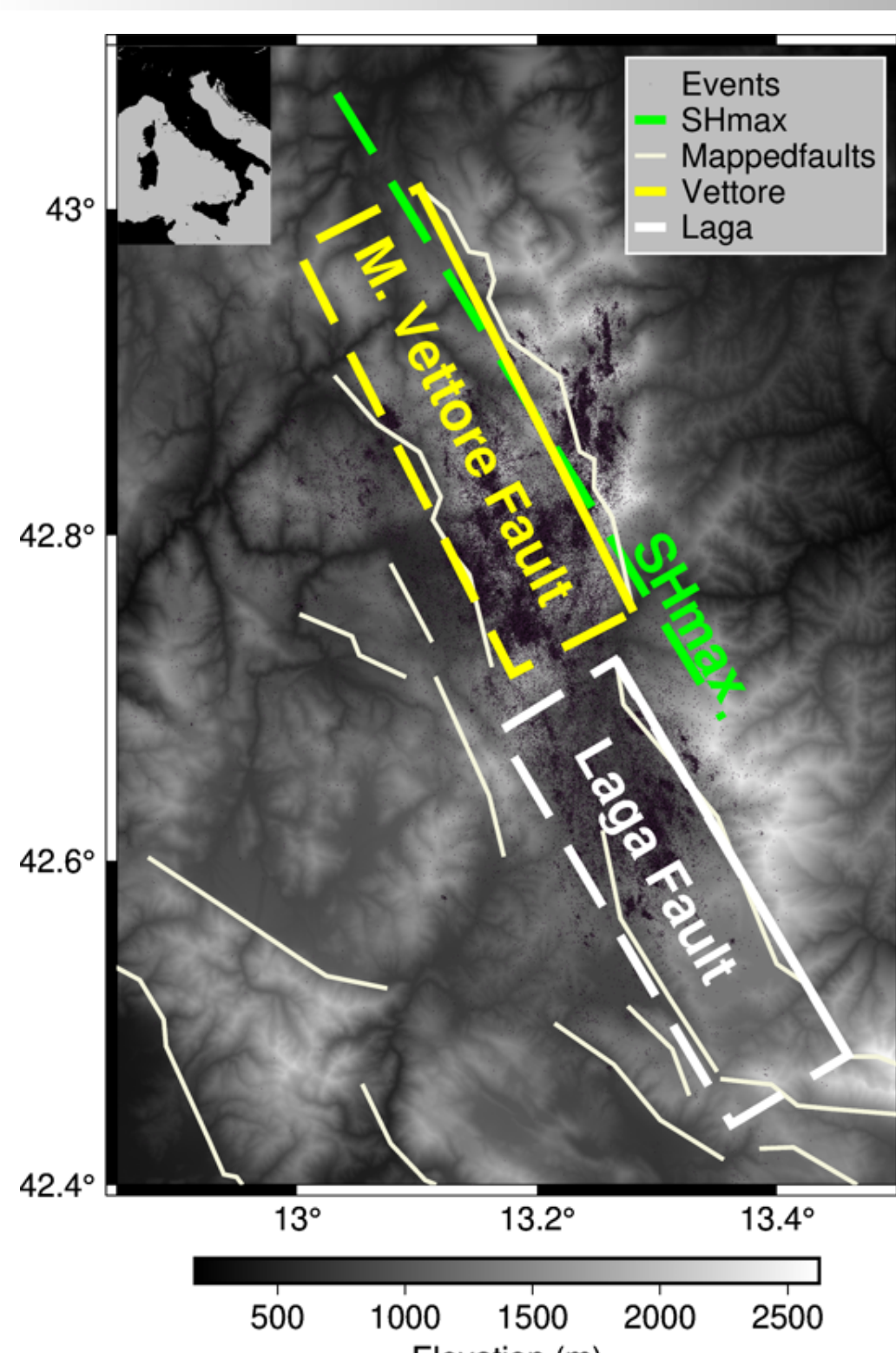


Exploring complex normal faulting systems through physics-based dynamic modeling.

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1. Introduction



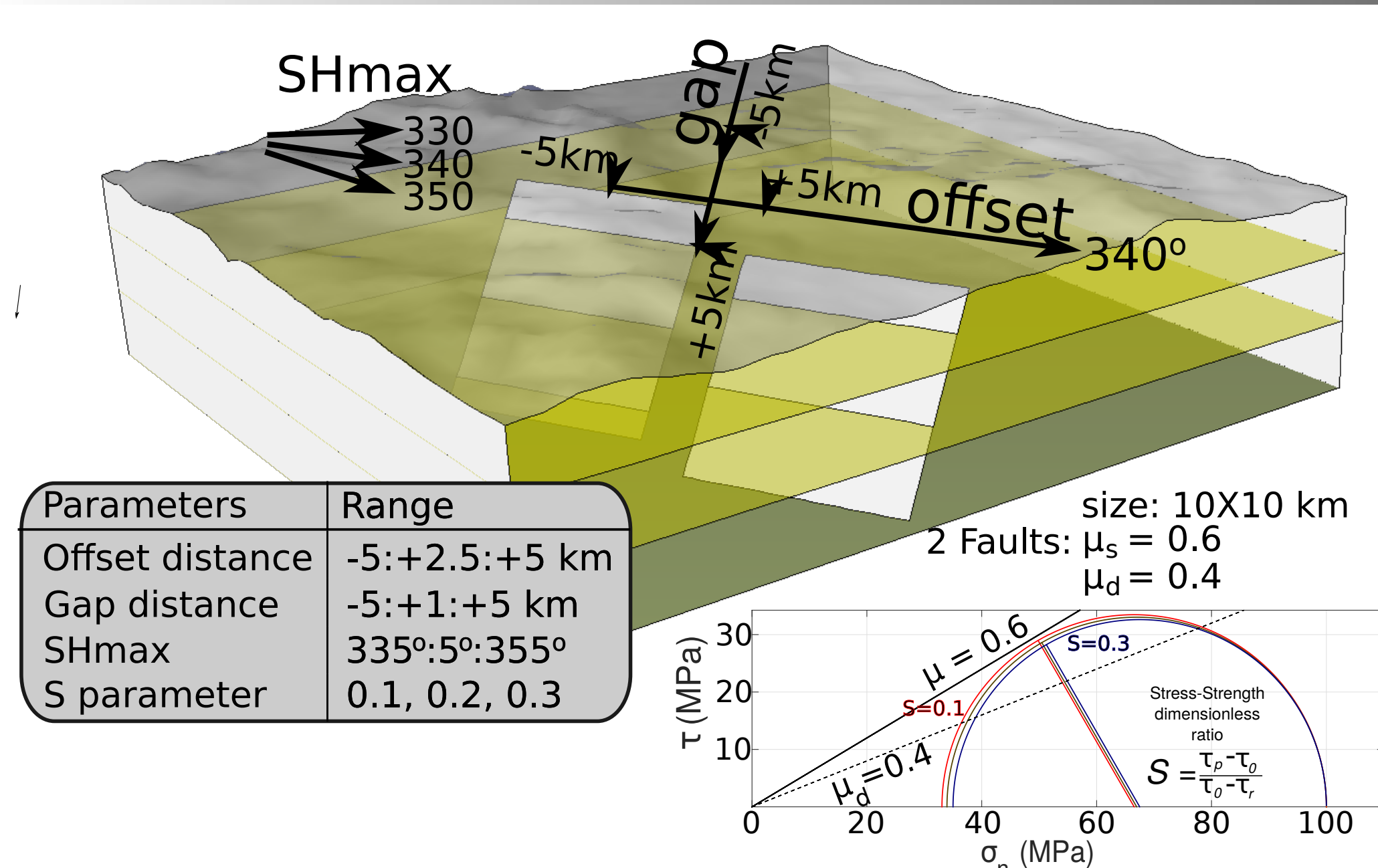
Geological context:

The Apennine seismic belt in Italy is an extensional province characterized by multi-fault normal-faulting seismic activity. Earthquakes and/or seismic sequences occurring across multi-fault segments during a single event (e.g. 1980 Ms 6.9 Irpinia Bernard & Zollo (1989)) or sequences spanning a period of days (e.g. 2009 Mw 6.1 L'Aquila Valoroso et al (2013)) to

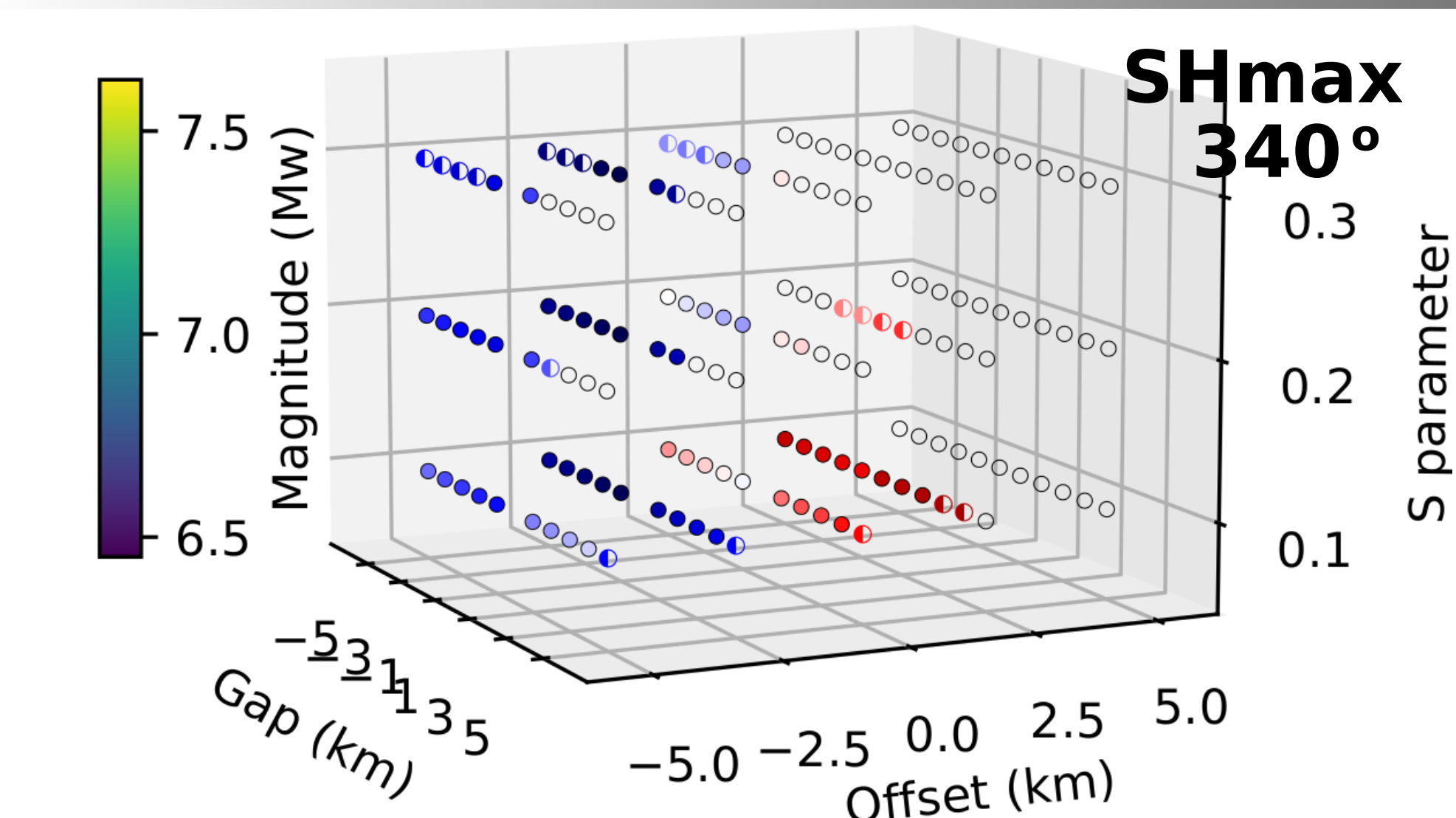
months (e.g. 2016 Amatrice-Visso-Norcia Improta et al. (2019)), are controlled by the physical complexities of the active normal fault system. Understanding rupture propagation across step-overs, breaking multiple fault segments during a single earthquake, is crucial to enhance the current SHA Bai and Ampuero (2017).

Goal: Explore dynamic rupture parameters to better understand the physical condition promoting rupture jumps in normal faulting systems

2. Geometry-Settings



3. Simulation-Results



156 Simulations using this configuration, S depends on the stress level, not on μ_s or μ_d . Some cases did not break both faults, mainly due to prestress state.

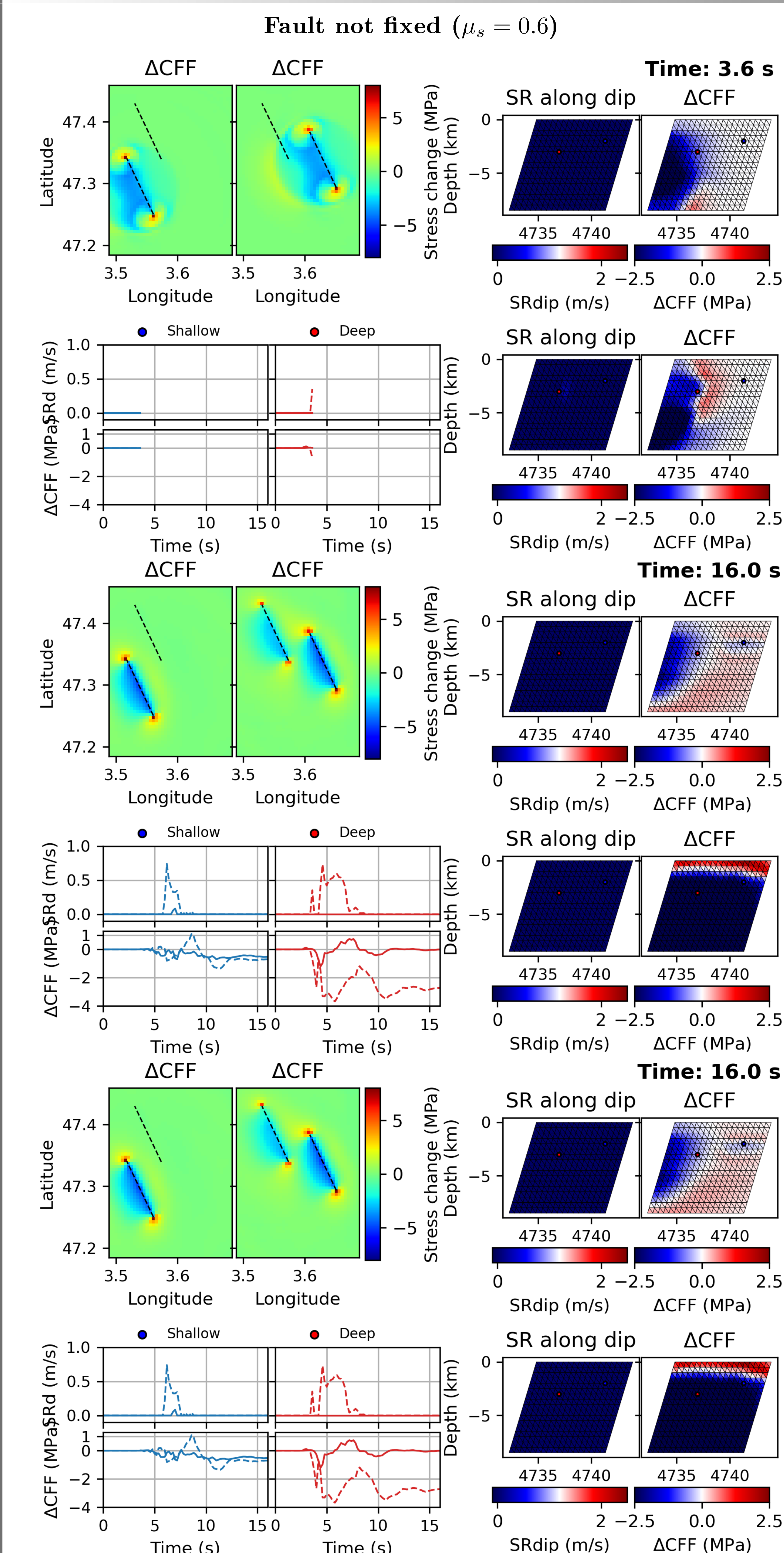
Hanging/foot wall asymmetry:

A small asymmetry regarding the triggering potential of the secondary fault related to its location with respect to the main fault (hanging or foot wall) is observed. When the secondary fault is on the hanging wall, the dynamically triggered rupture is more likely to be self-sustainable.

Stress shadow:

The final energy released (estimated magnitude) increases/decreases according to the distance between faults (i.e. offset and gap). Although the overlap increases the triggering effect, the stress shadow, due to the fault proximity, inhibits a large stress drop on the secondary fault.

4. Jump ? How ? When ? Why ?



5. Conclusion & Discussion

References

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