

CSSE2010/CSSE7201

Lecture 22

Memory & Disks

School of Information Technology and Electrical Engineering
The University of Queensland

Outline

- Admin
- Computer Memory
 - Different types of memory
 - Memory Hierarchy
- Disks

Admin

- Quiz 9 from last week: 336 attempts, average 3.9/5 and median 4/5.
- Quiz 10 (the last one) is due this week's Friday 22/10/21 4:00PM AEST
- Lab Assignment 2
 - There have been some corrections posted to the specification. Please take note.
 - More tutoring staff has been allocated for week 12 and 13 to give you extra help.

Reminder

- SECaT Course and Teaching Evaluation now open
 - There are **two surveys**: one is for the **course** and one is for **teaching**.
 - Surveys can be accessed at <https://eval.uq.edu.au>
 - Please take some time to provide feedback on how it all went for CSSE2010/7201 this semester
 - The surveys close on **11.59PM Friday 5th November** (revision week)

Computer Memory

- Computers need memory to
 - Store temporary results
 - Store programs
 - Remember settings when power off
- Many different types
 - Random access
 - Static vs. dynamic
 - Volatile vs. non-volatile
 - Read-only
 - Primary vs. secondary

Memory Types

- **Static** memory
 - Flip-flops or latches used to store bits
- **Dynamic** memory
 - Each cell is a switch (transistor) plus capacitor
- These are both types of **RAM** = **R**andom **A**ccess **M**emory
 - “RAM” originally meant could access any cell
 - (Compared with sequential access)
 - Now means volatile read/write memory
 - Static memory = **SRAM**
 - Dynamic memory = **DRAM**

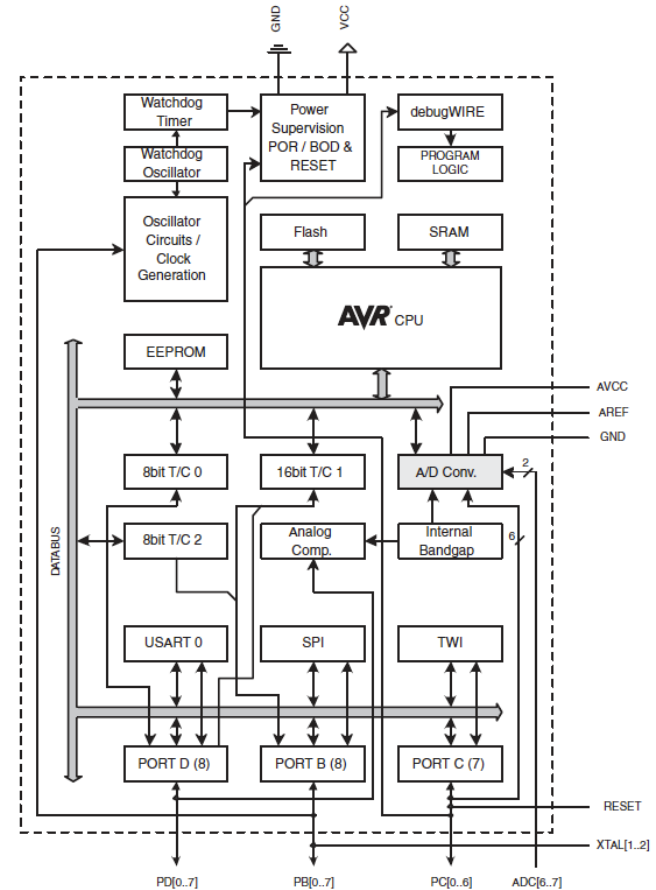
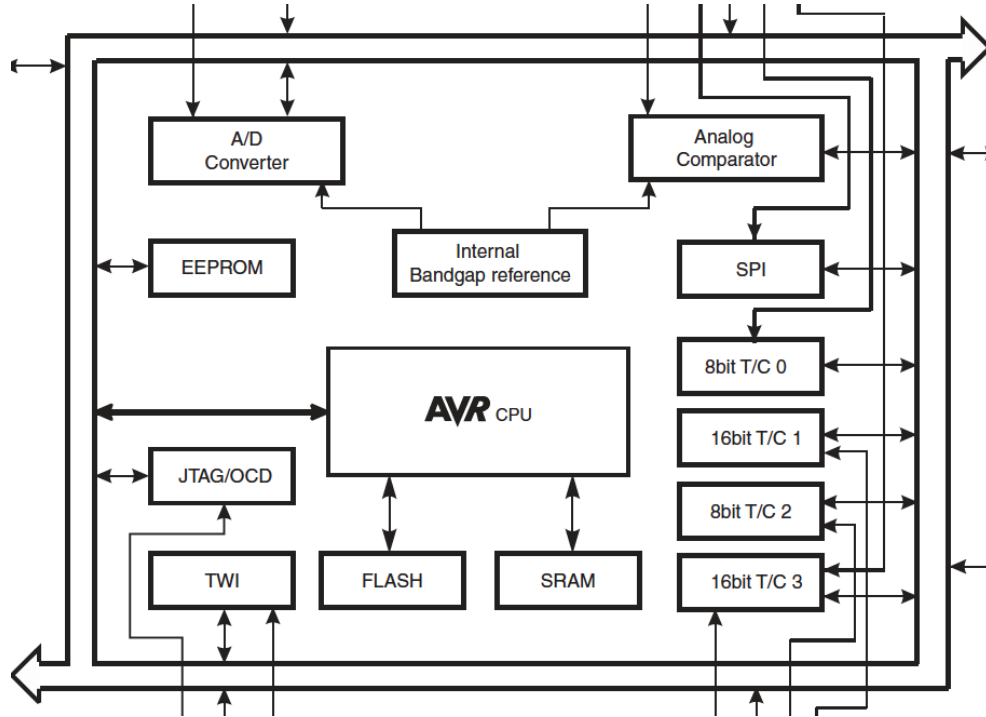
Volatility

- **Volatile** memory
 - Contents “forgotten” when power off
 - Both SRAM and DRAM are volatile
(DRAM forgets contents within milliseconds if not refreshed, i.e. contents rewritten)
- **Non-volatile** memory
 - Contents remembered when power off
 - Many types
 - ROM
 - EPROM
 - EEPROM
 - Flash

Non-volatile memory chips

- **ROM** = Read Only Memory
 - Programmed by memory manufacturer – contents hardwired in silicon
- **EPROM** = Erasable Programmable ROM
 - Can erase, e.g. with ultraviolet light
- **EEPROM** = Electrically Erasable PROM
 - Can erase by applying a certain voltage
- **Flash** = New EEPROM
 - (Used to be different technology to EEPROM but converging)
 - Main difference – Flash memory written/erased in blocks, EEPROM written/erased one cell at a time
 - ATmega324A supports two flash blocks – Application section + Boot Loader section
 - Other AVR devices have one, others have more

ATmega324A/328P Memory



When is a Megabyte not a Megabyte?

- When it's a million bytes
- Conventionally (or at least historically)
 $1 \text{ MB} = 2^{10}\text{kB} = 1,024\text{kB} = 2^{20} = 1,048,576\text{B}$
 - Sometimes, $1\text{MB} = 10^6\text{B} = 1,000,000\text{B}$
 - Or could be in between: $1000\text{kB} = 1,024,000\text{B}$
- Conventionally
 $1 \text{ GB} = 2^{10}\text{MB} = 2^{20}\text{kB} = 2^{30}\text{B}$
 $= 1,073,741,824\text{B}$
 - Sometimes, $1\text{GB} = 10^9\text{B} = 1,000,000,000\text{B}$
 - This is a 7.4% difference
 - Or could be in between: e.g. $1000 \times 2^{20} = 1,048,576,000$

When do we use powers of 2?

When do we use powers of 10?

- For **main memory** capacity, always based on powers of 2, e.g.
 - $1\text{GB} = 1024 \times 1024 \times 1024 \text{ bytes} = 2^{30} \text{ bytes}$
- For **hard disks**, manufacturers base sizes on powers of 10, e.g.
 - $1\text{GB} = 1000 \times 1000 \times 1000 \text{ bytes} = 10^9 \text{ bytes}$
 - (Makes hard disks seem bigger)
 - Operating Systems (e.g. Windows) base sizes on powers of 2
- For **data speeds (transfer rates)**, usually based on powers of 10, e.g.
 - $1\text{Gbps (gigabit per second)} = 10^9 \text{ bits per second}$
- Occasionally, a mixture
 - $1.44\text{MB floppy disk stores } 1.44 \times 1000 \times 1024 \text{ bytes}$

Kibibytes, Mebibytes

- Kilo-, mega-, giga- prefixes mean powers of 10 in SI units
- To avoid confusion, standardised terms have been created for binary prefixes, e.g.
 - 1 **kibibyte** = 1KiB = 1024 bytes
 - 1 **mebibyte** = 1MiB = 1024KiB
 - 1 **gibibyte** = 1GiB = 1024MiB
- Unfortunately, very few people use them
- We'll use kilo-, mega-, giga- etc. but meaning could vary depending on context

Types of DRAM

- Bits stored as charge on capacitor, not in flip-flops
- Cells are smaller, so can pack more bits on a chip than for static memory
- Slower than static memory
- Many different types of DRAM over the ages...
 - Fast Page Mode (FPM DRAM)
 - Extended Data Out (EDO DRAM)
 - Synchronous DRAM (SDRAM)
 - Rambus DRAM (RDRAM)
 - Double Data Rate DRAM (DDR DRAM) 1, 2, 3 and 4

What is the approximate cost per Gigabyte of DRAM?

13% **A.** \$0.01

13% **B.** \$0.10

13% **C.** \$1.00

13% **D.** \$10.00

13% **E.** \$100.00

13% **F.** \$1,000.00

13% **G.** \$10,000.00

13% **H.** \$100,000.00

What is the approximate cost per Gigabyte of Flash memory?

- 0% **A.** \$0.01
- 0% **B.** \$0.10
- 0% **C.** \$1.00
- 0% **D.** \$10.00
- 0% **E.** \$100.00
- 0% **F.** \$1,000.00
- 0% **G.** \$10,000.00
- 0% **H.** \$100,000.00

What is the approximate cost per Gigabyte of Hard Disk Storage?

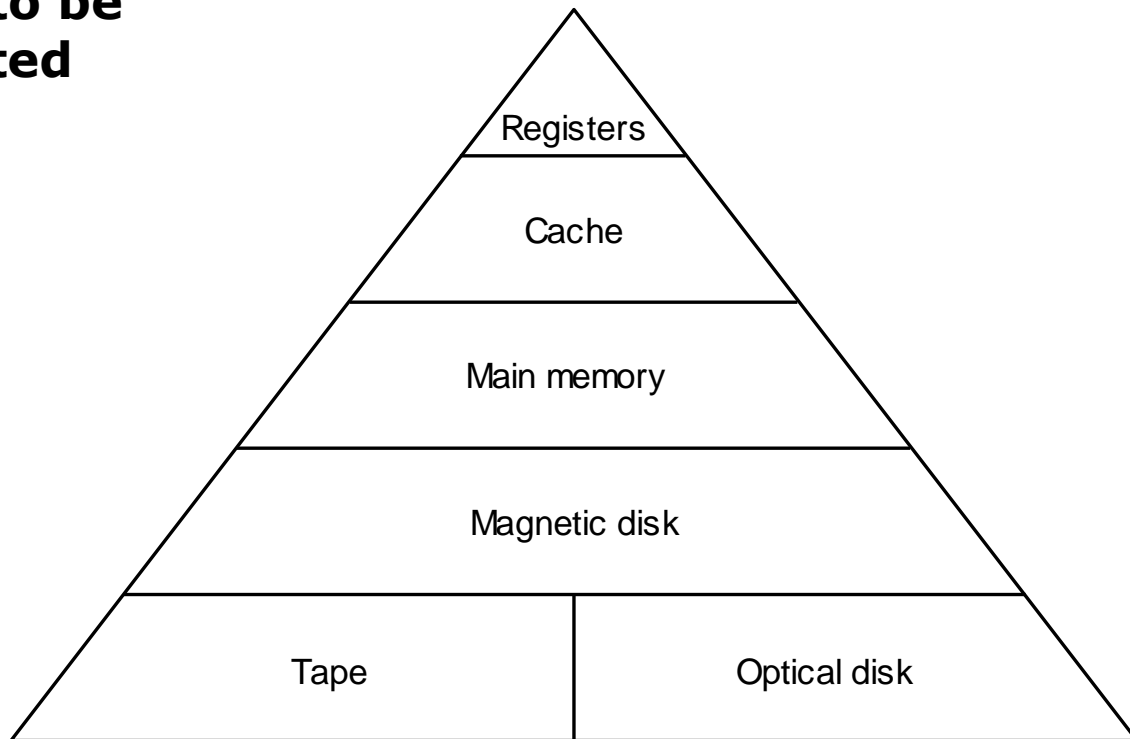
- 0% **A.** \$0.01
- 0% **B.** \$0.10
- 0% **C.** \$1.00
- 0% **D.** \$10.00
- 0% **E.** \$100.00
- 0% **F.** \$1,000.00
- 0% **G.** \$10,000.00
- 0% **H.** \$100,000.00

What is the approximate cost per Gigabyte of SRAM?

- 0% **A.** \$0.01
- 0% **B.** \$0.10
- 0% **C.** \$1.00
- 0% **D.** \$10.00
- 0% **E.** \$100.00
- 0% **F.** \$1,000.00
- 0% **G.** \$10,000.00
- 0% **H.** \$100,000.00

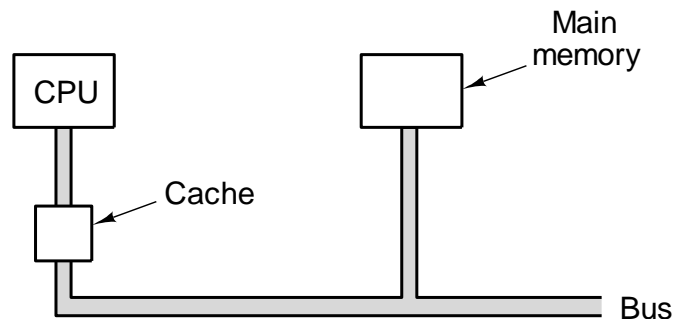
Memory Hierarchy

**Figure to be
annotated
in class**



Cache Memory

- CPUs are faster than main memory
 - Very fast memory is expensive
- Performance suffers if CPU always waiting for memory
- **Cache**
 - Small amount of very fast memory combined with larger slow memory
 - Most commonly used memory words kept in cache
- CPU looks in cache before main memory
- Average access time greatly reduced if many words are in the cache



Cache Levels

- Often multiple levels of cache
- **Level 1 (L1)**
 - Inside CPU itself
 - e.g. 32kB to 128kB
 - Runs at same speed as CPU
- **Level 2 (L2)**
 - May be separate chip (possibly inside same module) or on same chip as CPU
 - e.g. 256kB to 16MB
 - May be slightly slower than CPU
- **Level 3 (L3)**
 - Some machines have a third level (e.g. 2MB to 256MB)

Note:
B = byte
b = bit

“Cache” for Disks

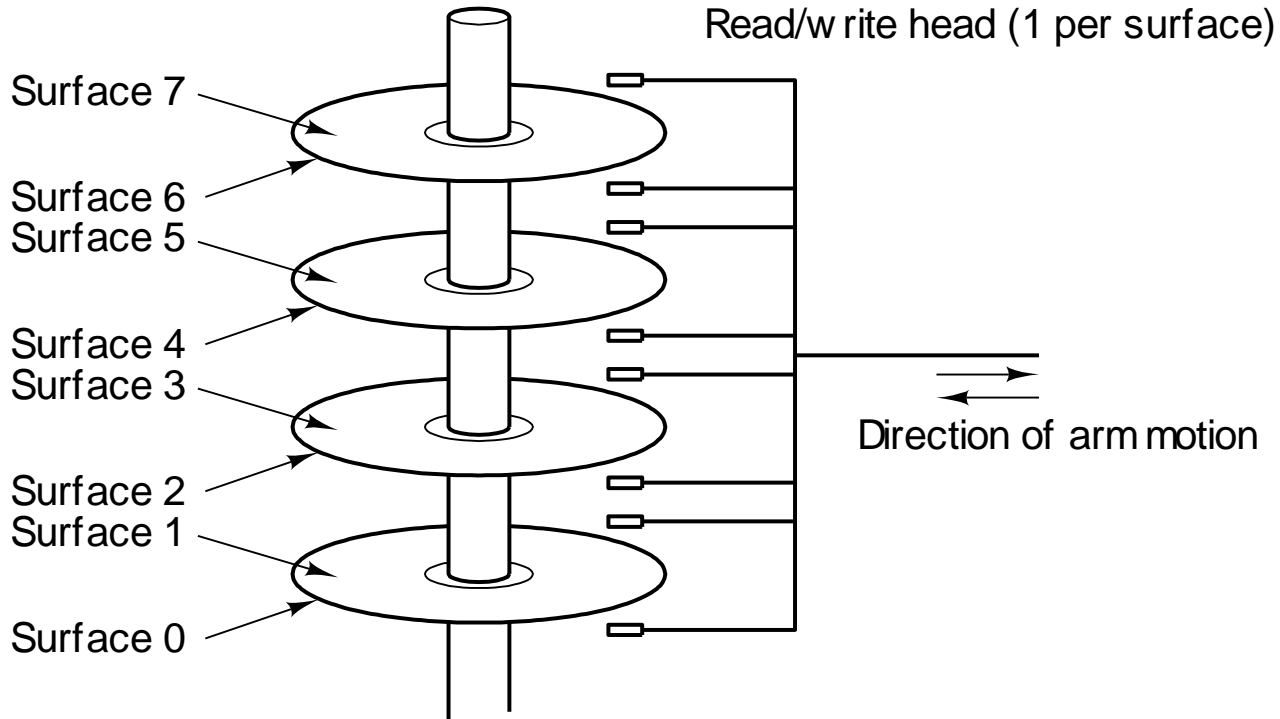
- Increasingly common
- Small fast solid state drive (Flash memory) caches content from larger slower magnetic disk

Magnetic Disks

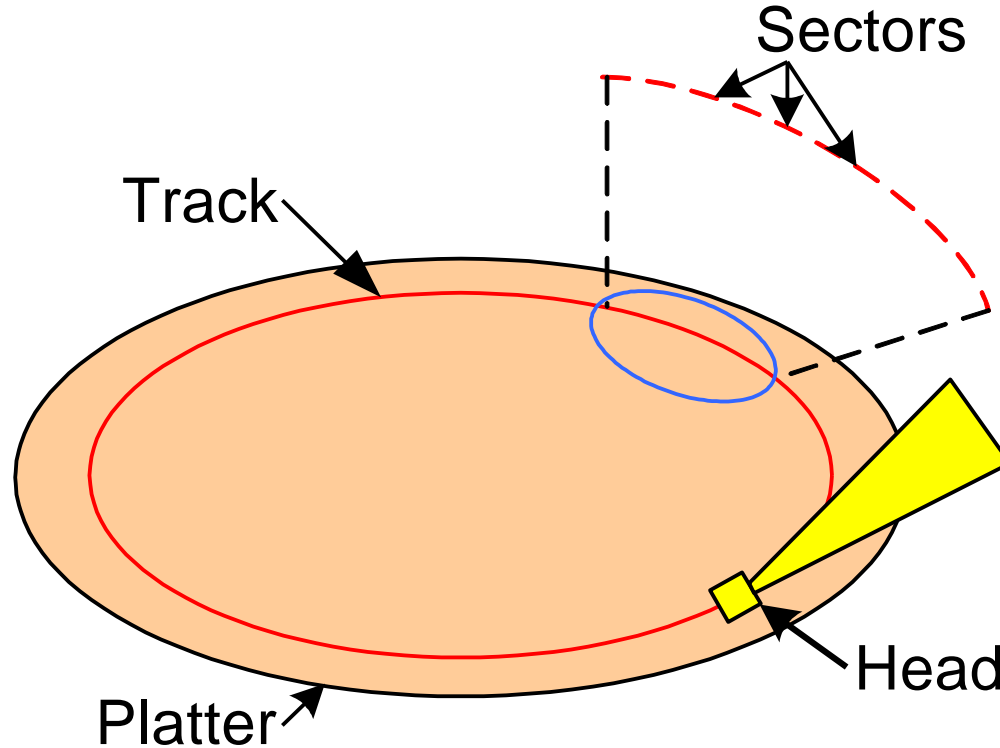
- Rotating **platters** with magnetised coating
 - Stack of platters
- Data stored magnetically in circular **tracks**
- Read/write **heads** float above platter surfaces
- Usually use both sides of platters



Magnetic Disks – Simplified view

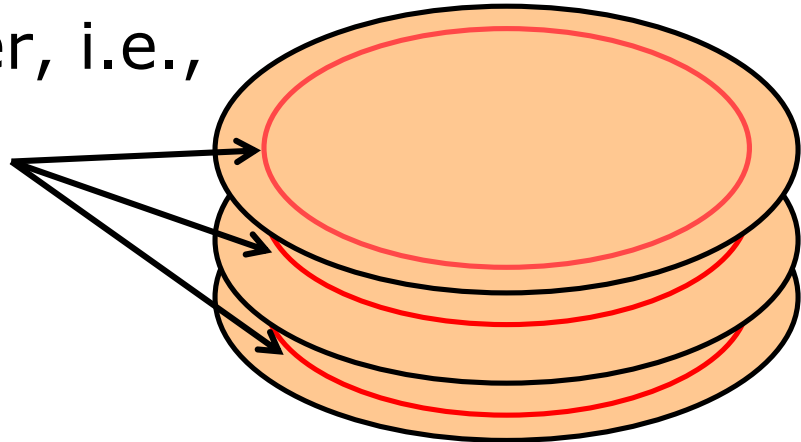


Sectors and Tracks



Cylinders

- Set of tracks at a given radial position
- Number of tracks in cylinder =
2 x number of platters
(assuming both sides of all platters used)
- Heads move together, i.e.,
to a certain cylinder



Sectors

- Tracks divided into fixed-length sectors
 - Smallest data unit, i.e. must read/write a whole sector at a time
- Sector consists of:
 - Preamble
 - Allows head to synchronise to data
 - Data
 - Error correction codes (ECCs)
 - Inter-sector gap
- About 85% of disk capacity usable by operating system
 - About 95% of this usable for user data
 - Remaining ~5% file system overhead

Access Time

- **Access time** =
seek time +
rotational latency +
transfer time
- **Seek time**
 - Time to move heads to right cylinder
- **Rotational latency**
 - Time to wait for sector to arrive under head
- **Transfer time**
 - Time for sector to pass under head
 - Negligible compared with above

Calculating Access Time

- Example:
What's the *average* access time for a hard disk which rotates at 7200rpm and has an edge-to-edge seek time of 10ms? (Assume that seek time is proportional to the number of tracks to seek.)