

# phyMOTION<sup>TM</sup>

### Modular multi-axes controller for stepper motors

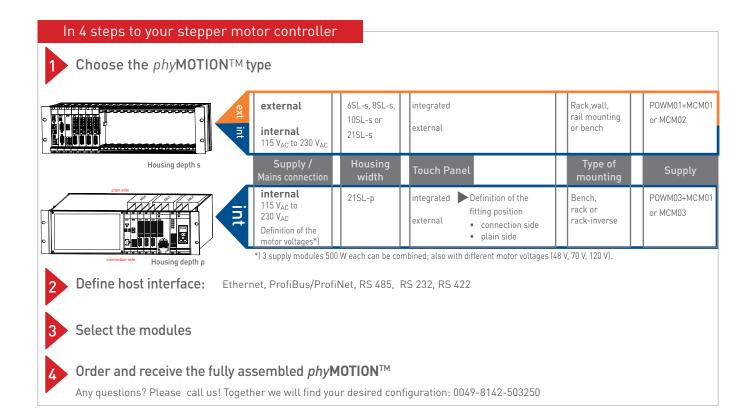
The phyMOTION<sup>TM</sup> combines PLC and motion control functions into a flexible and convenient framework for multi axis stepper motor applications. The free software phyLOGIC<sup>TM</sup> Toolbox, the LabVIEW interface, the Androidbased touch interface (internal/external) and the open protocol for controller drive and parameterising create additional scope for development. The integra-

ted, high resolution power stages up to 15  $\rm A_{Peak}$  at 120  $\rm V_{DC}$  simplify the wiring significantly.

#### Designed for Industry 4.0

The phyMOTION™ can be operated below existing PLC systems as a slave system, as distributed intelligence or as a stand-alone motion control solution. Online parameterising and -diag-

nostics are also standard feature as limit switch/reference switch inputs per axis. Each axis can be expanded with encoder (Endat, SSI- /Quadrature) and temperature evaluation. Besides standard PLC functions such as analogue and digital I/Os, a variety of interfaces (Ethernet, Profibus, Profinet, RS232/485, USB) the phyMOTION™ also provides linear and circular interpolation.



#### Module selection for your *phy***MOTION**™

To make the module selection as comfortable as possible, we coded the modules by main and auxiliary functions.



This main function is included in the respective module.



The main function is not available in the respective module.



I/O D Auxiliary functions are shown only if the module supports them.



means the main or auxiliary function is selectable as option.

ΑG		
С	*	

S	POWER SUPPLY			
nction	CPU	Modules with CPU contain intelligent processors and can execute the total sequential programs and enable the $phy$ MOTION <sup>TM</sup> to drive in stand-alone mode.		
Main functions	INDEX	The INDEXER represents the functionality to generate signals from commands of a programming language, which the power stage can amplify. Normally, the signal is control pulses/direction or SIN/COS.		
Σ	POWER STAGE	POWER STAGE represents a stepper motor amplifier. Incoming control pulses/direction or SIN/COS signals are amplified and output to the motor		
ns	ENC	Encoder evaluation POW IN Power distribution		
nctio	TEMP	Motor temperature evaluation COM Host interface		
y fur	I/0 D	Digital inputs and/or outputs SAFETY Safe Torque Off		
Auxiliary functions	I/0 A	Analogue inputs and/or outputs		
Aux				

#### Options for your *phy***MOTION**™

Options are available for the main or auxiliary functions. The following overview will make the option selection as easy as possible:



#### Option selectable power stage

- APS power stage (APS01):
  - step frequeny up to 500.000 steps/sec.
  - up to 5  $A_{\mbox{\tiny PEAK}}$  at 24 to 70  $V_{\mbox{\tiny DC}}$  (Derating dep.on application)
  - precision up to 1/512 step resolution
  - Sinusoidal current curve
  - Overdrive function (a motor independent compensation of the phase current decrease in the upper speed
- LPS power stage (LPS01):
  - step frequeny up to 250.000 steps/sec.
  - up to 9  $\rm A_{\rm PEAK}$  at 24 to 70  $\rm V_{DC}$  (Derating dep.on application)
  - precision up to 1/256 step resolution
  - Sinusoidal-like current curve

#### **ENC \* Option selectable encoder evaluation**

	cupply	supply resolution	aumanted tunes	option (submodule)			
Encoder type	supply	resolution	supported types	ECAS01	ECES01	ECBS01	ECMS01
differential	5 V / 5.5 V 500 mA	232	Quadrature with zero track	✓	✓	✓	
SSI	5 V / 5.5 V 500 mA	231	SSI	✓	✓	✓	
BiSS	5 V / 5.5 V 500 mA	231	BiSS-C BiSS-B			✓	
EnDat	5 V / 5.5 V 500 mA	<b>2</b> <sup>31</sup>	Endat 01 02 21 22 T		✓		
Resolver	5 to 10 Vrms 1 to 10 kHz	212	Resolver 6-wire LVDT / RVDT 4-/5-/6-wire				<b>√</b>

#### Option selectable motor temperature evaluation

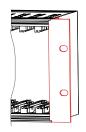
- with KTS01 submodule: the stepper motor temperature is evaluated with the metall thermocouple type K by comparison measurement
- with PTS01 submodule: the stepper motor temperature mesurement with the Pt resistor sensors

### 1 Housing and Supply

#### Housing types of the *phy***MOTION**™:



Bench or rail mounting



Rack mounting (connection side is the

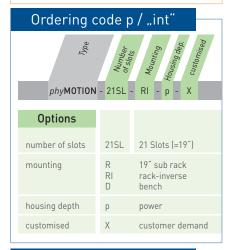


Wall mounting or rack-inverse (like rack mounting, but connection side is back)

Housing depth / current supply	Slots	U	Width	Height	Depth	Mounting
	6	24	137	132.5 121	101	R/W/MR/D
s / external or s / internal	8	32	177.6			
	10	40	218.3		K/W/MK/D	
	21	84	442.4			
p / internal	21	84	442.4	132.5	360	R/RI/D

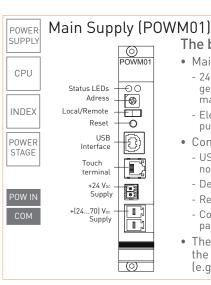
Mounting bracket for rack, rack-inverse or wall mounting: +40.6 mm

Ordering code s/"ext"			
The	Number of slote	Mounting Housing dep. Customised	
phyMOTION	- 6SL -	MR - s - X	
Options			
number of slots	6SL 8SL 10SL 21SL	6 slots 8 slots 10 slots 21 slots (=19")	
mounting	W MR R D	wall mounting rail 19"sub rack bench	
housing depth	S	small	
customised	Χ	customer demand	



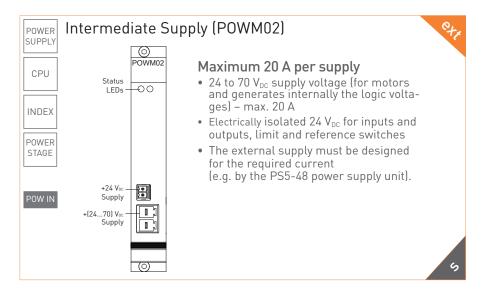


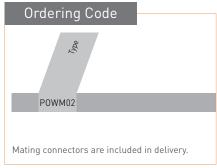
Ordering Code	
Ordering Code	
9	
Jpe	
POWM01	
Mating connectors are included in delivery.	

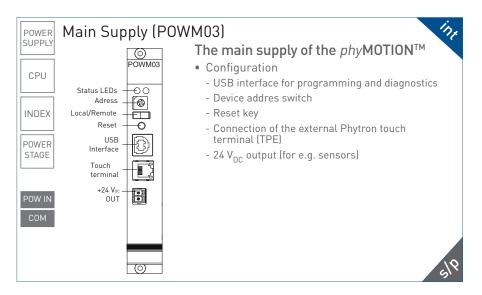


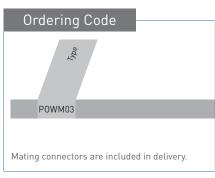
### The beginning of each phyMOTION™

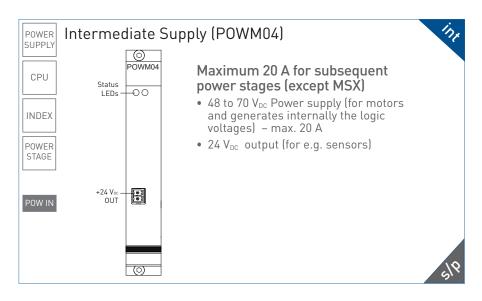
- Main supply:
- 24 to 70  $V_{\text{DC}}$  supply voltage (for motors and generates internally the logic voltages) -
- Electrically isolated 24  $V_{\text{DC}}$  for inputs/outputs, limit and reference switches
- Configuration
  - USB interface for programming and diagnostics
  - Device address switch
  - Reset key
  - Connection of an external Phytron touch
- The external supply must be designed for the required current (e.g. by the PS5-48 power supply unit).

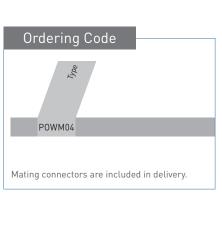


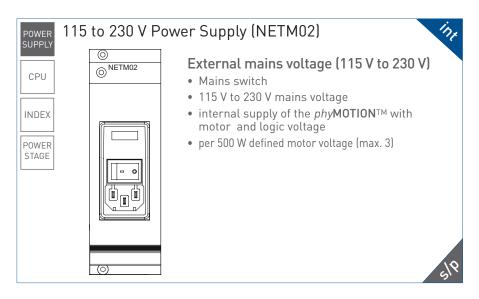


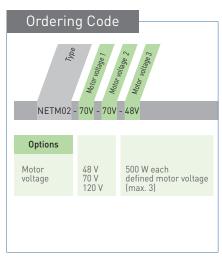


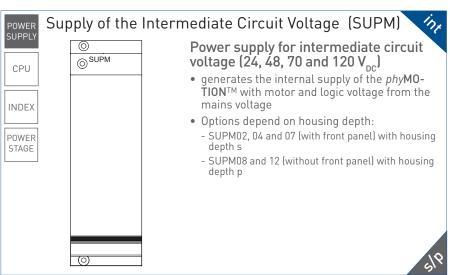




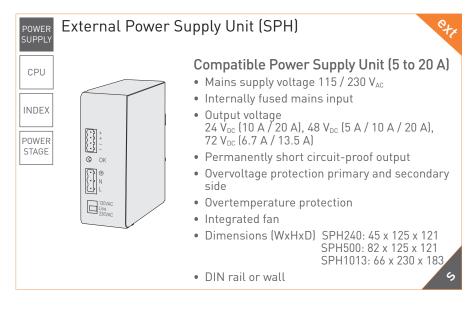


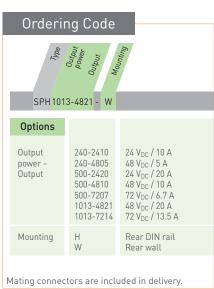




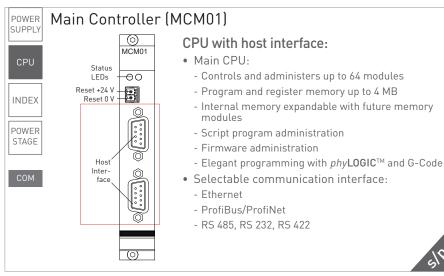


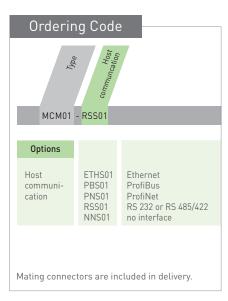


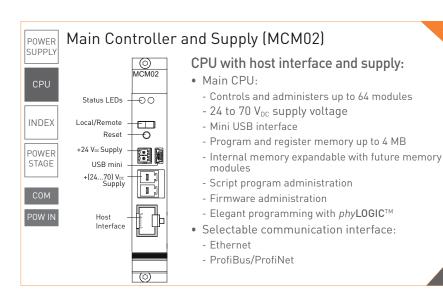


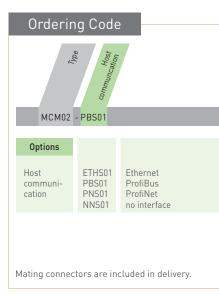


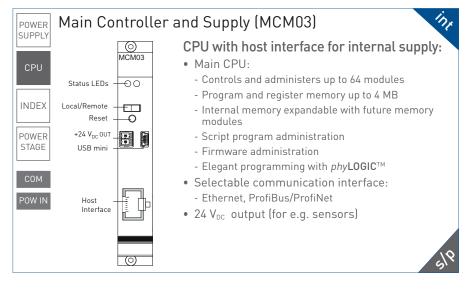
### 2 Host Interface

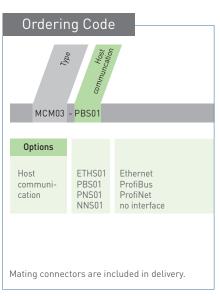




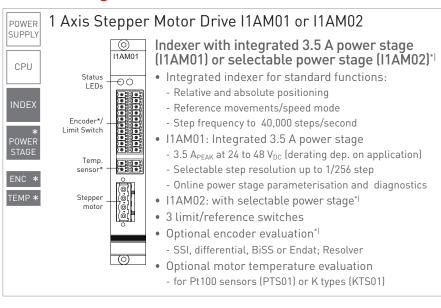


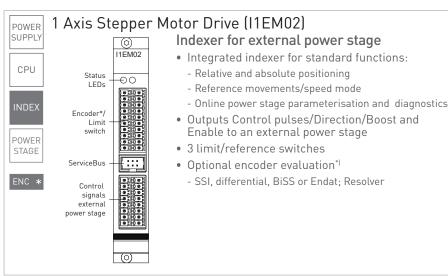


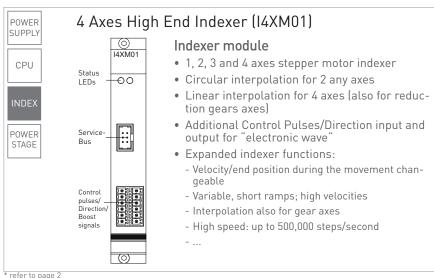


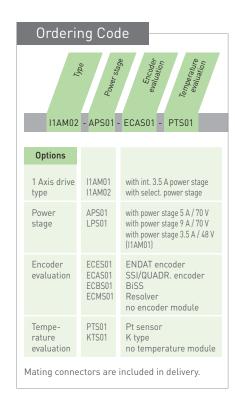


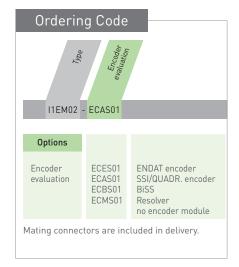
### 3 Power Stages and Indexer

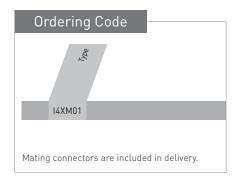


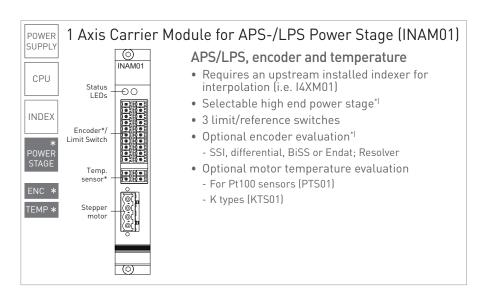


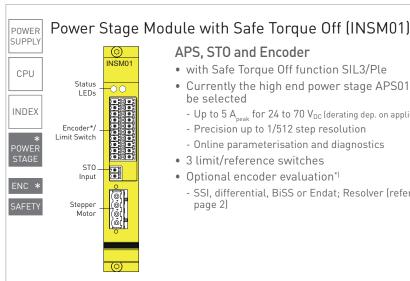






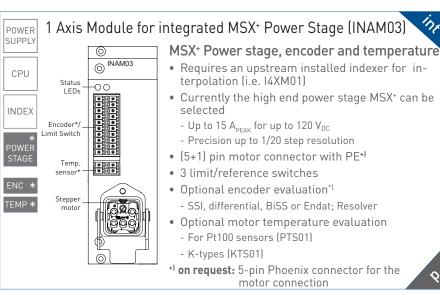


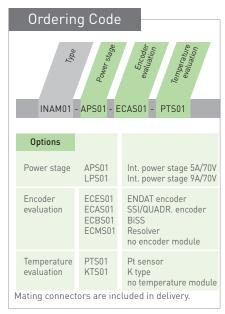


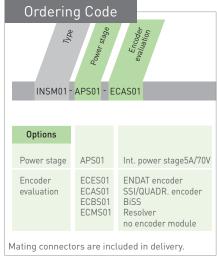


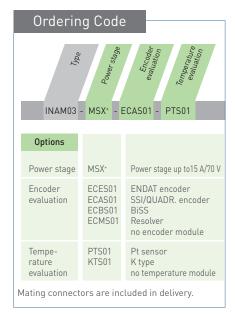
#### APS, STO and Encoder

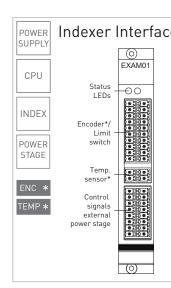
- with Safe Torque Off function SIL3/Ple
- Currently the high end power stage APS01 can be selected
  - Up to 5  $A_{peak}$  for 24 to 70  $V_{DC}$  (derating dep. on application)
  - Precision up to 1/512 step resolution
  - Online parameterisation and diagnostics
- 3 limit/reference switches
- Optional encoder evaluation\*)
  - SSI, differential, BiSS or Endat; Resolver (refer to page 2)









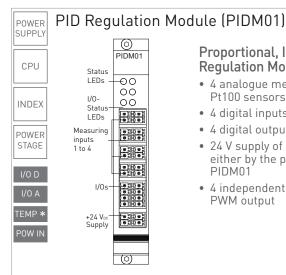


## Indexer Interface (EXAM01) for External Power Stage

#### Interface between indexer and external power stages

- Requires an upstream installed indexer (i.e. I4XM01)
- Outputs Control pulses/Direction/Boost and Enable to an external power stage
- External power stages with ServiceBus can be parameterised online by the interface on the indexer module (i.e. I4XM01) and be diagnosed.
- 3 limit/reference switches
- Optional encoder evaluation\*)
  - SSI, differential, BiSS or Endat; Resolver
- Optional motor temperature evaluation
  - for Pt100 sensors (PTS01) or K types (KTS01)

### I/Os (analogue/digital)

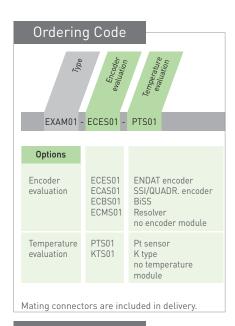


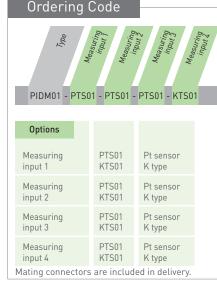
### Proportional, Integral, Derivative

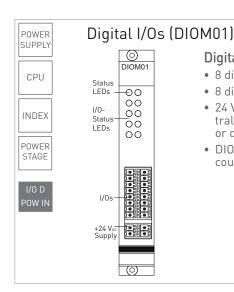
- 4 analogue measuring inputs i.e. for Pt100 sensors and K types
- 4 digital inputs 24 V

Regulation Module

- 4 digital outputs 24 V, max. 1 A
- 24 V supply of the I/O is centrally delivered either by the power modules or directly at the PIDM01
- 4 independent PID controllers with PWM output

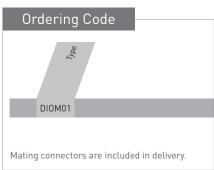




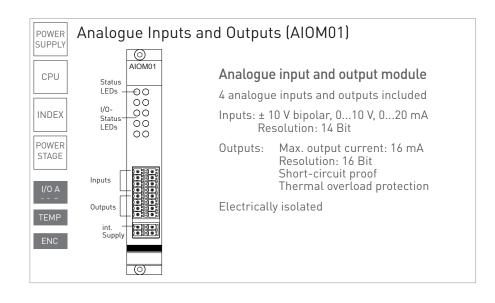


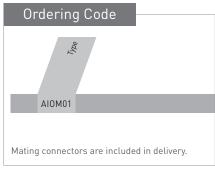
#### Digital I/O module

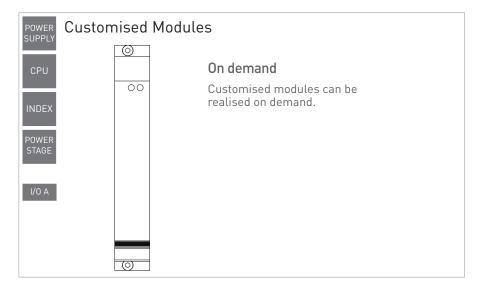
- 8 digital inputs 24 V<sub>DC</sub>
- 8 digital outputs 24 V<sub>DC</sub>, max. 1 A
- 24 V supply of the inputs and outputs is centrally delivered either by the power modules or directly at the DIOM01.
- DIOM01 can also be used as a single channel counter module.



<sup>\*</sup> see page 2







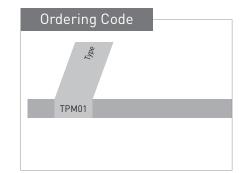
#### HMI-Interfaces

#### Android-based integrated Touch Panel (TPM01)

#### Integrated human-machine interface



- 800 x 480 px TFT display
- Integrated in the phyMOTION<sup>™</sup> housing
- Touch functionality
- As user interface i.e. for parameter selection
- For support, parameterisation and diagnostics



### Control via Android-based Tablets (from version V 4.0)



#### External humanmachine interface

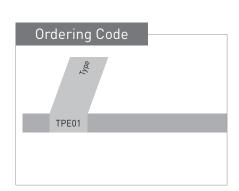
- from 480 x 800 px (recommended: 7"-display) – TFT display
- For connection to the POWM01 main power module (Ethernet or WLAN)
- Touch functionality
- As user interface i.e. for parameter selection
- For support, parameterisation and diagnostics

#### Control with Operator Touch Panel (TPE01)

#### External human-machine interface



- For connectio to the POWM01 main power module (terminal interface)
- 800 x 480 px TFT display
- Touch functionality
- For configuration, service snd diagnostics
- Housing: Rear cover: galvanised steel BTK housing frame: PC UL 94 V0 BTA front frame: aluminium anodised
- up to IP 65/DIN EN 60529

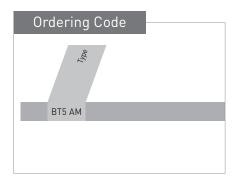


#### Control with Operator Panel BT5 AM

# 

#### External humanmachine interface

- For connection to the POWM01 main power module (terminal interface)
- For support, parameterisation and diagnostics
- Status display, operating mode
- Parameter reading
- Function keys
- Remote or Local mode



#### Software

#### phy**LOGIC**™ ToolBox



## Free of charge development environment

- Operating software and development environment for the phyMOTION™ Phytron controller
- Easy to program:
   Drawing and converting of 2D contours in phyLOGIC™ commands (Motion Creator)
- Parameterising, programming, editing, debugging
- Support in the commissioning phase i.e. by test functions
- Display of status and graphical presentation of a current XY position
- Archiving of parameter sets and programs

#### *phy***LOGIC**<sup>™</sup> Control



## Free of charge App for tablets and mobile phones

- Operating software for tablets connected to the phyMOTION™ Phytron controller
- Direct mode, operating mode, I/O monitor, configuration of the controller
- Status display and parameter reading

#### LabVIEW®-VI



#### VIs for phyMOTION™

- Simulation software with a graphical style
- Use the VIs (Virtual Instruments) generated by Phytron and integrate them in your LabVIEW® project. So you can easily control the Phytron controller phyMOTION™ from your usual programming environment.

#### **EPICS Motor Module**



## Software environment for large-scale experiments

- Software environment to develop and realise distributed control systems for largescale experiments such as telescopes and accelerators. EPICS provides the SCADA support.
- Download of the driver at: http://www.aps.anl.gov/bcda/synApps/motor/tar/motorR6-9.tar.gz
   to integrate the Phytron controller phyMOTION™ into the EPICS environment.
- Also in multi-axis operation: positioning, limit switches, encoder evaluation

### Equipment

#### Motor Shield Clamp



#### Shielding for motor connection

- Easy to go
- Plug-in connection for motor shielding of the following modules of the Phytron controller phyMOTION™: INAM-, EXAM-, I1AM01- or I1AM02module
- On delivery: shielded clamp with cableties and screws
- The motor connectors are included in the package of your phyMOTION™ controller.

#### Ordering ID

# 10015002

#### Strain Relief for Motor cable



## Mountable rail for strain relief of the motor cables

- Dimension: (482.6 x 44.5 x 8) mm
- Material: Aluminium
- 21 cable clamps
- Mountable at the 19"-switching cabinet with two M3 screws

#### Ordering ID

# 10019310

#### Carrying and Assembly Handle



#### For 19"-Housing

- Shapely and universal
- Grip adjustment by pushbutton by 30°
- Material: handle profile: extruded aluminium handle bar, housing adapter: zinc die cast
- Surface: handle bar: RAL 9011 graphite black pushbutton, srew lens: black plastic
- Carrying capacity: 50 kg

#### Ordering ID

# 10019311

De



### 4 Order and Receive the Fully Assembled *phy*MOTION™

### Configuration Example

 $\textit{phy} \texttt{MOTION}^{\texttt{TM}}$  with internal supply and housing depth p

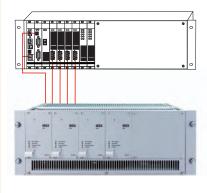
#### Ordering code example:

	Ordering code	Description
Housing	phyMOTION-21SL-R-p	19" subrack housing, housing depth 360 mm



Modules	Ordering code	Description
Slot 1	MCM03-ETHS01	Main controller with Ethernet interface, internal supply
Slot 2	DIOM01	Digital I/O module
Slot 3	DIOM01	Digital I/O module
Slot 4	DIOM01	Digital I/O module
Slot 5	I4XM01	4 axes indexer module
Slot 6	INAM02-MSX*-ECAS01	MSX⁺ power stage with Quadratic encoder evaluation
Slot 7	INAM02-MSX*-ECES01	MSX <sup>+</sup> power stage with Endat encoder evaluation
Slot 8	INAM02-MSX+-ECAS01	MSX <sup>+</sup> power stage with Quadratic encoder evaluation
Slot 9	INAM01-APS01-ECES01-KTS	Internal 5 A power stage with Endat-Enc./Motor tempevaluation
Slot 10 -19	-	blank front panels
Slot 20	NETM01-230V-120V-120V-120V	Ext. mains voltage 230 V, 3 x 500 W for 120 V

#### phyMOTION™ with SLS



#### Ordering Code Example:

	Ordering code	Description
Housing	phyMOTION-21SL-R-p	19"subrack housing, housing depth 360 mm

Modules	Ordering code	Description
Slot 1	P0WM01	Main supply module
Slot 2	MCM01-RSS485	Main controller with RS 485 interface
Slot 3	I4XM01	4 axes indexer module
Slot 4	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval.
Slot 5	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval
Slot 6	EXAM01-ECAS01	Indexer interface for MSX power stage with Quadrencoder eval
Slot 7	EXAM01-ECES01-KTS	Indexer interface for MSX power stage with Endat-encoder-/ Motor temp. evaluation
Slot 8	DIOM01	Digital I/O module
Slot 9	DIOM01	Digital I/O module

### **APPLICATION in SCIENCE**



#### Use for Vacuum Chambers



Vacuum chambers are the core of many modern research and production plants.

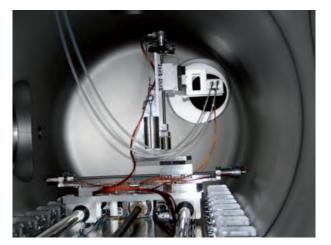
The phyMOTION<sup>TM</sup> offers additional functions for the control of also complex machines from outside the vacuum chamber such as temperature monitoring, encoder and resolver evaluation as well as linear and circular interpolation for high-precision positioning. The heating of the motors is minimised in the application by the high-quality power stage design.

The <code>phyMOTIONTM</code> with integrated power stages close to the vacuum chamber allows a low-noise monitoring of the temperatur sensors and a direct motor cable connection.

For large systems make sure that the automation for the vacuum actuators can be seamlessly integrated into the excisting PLC world despite the special requirements.

The integrated power stages can be optionally provided with temperature monitoring and encoder evaluation.

The integrated field bus interface allows both the control out of a PLC system SPS-System and the operation via spplied software, LabView interface or touch panel.



The phyMOTION<sup>TM</sup> is also successfully used in the research plant Max Planck Institute for Extraterrestrial Physics, Neuried for aligning optical systems in a vacuum.

The controller is controlled via Ethernet and LabView.



Configuration:

phyMOTION<sup>TM</sup> with external supply:

MCM01, POWM01, POWM02, 2 x I4XM01, 6 x I1AM01, 2 x DIOM01

### APPLICATION in FOOD



### XY Alignment for Cutting Baked Wafer Blanks



The phyMOTION<sup>TM</sup> is part of the circular cutting machine for wafers. Here, the baking wafers are cut with a rotating circular blade out of the baked blanks



The radius-dependent, area optimisation XY positioning of the semi-finished goods under the punching knife is controlled by the phyMOTION $^{TM}$ .

The external touch panel allows a comfortable operation.



#### Configuration:

<code>phyMOTIONTM</code> in combination with a plug-in power stage unit SLS with internal power supply: MCM02 with ETHS01, I4XM01, 2x INAM02, 1x DIOM01, 2x MSX152 power stages, external touch operator panel

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#### Configuration Example

19" rack housing with internal supply and integrated touch panel: 4 axes with indexer and I/Os

Ordering Code Example:

Slot 10

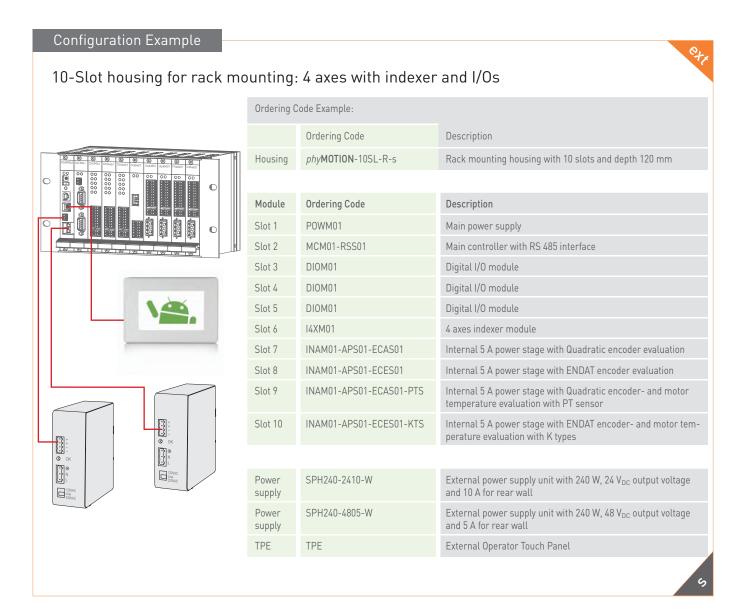
NETM01



	Ordering Code	Description
Housing	phyMOTION-21SL-p	19" rack mounting housing with 10 slots, integrated touch panel and depth 360 mm
Module	Ordering Code	Description
TPM01	TPM01	Android-based integrated touch panel
Slot 1	POWM03	Main power supply
Slot 2	MCM03-PBS01	Main controller with ProfiBus interface
Slot 3	DIOM01	Digital I/O module
Slot 4	DIOM01	Digital I/O module
Slot 5	14XM01	4 axes indexer module
Slot 6	INAM01-APS01-ECAS01	Internal 5 A power stage with Quadratic encoder evaluation
Slot 7	INAM02-MSX*-ECMS01	1 axis module for integrated MSX* power stage with resolver
Slot 8	INAM02-MSX*-ECMS01	1 axis module for integrated MSX* power stage with resolver
Slot 9	INAM02-MSX+-ECMS01	1 axis module for integrated MSX* power stage with resolver

230 V (115 V) supply with grounding connection if motor voltage >70 V  $\,$ 

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All illustrations, descriptions and technical specifications are subject to modifications, no responsibility is accepted for the accuracy of this information.

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