

# ARIMA models (3.6 - 3.9)

①

Definition 3.11 A process  $X_t$  is said to be ARIMA( $p, d, q$ ) if  $\nabla^d X_t = (1-B)^d X_t$  is ARMA( $p, q$ ).

We will write as  $\phi(B)(1-B)^d X_t = \theta(B)w_t$

If  $E(\nabla^d X_t) = \mu$ ,  $\phi(B)(1-B)^d X_t = \delta + \theta(B)w_t$ ,  $\delta = \mu(1 - \phi_1 - \dots - \phi_p)$ .

Let  $y_t = \nabla^d X_t$ , the forecasts of  $y_t$  can lead to the forecasts of  $X_t$

For example  $y_t = \nabla X_t = X_t - X_{t-1}$ , then we have

$$E(y_{n+m} | X_n, X_{n-1}, \dots, X_1) = E(y_{n+m} | y_n, y_{n-1}, \dots, y_2, X_1) \stackrel{\text{let}}{=} y_{n+m}^n$$

And hence  $y_{n+m}^n = E(X_{n+m} | X_n, \dots, X_1) - E(X_{n+m-1} | X_n, \dots, X_1)$   
 $= X_{n+m}^n - X_{n+m-1}^n$

$\Rightarrow X_{n+m}^n = y_{n+m}^n + X_{n+m-1}^n$  with initial condition  $X_{n+1}^n = y_{n+1}^n + X_n$

As in (3.86), we approximate  $\text{Var}(X_{n+m} - X_{n+m}^n)$  by  $\text{Var}(X_{n+m} - X_{n+m}^n)$

$$= \sigma_w^2 \sum_{j=0}^{m-1} \psi_j^{*2}, \text{ where } \psi^*(z) = \theta(z) / [\phi(z)(1-z)^d] = \sum_{j=0}^{\infty} \psi_j^* z^j$$

Example 3.37 ARIMA(0,1,0), i.e.  $\phi(B)=1$ ,  $d=1$ ,  $\theta(B)=1$

$$\Rightarrow \phi(B)(1-B)X_t = \delta + \theta(B)w_t$$

$$\Rightarrow y_t = X_t - X_{t-1} = \delta + w_t \text{ which is a random walk with drift}$$

For  $w_t \sim \text{iid } N(0, \sigma_w^2)$

$$y_{n+m}^n = E(\delta + w_{n+m} | y_n, y_{n-1}, \dots, y_2, X_1) = \delta$$

$$\therefore X_{n+m}^n = X_{n+m-1}^n + y_{n+m}^n = X_{n+m-1}^n + \delta = X_n + m\delta$$

m-step-ahead prediction error is given by

$$P_{n+m}^n = \sigma_w^2 \sum_{j=0}^{m-1} \psi_j^{*2} = m\sigma_w^2$$

$$\therefore \psi^*(z) = \theta(z) / [\phi(z)(1-z)^d] = \frac{1}{1-z} = \sum_{j=0}^{\infty} z^j \Rightarrow \psi_j^* = 1 \quad \forall j$$

Example 3.38 | A frequently used, and abused, forecasting method (2) called exponentially weighted moving averages (EWMA) is of the form

$$\tilde{X}_{n+1}^n = (1-\lambda)X_n + \lambda \tilde{X}_n^{n-1},$$

which only require us to retain the previous forecast value and the current observation to forecast the next time period. It is indeed based on ARIMA(0,1,1) model:  $X_t = X_{t-1} + W_t - \lambda W_{t-1}$ ,  $|\lambda| < 1$

Let  $y_t = X_t - X_{t-1} = (1-B)X_t = (1-\lambda B)W_t$ , a MA(1) model.

For MA model, we consider  $\tilde{y}_{n+m} = E(y_{n+m} | y_n, y_{n-1}, \dots)$

$$W_t = \lambda W_{t-1} + y_t = \lambda^2 W_{t-2} + \lambda y_{t-1} + y_t = \sum_{j=1}^{\infty} \lambda^j y_{t-j} + y_t$$

Note that  $\tilde{y}_{n+m} = 0$  for  $m \geq 2$

$$\begin{aligned} \tilde{y}_{n+1} &= \sum_{j=1}^{\infty} -\lambda^j y_{n+1-j} \Rightarrow \tilde{X}_{n+1} - X_n = \sum_{j=1}^{\infty} (-\lambda^j) (X_{n+1-j} - X_{n-j}) \\ &= \sum_{j=1}^{\infty} (-\lambda^j) X_{n+1-j} + \sum_{j=1}^{\infty} \lambda^j X_{n-j} \\ &= -\lambda X_n + \sum_{j=2}^{\infty} (-\lambda^j) X_{n+1-j} + \sum_{j=2}^{\infty} \lambda^{j-1} X_{n+1-j} \end{aligned}$$

$$\Rightarrow \tilde{X}_{n+1} = (1-\lambda)X_n + \sum_{j=2}^{\infty} \lambda^{j-1} (1-\lambda) X_{n+1-j} = \sum_{j=1}^{\infty} (1-\lambda) \lambda^{j-1} X_{n+1-j}$$

$$\text{or } = (1-\lambda)X_n + \lambda \sum_{j=1}^{\infty} \lambda^{j-1} (1-\lambda) X_{n-j} = (1-\lambda)X_n + \lambda \tilde{X}_n$$

Recall that  $\tilde{X}_{n+1}^n$  is formed by setting  $\sum_{j=n+1}^{\infty} \pi_j X_{n+1-j} = 0$  ( $\pi_j = (1-\lambda)\lambda^{j-1}$ )

$\therefore$  We also have  $\tilde{X}_{n+1}^n = (1-\lambda)X_n + \lambda \tilde{X}_n^{n-1}$

Now

$$(1-B)X_t = (1-\lambda B)W_t \Rightarrow X_t = \psi(B)W_t = \sum_{j=0}^{\infty} \psi_j^* W_t$$

$$\text{with } \psi(z) = \frac{1-\lambda z}{1-z} = 1 + (1-\lambda) \frac{z}{1-z} = 1 + (1-\lambda) \sum_{j=1}^{\infty} z^j \quad \text{for } |z| < 1$$

$$\therefore \psi_0^* = 1 \quad \psi_j^* = 1-\lambda \quad \text{for } j \geq 1$$

$$\therefore P_{n+m}^n \approx E(X_{n+m} - \tilde{X}_{n+m}) = \sigma_w^2 \sum_{j=0}^{m-1} \psi_j^{*2} = \sigma_w^2 [1 + (m-1)(1-\lambda)^2]$$

# Building ARIMA models

(3)

STEP 1: Plotting the data

STEP 2: Possibly transforming the data

See if the time series looks stationary. If not, we need to first transform the data. For example,

(i) increasing variance (e.g.  $X_t = 2X_{t-1}$ ), we may take  $\log$  (e.g.  $y_t = \log X_t = \log 2 + \log X_t$ )

(ii) increasing trend (e.g.  $X_t = t + W_t$ ), we may apply detrending (e.g. fitting a linear regression of  $X_t$  on  $\alpha + \beta t$ , and then consider  $y_t = X_t - \hat{\alpha} - \hat{\beta}t$ )

(iii) Random walk, we may apply differencing.

If differencing is called for, then start from  $d=1$ , and inspect the time plot of  $\nabla X_t$ . If additional differencing is necessary, then try differencing again.

Avoid overdifferencing. For example,  $X_t = W_t$  is uncorrelated by  $\nabla X_t = W_t - W_{t-1}$  is  $MA(1)$ .

STEP 3: Identifying the dependence orders of the model  $(p, d, q)$

Another way to determine  $d$  is by plotting the ACFs. Recall (3.50) for  $AR(p)$  model,  $\rho(h) = z_1^{-h} P_1(h) + z_2^{-h} P_2(h) + \dots + z_r^{-h} P_r(h)$ ,  $h \geq p$  where  $z_i$ 's are the roots of  $\phi(z) = 0$ .

If differencing is needed, then  $z_i = 1$  for some  $i$ .

$\Rightarrow \hat{\rho}(h)$  will not decay to zero fast as  $h$  increases

After  $d$  is selected, we can check the sample ACF and PACF of  $\nabla^d X_t$  to select a set of  $(p, d, q)$  candidates.



STEP 4 : Parameter estimation

STEP 5 : Diagnostics

STEP 6 : Model choice

For each candidate  $(p, d, q)$ , if the model is correct, then

$$X_{t+1} - \tilde{X}_{t+1} \sim N(0, P_{t+1}^*) \text{ if } w_t \sim \text{iid} N(0, \sigma_w^2)$$

The normal distribution for  $w_t$  is useful for constructing prediction interval for forecasts. To check this assumption, we construct

$$e_t = \frac{X_t - \hat{X}_t^{t-1}}{\hat{P}_t^{t-1}},$$

where  $\hat{X}_t^{t-1}$  and  $\hat{P}_t^{t-1}$  are the estimate of  $\tilde{X}_t^{t-1}$  (or  $\tilde{X}_t$ ) and  $P_t^{t-1}$  with estimated parameters  $\hat{\phi}$ ,  $\hat{\theta}$  and  $\hat{\sigma}_w^2$ .

To check the normality, we can plot a Q-Q plot with normal distribution.

To check the independence, beside checking if the sample ACF  $\hat{\rho}_e(h)$  are small in magnitude, we can apply the Ljung-Box test to test  $H_0: \rho_e(1) = \dots = \rho_e(H) = 0$  (Typically we choose  $H=20$ )

The test statistic is  $Q = n(n+2) \sum_{h=1}^H \frac{\hat{\rho}_e^2(h)}{n-h} \approx n \sum_{h=1}^H \hat{\rho}_e^2(h)$

Recall from Property 1.2 that  $\hat{\rho}_x(h) \xrightarrow{d} N(0, \frac{1}{n})$  if  $X_t \sim \text{iid}(0, \sigma_w^2)$

Under  $H_0$ ,  $Q \xrightarrow{d} \chi_{H-p-q}^2$ .  $\therefore H_0$  is rejected if the observed value of  $Q$  exceeds the  $(1-\alpha)$ -quantile of  $\chi_{H-p-q}^2$ .

Note that if you use the R function `Box.test` on  $\{e_t\}$ , the function will assume  $p=q=0$ .

Finally, for the remaining promising  $(p, d, q)$  models, we pick the one with minimum AIC, AICc or BIC value.

## Regression with autocorrelated errors

Consider the regression model  $y_t = \sum_{j=1}^r \beta_j z_{tj} + X_t$ ,  $t=1, \dots, n$ , and  $\{X_1, \dots, X_n\}$  are correlated. Let  $\vec{y} = (y_1, \dots, y_n)^T$ ,  $\vec{Z} = (z_{tj})_{1 \leq t \leq n, 1 \leq j \leq r}$ ,  $\vec{\beta} = (\beta_1, \dots, \beta_r)^T$  and  $\vec{X} = (X_1, \dots, X_n)^T$ . If we know that  $\vec{X} \sim N(0, \vec{P}) \Rightarrow \vec{P}^{-1/2} \vec{X} \sim N(0, \mathbf{I})$  then  $\vec{y}^* = \vec{P}^{-1/2} \vec{y} = \vec{P}^{-1/2} (\vec{Z} \vec{\beta} + \vec{X}) = (\vec{P}^{-1/2} \vec{Z}) \vec{\beta} + \vec{P}^{-1/2} \vec{X} = \vec{Z}^* \vec{\beta} + \vec{\delta}$ , where  $\vec{\delta} \sim N(0, \mathbf{I})$  and hence we can estimate  $\vec{\beta}$  by the usual OLS estimator  $\hat{\beta} = (\vec{Z}^{*T} \vec{Z}^*)^{-1} \vec{Z}^{*T} \vec{y}^* = (\vec{Z}^T \vec{P}^{-1} \vec{Z})^{-1} \vec{Z}^T \vec{P}^{-1} \vec{y}$ . However, if we don't have prior information about  $\vec{P}$ , the estimate of  $\vec{P}$  based on stationary assumption of  $\vec{X}$  can be very poor.

A better way is to assume  $X_t$  follows ARMA( $p, q$ ) model that is invertible so that  $\pi(B) X_t = w_t$ , where  $w_t \sim WN(0, \sigma_w^2)$ . Then we have

$$y_t^* = \pi(B) y_t = \sum_{j=1}^r \beta_j \pi(B) z_{tj} + \pi(B) X_t = \sum_{j=1}^r \beta_j z_{tj}^* + w_t$$

Note that  $\pi(B)$  involves parameters  $\vec{\phi} = (\phi_1, \dots, \phi_p)$  and  $\vec{\theta} = (\theta_1, \dots, \theta_q)$ . We estimate the parameters by

$$(\hat{\phi}, \hat{\theta}, \hat{\beta}) = \arg \min_{\phi, \theta, \beta} \sum_{t=1}^n \left( \pi(B) y_t - \sum_{j=1}^r \beta_j \pi(B) z_{tj} \right)^2 \quad (1)$$

The optimization can be done by R function "sarima"; see Example 3.44.

General procedure for fitting  $y_t = \sum_{j=1}^r \beta_j z_{tj} + X_t$

- (i) Compute  $\hat{\beta}_j^0$  by OLS as usual to get  $\hat{X}_t = y_t - \sum_{j=1}^r \hat{\beta}_j^0 z_{tj}$
- (ii) Identify ARMA model (choosing  $p$  and  $q$ ) for  $\hat{X}_t$ . Let  $\hat{X}_t$  follow  $\phi(B) \hat{X}_t = \theta(B) w_t \Rightarrow w_t = \pi(B) \hat{X}_t$ . If  $p=q=0$ , output  $\hat{\beta} = \hat{\beta}^0$
- (iii) Compute  $(\hat{\phi}, \hat{\theta}, \hat{\beta})$  by solving (1)
- (iv) Inspect the residuals  $\hat{w}_t$  for whiteness, and adjust the model if necessary.

(6)

A pure seasonal ARMA model,  $\text{ARMA}(P, Q)_s$ , takes the form

$$\Phi_p(B^s) X_t = \Theta_q(B^s) w_t,$$

where  $\Phi_p(B^s) = 1 - \Phi_1 B^s - \Phi_2 B^{2s} - \dots - \Phi_p B^{ps}$

$$\Theta_q(B^s) = 1 + \Theta_1 B^s + \Theta_2 B^{2s} + \dots + \Theta_q B^{qs}$$

Example 3.46

$$\text{ARMA}(1, 0)_{12}$$

$$(1 - \Phi_1 B^{12}) X_t = w_t$$

$$\Rightarrow X_t = \Phi_1 X_{t-12} + w_t$$

A multiplicative seasonal ARMA model,  $\text{ARMA}(p, q) \times (P, Q)_s$ , takes the form

$$\Phi_p(B^s) \phi(B) X_t = \Theta_q(B^s) \theta(B) w_t$$

Example 3.47

Consider an  $\text{ARMA}(0, 1) \times (1, 0)_{12}$

$$(1 - \Phi B^{12})(1) X_t = (1)(1 + \Theta B) w_t$$

$$|\Phi| < 1 \text{ and } |\Theta| < 1$$

$$\Rightarrow X_t - \Phi X_{t-12} = w_t + \Theta w_{t-1}$$

$$\gamma(0) = \text{Var}(X_t) = \text{Var}(\Phi X_{t-12} + w_t + \Theta w_{t-1}) = \Phi^2 \gamma(0) + \sigma_w^2 + \Theta^2 \sigma_w^2$$

$$\Rightarrow \gamma(0) = \frac{1 + \Theta^2}{1 - \Phi^2} \sigma_w^2$$

$$\begin{aligned} \gamma(1) = \text{Cov}(X_t, X_{t-1}) &= \Phi \text{Cov}(X_{t-12}, X_{t-1}) + \text{Cov}(w_t, X_{t-1}) + \Theta \text{Cov}(w_{t-1}, X_{t-1}) \\ &= \Phi \gamma(11) + \Theta \sigma_w^2 \end{aligned}$$

$$\gamma(h) = \Phi \gamma(h-12) \quad \text{for } h \geq 2$$

$$\therefore \text{For } h = 12m + n, \quad m \geq 0, \quad 0 \leq n \leq 12, \quad \gamma(12m + n) = \Phi^m \gamma(n)$$

$$\begin{aligned} \text{For } 2 \leq n \leq 12, \quad \gamma(n) &= \Phi \gamma(n-12) = \Phi \gamma(12-n) \\ \Rightarrow \gamma(11) &= \Phi \gamma(1) \end{aligned}$$

$$\therefore \gamma(1) = \Phi (\Phi \gamma(1)) + \Theta \sigma_w^2 \Rightarrow \gamma(1) = \frac{\Theta}{1 - \Phi^2} \sigma_w^2$$

$$\rho(1) = \frac{\gamma(1)}{\gamma(0)} = \frac{\Theta}{1 + \Theta^2}$$

$$\rho(12m) = \frac{\gamma(12m)}{\gamma(0)} = \frac{\Phi^m \gamma(0)}{\gamma(0)} = \Phi^m, \quad m = 0, 1, 2, \dots$$

$$\rho(12m-1) = \rho(12(m-1)+11) = \Phi^{m-1} \rho(11) = \Phi^m \rho(1) \quad \text{for } m = 1, 2, \dots$$

$$\rho(12m+1) = \Phi^m \rho(1) = \frac{\Theta}{1 + \Theta^2} \Phi^m \quad (\text{also true for } m=0)$$

otherwise, for  $2 \leq n \leq 10$ , so that  $12m+n$  is not of the form  $12m$  or  $12m \pm 1$

$$\rho(12m+n) = \Phi^m \rho(n) = \Phi^m \Phi \gamma(12-n) = \Phi^{m+1} \Phi \gamma(n) = \Phi^{\infty} \rho(n) = 0$$



Consider the model  $X_t = S_t + W_t$ ,  $S_t = S_{t-12} + V_t$   
where  $W_t \sim WN(0, \sigma_w^2)$   $V_t \sim WN(0, \sigma_v^2)$

Here  $S_t$  is a random walk and hence  $X_t$  is non-stationary. We can handle it by differencing.

$(1 - B^{12})X_t = X_t - X_{t-12} = S_t - S_{t-12} + W_t - W_{t-12} = V_t + W_t - W_{t-12}$   
Seasonal differencing can be indicated when ACF decays slowly at multiples of some season  $s$ , but is negligible between the periods.

A seasonal difference of order  $D$  is defined as  $\nabla_s^D X_t = (1 - B^s)^D X_t$   
 $D = 1, 2, \dots$  Typically  $D = 1$  is sufficient to obtain seasonal stationarity.

**Definition 3.12** The multiplicative seasonal ARIMA model, or SARIMA is given by  $\Phi_p(B^s)\phi(B)\nabla_s^D\nabla^d X_t = \delta + \Theta_q(B^s)\theta(B)W_t$ ,  $W_t \sim N(0, \sigma)$   
which is denoted as  $ARIMA(p, d, q) \times (P, D, Q)_s$

**Example 3.48** Consider  $ARIMA(0, 1, 1) \times (0, 1, 1)_{12}$  model with  $EX_t = 0$   
 $(1)(1)(1 - B^{12})(1 - B)X_t = (1 + \Theta B^{12})(1 + \theta B)W_t$   
 $\Rightarrow (1 - B - B^{12} + B^{13})X_t = (1 + \theta B + \Theta B^{12} + \Theta\theta B^{13})W_t$   
 $\Rightarrow X_t = X_{t-1} + X_{t-12} - X_{t-13} + W_t + \theta W_{t-1} + \Theta W_{t-12} + \Theta\theta W_{t-13}$

**Example 3.49** Consider the R data set "AirPassengers"  
STEPs 1 and 2 (Plotting and transforming)  
 $\text{plot}(X_t) \rightarrow$  increasing trend and increasing variance  
 $\log X_t = \log X_t$  (to handle increasing variance)  $\rightarrow$  stabilized variance  
 $\Delta \log X_t = \nabla \log X_t \rightarrow$  trend removed. Obvious persistence in the seasons  
( $\nabla \log X_t \approx \nabla \log X_{t-12}$ )  
 $\Delta \Delta \log X_t = \nabla_{12} \nabla \log X_t \rightarrow$  seems stationary

(8)

STEP 3: Choose  $p, q, P$  and  $Q$

Plot ACF and PACF of  $ddlx$

- Seems to be cut-offs after lag 1 for both ACF and PACF

$\Rightarrow$  try  $(p, q) = (1, 0), (0, 1)$  and  $(1, 1)$

- (Seasonal) ACF and PACF are both significant at  $h=12$ .

The clear cut-off after lag 1s ( $s=12$ ) for ACF (i.e. ACFs are very close to 0 for  $h=2s, 3s$  and  $4s$ ) suggests  $(P, Q) = (0, 1)$ .

Then compare the AIC, AICc, BIC for various  $ARIMA(p, d, q) \times (P, D, Q)_s$  models, all information criteria prefer the

$ARIMA(0, 1, 1) \times (0, 1, 1)_{12}$  model

We can further compute the residuals to see if the assumption  $u_t \sim N(0, \sigma_u^2)$  valid