

COMS W4701: Artificial Intelligence

Written Homework 2

Huibo Zhao (hz2480)

October 22, 2017

Problem 1

Which techniques mentioned in the Wired article are also used in AlphaGo? Which techniques are novel to AlphaGo?

In the wired article, it mentioned that Coulom combined the advantages of tree search and Monte Carlo to form a new algorithm Monte Carlo Tree Search. In AlphaGo, this technique is applied for neural networks as it "simulate thousands of random games of self-play". Another common technique mentioned in both article is that the program will learn from the human. in wired article, the program tried to mimic expert's move whereas AlphaGo trained supervised learning from expert moves.

The new technique in AlphaGo is a search algorithm that combines Monte Carlo simulation with value and policy networks. More specifically, value networks are for evaluating board positions and policy networks are for selecting moves. AlphaGo applied supervised learning and reinforcement learning to enhance these networks.

Which problems specific to Go are addressed by each technique?

The huge game's breadth and depth factors makes exhaustive search impossible. People used refined Monte Carlo Tree Search combined with neural networks to narrow the search.

The decision for each move is hard to decide. As introduced in wired article, the movement is not very predictable in professions' levels. An experienced human player may choose an excellent movement by his feeling of the game. However, this feeling is very hard to apply to the program. In wired article, people initially trained program by learning and mimicking professions' moves. AlphaGo used policy networks to select best move.

Also, it is hard to analyze the current game situation for Go. There are just too many factors that will affect evaluating the board configuration. It is hard to quantify them using program. So AlphaGo applied value networks to evaluate board positions.

Why do you think AlphaGo is successful where other Go programs have failed.

AlphaGo combined different neural networks for evaluating the positions and movements with Monte Carlo Tree Search. In essence, I think it is deep neural networks that make AlphaGo successful.

Problem 2

As shown below

step	node	α	β	result	children	skipped
1	A	$-\infty$	∞	11		
2	B	$-\infty$	∞	4		
3	E	13	∞	13		
4	F	$-\infty$	13	4		
5	G	$-\infty$	4	5	8	
6	C	4	∞	7		
7	H	4	∞	15		
8	I	4	15	7		
9	J	4	7	16	4,-12	
10	D	7	$-\infty$	11		
11	K	7	$-\infty$	11		
12	L	7	11	12	13,-15	
13	M	7	11	19		

Problem 3

1.

The variables are 1,2,3,4,5 corresponding to the 5 classes.

The values are A,B,C corresponding to the 3 professors.

The domain for class 1 is [A]

The domain for class 2 is [A,B]

The domain for class 3 is [A,B,C]

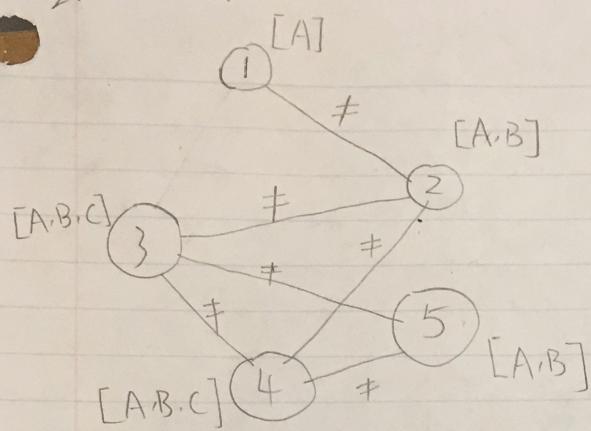
The domain for class 4 is [A,B,C]

The domain for class 5 is [A,B]

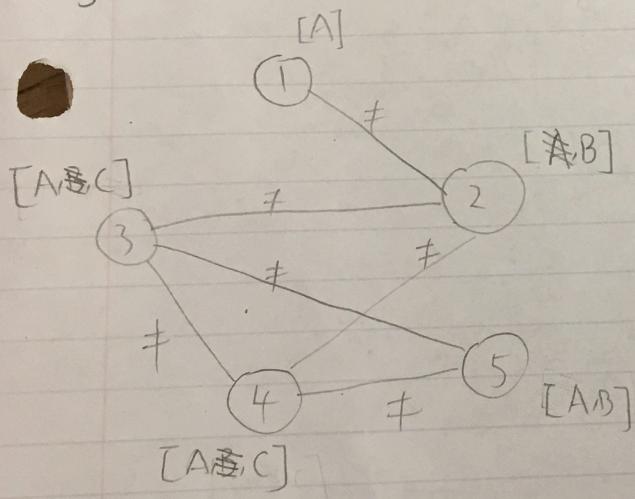
The constraint is due to the time conflict between the classes

That is $1 \neq 2, 2 \neq 3, 3 \neq 4, 2 \neq 4, 3 \neq 5, 4 \neq 5$

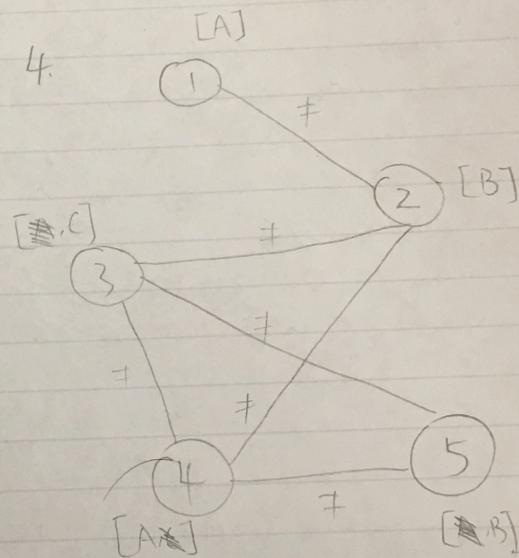
2.



3.



4.



MRV	LCV	1	2	3	4	5
1	A	A	B	AC	AC	AB
2	B	A	B	AC	AC	AB
3	C	A	B	C	A	AB
4	A	A	B	C	A	B
5	B	A	B	C	A	B

Problem 4

We introduce the auxiliary variable X. The domain for X contains all valid sets of 3-value tuple corresponding to $A+B=C$. So for any tuple in X, the binary constraint is that A is the first element of that tuple, B is the second element and C is the third element. By picking element A, B or C, we will reduce the domain of X and lastly there will be only tuple(s) that satisfied all 3 binary constraints left.

For constraints involving more than three variables, the problem can be treated similarly. Assume there are n variables involved, we can turn that into n binary constraints between a new auxiliary variable. The domain for the new auxiliary variables contains all valid sets of n-value tuple that satisfy that single constraint.