

CSSE2010/CSSE7201

Lecture 19

More I/O

School of Information Technology and Electrical Engineering
The University of Queensland

Today

- More I/O

- ✓ ■ I²C, TWI, SPI

- Synchronous Serial

- AVR I/O coding

- ✓ ■ Volatile variables

- Setting/clearing bits in I/O registers

UART
(USART)

Bus Masters and Slaves

- Master

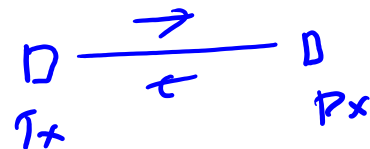
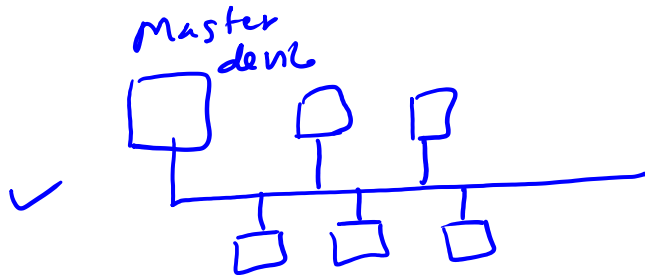
- ✓ ■ Device which initiates (and controls) the transfer of data

- Slave

- ✓ ■ Waits for requests
- Responds to master

- ✓ ● Some devices can be both masters and slaves (at different times)

- Memory can never be a bus master

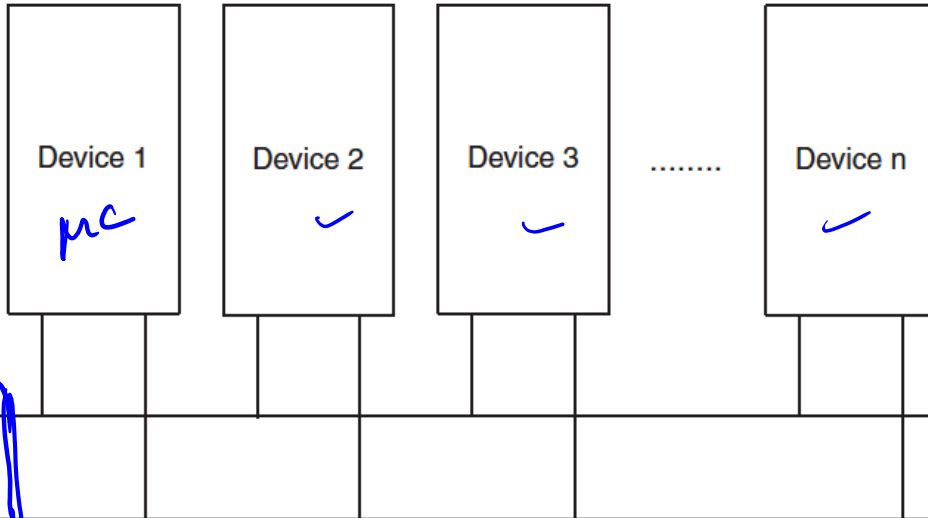


I²C, TWI

AVR
name

- I²C = Inter-Integrated Circuit
 - created by Philips Semiconductor (now NXP)
- TWI = Two-wire Interface
 - Name used by Atmel

up to
128 devices



101010

Serial comm.
Synchronous.

Common
BUS
line. TX

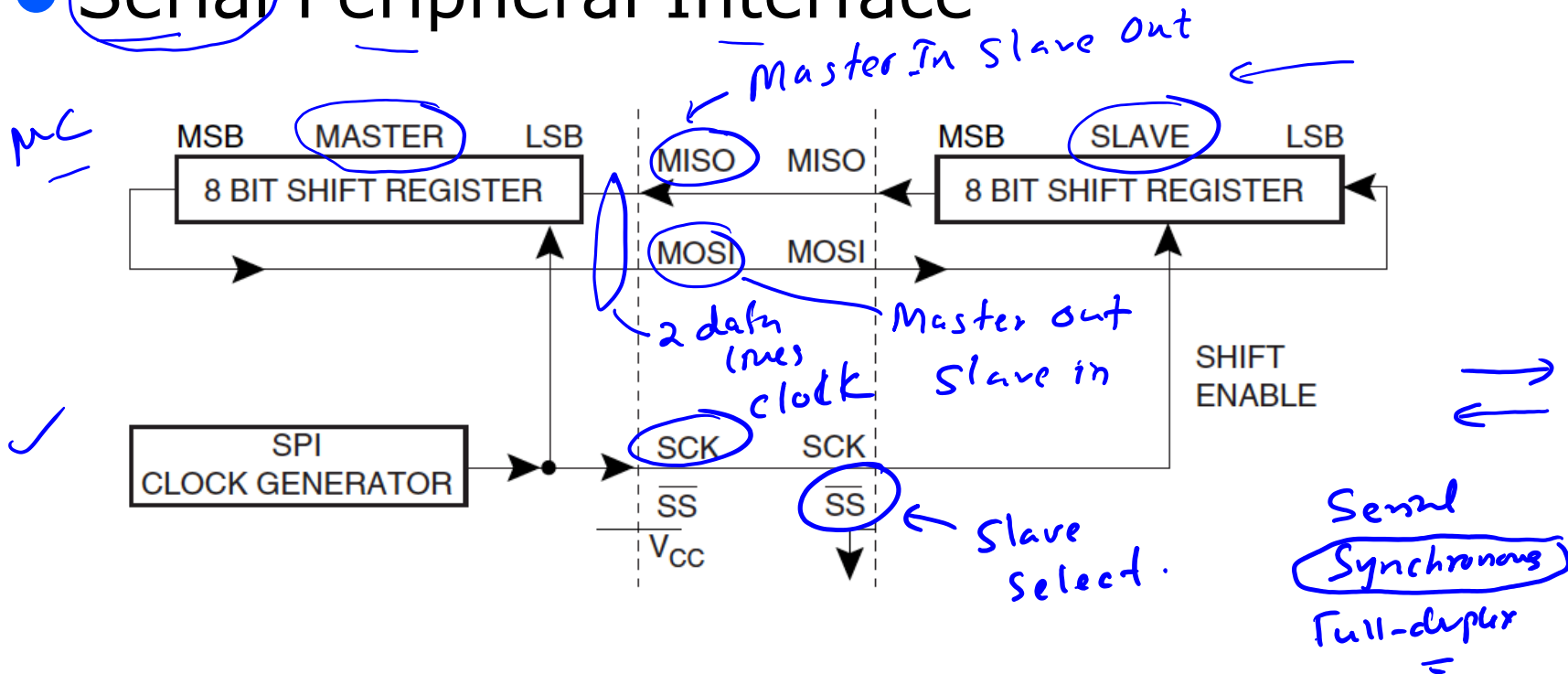
data Rx
clock.

TWI on AVR

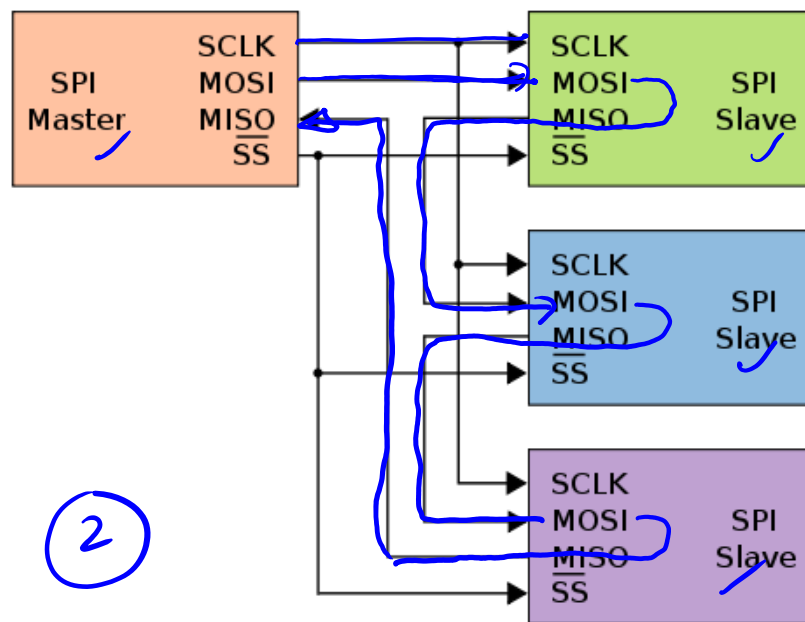
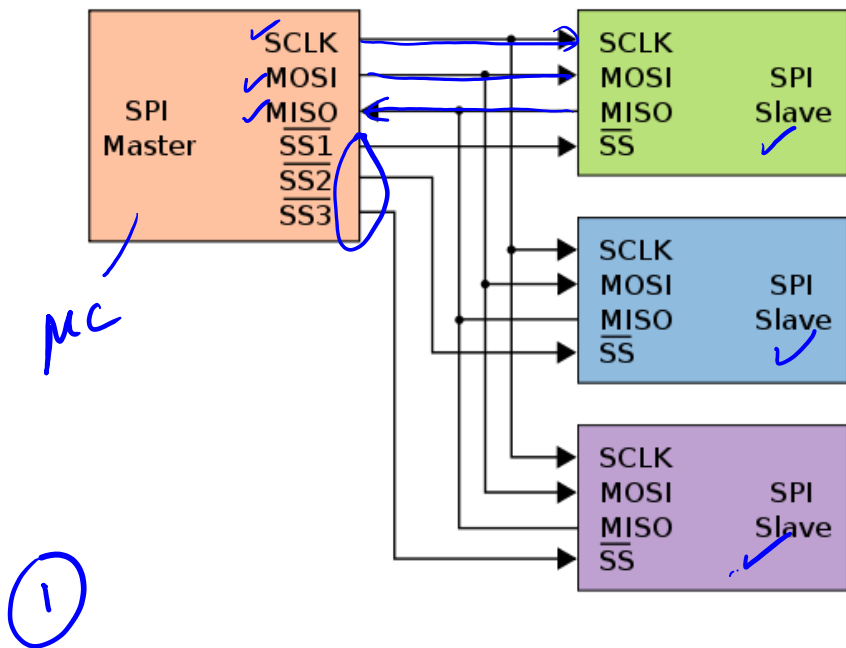
- ATmega324A has one TWI port
 - Alternate use for pins
 - C0 (SCL) ✓
 - C1 (SDA) ✓
- See datasheet pages 211 to 239 for details
 - Includes full description of TWI

SPI

Serial Peripheral Interface

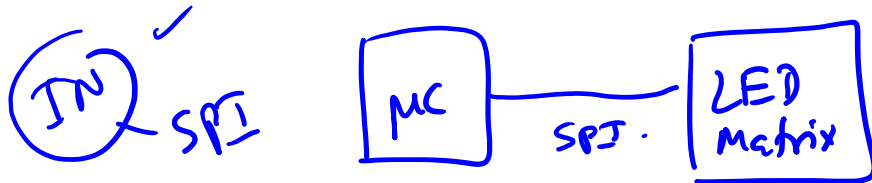


SPI – Other configurations



SPI on the AVR

- ATmega324A has one SPI port
 - ✓ ■ Shares pins with upper half of port B
 - ✓ ■ Hardware takes care of generating signals
 - Can be master or slave
 - See datasheet pages 166 to 174
 - ✓ ■ USARTs can also be used as SPI masters

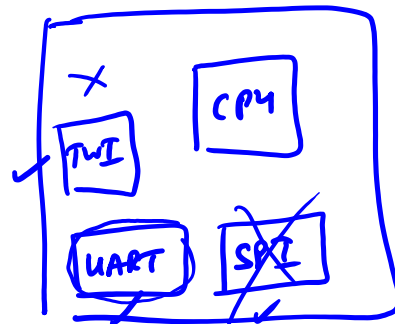
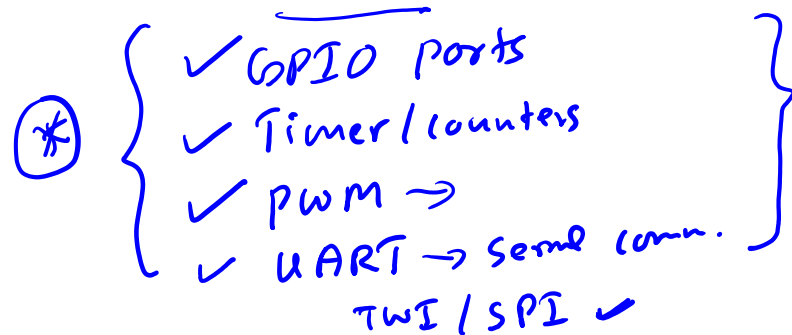


SPI on the AVR (cont.)

- For Master operation, can choose clock rate divider:
 - 2 (4MHz @ 8MHz clock)
 - 4 (2MHz)
 - 8 (1MHz)
 - 16 (500kHz)
 - 32 (250kHz)
 - 64 (125kHz)
 - 128 (62.5kHz)
- For slave operation, fastest clock is $f_{\text{osc}} / 4$ (2MHz in our case)

Bit Bashing

- Sometimes microcontroller doesn't have support for a bus standard
 - Or enough interfaces of a particular standard
- Can simulate I/O standards using general purpose ports



AVR I/O Coding

Volatile variables

- Example: `volatile int running;`
- Tells compiler that variable can change outside of standard flow of control
 - e.g. in interrupt handler or a thread
- Prevents compiler applying optimisations
- Example:



```

running = 0;
while(!running) {
    ; /* Do nothing */
}
    
```



Without volatile, optimising compiler will change this to

```

while(1) {
    ;
}
    
```

AVR I/O Coding

Setting I/O register bits

- When setting/clearing specific bits in I/O registers, be explicit about the bits

Example (all have the same effect):

LDI r16, 0x11
OUT PORTC, r16

- Poor:

TCCR1B = 10;

1000

10

- Better:

TCCR1B = 0x0A;

$1 \ll 3$

$1 \ll 1$

0b1010 = 10
↑
binary. ↑
ten

- Best:

TCCR1B = (1 << 3) | (1 << 1);

- Makes code easier to understand

PORTC = 0x11 ✓
R - M - W
↑ ↑ ↑
IN/LO out ST

Setting I/O register bits

- Where do names come from?
 - See datasheet (note errors – see IO register summary)
- e.g. for TCCR0B (page 112)

Bit	7	6	5	4	3	2	1	0
0x25 (0x45)	FOC0A	FOC0B	–	–	WGM02	CS02	CS01	CS00
Read/Write	W	W	R	R	R/W	R/W	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

- Bit names are defined as macros, e.g.
 - ✓ `#define WGM02 3`
- Can use same names in assembly language also, e.g.
 - `ldi r16, (1<<WGM02) | (1<<CS01)`

assembler converts this to a constant.

Clearing/Toggling I/O register bits

- Same rules apply

- To clear a bit, e.g.

PINC &= $\sim(1 \ll 5)$;

00010000
 $PINC = PINC \& (11101111)$
 ↑ bit mask

- To toggle a bit, e.g.

/* Enable Output Compare A Interrupt
 ** for timer 2 */

TIMSK2 $\hat{=}$ $(1 \ll OCIE2A)$;



$$\begin{aligned} x \oplus 0 &= x \\ x \oplus 1 &= \bar{x} \end{aligned}$$

