

Refer class slides

$$L = PE - KE$$

Eqn of motion

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{p}} \right) - \frac{\partial L}{\partial p} = 0$$

for pendulum

$$p = \begin{bmatrix} l \sin \theta \\ -l \cos \theta \end{bmatrix} \rightarrow KE = \frac{1}{2} m \|\dot{p}\|^2$$

$$L = \frac{1}{2} m l^2 \dot{\theta}^2 + mgl \cos \theta$$