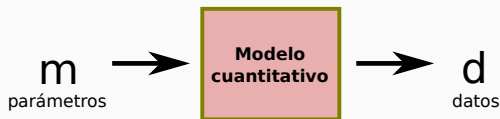
$$T_1 = a + bt_1$$

$$T_2 = a + bt_2$$

⋮

$$T_N = a + bt_N$$





$$Gm = d$$

Modelo \rightarrow línea recta

en algebra lineal:

ejemplo:

$$T_1 = a + bt_1$$

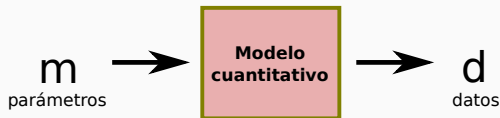
$$T_2 = a + bt_2$$

$$\vdots$$

$$T_N = a + bt_N$$

$$\begin{bmatrix} T_1 \\ T_2 \\ \vdots \\ T_N \end{bmatrix} = \begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_N \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\underline{d} = \underline{Gm}$$



$$Gm = d$$

Modelo \rightarrow línea recta

en algebra lineal:

ejemplo:

$$T_1 = a + bt_1$$

$$T_2 = a + bt_2$$

\vdots

$$T_N = a + bt_N$$

$$\begin{bmatrix} T_1 \\ T_2 \\ \vdots \\ T_N \end{bmatrix}_{[N \times 1]} = \begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_N \end{bmatrix}_{[N \times 2]} \begin{bmatrix} a \\ b \end{bmatrix}_{[2 \times 1]}$$

$$\underline{d} = \underline{\underline{G}}m$$

**Inverse problem (and/or
optimization) specific notions**

Why inverse problem are difficult?

- We are concerned with far more than just finding an acceptable model m_i that fits the data d_i , assuming a physical model G .
- There may be several acceptable solutions
- Essential issues are i) solution existence, ii) solution uniqueness and iii) instability of the solution process
- There may be no model that exactly fits the data
 - The model is wrong, or approximate
 - Data are noisy
- Rank deficiency in the model space; null space= a set of parameter combination that do not change the data:
$$d = G(m + \lambda * m_0)$$
$$\lambda = \text{model resolution analysis}$$
because the solution may be biased with respect to the reality
- ii) Several solutions can fit equally the same dataset:
in potential field, several density distribution produce the

The linear case
