# CSC 4020 Fundamental of Machine Learning: Bias-Variance Tradeoff

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- The relationship between the input features x and the output y is

$$y = h(\mathbf{x}) + e, \ e \sim \mathcal{N}(0, \sigma^2), \tag{1}$$

$$p(y|\mathbf{x}) = \mathcal{N}(h(\mathbf{x}), \sigma^2 \mathbf{I}),$$
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• The goal of machine learning is to learn a hypothesis function based on the training dataset D using some learning algorithm  $\mathcal{A}$ , *i.e.*,

$$h_D = \mathcal{A}(D)$$

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$$E_{(\boldsymbol{x},y)\sim P}[(h_D(\boldsymbol{x})-y)^2] = \int_{\boldsymbol{x}} \int_{y} (h_D(\boldsymbol{x})-y)^2 p(x,y) d\boldsymbol{x} dy$$

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$$E_{(\boldsymbol{x},y)\sim P,D\sim P^n}\left[(h_D(\boldsymbol{x})-y)^2\right] = \int_D \int_{\boldsymbol{x}} \int_{\boldsymbol{y}} (h_D(\boldsymbol{x})-y)^2 p(\boldsymbol{x},y) d\boldsymbol{x} dy dD$$

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• We are interested in evaluating the quality of a machine learning algorithm  $\mathcal{A}$  with respect to a data distribution  $P(\mathcal{X}, \mathcal{Y})$ . In the following we will show that this expression decomposes into three meaningful terms.

• The **expected test error** can be decomposed as follows

$$E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-y)^2] = E_{(\boldsymbol{x},y),D}[[h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))+(\bar{h}(\boldsymbol{x})-y)]^2]$$

$$=E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))^2]+2E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))(\bar{h}(\boldsymbol{x})-y)]$$

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$$+E_{(\boldsymbol{x},y),D}\left[(\bar{h}(\boldsymbol{x})-y)^2\right]$$

We have

$$E_{(\boldsymbol{x},y),D} \left[ (h_D(\boldsymbol{x}) - \bar{h}(\boldsymbol{x}))(\bar{h}(\boldsymbol{x}) - y) \right]$$

$$= E_{(\boldsymbol{x},y)} \left[ E_D \left[ (h_D(\boldsymbol{x}) - \bar{h}(\boldsymbol{x}))(\bar{h}(\boldsymbol{x}) - y) \right] \right]$$

$$= E_{(\boldsymbol{x},y)} \left[ (E_D \left[ (h_D(\boldsymbol{x})] - \bar{h}(\boldsymbol{x}))(\bar{h}(\boldsymbol{x}) - y) \right] = 0$$

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• Then, we have

$$E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-y)^2] = E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))^2] + E_{(\boldsymbol{x},y),D}[(\bar{h}(\boldsymbol{x})-y)^2]$$

• We also have

$$E_{(\boldsymbol{x},y),D}\left[(\bar{h}(\boldsymbol{x})-y)^{2}\right] = E_{(\boldsymbol{x},y),D}\left[\left[(\bar{h}(\boldsymbol{x})-h(\boldsymbol{x}))+(h(\boldsymbol{x})-y)\right]^{2}\right]$$

$$=E_{\boldsymbol{x},y}\left[(h(\boldsymbol{x})-y)^{2}\right] + E_{\boldsymbol{x},y}\left[\bar{h}(\boldsymbol{x})-h(\boldsymbol{x})\right]^{2} + 2E_{\boldsymbol{x},y}\left[(h(\boldsymbol{x})-y)(\bar{h}(\boldsymbol{x})-h(\boldsymbol{x}))\right]$$

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• Finally, we have

$$E_{(\boldsymbol{x},y),D}\left[(h_D(\boldsymbol{x})-y)^2\right]$$

$$=E_{(\boldsymbol{x},y),D}\left[(h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))^2\right]+E_{(\boldsymbol{x},y)}\left[(\bar{h}(\boldsymbol{x})-h(\boldsymbol{x}))^2\right]+E_{\boldsymbol{x},y}\left[(h(\boldsymbol{x})-y)^2\right]$$

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= $E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x}) - \bar{h}(\boldsymbol{x}))^2] + E_{(\boldsymbol{x},y)}[(\bar{h}(\boldsymbol{x}) - h(\boldsymbol{x}))^2] + E_{\boldsymbol{x},y}[(h(\boldsymbol{x}) - y)^2]$ 

• Above three terms are variance, bias, noise, respectively.

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• variance: Captures how much your classifier changes if you train on a different training set. How "over-specialized" is your classifier to a particular training set (overfitting)? If we have the best possible model for our training data, how far off are we from the average classifier?

$$E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-y)^2]$$

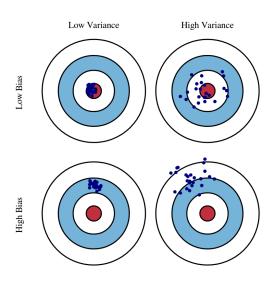
$$=E_{(\boldsymbol{x},y),D}[(h_D(\boldsymbol{x})-\bar{h}(\boldsymbol{x}))^2]+E_{(\boldsymbol{x},y)}[(\bar{h}(\boldsymbol{x})-h(\boldsymbol{x}))^2]+E_{\boldsymbol{x},y}[(h(\boldsymbol{x})-y)^2]$$

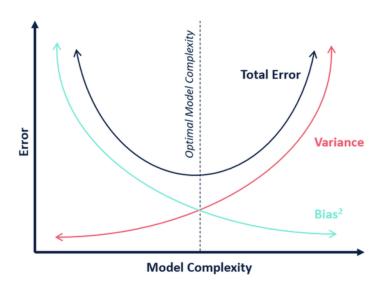
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- **Bias**: What is the inherent error that you obtain from your classifier even with infinite training data? This is due to your classifier being "biased" to a particular kind of solution (*e.g.*, linear classifier). In other words, bias is inherent to your model.

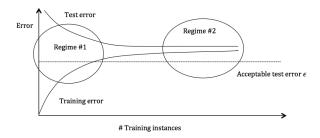
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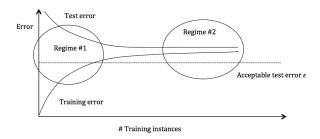
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- Noise: How big is the data-intrinsic noise? This error measures ambiguity due to your data distribution and feature representation. You can never beat this, it is an aspect of the data.









#### Regime 1 (High Variance)

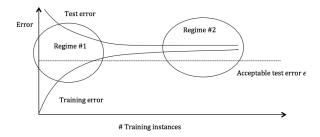
In the first regime, the cause of the poor performance is high variance.

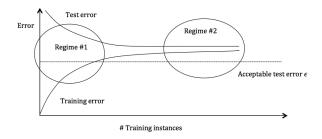
#### Symptoms:

- 1. Training error is much lower than test error
- 2. Training error is lower than  $\epsilon$
- 3. Test error is above  $\epsilon$

#### Remedies:

- · Add more training data
- Reduce model complexity -- complex models are prone to high variance





#### Regime 2 (High Bias)

Unlike the first regime, the second regime indicates high bias: the model being used is not robust enough to produce an accurate prediction.

#### Symptoms:

1. Training error is higher than  $\epsilon$ 

#### Remedies:

- · Use more complex model (e.g. kernelize, use non-linear models)
- Add features

More details can be found at https://www.cs.cornell.edu/courses/cs4780/2018fa/lectures/lecturenote12.html