



# Android EL0 and EL1 debugging nightmares

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# Table of contents

- 1 Whoami
- 2 Problem statement
- 3 Preparation
  - Patching GDB
    - Cross-compiling GDB
- 4 Android userland (EL0) debugging
  - Native code debugging
    - Initiating a debugging session
  - ART debugging
    - ro.debuggable, JDWP and JDB
    - Placing runtime Java hooks
  - Automation
  - Demo
- 5 Android kernel (EL1) debugging
  - Kernel debugging subsystem internals
  - Debugging over ttyUSB
  - Debugging over ttyGS
  - Automation
  - Demo
- 6 Conclusion
- 7 Future
- 8 Questions & Thanks

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# Problem statement



# What's the problem?

- The Android ecosystem is composed of several players (hardware vendors, OEMs, carriers, etc.)
  - Endless customizations on various Android components
- Admittedly, there's a lack of:
  - Standards and procedures (e.g. OEM unlock, firmware updates)
  - Public resources (tools, documentation etc.) but for high level stuff
  - Usable interfaces (only USB, headset jack on Nexus)

# What do we need?

## Ultimate goal

Make exploit development easier

- More specific goals:
  - Be able to debug a userland (EL0) application
  - Be able to debug a kernel (EL1) on a live production device
  - Automate debugging tasks on EL0 and EL1
- We need a well designed, device agnostic methodology for doing all the above
  - Start from a developer-friendly device (e.g. Samsung S7 Exynos)
  - Generalize and apply the results to devices with stricter security policies (e.g. Samsung S7 Qualcomm)
- Push vendors to enable debugging facilities on Android phones by default!
  - According to the **Android CDD** (Compatibility Definition Document), `systrace` (which uses `fttrace`) must be supported on all devices! This a good step!

# How to get it?

## Means

Turn a production device into a fully configurable debugging environment by gradually bypassing its protections one by one

- Steps (not necessarily in this order; actual order may vary depending on the device's security features):
  - Get root
  - Boot custom kernel
  - Setup kernel debugging
  - Enable userland debugging
  - Setup userland debugging
  - Automate using ADB, JDB, GDB, Python etc.
- We assume:
  - Device has been rooted
  - SELinux has been bypassed

# So what?

- Not interested in showing off about how I exploited a specific vulnerability
  - If you can setup a functional debugging environment, then you can easily write your own exploits
  - ...but still, there's Google Project Zero if you like
- This presentation summarizes part of our 1-year research on Android debugging and exploitation
  - Many details have been left out for brevity
  - Many things might seem obvious at first sight, but keep in mind that is hard to debug a kernel when you don't have a debugger
  - Interested in discussing ideas
  - Don't hesitate to contact me if you would like to discuss privately



# Preparation



# Preparation

- Need to cross-compile GDB
  - Host Darwin/Linux, target ARM/Aarch64 (remote debugging)
  - Host ARM/Aarch64, target ARM/Aarch64 (local debugging)
- Required for both kernel and userland debugging
- Steps
  - 1 Patch GDB source
  - 2 Prepare GCC hook scripts to force PIE (where is `--enable-pie?`)
  - 3 Prepare environment (CC, CFLAGS, CXX, CXXFLAGS, etc.)
  - 4 Build and deploy

# Patching GDB

## Bug #1 - Breakpoints just don't work

- GDB developers still believe Rust support is of higher priority than ARM/Aarch64 breakpoint support
- Breakpoints hit on debuggee but never caught on debugger
  - `CORE_ADDR` for stored Thumb mode breakpoint holds address with low bit set, while `CORE_ADDR` of current PC does not
  - `ptrace(PTRACE_CONT, ...)` signal delivery not working
  - Quoting `ptrace(2)`: "If data is nonzero, it is interpreted as the number of a signal to be delivered to the tracee;"
  - Debuggee remains in a frozen state forever
    - `kill -CONT` also caught by GDB and never delivered
    - Debugger process acts like parent in signal delivery

# Patching GDB

Bug #1 - Breakpoints just don't work

```

1  int
2  breakpoint_address_match (struct address_space *aspace1, CORE_ADDR addr1,
3                           struct address_space *aspace2, CORE_ADDR addr2)
4  {
5      /* If target is ARM and this is a Thumb breakpoint, adjust PC. */
6      if (gdbarch_bfd_arch_info (target_gdbarch ())->arch == bfd_arch_arm
7          && (addr1 & 1))
8          addr1 -= 1;
9
10     return ((gdbarch_has_global_breakpoints (target_gdbarch ())
11             || aspace1 == aspace2)
12            && addr1 == addr2);
13 }
```

# Patching GDB

## Bug #2 - CPSR bit width

- On Aarch64, representing PSTATE requires more than 32-bits (see the ARMv8 specification, chapter D1.7), but GDB's XML configuration specifies CPSR for Aarch64 as a 32-bit quantity
- Confuses GDB when connected to KGDB

`gdb/features/aarch64-core.xml`

```
- <reg name="cpsr" bitsize="32"/>  
+ <reg name="cpsr" bitsize="64"/>
```

# Patching GDB

## Other modifications

- Made other minor modifications so that GDB could be cross-compiled with a standard NDK standalone toolchain
  - Fixed use of undefined `ptrace()` constants
  - Replaced undefined `W_STOPCODE()` macro with `WSETSTOP()`
  - Made GDB treat `td_thrhandle_t` as opaque object
  - Removed unresolved calls to `__fsetlocking()` (why do we need this anyway?)
  - Removed unresolved calls to `setpwent()`
  - Tweaked a few Makefiles
- Hopefully all this will be published in the near future

# Cross-compiling GDB

Forcing PIE

Compiler trickery used to actually compile GDB as PIE

## Prepare GCC hook script

```
$ ls -l cchook-arm/
total 80
lrwxr-x--- ... cc -> cchook.sh
-rwxr-x--- ... cchook.sh
-rw-r----- ... env.sh
lrwxr-x--- ... g++ -> cchook.sh
lrwxr-x--- ... gcc -> cchook.sh
lrwxr-x--- ... ld -> cchook.sh
lrwxr-x--- ... real_cc -> real_gcc
lrwxr-x--- ... real_g++ -> /toolchain-arm/bin/arm-linux-androideabi-g++
lrwxr-x--- ... real_gcc -> /toolchain-arm/bin/arm-linux-androideabi-gcc
lrwxr-x--- ... real_ld -> /toolchain-arm/bin/arm-linux-androideabi-ld
```

# Cross-compiling GDB

Forcing PIE

cclink.sh

Prepare and export  
environment variables

./configure && make

Use environment variables

\$CC

\$CXX

cchook.sh

Modify compiler  
command line arguments

Follow symlinks

Original  
\$CC

Original  
\$CXX



# Cross-compiling GDB

Forcing PIE

## cchook.sh

```
local extra_ops=
if [[ "$program" =~ -?g?cc$ || "$program" =~ -?g\+\+$ ||
    "$program" =~ -?ld$ ]]; then
    local link=1
    local shared=0
    for opt in "$@"; do
        if [[ "$opt" = "-shared" ]]; then
            shared=1
        elif [[ "$opt" = "-c" ]]; then
            link=0
        fi
    done

    if [[ $link -eq 1 && $shared -eq 0 ]]; then
        extra_ops="-pie"
    fi
fi

...

"$program" $@ $extra_ops
```

# Cross-compiling GDB

## Forcing PIE

### Prepare environment

```
$ cd cchook-arm/  
$ export CROSS_COMPILE=/toolchain-arm/bin/arm-linux-androideabi-  
..  
  
$ export d=$(pwd)  
$ export CC="$d/gcc"  
$ export CXX="$d/g++"  
$ export LD="$d/ld"  
$ export AS="$${CROSS_COMPILE}as"  
$ export AR="$${CROSS_COMPILE}ar"  
$ export RANLIB="$${CROSS_COMPILE}ranlib"  
$ export NM="$${CROSS_COMPILE}nm"  
$ export OBJDUMP="$${CROSS_COMPILE}objdump"
```

# Cross-compiling GDB

## Building

- Always use well defined triplets/quadruplets in `configure` options
- Not doing so may break certain Makefiles

### Prepare environment

```
$ ./configure --prefix=/usr --host=arm-none-linux-androideabi \  
--target=arm-none-linux-androideabi  
$ ./configure --prefix=/usr --host=aarch64-none-linux-androideabi \  
--target=aarch64-none-linux-androideabi  
$ make
```

# Cross-compiling GDB

## Building

Voila!

### Compiled binaries

```
$ find bins/ -type f
bins/host-aarch64-target-aarch64/gdb-aarch64
bins/host-aarch64-target-aarch64/gdbserver-aarch64
bins/host-arm-target-arm/gdb-arm
bins/host-arm-target-arm/gdbserver-arm
bins/host-darwin-target-aarch64/gdb
bins/host-darwin-target-arm/gdb
```

# Android userland (EL0) debugging



# Initiating a debugging session

GDB 101

Once our modified GDB has been compiled, debugging a userland application is just a matter of firing gdbserver

## Debuggee (Samsung S7)

```
# cd /data/local/tmp  
# ./gdbserver-arm --attach *:31337 $(pgrep whatever)
```

## Debugger (Ubuntu)

```
$ adb forward tcp:31337 tcp:31337  
$ gdb  
...  
  
(gdb) target remote 127.0.0.1:31337
```

- Ctrl+C will not work (see how signal delivery works on `ptrace()`'d processes for more information)
- Use `kill -TRAP` instead

## Debugger (Ubuntu)

```
(gdb) set pagination off
(gdb) handle SIG33 nostop
(gdb) continue
```

## Debuggee (Samsung S7)

```
# kill -TRAP $(pgrep whatever)
```

# ro.debuggable, JDWP and JDB

Enabling ro.debuggable

- Unfortunately `ro.debuggable` is not set on production devices
- Property service managed by `init`
- On newer kernels we can `ptrace()` PID 1, and modify the property store mapped from `/dev/__properties__`
  - Format varies depending on the Android version
  - Tree vs. array storage
- Of course, we need root and SELinux bypass first



# ro.debuggable, JDWP and JDB

Enabling ro.debuggable

## Debuggee (Samsung S7)

```
$ ./setprop
[*] Getting root ;)
[*] I haz UID 0
[*] Attaching to PID 1
[*] Locating property tree node
[*] Currently @node "", left=+0, right=+0, children=+0x14
[*] Currently @node "ro", left=+0x5734, right=+0x1AA8, children=+0x2C
[*] Traversing /dev/__properties__ tree
[*] Currently @node "ro", left=+0x5734, right=+0x1AA8, children=+0x2C
...
[*] Traversing /dev/__properties__ tree
...
[*] Currently @node "debuggable", left=+0, right=+0x16ED0, children=+0
[*] Current value "0"
[*] Updating value
[*] Verifying
[*] Updated value "1"
[*] Success!
```

# ro.debuggable, JDWP and JDB

## Attaching

Last but not least, attach to the JVM using JDB

### Debugger (Ubuntu)

```
$ adb jdwp  
...  
$ adb forward tcp:31337 jdwp:whatever  
$ jdb -attach 127.0.0.1:31337
```

- JDB is practically unusable when you don't have the source
  - No way to insert breakpoints at arbitrary locations
  - No way to examine locals (only `this` is available)
- JDB is unusable anyway
  - Super difficult to handle overloaded methods
  - No way of automating debugging tasks (combining `monitor` and `read` commands randomly switches between threads)
  - Obviously, `redefine` not implemented in ART
  - I guess not even JDB developers use JDB
- How come noone solved this problem yet?

# Placing runtime Java hooks

Public domain tools

- The limitations of JDB can only be avoided using a Java hooking framework
- Unfortunately **Cydia substrate** just doesn't work
  - ...and Saurik won't even reply to e-mails but who gives a fuck anyway?
- **Xposed** modifies the filesystem and triggers **dm-verity** failures
- **ARTDroid** kept crashing (found several problems in its source code in just a few seconds)
- **Frida** has limited ART support but its API looks really good
- **Legend** also seems like a good choice
- Didn't have enough time to evaluate all these frameworks (TODO)

# Placing runtime Java hooks

Our technique

- Developed a simple DSO which can be injected in an Android process using **injectoid** to hook arbitrary Java methods
  - Technique is almost similar to Legend's
- Steps:
  - 1 Get Java VM pointer using JNI's `JNI_GetCreatedJavaVMs()`
  - 2 Hook `AttachCurrentThread()` to catch newly created threads
  - 3 Wait until a thread that uses a class loader other than Java's default is detected
  - 4 Unhook `AttachCurrentThread()`
  - 5 Load custom Java classes from custom JAR/APK using application's class loader
    - This is where our custom Java hooks should be defined
  - 6 Modify ART's **ArtMethod** instances to redirect application methods to our Java hooks

# Placing runtime Java hooks

## Automation

- Still haven't implemented any automation features
- We will have a look at Frida's ART hooking support first and act accordingly
  - Patch/extend Frida
  - Develop custom tool with Python API

DEMO

## Android kernel (EL1) debugging





# Kernel debugging subsystem internals

## Kernel debugging core

- Kernel debugging subsystem at `kernel/debug/debug_core.c` (comes with GDB stub at `kernel/debug/gdbstub.c`)
- Kernel parameter parsing in `drivers/tty/serial/kgdboc.c` (calls `param_set_kgdboc_var()`)
- Calls `configure_kgdboc()` that locates the appropriate TTY polling driver (more on this later)
- Calls `kgdb_register_io_module()` that installs the struct `kgdb_io` callbacks for GDB protocol I/O
  - They just off-load the actual task to the TTY driver
- Calls `kgdb_register_callbacks()` which also registers the KGDB console if enabled
  - It's just a `printk()`-supported console driver
  - Use the `kgdb-agent-proxy` or a custom Python script to receive, parse and display messages as GDB just ignores them (this world is full of surprises)

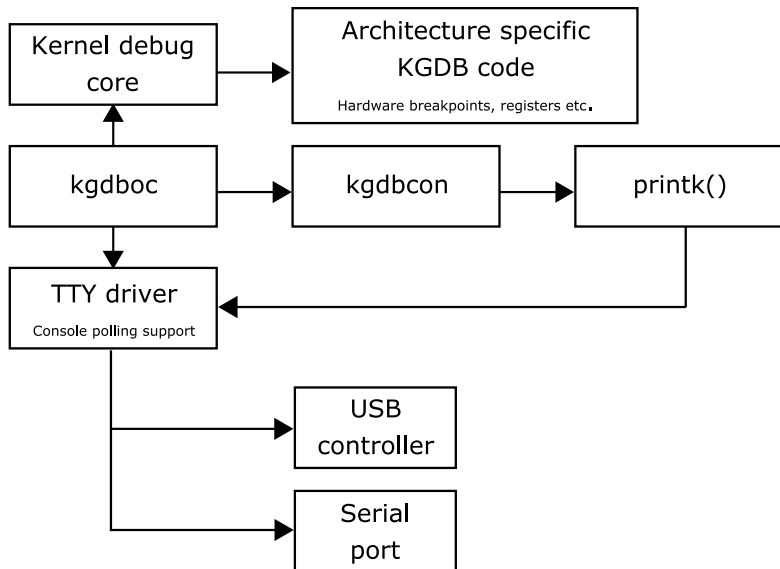
# Kernel debugging subsystem internals

TTY operations & console polling support

- TTY drivers that support console polling should implement the following callbacks in their `struct tty_operations`
  - `poll_init()` - Receives the string passed to `kgdboc` kernel boot parameter
    - On the contrary to what [kernel-parameters.txt](#) mentions, this boot parameter can have any format
  - `poll_get_char()` - Synchronously read one character (should block until the character is received)
  - `poll_put_char()` - Synchronously write one character (should block until the character has been received from the remote end)
- More information can be found in [Documentation/serial/driver](#)
- Quoting [Using kgdb and the kgdb internals](#) by Jasson Wessel, Tom Rini & Amit S. Kale: "Keep in mind that polling hooks have to be implemented in such a way that they can be called from an atomic context and have to restore the state of the UART chip on return such that the system can return to normal when the debugger detaches."

# Kernel debugging subsystem internals

## Architecture



# Kernel debugging subsystem internals

## Sample

### Sample driver at drivers/tty/serial/serial\_core.c

```
1  _____ TTY operations _____  
2  static const struct tty_operations uart_ops = {  
3      ...  
4      #ifdef CONFIG_CONSOLE_POLL  
5          .poll_init = uart_poll_init,  
6          .poll_get_char = uart_poll_get_char,  
7          .poll_put_char = uart_poll_put_char,  
8      #endif  
9  };
```

# Kernel debugging subsystem internals

## Prerequisites

### KGDB prerequisite

To enable KGDB, we first need to implement console polling support in the available serial driver(s)

#### ■ Steps

- 1 Locate the serial port hardware
- 2 Locate serial driver in the Linux kernel source tree
- 3 Implement console polling support
- 4 Recompile and boot custom kernel (boot parameters can be hardcoded into the kernel using `CONFIG_CMDLINE`)

#### ■ Let's have a look at `ttyUSB` and `ttyGS`

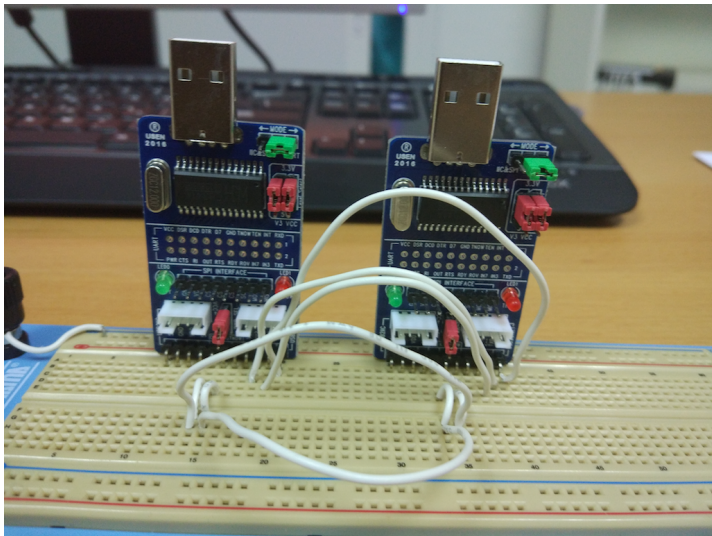
# Debugging over ttyUSB

Idea #1

- Most (all?) Android devices come with support for USB OTG (On-The-Go)
- Why not plug an all-in-one USB to SPI/I2C/UART YSUMA01-341A?
  - Driver source already in vanilla at `drivers/usb/serial/ch341.c`
- Device may or may not function depending on device's kernel configuration
  - Requires `USB_SERIAL` & `USB_SERIAL_CH341`
- Bridged two USB-to-serial adapters using a raster board and cables (could have been better with dupont cables though)
  - Connected one end to Android device with custom kernel and the other end on an Ubuntu Desktop host
- Let's use `tttyUSB0` for KGDB I/O

# Debugging over ttyUSB

Test setup



# Debugging over ttyUSB

## Test setup

Issued the following commands but no data arrived on the debugger host

### Debugger (Ubuntu)

```
# stty -F /dev/ttyUSB0 115200 raw -echo crtscts  
# cat /dev/ttyUSB0
```

### Debuggee (Samsung S7)

```
# stty -F /dev/ttyUSB0 115200 raw -echo crtscts  
# echo -n test > /dev/ttyUSB0
```



# Debugging over ttyUSB

## USB-to-serial subsystem modifications

- CH341 is part of the kernel's generic USB-to-serial support
  - Bulk transfer mode used by default by the generic driver (even though USB device descriptors exported by the device also define an interrupt endpoint)
  - CH341 bulk transfer size is 16 bytes
- Modified `usb/serial/generic.c` to pad messages to 16 bytes and prefix them with a size byte
  - Messages similarly unpacked on the other side
  - Modified `generic.c` should also be used on the host side
- Also made minor modifications to `ch341.c`
- Alternatively we could have used FTDI TTL-232RG

# Debugging over ttyUSB

## USB-to-serial subsystem modifications

- Written URBs (USB Request Blocks) should be padded and prefixed with the actual message length to avoid caching on the hardware side

```
1  _____ usb_serial_generic_write_start() _____  
2  urb = port->write_urbs[i];  
3  memset(urb->transfer_buffer, 0, port->bulk_out_size);  
4  count = port->serial->type->prepare_write_buffer(port, urb->transfer_buffer,  
5  port->bulk_out_size - 1);  
6  *((char *)urb->transfer_buffer + port->bulk_out_size - 1) =  
7  (char)(count & 0xff);  
8  urb->transfer_buffer_length = port->bulk_out_size;
```

- Read URBs should be unpacked on the receiving side

```
1  _____ usb_serial_generic_process_read_urb() _____  
2  count = ch[urb->actual_length - 1];  
3  if(count < 0 || count >= port->bulk_in_size)  
4  {  
5      ...  
6  }  
7  urb->actual_length = count;
```

# Debugging over ttyUSB

USB-to-serial subsystem modifications

## Hook process\_read\_urb() to append data in a K\_FIFO

```
1  static int serial_poll_init(struct tty_driver *driver, int line, char *options)
2  {
3      ...
4
5      kgdb_port = usb_serial_port_get_by_minor(line);
6      ...
7
8      spin_lock_irqsave(&kgdb_port->lock, flags);
9
10     process_read_urb = kgdb_port->serial->type->process_read_urb;
11     kgdb_port->serial->type->process_read_urb = process_read_urb_hook;
12
13     write_bulk_callback = kgdb_port->write_urbs[0]->complete;
14     for(i = 0; i < ARRAY_SIZE(kgdb_port->write_urbs); i++)
15         kgdb_port->write_urbs[i]->complete = write_bulk_callback_hook;
16
17     spin_unlock_irqrestore(&kgdb_port->lock, flags);
18     ...
19
20     kgdb_port->serial->type->open(NULL, kgdb_port);
21     ...
22 }
```

# Debugging over ttyUSB

USB-to-serial subsystem modifications

## Use K\_FIFO for KGDB I/O

```
1 static int serial_poll_get_char(struct tty_driver *driver, int line)
2 {
3     int ch = 0;
4
5     kgdb_unlock();
6
7     if(kfifo_is_empty(&kgdb_fifo) ||
8         kfifo_out_locked(&kgdb_fifo, (char *)&ch, 1, &kgdb_fifo_lock) < 1)
9         ch = NO_POLL_CHAR;
10
11     kgdb_lock();
12     return ch;
13 }
```

```
1 static void serial_poll_put_char(struct tty_driver *driver, int line, char ch)
2 {
3     kgdb_unlock();
4
5     atomic_set(&sent, 0);
6     while(kfifo_is_full(&kgdb_port->write_fifo) ||
7         usb_serial_generic_write(NULL, kgdb_port, &ch, 1) < 1) {};
8
9     while(atomic_read(&sent) != 1) {};
10
11     kgdb_lock();
12 }
```

# Debugging over ttyUSB

Pros & Cons

## ■ Pros

- 1 Reliable

## ■ Cons

- 1 Requires special hardware
  - 2 Requires kernel source code modifications on both communicating ends
  - 3 Slow even when operated on 115200 bauds
- ## ■ Ideally we would like a solution which is faster and less complex
- Certain debugging tasks require large volumes of data transfer (e.g. locating a pattern in memory)
  - Trade some reliability in favor of speed

# Debugging over ttyGS

Idea #2

- Most (all?) Android devices come with **USB gadget** support

## Serial gadget device

```
$ ls -la /dev/ttyGS0  
crw-rw---- system system 229, 0 2016-02-10 22:39 ttyGS0
```

- Source code for serial port USB gadget contained in two files:
  - `drivers/usb/gadget/function/u_serial.c`
  - `drivers/usb/gadget/function/f_serial.c`
- Primarily used for communication between a gdbserver running on the device and a GDB client on the host
- Let's use `ttyGS0` for KGDB I/O
- Work already published by **Jack Tang of Trend Micro**
  - His solution is slightly more elegant than ours

# Debugging over ttyGS

Serial gadget modifications

On initialization, read the DWC3 IRQ number

## Find DWC3 IRQ number

```
# grep dwc3 /proc/interrupts
245:    2204    0    0    0    0    0    GIC 245    dwc3
# cat /proc/irq/245/smp_affinity
0f
```

```
1 static int gs_poll_init(struct tty_driver *driver, int line, char *options)
2 {
3     ...
4
5     dwc3_irq = DWC3_IRQ_DEFAULT;
6     if(options != NULL)
7         dwc3_irq = (int)simple_strtol(options, NULL, 10);
8     ...
9 }
```

# Debugging over ttyGS

## Serial gadget modifications

Running in atomic context; schedule DWC3 I/O IRQ to fire on a different CPU

```
1 static int gs_poll_get_char(struct tty_driver *driver, int line)
2 {
3     ...
4     kgdb_unlock();
5     ...
6     while(kfifo_is_empty(&kgdb_fifo) ||
7           kfifo_out_locked(&kgdb_fifo, &ch, 1, &kgdb_fifo_lock) < 1)
8     {
9         cpu = task_cpu(current);
10        cpumask_setall(&mask);
11        cpumask_clear_cpu(cpu, &mask);
12        irq_set_affinity(dwc3_irq, &mask);
13        ...
14        atomic_set(&recvd, 0);
15        while(usb_ep_queue(ep, req, GFP_ATOMIC) < 0) {}
16        while(atomic_read(&recvd) != 1) {}
17        ...
18    }
19    kgdb_lock();
20    return ch;
21 }
22
23
24
25 }
```



# Debugging over ttyGS

## Serial gadget modifications

### Same for writing characters

```
1 poll_put_char()
2 static void gs_poll_put_char(struct tty_driver *driver, int line, char ch)
3 {
4     kgdb_unlock();
5     ...
6     cpu = task_cpu(current);
7     cpumask_setall(&mask);
8     cpumask_clear_cpu(cpu, &mask);
9     irq_set_affinity(dwc3_irq, &mask);
10    ...
11
12    atomic_set(&sent, 0);
13    while(usb_ep_queue(ep, req, GFP_ATOMIC) < 0) {}
14    while(atomic_read(&sent) != 1) {}
15    ...
16
17    kgdb_lock();
18 }
```

# Debugging over ttyGS

Pros & Cons

## ■ Pros

- 1 No special hardware required
- 2 Less kernel source code modifications (only in the debuggee's kernel)
- 3 Much faster

## ■ Cons

- 1 Less reliable (ADB seems to mess with USB transfers and slows down things some times)
- Works quite reliably in practice
  - We have been using it to automate debugging tasks on production devices

# Automation

- Developed set GDB Python extensions for examining kernel structures (ION, `kmalloc()`, etc.); code named KBBD (Kernel Black-Box Debugger)
  - Simple API for defining new kernel structures
  - Automated detection of KASLR
  - Custom commands for easier exploit development
  - Simple heap spray detection logic
  - etc.
- Additional kernel debugging scripts at `scripts/gdb`
- Production was boosted!

DEMO

# Conclusion

- We have presented ways of performing reliable debugging on Android
  - Userland (EL0) components, native executables and application bundles, using GDB, JDB and Java hooks
  - The Android kernel (EL1) using GDB/KGDB and Python scripts
- We have also discussed the potential of automating debugging tasks
- Unfortunately...
  - Android is on version 7.1 and still lacks proper debugging tools... but also still lacks a sane runtime
  - Vendors follow Apple's foot-steps by introducing various incompatibilities instead of unifying their custom bullshit
  - We still have to pay hundreds of USD for a smartphone that we don't actually own... just like iPhone

- Finish all our automation methods
- Maybe publish all our kernel patches, toolchain patches and Python scripts?
- Compiler toolchain on the smartphone (90% done)
- EL2/EL3 debugging (20% done)

Questions? Kthanxbai!