CSC 4020 Fundamentals of Machine Learning: Support Vector Machine I

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Outline

Motivation

2 Derivation I: large margin

3 Derivation II: hinge loss

Binary classification:

Binary classification:

• Given training data set $D = \{(\boldsymbol{x}_i, y_i)\}_{i=1}^{m}$, and $\underline{\boldsymbol{x}}_i \in \mathbb{R}^{m}, \underline{y}_i \in \{-1, +1\}$

Binary classification:



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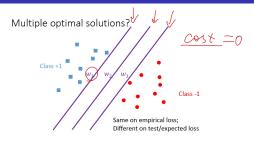
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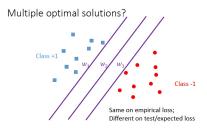
ener, we require that

• If
$$y_i = +1$$
, then $\mathbf{w}^{\top} \mathbf{x} > 0$

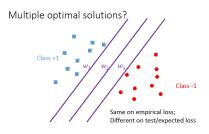
• If $y_i = -1$, then $\mathbf{w}^{\top} \mathbf{x} \leq 0$



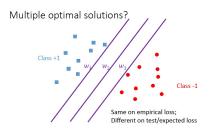
 There could be multiple decision boundaries to perfectly separate the above data.



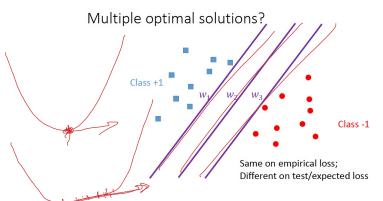
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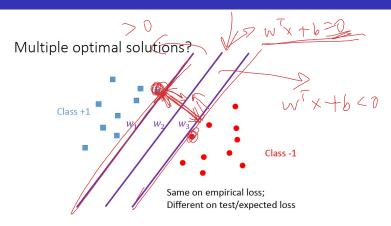
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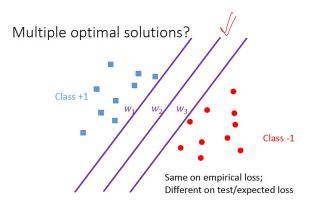
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- For regularized logistic regression, the objective function (i.e., cross entropy loss $+ \lambda \cdot \ell_2$ regularization) is strictly convex, which has the unique optimal solution. However, it depends on the trade-off hyper-parameter λ . For sure you can use cross-validation to use a suitable λ , but is there any more elegant approach?



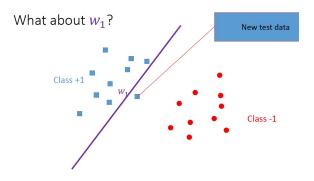
• Just following your intuition, which decision boundary do you prefer?



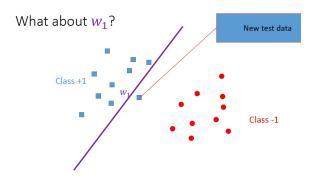
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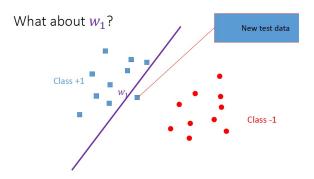
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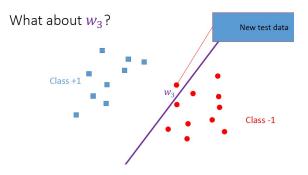
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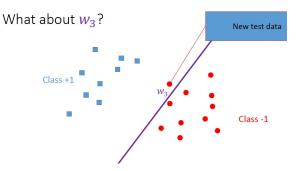
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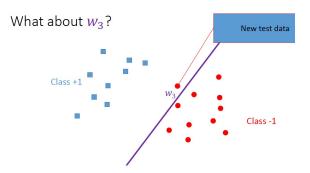
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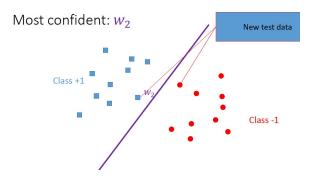
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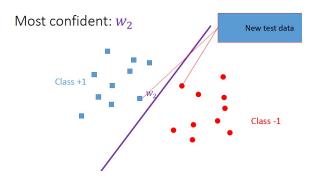
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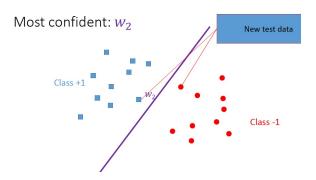
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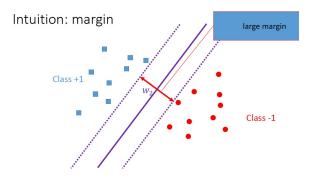


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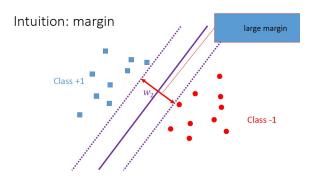
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Large margin intuition

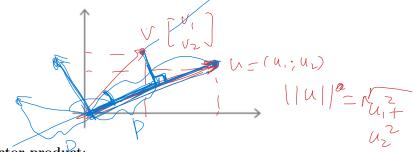


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Large margin intuition



- We introduce the concept **margin**: the distance from the closest point of positive and negative classes to the decision boundary
- The intuition is to choose the decision boundary with large margin, which is called **large margin classifier**, also called **support vector machine** (SVM)



$$\bullet \ \boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \ \boldsymbol{\nu} = \begin{bmatrix} \nu_1 \\ \nu_2 \end{bmatrix}$$



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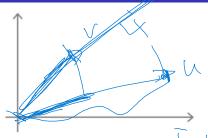
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- $\|\boldsymbol{\mu}\| = \sqrt{\mu_1^2 + \mu_2^2}$, the length of $\boldsymbol{\mu}$
- $\mu^{\top} \nu = \mu_1 \nu_1 + \mu_2 \nu_2$.



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Inner vector product:

$$\bullet \ \boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \ \boldsymbol{\nu} = \begin{bmatrix} \nu_1 \\ \nu_2 \end{bmatrix}$$

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- $\bullet \mu^{\top} \nu = \mu_1 \nu_1 + \mu_2 \nu_2$. How to represent it in the above plot?
- $\mu^{\top} \nu = p \cdot ||\mu||$, where p is the length of projection of ν on μ

- P2. [[v]]



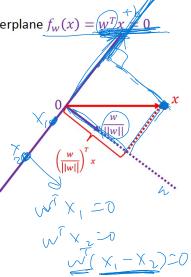
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- $\mu^{\top} \nu = \mu_1 \nu_1 + \mu_2 \nu_2$. How to represent it in the above plot?
- $\mu^{\top} \nu = p \cdot ||\mu||$, where p is the length of projection of ν on μ
- Note that if the angle between μ and ν is larger than 90°, then p<0

• Lemma 1: x has distance $\frac{|f_W(x)|}{||w||}$ to the hyperplane $f_W(x) = w^T x + 0$ Proof:

- ullet w is orthogonal to the hyperplane
- The unit direction is $\frac{w}{||w||}$
- The projection of x is $\left(\frac{w}{||w||}\right)^T x = \frac{f_w(x)}{||w||}$



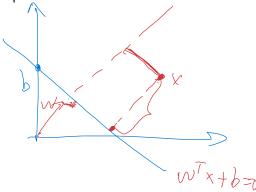


- Claim 1: w is orthogonal to the hyperplane $f_{w,b}(x) = w^T x + b = 0$ Proof:
- pick any x_1 and x_2 on the hyperplane

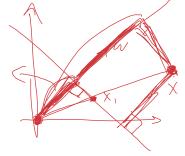
•
$$w^T x_1 + b = 0$$

$$\bullet w^T x_2 + b = 0$$

• So
$$w^T(x_1 - x_2) = 0$$



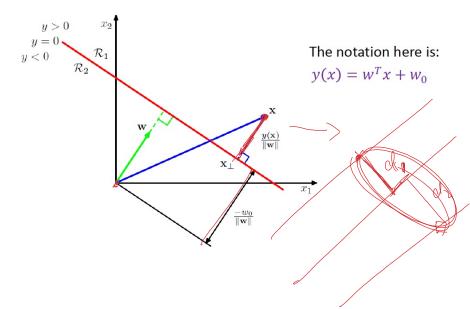
- Claim 2: 0 has distance $\frac{-b}{||w||}$ to the hyperplane $w^Tx + b = 0$ Proof:
- pick any x_1 the hyperplane
- Project x_1 to the unit direction $\frac{w}{||w||}$ to get the distance



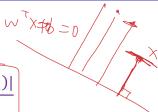
• Lemma 2: x has distance $\frac{|f_{w,b}(x)|}{||w||}$ to the hyperplane $f_{w,b}(x)=w^Tx+b=0$

Proof:

- Let $x = x_{\perp} + r \frac{w}{||w||'}$ then |r| is the distance
- Multiply both sides by \boldsymbol{w}^T and add \boldsymbol{b}
- Left hand side: $w^T x + b = f_{w,b}(x)$
- Right hand side: $w^T x_{\perp} + r \frac{w^T w}{||w||} + b = 0 + r||w||$



Large margin classification



Margin over all training data points:

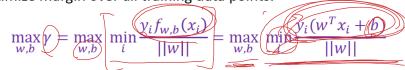
$$\gamma = \min_{i} \frac{|f_{w,b}(x_i)|}{||w||}$$

• Since only want correct $f_{w,b}$, and recall $y_i \in \{+1, -1\}$, we have

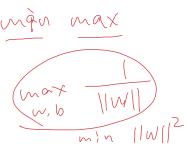
$$\gamma = \min_{i} \frac{y_{i}y_{v,b}(x_{i})}{||w||}$$

• If $f_{w,b}$ incorrect on some x_i , the margin is negative

• Maximize margin over all training data points:



• A bit complicated ...



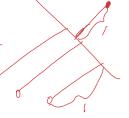
• Observation: when (ψ, \underline{b}) scaled by a factor c, the margin unchanged

$$\frac{y_i(cw^Tx_i + cb)}{||cw||} = \frac{y_i(w^Tx_i + b)}{||w||}$$

· Let's consider a fixed scale such that

$$y_{i^*}(w^T(x_{i^*})+b)=1$$

where x_{i^*} is the point closest to the hyperplane



Let's consider a fixed scale such that

$$y_{i^*}(w^Tx_{i^*}+b)=1$$

where x_{i^*} is the point closet to the hyperplane

• Now we have for all data $\underbrace{y_i(w^Tx_i+b)}_{\text{and at least for one }i \text{ the equality holds}}$

• Then the margin is $\frac{1}{||w||}$

• Optimization simplified to

$$\min_{w,b} \frac{1}{2} ||w||^{2}$$

$$y_{i}(w^{T}x_{i} + b) \ge 1, \forall i$$

• Hypothesis function:

$$h_{\boldsymbol{w}}(\boldsymbol{x}) = \frac{1}{1 + \exp(-\boldsymbol{w}^{\top}\boldsymbol{x})} = g(z)$$

where $z = \boldsymbol{w}^{\top} \boldsymbol{x}$

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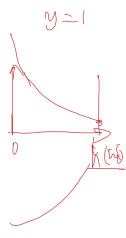
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- If y=1, we want $h_{\boldsymbol{w}}(\boldsymbol{x})\approx 1$, i.e., $\boldsymbol{w}^{\top}\boldsymbol{x}\gg 0$ If y=-1, we want $h_{\boldsymbol{w}}(\boldsymbol{x})\approx 0$, i.e., $\boldsymbol{w}^{\top}\boldsymbol{x}\ll 0$ Objective function of logistic regression

$$J(\boldsymbol{w}) = -\delta_{y=1} \log(h_{\boldsymbol{w}}(\boldsymbol{x})) - \delta_{y=-1} \log(1 - h_{\boldsymbol{w}}(\boldsymbol{x})), \tag{1}$$

where $\delta_a = 1$ if a is true, otherwise 0.



• Objective function of logistic regression

$$\frac{1}{m} \sum_{i}^{m} \left[\delta_{y^{(i)}=1} \left(-\log(h_{\boldsymbol{w}}(\boldsymbol{x}^{(i)})) \right) + \delta_{y^{(i)}=-1} \left(-\log(1-h_{\boldsymbol{w}}(\boldsymbol{x}^{(i)})) \right) \right] + \frac{\lambda}{2m} \sum_{j=1}^{n} w_{j}^{2}$$

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• Objective function of support vector machine

$$\frac{1}{m} \sum_{i}^{m} \left[\delta_{y^{(i)}=1} \operatorname{cost}_{1}(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b) + \delta_{y^{(i)}=-1} \operatorname{cost}_{-1}(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b) \right] + \frac{\lambda}{2m} \sum_{j=1}^{n} w_{j}^{2}$$

$$\equiv C \sum_{i}^{m} \left[\delta_{y^{(i)}=1} \underbrace{\operatorname{cost}_{1}(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b) + \delta_{y^{(i)}=-1} \underbrace{\operatorname{cost}_{-1}(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b)}}_{} \right] + \frac{1}{2} \sum_{j=1}^{n} w_{j}^{2}$$

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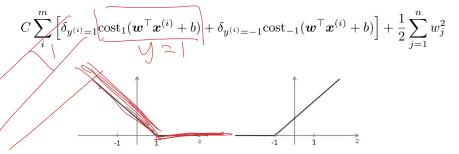
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$$\bigvee = \uparrow \setminus \qquad \qquad \bigvee = -\downarrow$$

$$\bigvee = \downarrow \downarrow$$

$$\bigvee = \downarrow$$

• Objective function of support vector machine



• If $\underline{y} = \pm 1$, we require that $\underline{\boldsymbol{w}}^{\top} \underline{\boldsymbol{x}^{(i)}} + \underline{b} \geq 1$. In other words, $\cot_1(\underline{\boldsymbol{w}}^{\top} \underline{\boldsymbol{x}^{(i)}} + \underline{b}) = 0$ if $\underline{\boldsymbol{w}}^{\top} \underline{\boldsymbol{x}^{(i)}} + \underline{b} \geq 1$

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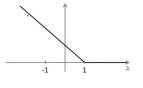
$$(0)$$

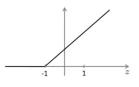
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max(0, 1- 4.Z)

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- If y = +1, we require that $\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b \leq -1$. In other words, $\cot_{-1}(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b) = 0$ if $\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b \leq -1$
- Hinge loss:

$$\max(0, 1 - y(\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b))$$
 (2)

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• However, hinge loss is non-smooth. We transform the objective function of support vector machine to the following

$$\min_{\mathbf{w}} \frac{1}{2} \sum_{j=1}^{n} w_{j}^{2}$$
s.t. $\mathbf{w}^{\top} \mathbf{x}^{(i)} + b \ge 1$, if $y^{(i)} = 1$; $\mathbf{w}^{\top} \mathbf{x}^{(i)} + b < -1$, if $y^{(i)} = -1$.

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$$\min_{\mathbf{w}} \frac{1}{2} \sum_{j=1}^{n} w_{j}^{2}
s.t. \ \mathbf{w}^{\top} \mathbf{x}^{(i)} + b > 1, \text{ if } y^{(i)} = 1; \ \mathbf{w}^{\top} \mathbf{x}^{(i)} + b < -1, \text{ if } y^{(i)} = -1.$$
(3)

• It can be simplified as follows

$$\left(\begin{array}{c}
\min_{\boldsymbol{w}} \frac{1}{2} \|\boldsymbol{w}\|^2 \\
s.t. \ \boldsymbol{y}^{(i)} (\boldsymbol{w}^{\top} \boldsymbol{x}^{(i)} + b) \ge 1, \forall i
\end{array}\right) \tag{4}$$

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 $s.t.\ y^{(i)}(\underline{\boldsymbol{w}^{\top}\boldsymbol{x}^{(i)}+b})\geq 1, \forall i$ • Utilizing $p=\frac{\underline{\boldsymbol{w}^{\top}\boldsymbol{x}+b}}{\|\boldsymbol{w}\|},$ we have

$$\underline{\boldsymbol{w}^{\top}\boldsymbol{x}^{(i)} + b = p^{(i)} \cdot \|\boldsymbol{w}\|} \tag{5}$$

• The objective function of support vector machine is transformed to

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s.t. \ y^{(i)} \left(p^{(i)} \cdot \|\boldsymbol{w}\| \right) \ge 1, \forall i$$
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where $p^{(i)}$ indicates the projection length of $\boldsymbol{x}^{(i)}$ on \boldsymbol{w} .

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• Let's see the following two decision boundaries (plot below)

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s.t. \ y^{(i)} \cdot p^{(i)} \cdot \|\boldsymbol{w}\| \ge 1, \forall i$$
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where $p^{(i)}$ indicates the projection length of $\boldsymbol{x}^{(i)}$ on \boldsymbol{w} .

- Let's see the following two decision boundaries (plot below)
- If the projection length p is larger, then $\|\boldsymbol{w}\|$ could be smaller, leading to better solution. Thus, we prefer large margin.



Reading material

Reading materials:

- Andrew Ng's note on <u>SVM</u>: https://see.stanford.edu/materials/aimlcs229/cs229-notes3.pdf
- Chapter 7.1 of Bishop's book