

### CSSE2010/CSSE7201 Lecture 22

## Memory & Disks

School of Information Technology and Electrical Engineering
The University of Queensland



### **Outline**

- Admin
- Computer Memory
  - Different types of memory
  - Memory Hierarchy
- Disks



### **Admin**

- Quiz 9 from last week: 336 attempts, average 3.9/5 and median 4/5.
- Quiz 10 (the last one) is due this week's Friday 22/10/21 4:00PM AEST
- Łab Assignment 2
  - There have been some corrections posted to the specification. Please take note.
  - More tutoring staff has been allocated for week 12 and 13 to give you extra help.



### Reminder

- SECaT Course and Teaching Evaluation now open
  - There are two surveys: one is for the course and one is for teaching.
  - Surveys can be accessed at https://eval.uq.edu.au
  - Please take some time to provide feedback on how it all went for CSSE2010/7201 this semester
  - The surveys close on 11.59PM Friday 5<sup>th</sup> November (revision week)



## **Computer Memory**

- Computers need memory to
  Store temporary results

  - Store programs
  - Remember settings when power off
- Many different types

  Random access

  - Static vs. dynamic
  - ✓ Volatile vs. non-volatile
  - Read-only
  - Primary vs. secondary



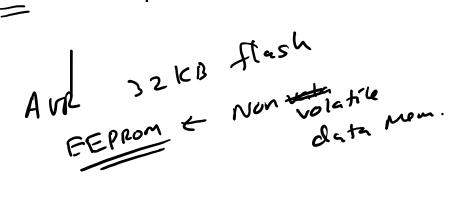
### **Memory Types**

- **Static** memory
- Flip-flops or latches used to store bits
- Dynamic memory
  - Each cell is a switch (transistor) plus capacitor
- These are both types of RAM = Random Access Memory
  - "RAM" originally meant could access any cell
    - (Compared with sequential\_access)
  - Now means volatile read/write memory
  - Static memory = SRAM AVR LAL Mem 2 KB
  - Dynamic memory = DRAM



## **Volatility**

- **Volatile** memory
  - Contents "forgotten" when power off
  - Both SRAM and DRAM are volatile (DRAM forgets contents within milliseconds if not refreshed, i.e. contents rewritten)
  - Non-volatile memory
- Contents remembered when power off
  - Many types
    - **✓** ROM
    - EPROM
    - ✓ EEPROM (\*)
    - Flash (\*)





### Non-volatile memory chips



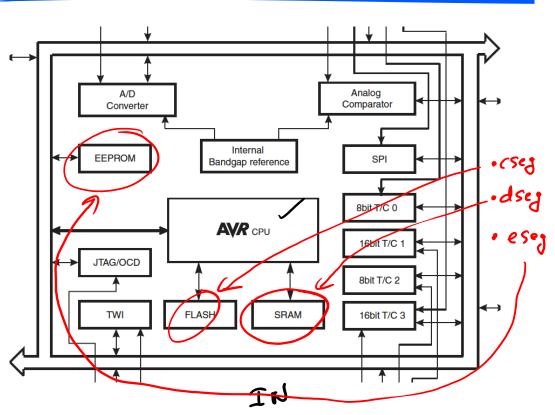
Programmed by memory manufacturer – contents hardwired in silicon

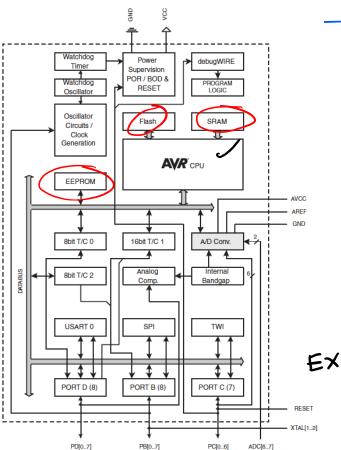
- **▶ EPROM** = Erasable Programmable ROM
  - Can erase, e.g. with ultraviolet light
- EEPROM = Electrically Erasable PROM
  - Can erase by applying a certain voltage
- Flash = New EEPROM
  - (Used to be different technology to EEPROM but converging)
  - Main difference Flash memory written/erased in blocks, EEPROM written/erased one cell at a time
    - ATMega324A supports two flash blocks Application section + Boot Loader section
    - Other AVR devices have one, others have more





## ATmega324A/328P Memory







### When is a Megabyte not a Megabyte?

- When it's a million bytes
- Conventionally (or at least historically)  $1 \text{ MB} = 2^{10}\text{kB} = 1,024\text{kB} = 2^{20} = 1,048,576\text{B}$ 
  - Sometimes,  $1MB = 10^{6}B = 1,000,000B$
  - Or could be in between: 1000kB = 1,024,000B
- Conventionally

$$1 \text{ GB} = 2^{10}\text{MB} = 2^{20}\text{kB} = 2^{30}\text{B}$$
  
= 1,073,741,824B

- Sometimes,  $1GB = 10^9B = 1,000,000,000B$
- This is a 7.4% difference
- Or could be in between: e.g.  $1000 \times 2^{20} = 1,048,576,000$



# When do we use powers of 2? When do we use powers of 10?

- For main memory capacity, always based on powers of 2, e.g.
  - $1GB = 1024 \times 1024 \times 1024$  bytes =  $2^{30}$  bytes
- For **hard disks**, manufacturers base sizes\_on powers of 10, e.g.
  - 1GB =  $1000 \times 1000 \times 1000$  bytes =  $(10^9)$  bytes
  - Makes hard disks seem bigger)
  - Operating Systems (e.g. Windows) base sizes on powers of 2
- For **data speeds (transfer rates)**, usually based on powers of 10, e.g.
  - 1Gbps (gigabit per second) = 10<sup>9</sup> bits per second
- Occasionally, a mixture
  - 1.44MB floppy disk stores 1.44 x 1000 x 1024 bytes





## Kibibytes, Mebibytes

- Kilo-, mega-, giga- prefixes mean powers of 10 in SI units
- To avoid confusion, standardised terms have been created for binary prefixes, e.g.
  - 1 **kibibyte** = 1KiB = 1024 bytes 2
  - 1 mebibyte = 1MiB = 1024KiB
  - 1 **gibibyte** = 1GiB = 1024MiB
- Unfortunately, very few people use them
- We'll use kilo-, mega-, giga- etc. but meaning could vary depending on context

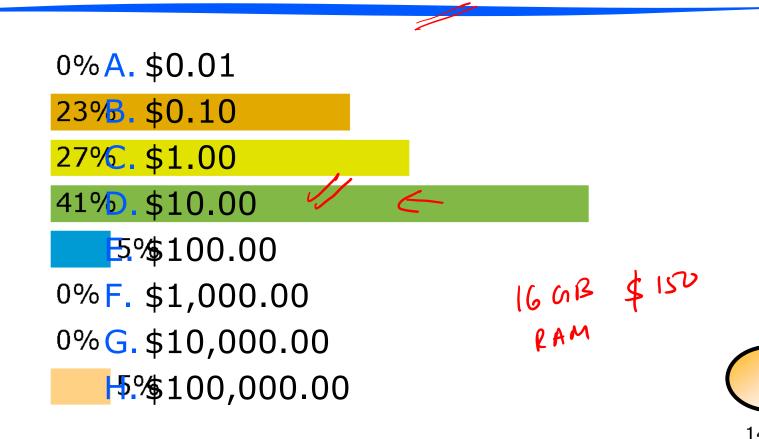


### **Types of DRAM**

- Bits stored as charge on capacitor, not in flip-flops
- Cells are smaller, so can pack more bits on a chip than for static memory
- Slower than static memory
- Many different types of DRAM over the ages...
  - Fast Page Mode (FPM DRAM)
  - Extended Data Out (EDO DRAM)
  - Synchronous DRAM (SDRAM)
  - Rambus DRAM (RDRAM)
  - Double Data Rate DRAM (DDR DRAM) 1, 2, 3 and 4

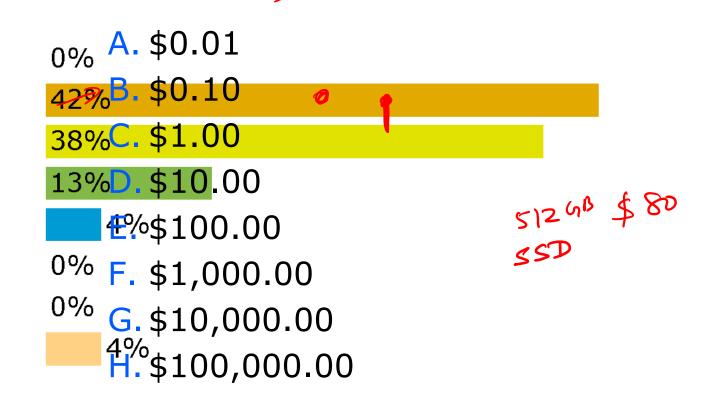


# What is the approximate cost per Gigabyte of DRAM?



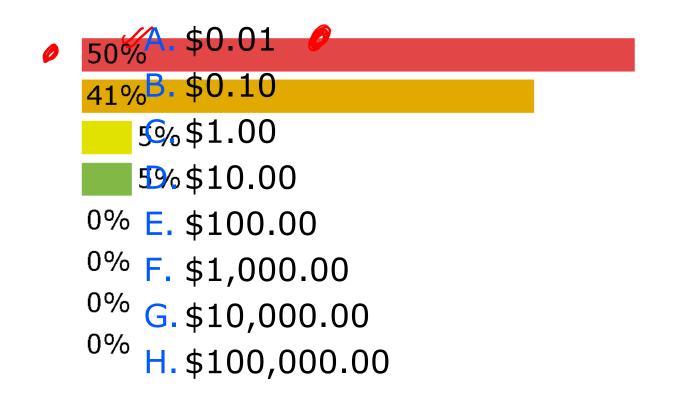


## What is the approximate cost per Gigabyte of Flash memory?



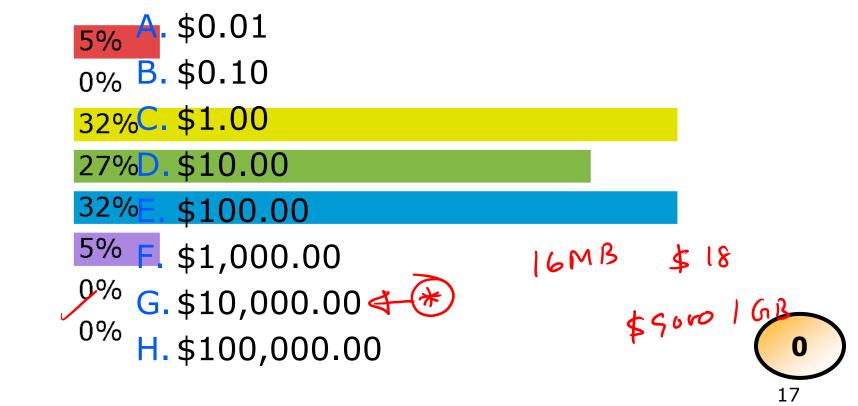


## What is the approximate cost per Gigabyte of Hard Disk Storage?



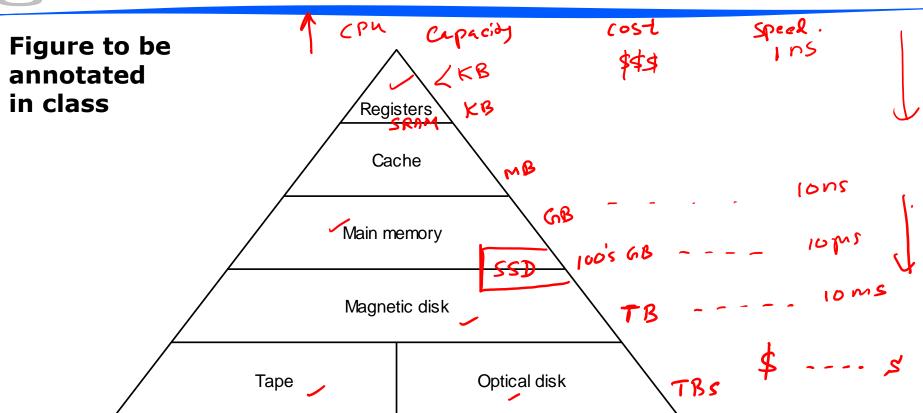


# What is the approximate cost per Gigabyte of SRAM?





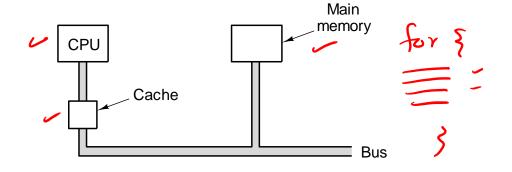
## **Memory Hierarchy**





## **Cache Memory**

- CPUs are faster than main memory
  - Very fast memory is expensive
  - Performance suffers if CPU always waiting for memory
  - Cache
    - Small amount of very fast memory combined with larger slow memory
    - Most commonly used memory words kept in cache
  - CPU looks in cache before main memory
  - Average access time greatly reduced if many words are in the cache





### **Cache Levels**

- Often multiple levels of cache
- Level 1 (L1)
  - Inside CPU itself
  - e.g. 32kB to 128kB
  - Runs at same speed as CPU
- Level 2 (L2)
  - May be separate chip (possibly inside same module) or on same chip as CPU
  - e.g. 256kB to 16MB
  - May be slightly slower than CPU
- **Level 3** (L3)
  - Some machines have a third level (e.g. 2MB to 256MB)

#### Note:

B = byte

b = bi



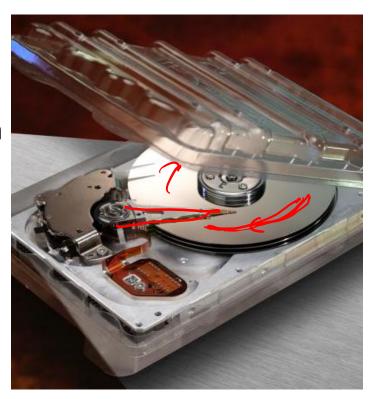
### "Cache" for Disks

- Increasingly common
- Small fast solid state drive (Flash memory) caches content from larger slower magnetic disk



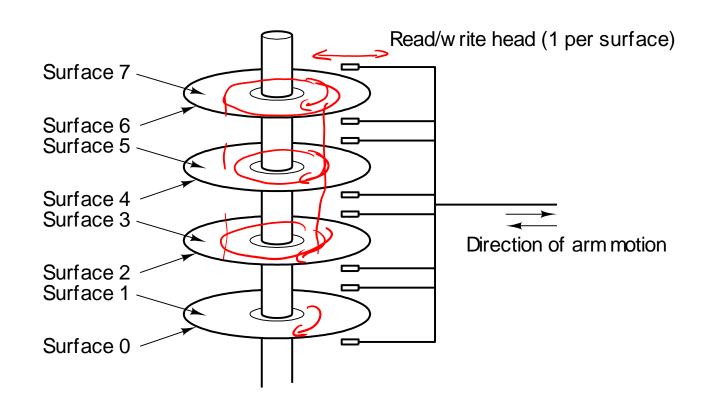
### Magnetic Disks

- Rotating platters with magnetised coating
  - Stack of platters
- Data stored magnetically in circular tracks
- Read/write heads float above platter surfaces
- Usually use both sides of platters



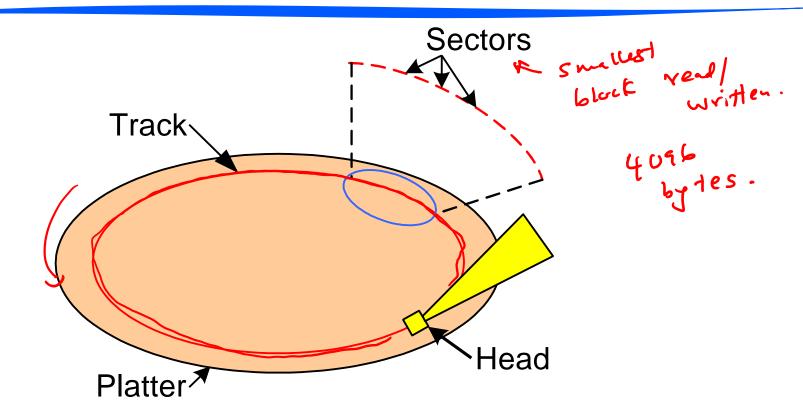


### **Magnetic Disks – Simplified view**





### **Sectors and Tracks**





## **Cylinders**

- Set of tracks at a given radial position
- Number of tracks in cylinder =
   2 x number of platters
   (assuming both sides of all platters used)

 Heads move together, i.e., to a certain cylinder



#### Sectors

- 4096 57tes. Tracks divided into fixed-length sectors
  - Smallest data unit, i.e. must read/write a whole sector at a time
- Sector consists of:
  - 1010101010 -. Preamble
    - Allows head to synchronise to data
  - Data \( 4096 bytes. \( 851.06 the Error correction codes (ECCs) \quad quoted capacity
  - Error correction codes (ECCs)
  - Inter-sector gap
- About 85% of disk capacity usable by operating system
  - About 95% of this usable for user data
  - Remaining ~5% file system overhead



### **Access Time**

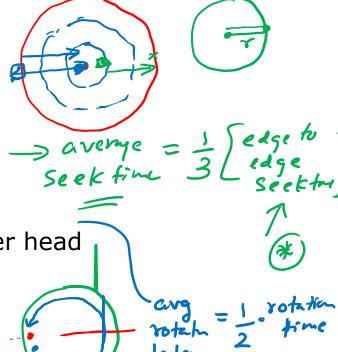


#### Access time =

- ->seek time +

  rotational latency +

  transfer time neglected.
- Seek time
  - Time to move heads to right cylinder
- Rotational latency
  - Time to wait for sector to arrive under head
- Transfer time
  - Time for sector to pass under head
  - Negligible compared with above





## **Calculating Access Time**

#### • Example:

What's the average access time for a hard disk which rotates at 7200rpm and has an edge-to-edge seek time of 10ms? (Assume that seek time is proportional to the number of tracks to seek.)

Aug acress time = Aug seek time + Aug rotational (atency)
$$= \frac{1}{3} \left[ \text{edge to edge seek time} \right] + \frac{1}{2} \left[ \text{rotation time} \right]$$

$$= \frac{1}{3} \left[ 10 \text{ ms} \right] + \frac{1}{120} \text{ s} = 3$$

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