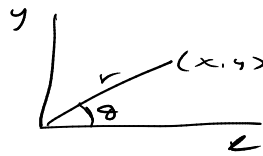


Polar Coordinates.



$$\begin{aligned} r^2 &= x^2 + y^2 \\ x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$$

$$(1) \quad df = \left(\frac{\partial f}{\partial x}\right)_y dx + \left(\frac{\partial f}{\partial y}\right)_x dy = f_x dx + f_y dy$$

$$(2) \quad x = r \cos \theta \Rightarrow dx = dr \cos \theta - r \sin \theta d\theta$$

$$(3) \quad y = r \sin \theta \Rightarrow dy = dr \sin \theta + r \cos \theta d\theta$$

(4) Put (2) and (3) in (1)

$$df = f_x (dr \cos \theta - r \sin \theta d\theta) + f_y (dr \sin \theta + r \cos \theta d\theta)$$

(5) when $r = \text{constant}$ i.e. $dr = 0$, we get (4) as

$$dr = 0 \xrightarrow{(4)} df = f_x (0 - r \sin \theta d\theta) + f_y (0 + r \cos \theta d\theta)$$

$$\text{So that } \left(\frac{\partial f}{\partial \theta}\right)_r = f_\theta = -r \sin \theta f_x + r \cos \theta f_y = -y f_x + x f_y$$

(6) when $\theta = \text{constant}$ i.e. $d\theta = 0$, we see (4) as

$$d\theta = 0 \xrightarrow{(4)} df = f_x (dr \cos \theta + 0) + f_y (dr \sin \theta + 0)$$

$$\text{So that } \left(\frac{\partial f}{\partial r}\right)_\theta = f_r = \cos \theta f_x + \sin \theta f_y = \frac{1}{r} (x f_x + y f_y)$$

(7) combining (5) and (6) into matrix form

$$\begin{pmatrix} f_r \\ f_\theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} f_x \\ f_y \end{pmatrix}$$

which upon inverting the matrix gives

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \frac{1}{\cos \theta \cdot r \cos \theta - (-r \sin \theta)(\sin \theta)} \begin{pmatrix} r \cos \theta & -\sin \theta \\ +r \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} f_r \\ f_\theta \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} f_x \\ f_y \end{pmatrix} = \frac{1}{r} \begin{pmatrix} r \cos \theta & -\sin \theta \\ r \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} f_r \\ f_\theta \end{pmatrix} \quad \text{operators}$$

$$\star \quad f_x = \cos \theta f_r - \frac{\sin \theta}{r} f_\theta \quad \rightarrow (7a) \Rightarrow \frac{\partial}{\partial x} f = \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) f$$

$$f_y = \sin \theta f_r + \frac{\cos \theta}{r} f_\theta \quad \rightarrow (7b) \Rightarrow \frac{\partial}{\partial y} f = \left(\sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \right) f$$

(8) We are interested in Laplacian

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \text{ which can be obtained operators in (7a) and (7b)}$$

$$\frac{\partial^2}{\partial x^2} f = \frac{\partial}{\partial x} (f_x) = \frac{\partial}{\partial x} \left(\cos \theta \frac{\partial f}{\partial r} - \frac{\sin \theta}{r} \frac{\partial f}{\partial \theta} \right) = \left(\frac{\partial}{\partial x} \right) \left(\cos \theta f_r - \frac{\sin \theta}{r} f_\theta \right)$$

$$= \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) \left(\cos \theta f_r - \frac{\sin \theta}{r} f_\theta \right)$$

$$\Rightarrow \frac{\partial^2}{\partial x^2} f = \cos^2 \theta f_{rr} - \cos \theta \sin \theta \frac{\partial}{\partial r} \left(\frac{f_\theta}{r} \right) - \frac{\sin \theta}{r} \left[\frac{\partial}{\partial \theta} (\cos \theta f_r) - \frac{1}{r} \frac{\partial}{\partial \theta} (\sin \theta f_\theta) \right] \quad (8a)$$

Similarly

Let's do now $\frac{\partial^2 f}{\partial y^2} = \left(\frac{\partial}{\partial y} \right) (f_y) = \underbrace{\left(\sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \right)}_{\frac{\partial}{\partial y}} \underbrace{\left(\sin \theta \frac{\partial f}{\partial r} + \frac{\cos \theta}{r} \frac{\partial f}{\partial \theta} \right)}_{f_y}$

$$\frac{\partial^2 f}{\partial y^2} = \sin^2 \theta f_{rr} + \sin \theta \cos \theta \frac{\partial}{\partial r} \left(\frac{1}{r} f_\theta \right) + \frac{\cos \theta}{r} \left[\frac{\partial}{\partial \theta} (\sin \theta f_r) + \frac{1}{r} (\cos \theta f_\theta) \right] \quad \text{--- (86)}$$

from (8a) and (8b)

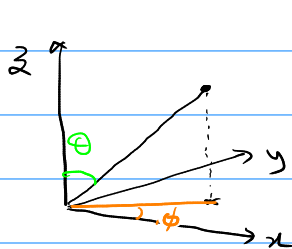
$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} &= (\cos^2 \theta + \sin^2 \theta) f_{rr} + \frac{2}{r} \left(\frac{f_\theta}{r} \right) [-\cos \theta \sin \theta + \sin \theta \cos \theta] \\ &\quad + \frac{1}{r} \left[\sin \theta \frac{\partial}{\partial \theta} (\cos \theta f_r) + \cos \theta \frac{\partial}{\partial \theta} (\sin \theta f_r) \right] \\ &\quad + \frac{1}{r^2} \left[\sin \theta \frac{\partial}{\partial \theta} (\sin \theta f_\theta) + \cos \theta \frac{\partial}{\partial \theta} (\cos \theta f_\theta) \right] \end{aligned}$$

$$\begin{aligned} \Rightarrow \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} &= f_{rr} + \frac{1}{r} \left[-\sin \theta [(-\sin \theta) f_r + \cos \theta f_{r\theta}] + \cos \theta [\cos \theta f_r + \sin \theta f_{r\theta}] \right] \\ &\quad + \frac{1}{r^2} \left[\sin \theta [\cos \theta f_\theta + \sin \theta f_{\theta\theta}] + \cos \theta [(-\sin \theta) f_\theta + \cos \theta f_{\theta\theta}] \right] \\ &= f_{rr} + \frac{1}{r} [f_r] \\ &\quad + \frac{1}{r^2} [f_{\theta\theta}] \end{aligned}$$

$$\Rightarrow \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = f_{rr} + \frac{1}{r} f_r + \frac{1}{r^2} f_{\theta\theta}$$

LAPLACIAN IN POLAR COORDINATES.

(10) 3-d. Spherical Coordinates.



$$r^2 = x^2 + y^2 + z^2$$

$$\theta = \cos^{-1} \left(\frac{z}{r} \right)$$

$$\tan \phi = y/x$$



Equivalently

$$\begin{cases} x^2 + y^2 + z^2 = r^2 \\ \frac{z}{\sqrt{x^2 + y^2 + z^2}} = \cos \theta \\ \frac{y}{x} = \tan \phi \end{cases}$$

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

(11)

$$df = \left(\frac{\partial f}{\partial x} \right)_{y,z} dx + \left(\frac{\partial f}{\partial y} \right)_{x,z} dy + \left(\frac{\partial f}{\partial z} \right)_{x,y} dz = f_x dx + f_y dy + f_z dz$$

(12a) $x = r \sin \theta \cos \phi \Rightarrow dx = dr \sin \theta \cos \phi + d\theta \cdot r \cos \theta \cos \phi - d\phi r \sin \theta \sin \phi$

(b) $y = r \sin \theta \sin \phi \Rightarrow dy = dr \sin \theta \sin \phi + d\theta \cdot r \cos \theta \sin \phi + d\phi r \sin \theta \cos \phi$

(c) $z = r \cos \theta \Rightarrow dz = dr \cos \theta - d\theta \cdot r \sin \theta$

(1) Substituting (12)(13)(14) in (11) and then for LHS using $\left(\frac{\partial f}{\partial r}\right) = \left(\frac{df}{dr}\right)_{\theta, \phi = \text{const}}$

$$(13a) \quad f_r = \left(\frac{\partial f}{\partial r}\right)_{\theta, \phi = \text{const}} = f_x (\sin \theta \cos \phi) + f_y (\sin \theta \sin \phi) + f_z \cos \theta$$

$$(13b) \quad f_\theta = \left(\frac{\partial f}{\partial \theta}\right)_{r, \phi = \text{const}} = f_x (r \cos \theta \cos \phi) + f_y (r \cos \theta \sin \phi) + f_z (-r \sin \theta)$$

$$(13c) \quad f_\phi = \left(\frac{\partial f}{\partial \phi}\right)_{r, \theta = \text{const}} = f_x (-r \sin \theta \sin \phi) + f_y (r \sin \theta \cos \phi) + f_z (0)$$

hence

$$\begin{pmatrix} f_r \\ f_\theta \\ f_\phi \end{pmatrix} = \underbrace{\begin{pmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ r \cos \theta \cos \phi & r \cos \theta \sin \phi & -r \sin \theta \\ -r \sin \theta \sin \phi & r \sin \theta \cos \phi & 0 \end{pmatrix}}_{\text{Matrix } M} \begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix}$$

$$\det(M) = \sin \theta \cos \phi (+r^2 \sin^2 \theta \cos \phi) - \sin \theta \sin \phi (-r^2 \sin^2 \theta \sin \phi) + \cos \theta (r^2 \cos \theta \sin \theta \cos^2 \phi + r^2 \cos \theta \sin \theta \sin^2 \phi)$$

$$= r^2 \sin^3 \theta + r^2 \cos^3 \theta \sin \theta = \boxed{r^2 \sin \theta (1) = \det(M)}$$

Since $\det(M)$ is non-zero, it is invertible and is

$$M^{-1} = \frac{1}{\det(M)} \begin{pmatrix} -r^2 \sin^2 \theta \cos \phi & +r^2 \sin^2 \theta \sin \phi & r \cos \theta \sin \theta (1) \\ -r \sin \theta \cos \theta \cos \phi & +r \sin \theta \cos \theta \sin \phi & r^2 \sin^2 \theta (1) \\ -r \sin \theta \sin \phi (1) & -r \cos \phi (1) & 0 \end{pmatrix}$$

Use $\det(M) = r^2 \sin \theta \Rightarrow M^{-1} = \frac{1}{r} \begin{pmatrix} -\sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ -\cos \theta \cos \phi & \cos \theta \sin \phi & \sin \theta \\ -\sin \phi / \sin \theta & -\cos \phi / \sin \theta & 0 \end{pmatrix}$

We have $\begin{pmatrix} f_x \\ f_y \\ f_z \end{pmatrix} = M^{-1} \begin{pmatrix} f_r \\ f_\theta \\ f_\phi \end{pmatrix}$

Then set $f_{x2} = (f_x)_2$
 $f_{y2} = (f_y)_2$
 $f_{z2} = (f_z)_2$ } and then get $f_{x2} + f_{y2} + f_{z2}$ in terms of spherical coordinates.

SEE NEXT PAGE FOR SLIGHTLY EASIER METHOD.

Spherical Coordinates

$$\begin{aligned}x &= r \sin \theta \cos \phi \\y &= r \sin \theta \sin \phi \\z &= r \cos \theta\end{aligned}$$

(14)

Introduce new variable $s = r \sin \theta \Rightarrow$

$$\begin{aligned}x &= s \cos \phi \\y &= s \sin \phi \\z &= r \cos \theta \\ \text{ie } s &= \sqrt{x^2 + y^2}, \quad s = r \sin \theta\end{aligned}$$

(14a) Consider xy planes (ie $z = \text{constant}$); we have already shown that

$$\partial_{xx}^2 + \partial_{yy}^2 = \partial_{ss}^2 + \frac{1}{s} \partial_s + \frac{1}{s^2} \partial_{\phi\phi}^2 \quad \begin{bmatrix} 0 & x = s \cos \phi \\ 0 & y = s \sin \phi \end{bmatrix}$$

(14b) Consider rz planes (ie $\phi = \text{constant}$), we have already shown that

$$\partial_{zz}^2 + \partial_{rr}^2 = \partial_{rr}^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_{\theta\theta}^2 \quad \begin{bmatrix} 0 & z = r \cos \theta \\ 0 & s = r \sin \theta \end{bmatrix}$$

From (14a) we have to eliminate s variable.

First step is to use (14b) to get ∂_{ss}^2 to put in RHS of (14a)

$$\Rightarrow \partial_{xx}^2 + \partial_{yy}^2 + \partial_{zz}^2 = \left(\partial_{rr}^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_{\theta\theta}^2 \right) + \frac{1}{s} \partial_s + \frac{1}{s^2} \partial_{\phi\phi}^2 \rightarrow (14c)$$

we only need to get ∂_s !

(14d) For any function f , we have $df = f_r dr + f_\theta d\theta + f_\phi d\phi$

$$\text{ie } \frac{\partial f}{\partial s} = f_r \frac{\partial r}{\partial s} + f_\theta \frac{\partial \theta}{\partial s} + f_\phi \frac{\partial \phi}{\partial s} \quad \text{and here } s = r \sin \theta \Rightarrow \boxed{\frac{\partial \phi}{\partial s} = 0}$$

$$\Rightarrow \frac{\partial f}{\partial s} = f_r \frac{\partial r}{\partial s} + f_\theta \frac{\partial \theta}{\partial s} \quad (14d)$$

for $\frac{\partial r}{\partial s}$ (14e) $r = \sqrt{s^2 + z^2} \Rightarrow \frac{\partial r}{\partial s} = \frac{1}{2r} \cdot 2s = \frac{s}{r} \Rightarrow \boxed{\frac{\partial r}{\partial s} = \frac{s}{r}} \quad (14e)$

for $\frac{\partial \theta}{\partial s}$ (14f) $s = r \sin \theta \Rightarrow \frac{\partial s}{\partial \theta} = \frac{\partial r}{\partial \theta} \sin \theta + r \cos \theta \frac{\partial \theta}{\partial \theta}$

$$1 = \left(\frac{s}{r} \right) \sin \theta + r \cos \theta \frac{\partial \theta}{\partial s} \Rightarrow \frac{\partial \theta}{\partial s} = \frac{\cos \theta}{r}$$

(14f)

Substituting (14f) and (14e) in (14d),

$$\text{we get } \partial_s f = f_r \cdot \frac{s}{r} + f_\theta \cdot \frac{\cos \theta}{r} \Rightarrow \boxed{\partial_s f = \left(\frac{s}{r} \partial_r + \frac{\cos \theta}{r} \partial_\theta \right) f} \quad (14g)$$

Substituting $s = r \sin \theta$ and (14g) in (14c) we get

$$\partial_{xx}^2 + \partial_{yy}^2 + \partial_{zz}^2 = \partial_{rr}^2 + \frac{2}{r} \partial_r + \frac{1}{r^2} \left[\partial_{\theta\theta}^2 + \frac{1}{\sin^2 \theta} \partial_{\phi\phi}^2 + \frac{\cos \theta}{\sin \theta} \partial_{\theta\phi}^2 \right]$$

THIS IS THE LAPLACIAN IN SPHERICAL COORDINATES