

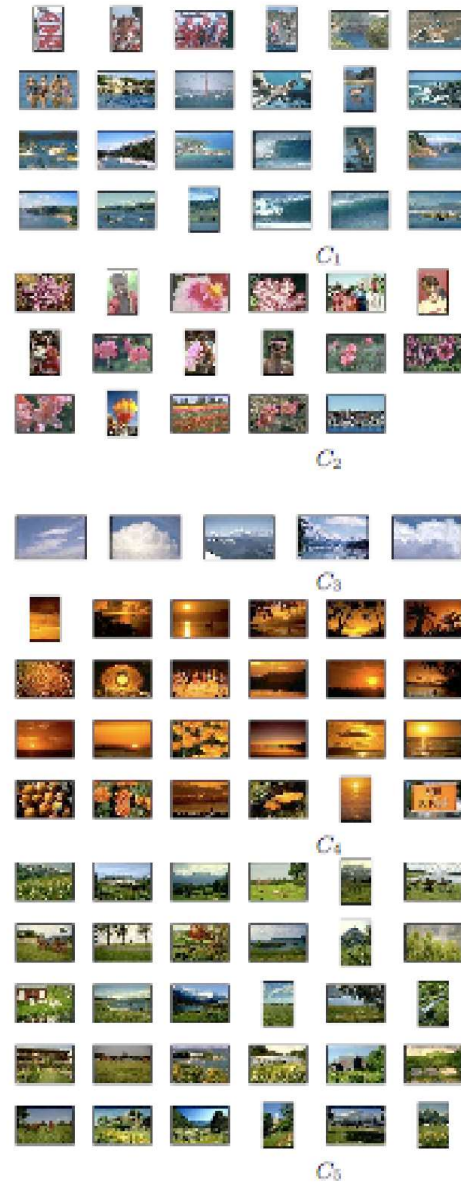
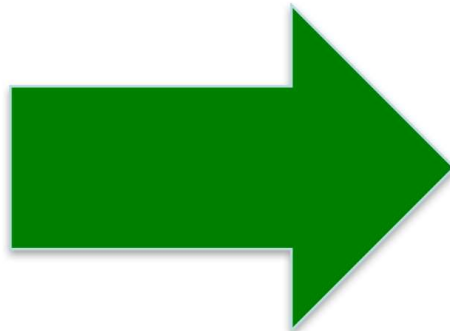
# Unsupervised Learning

ECE 449

# Unsupervised Learning

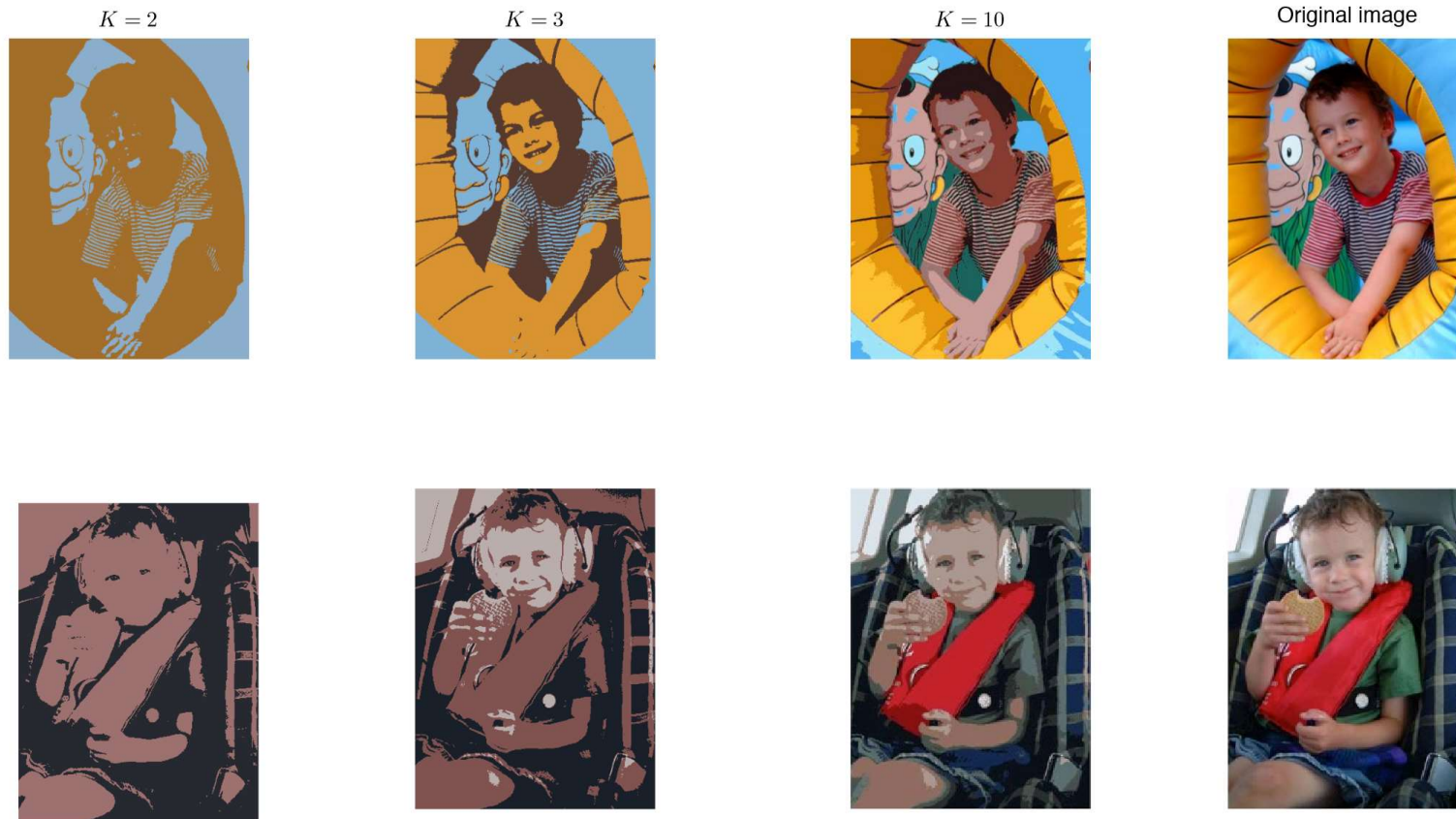
- Clustering: group similar things
  - Finding structure in data
  - Applications: group search results or customers, find anomalies
- Feature projections: dimensionality reduction
  - Feature reduction that preserves structure in data
  - Applications: improved learning, visualizing data
- General theme: no labels

# Clustering Images



[Goldberger et al.]

# Clustering for Segmentation

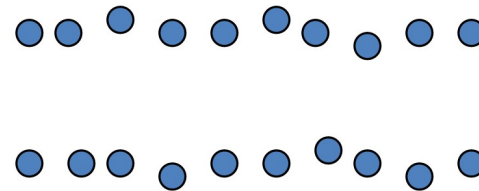
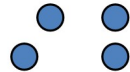
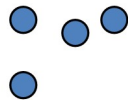


# Unsupervised Learning: Clustering

- (Dis)similarity
- Hierarchical clustering
- K-means (partitioning) and its variants
- Soft clustering (EM for GMM)
- Density based clustering
- Evaluating clusters
- Principle components analysis (PCA)

# Clustering

- Basic idea: group together similar instances
- Example: 2D point patterns



- What could “similar” mean?
  - For two different samples
  - Between a sample and a cluster

# What could Similar Mean

- With respect to another sample
  - Small distance
    - Euclidean distance (L2), city block (L1)
  - High match
    - Correlation, cosine distance (equivalent to L2)
    - Feature overlap
- With respect to the cluster
  - Close to (all, some, avg) members of the group

# Other Clustering Questions

- Will the algorithm converge?
- Will it find the true patterns in the data?
- How many clusters to pick?
- How good are the clusters?

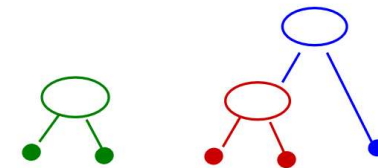
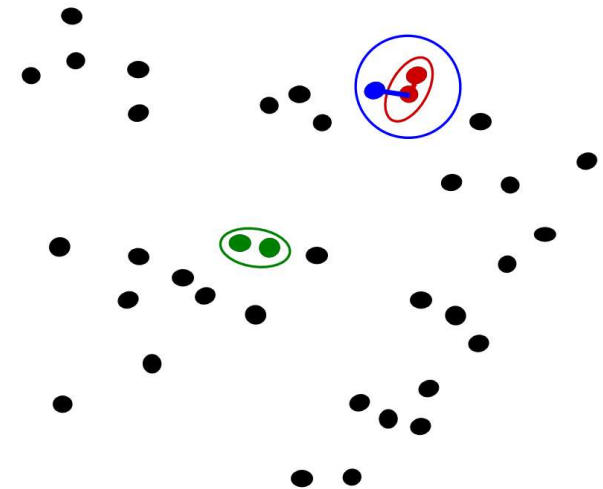


# Hierarchical Clustering

- Agglomerative
  - Iteratively group samples
  - Good for different linkages, but expensive
- Divisive clustering
  - Iteratively divide samples (iterative K-means)
  - Better decisions for a small number of clusters
- Both produce a hierarchy –good for when you don't know the # of clusters

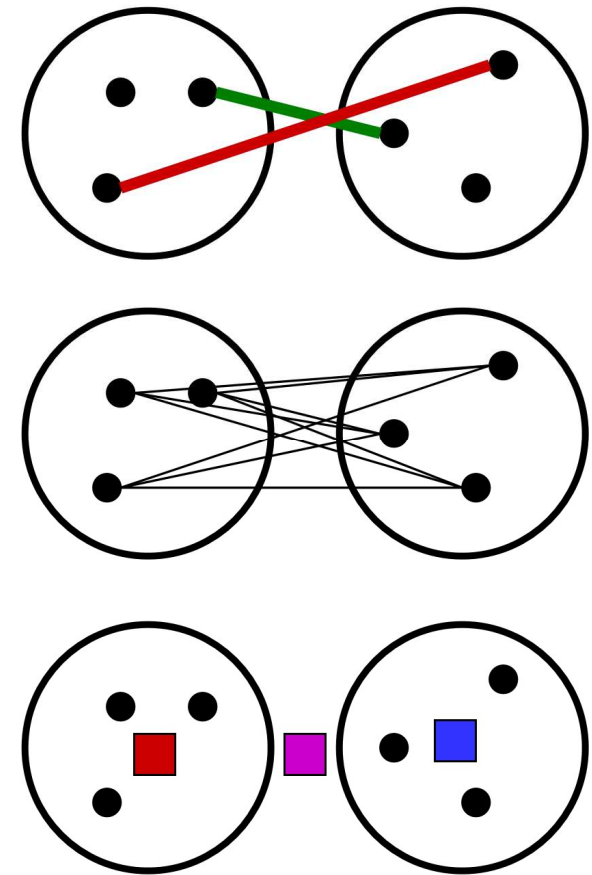
# Agglomerative Clustering

- Agglomerative clustering
  - First merge very similar instances
  - Incrementally build larger clusters out of smaller clusters
- Algorithm
  - Maintain a set of clusters
  - Initially, each instance in its own cluster
  - Repeat:
    - Pick the two closest clusters
    - Merge them into a new cluster
- Stop when there's only one cluster left
- Produces not one clustering, but a family of clusterings represented by a dendrogram

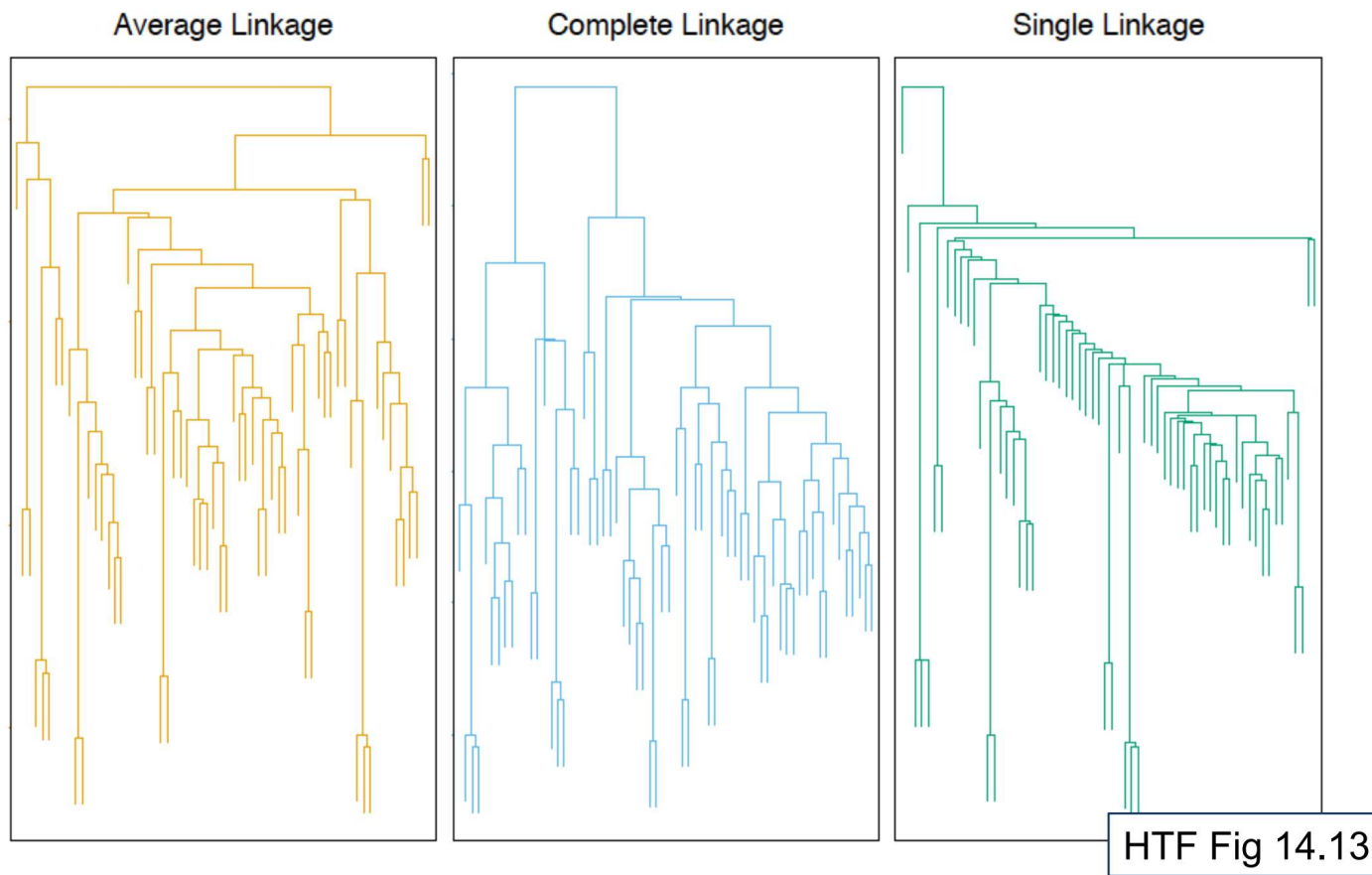


# Agglomerative Clustering

- How should we define “closest” for clusters with multiple elements?
- Many options:
  - Closest pair (single-link clustering)
  - Farthest pair (complete-link clustering)
  - Average of all pairs
  - Ward’s method (min variance, like k-means)
- Different choices create different clustering behaviors

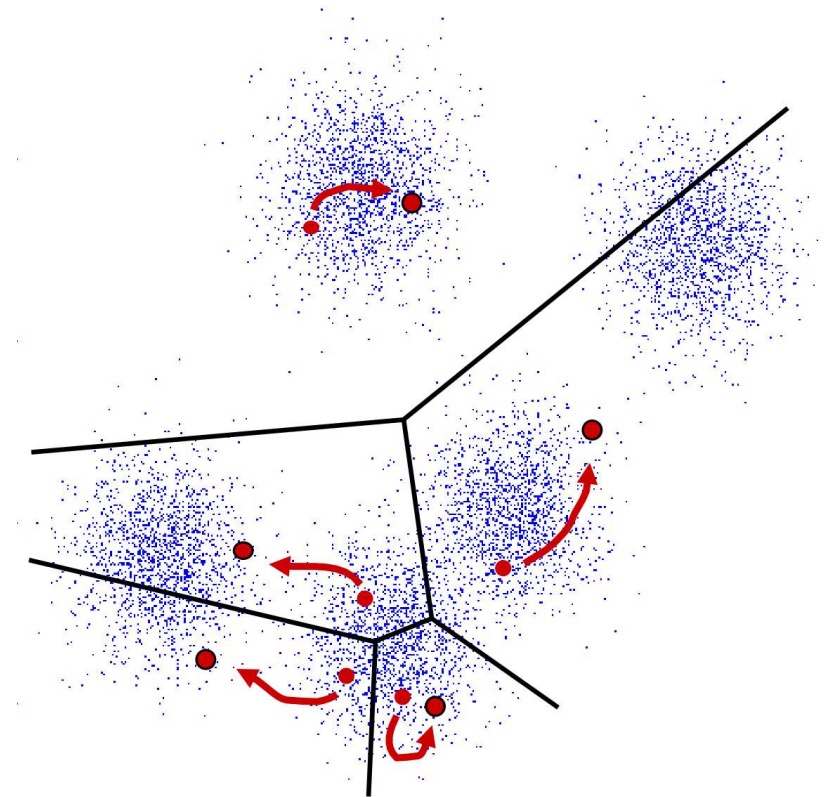


# Agglomerative Clustering: Diff Objectives



# K-Means

- An iterative clustering algorithm
  - Pick  $K$  random points as cluster centers (means),  $c^1 \dots c^k$
  - Alternate:
    - Assign each example  $x^i$  to the mean  $c^j$  that is closest to it
    - Set each mean  $c^j$  to the average of its assigned points
  - Stop when no points' assignments change



# K-Means

- Data:  $\{x^j \mid j=1..n\}$
- An iterative clustering algorithm
  - Pick K random cluster centers,  $c^1...c^k$
  - For  $t=1..T$ : [or, stop if assignments don't change]
    - for  $j = 1..n$ : [recompute cluster assignments]
  - for  $j= 1...k$ : [recompute cluster centers]

$$a^j = \arg \min_i \text{dist}(x^j, c^i)$$
$$c^j = \frac{1}{|\{i \mid a^i = j\}|} \sum_{\{i \mid a^i = j\}} x^i$$

# K-Means as Optimization

- Consider the total distance to the means

$$L(\underbrace{\{x^i\}}_{\text{points}}, \underbrace{\{a^i\}}_{\text{assignments}}, \underbrace{\{c^k\}}_{\text{means}}) = \sum_i \text{dist}(x^i, c^{a^i})$$

- Two stages each iteration:
  - Update assignments: fix means  $c$ , change assignments  $a$
  - Update means: fix assignments  $a$ , change means  $c$

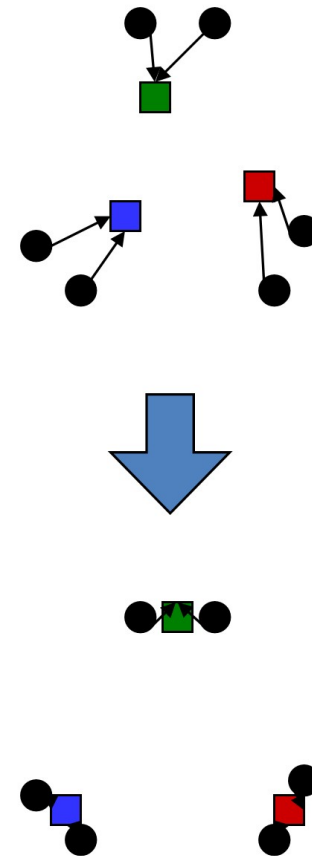
# Phase I: Update Assignments

- For each point, re-assign to closest mean

$$a^i = \arg \min_j \text{dist}(x^i, c^j)$$

- Can only decrease total distance L

$$L(\{x^i\}, \{a^i\}, \{c^k\}) = \sum_i \text{dist}(x^i, c^{a^i})$$



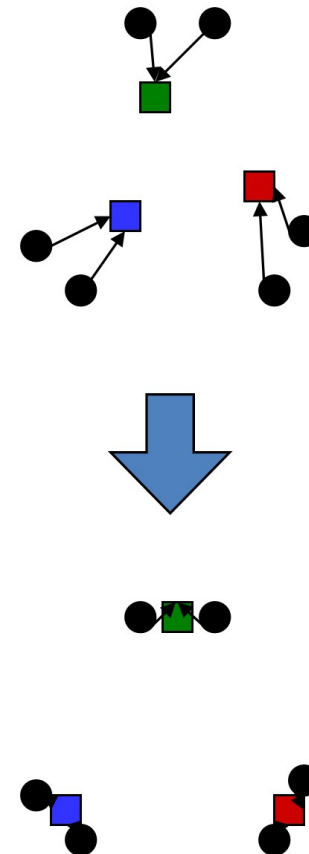


## Phase II: Update Means

- Move each mean to the average of its assigned points

$$c^j = \frac{1}{|\{i|a^i = j\}|} \sum_{\{i|a^i=j\}} x^i$$

- Also can only decrease total distance
- Fun fact: the point  $y$  with minimum squared Euclidean distance to a set of points  $\{x\}$  is their mean

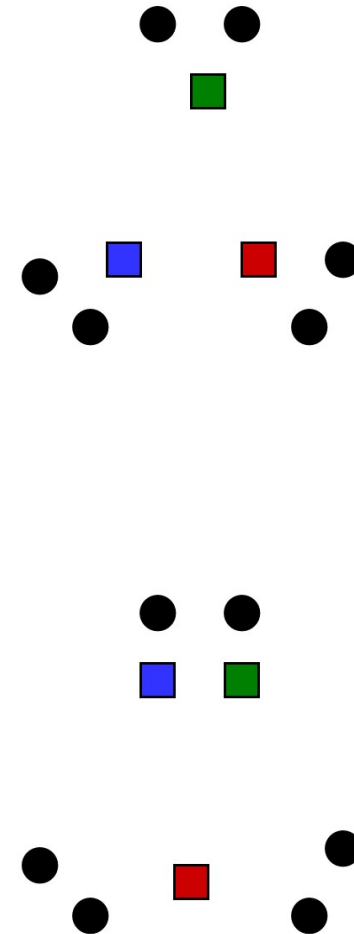


# Questions

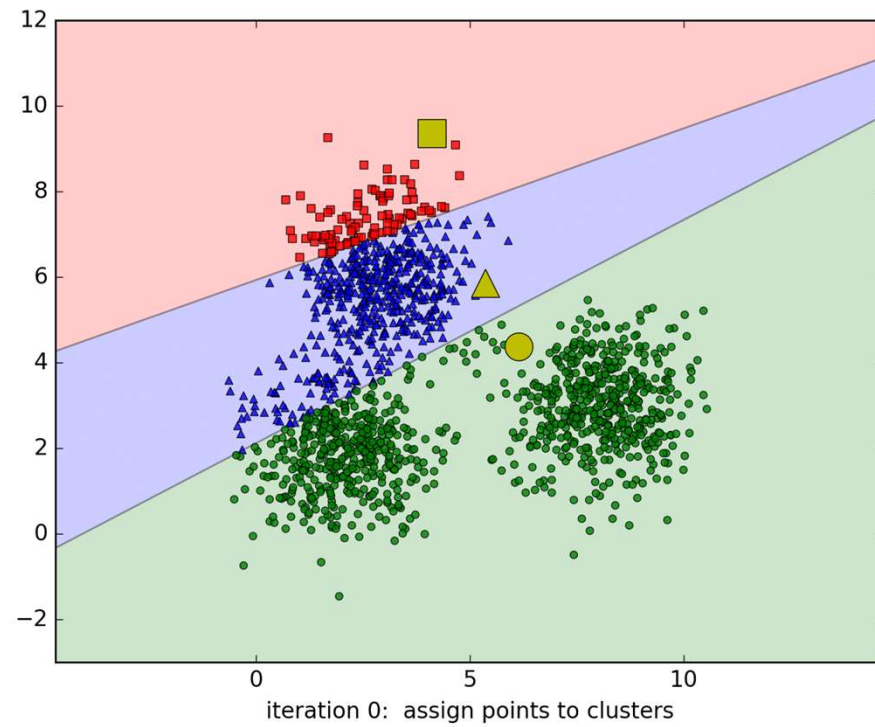
- Optimal solution?

# Initialization

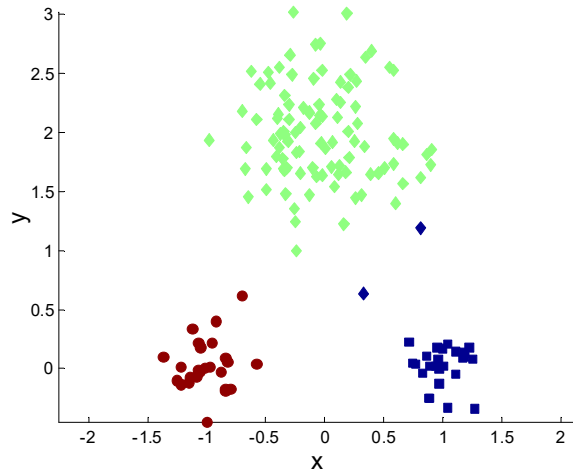
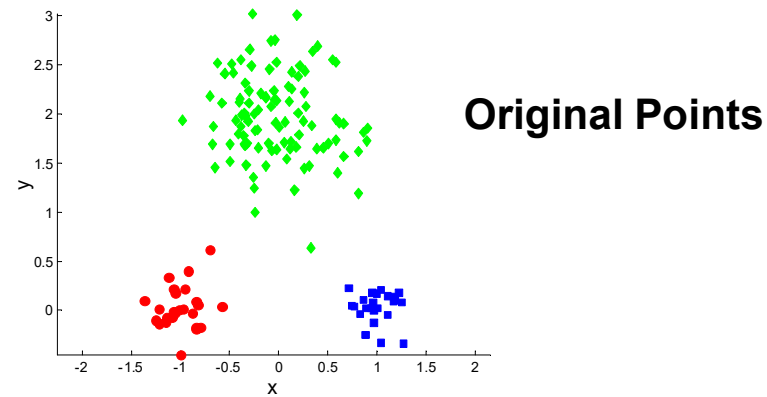
- K-means is non-deterministic
  - Requires initial means
  - It does matter what you pick!
- Various schemes for preventing this kind of thing:
  - Multiple random starts
  - Divisive clustering



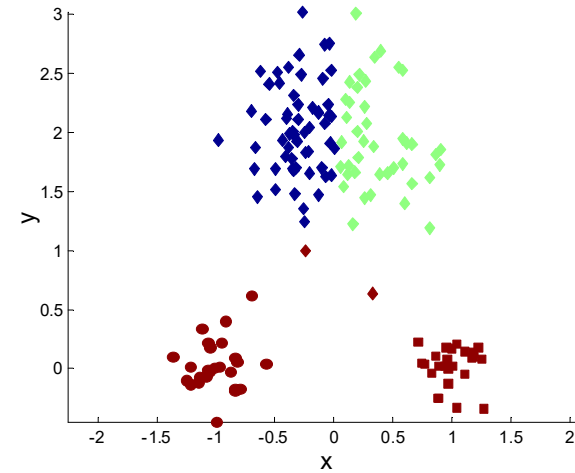
# Examples



# Importance of Choosing Initial Centroids

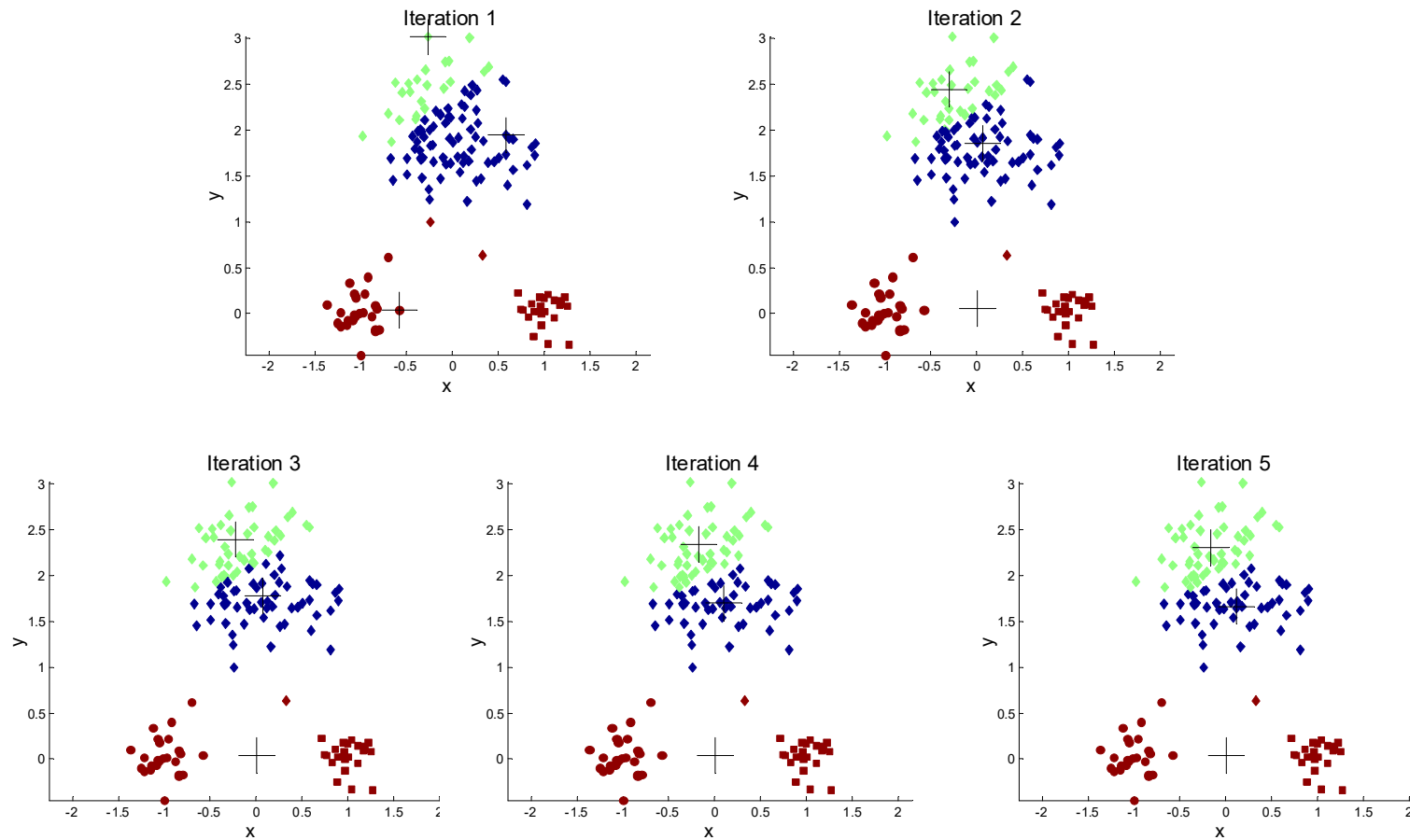


**Optimal Clustering**



**Sub-optimal Clustering**

# Importance of Choosing Initial Centroids



# Solutions to Initial Centroids Problem

- Multiple runs
  - Helps, but probability is not on your side
- Use some strategy to select the  $k$  initial centroids and then select among these initial centroids
  - Select most widely separated
    - K-means++ is a robust way of doing this selection
  - Use hierarchical clustering to determine initial centroids

# K-means++

- This approach can be slower than random initialization, but very consistently produces better results in terms of SSE
- To select a set of initial centroids,  $C$ , perform the following

Select an initial point at random to be the first centroid

For  $k - 1$  steps

For each of the  $N$  points,  $x_i$ ,  $1 \leq i \leq N$ , find the minimum squared distance to the currently selected centroids,  $C_1, \dots, C_j$ ,  $1 \leq j < k$ ,  
i.e.,  $\min_j d^2(C_j, x_i)$

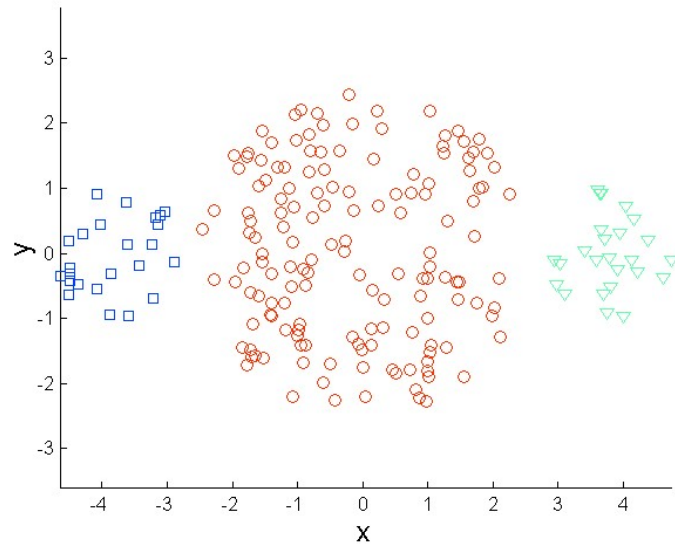
Randomly select a new centroid by choosing a point with probability  
proportional to  $\frac{\min_j d^2(C_j, x_i)}{\sum_i \min_j d^2(C_j, x_i)}$

End For

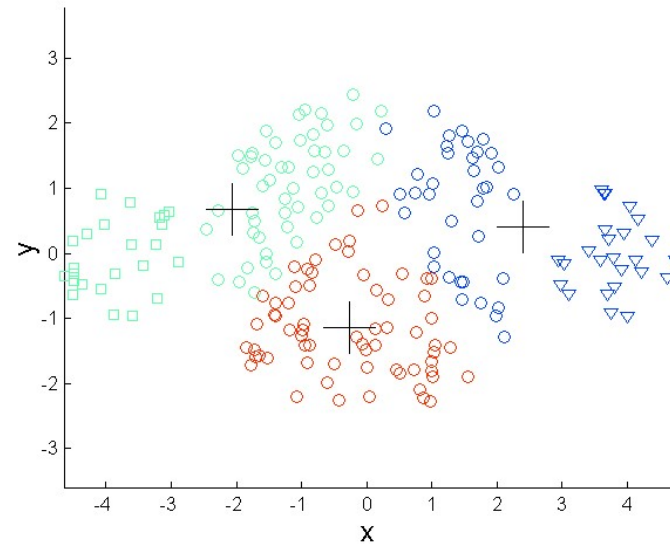


# Limitations

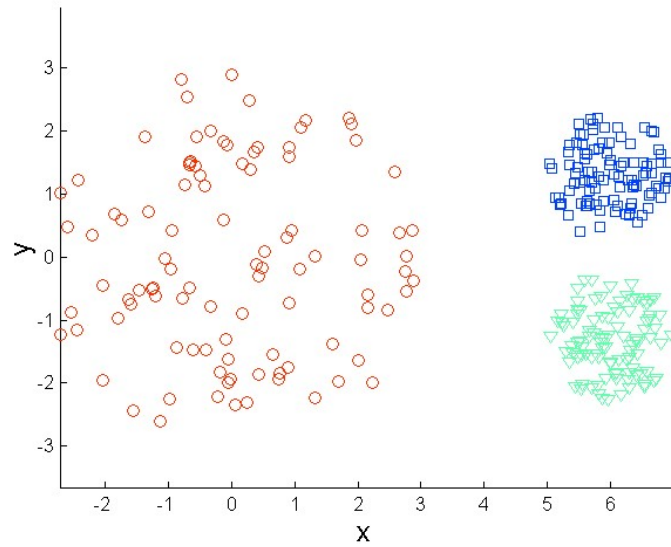
- K-means has problems when clusters are of differing
  - Sizes
  - Densities
  - Non-globular shapes
- K-means has problems when the data contains outliers.



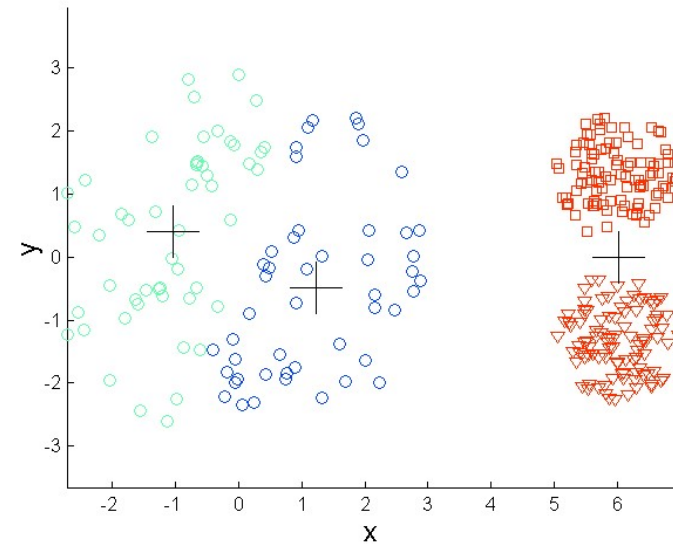
**Original Points**



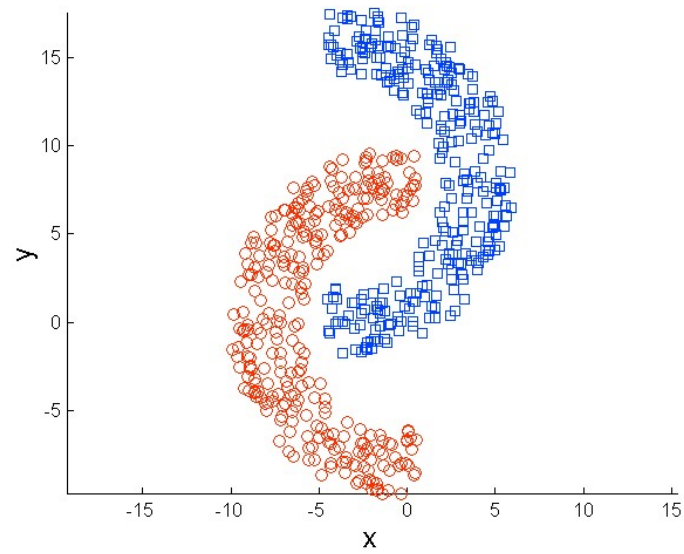
**K-means (3 Clusters)**



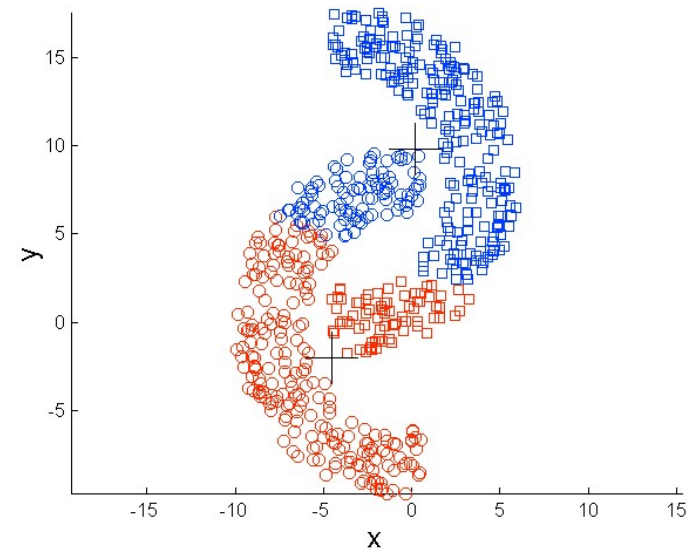
**Original Points**



**K-means (3 Clusters)**



**Original Points**



**K-means (2 Clusters)**