

LV 706.046 Summer Term 2019

Monday, March, 11

# Introduction and Overview

## From measuring Usability to measuring Causality

Assoc.Prof. Dr. Andreas Holzinger

Holzinger-Group, HCI-KDD, Institute for Medical Informatics/Statistics

Medical University Graz, Austria

&

Institute of interactive Systems & Data Science

Graz University of Technology, Austria

[a.holzinger@tugraz.at](mailto:a.holzinger@tugraz.at)

<https://hci-kdd.org/intelligent-user-interfaces-2019>



THIS IS YOUR MACHINE LEARNING SYSTEM?

YUP! YOU POUR THE DATA INTO THIS BIG  
PILE OF LINEAR ALGEBRA, THEN COLLECT  
THE ANSWERS ON THE OTHER SIDE.

WHAT IF THE ANSWERS ARE WRONG?

JUST STIR THE PILE UNTIL  
THEY START LOOKING RIGHT.



Image by Randall Munroe <https://xkcd.com>

- 01 The HCI-KDD approach: integrative ML
- 02 Application Area: Health
- 03 Probabilistic Learning
- 04 aML
- 05 iML
- 06 Causality and Causability
- 07 Measuring Causality?
- Our Goal for this semester: design  
develop & test a System Causability Scale

# 01 What is the



# approach?

- ML is a very practical field – algorithm development is at the core – however, successful ML needs a concerted effort of various topics ...



# MAchine Learning & Knowledge Extraction MAKE

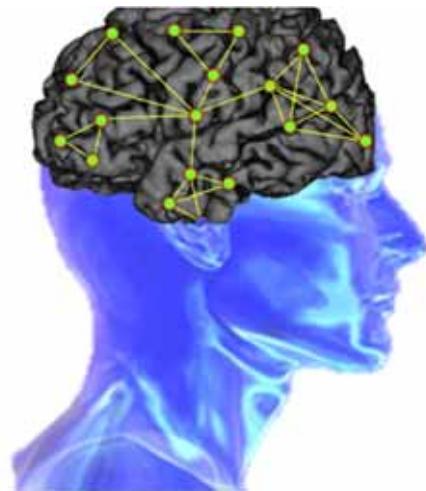
(Safety) 4 - Privacy, Data Protection, Safety & Security



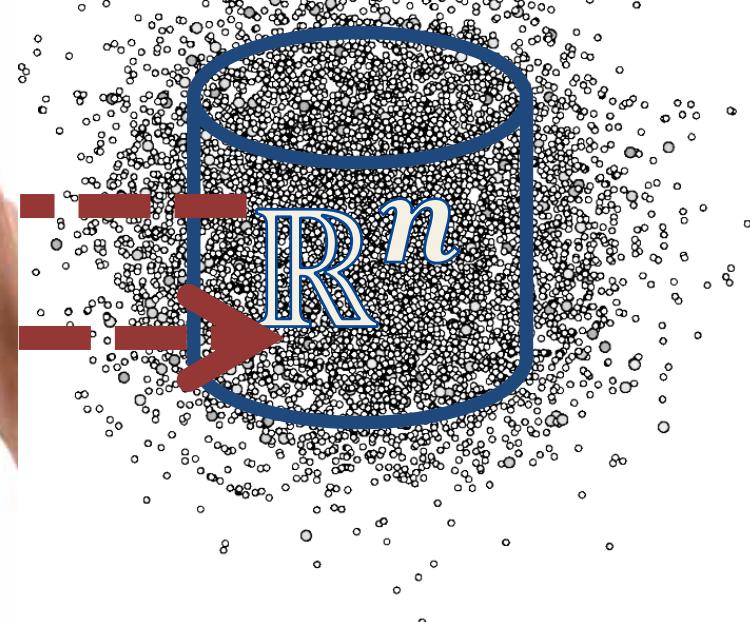
(Space and Time) 5 - Network, 6-Topology, 7-Entropy

Andreas Holzinger 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE).  
*Machine Learning and Knowledge Extraction*, 1, (1), 1-20, doi:10.3390/make1010001.

## Human intelligence (Cognitive Science)



## Machine intelligence (Computer Science)



Holzinger, A. (2013). Human–Computer Interaction & Knowledge Discovery (HCI-KDD): What is the benefit of bringing those two fields to work together? In: Lecture Notes in Computer Science 8127 (pp. 319-328)

- 1) **learn** from prior data
- 2) **extract** knowledge
- 2) **generalize**, i.e. guessing where a probability mass function concentrates
- 4) fight the curse of **dimensionality**
- 5) **disentangle** underlying explanatory factors of data, i.e.
- 6) **understand** the data in the **context** of an application domain



A photograph of an operating room. In the center, there is a complex piece of medical equipment with multiple monitors, tubes, and sensors. A sign above it displays the number '2'. To the left, a wooden table is visible. On the right, there is a red cooler and some pink bowls. The ceiling has a grid of fluorescent lights.

## 02 Application Area Health Informatics

# Why is this application area complex ?

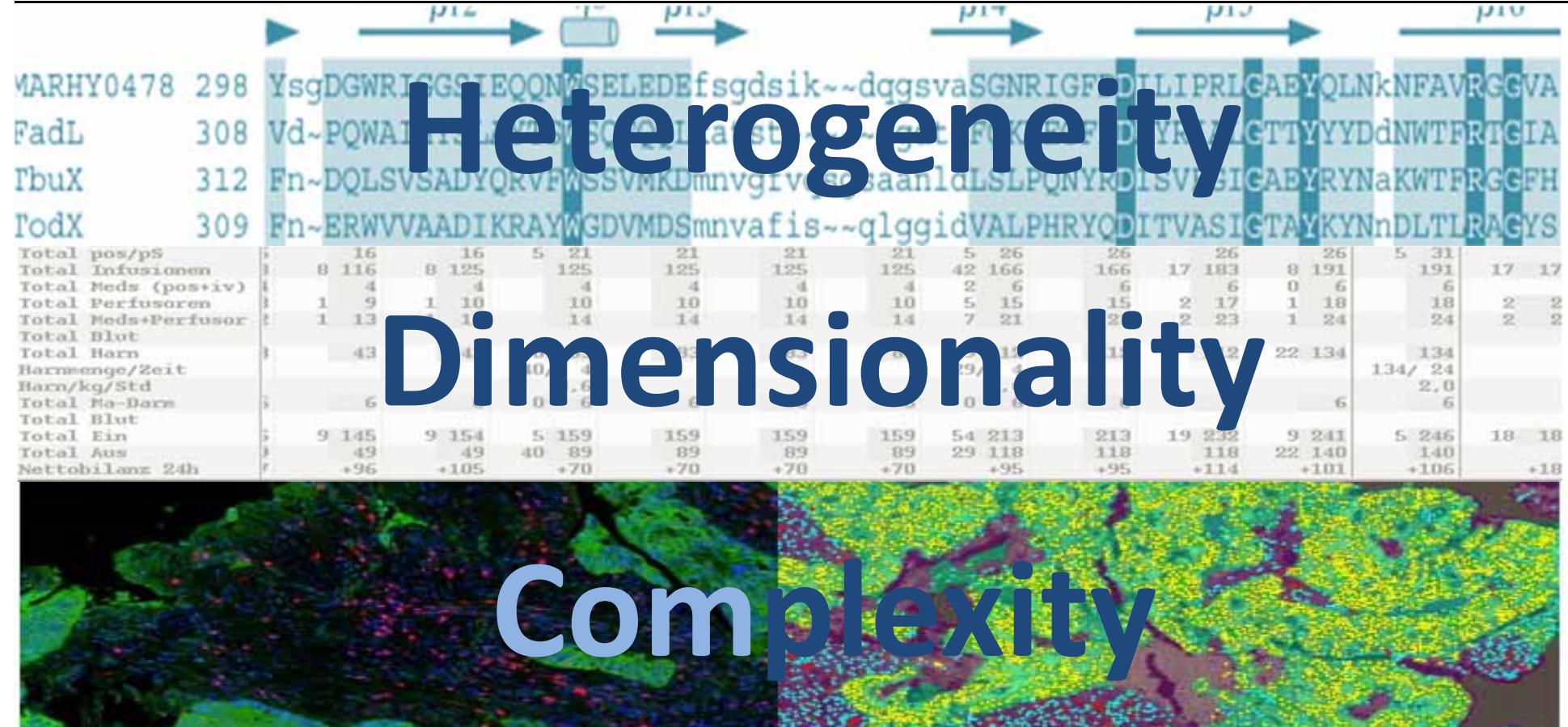


# Our central hypothesis: Information may bridge this gap

Holzinger, A. & Simonic, K.-M. (eds.) 2011. *Information Quality in e-Health. Lecture Notes in Computer Science LNCS 7058*, Heidelberg, Berlin, New York: Springer.



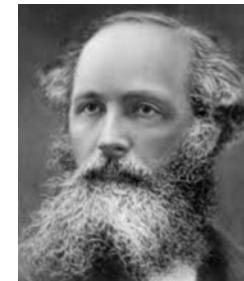
Where is the  
problem in building  
this bridge?



# Uncertainty

Holzinger, A., Dehmer, M. & Jurisica, I. 2014. Knowledge Discovery and interactive Data Mining in Bioinformatics - State-of-the-Art, future challenges and research directions. BMC Bioinformatics, 15, (S6), I1.

# 03 Probabilistic Learning



The true logic of this world is  
in the calculus of  
probabilities.

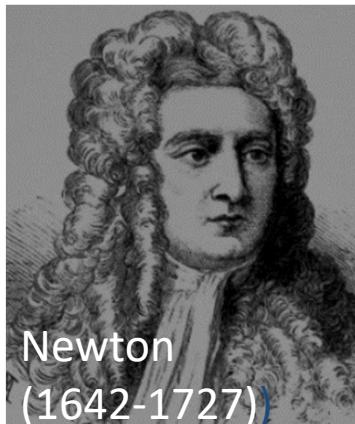
James Clerk Maxwell

Probability  
theory is  
nothing but  
common  
sense reduced  
to calculation

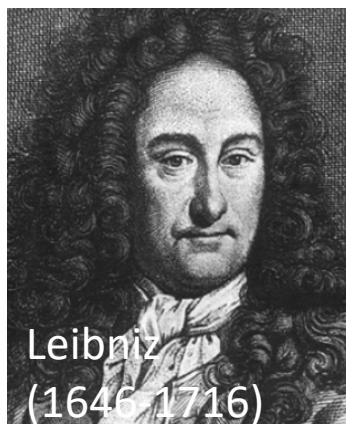
...



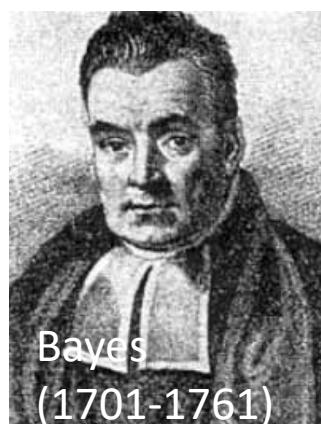
Pierre Simon de Laplace (1749-1827)



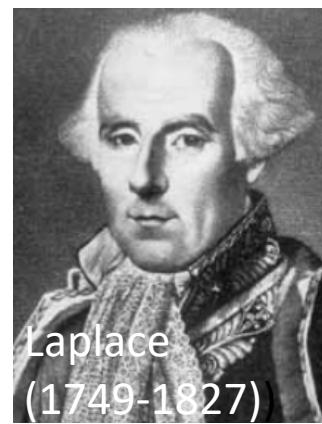
Newton  
(1642-1727)



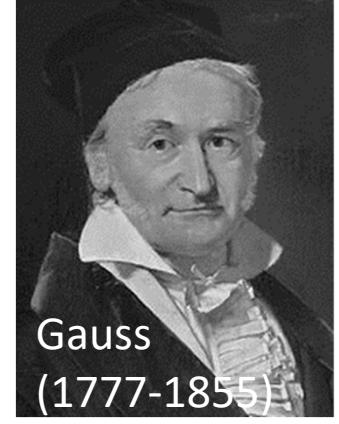
Leibniz  
(1646-1716)



Bayes  
(1701-1761)



Laplace  
(1749-1827)



Gauss  
(1777-1855)

- **Newton, Leibniz, ... developed calculus – mathematical language for describing and dealing with rates of change**
- **Bayes, Laplace, ... developed probability theory - the mathematical language for describing and dealing with uncertainty**
- **Gauss generalized those ideas**

What is the simplest mathematical operation for us?

$$p(x) = \sum_x (p(x, y)) \quad (1)$$

How do we call repeated adding?

$$p(x, y) = p(y|x) * p(y) \quad (2)$$

Laplace (1773) showed that we can write:

$$p(x, y) * p(y) = p(y|x) * p(x) \quad (3)$$

Now we introduce a third, more complicated operation:

$$\frac{p(x, y) * p(y)}{p(y)} = \frac{p(y|x) * p(x)}{p(y)} \quad (4)$$

We can reduce this fraction by  $p(y)$  and we receive what is called Bayes rule:

$$p(x, y) = \frac{p(y|x) * p(x)}{p(y)} \quad p(h|d) = \frac{p(d|h)p(h)}{p(d)} \quad (5)$$

$$p(x_i) = \sum P(x_i, y_j)$$

$$p(x_i, y_j) = p(y_j|x_i)P(x_i)$$

Bayes, T. (1763). An Essay towards solving a Problem in the Doctrine of Chances (Postum communicated by Richard Price). Philosophical Transactions, 53, 370-418.

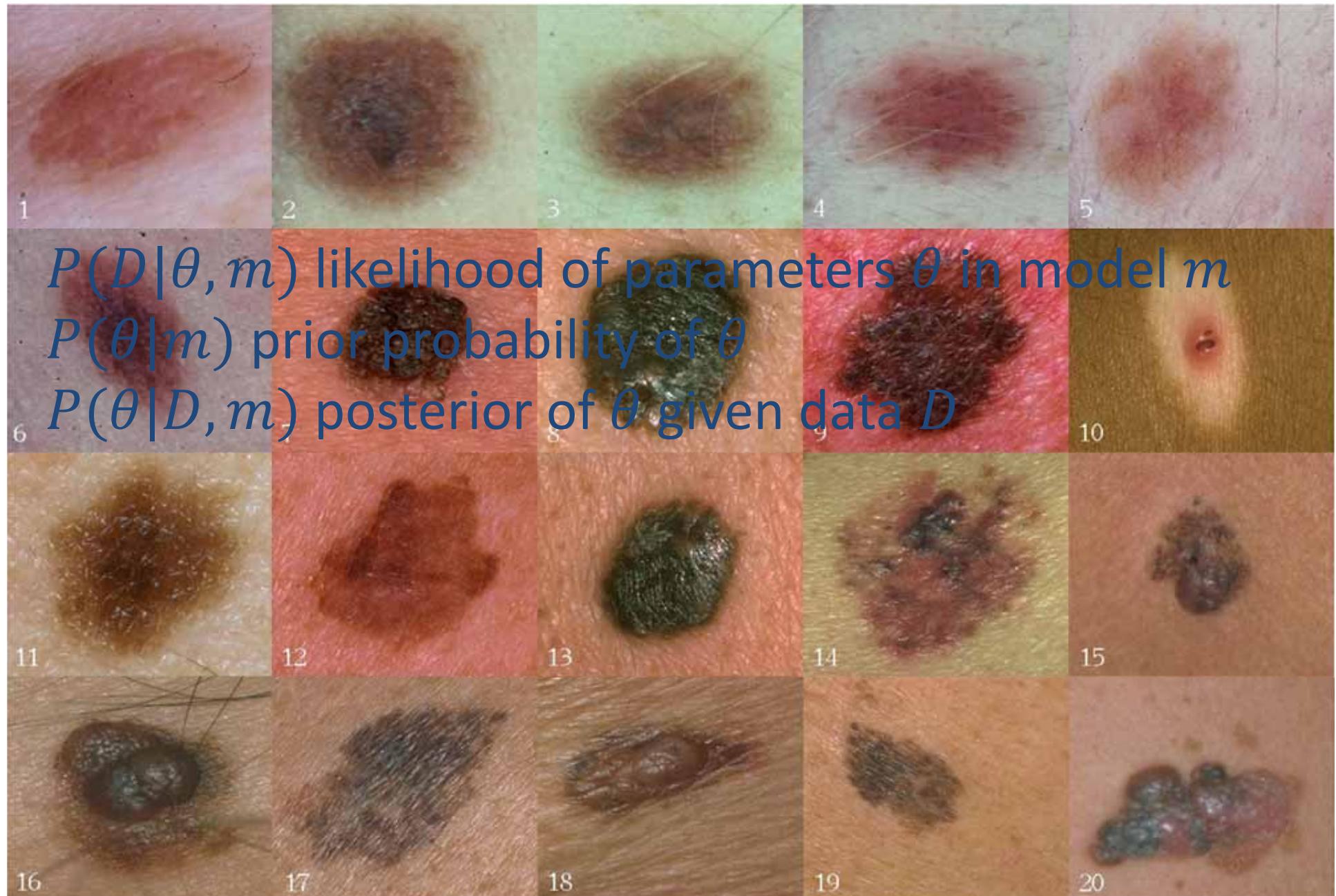
### Bayes' Rule is a corollary of the Sum Rule and Product Rule:

$$p(x_i|y_j) = \frac{p(y_j|x_i)p(x_i)}{\sum p(x_i, y_j)p(x_i)}$$

$$P(\text{hypothesis}|\text{data}) = \frac{P(\text{hypothesis})P(\text{data}|\text{hypothesis})}{\sum_h P(h)P(\text{data}|h)}$$

$$P(\theta|\mathcal{D}, m) = \frac{P(\mathcal{D}|\theta, m)P(\theta|m)}{P(\mathcal{D}|m)}$$

Barnard, G. A., & Bayes, T. (1958). Studies in the history of probability and statistics: IX. Thomas Bayes's essay towards solving a problem in the doctrine of chances. Biometrika, 45(3/4), 293-315.



$$\mathcal{D} = x_{1:n} = \{x_1, x_2, \dots, x_n\} \quad p(\mathcal{D}|\theta)$$



$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$$

$$posterior = \frac{likelihood * prior}{evidence}$$

The inverse probability allows to learn from data, infer unknowns, and make predictions

*d ... data*

$\mathcal{H} \dots \{H_1, H_2, \dots, H_n\}$

$\forall h, d \dots$

*h ... hypotheses*

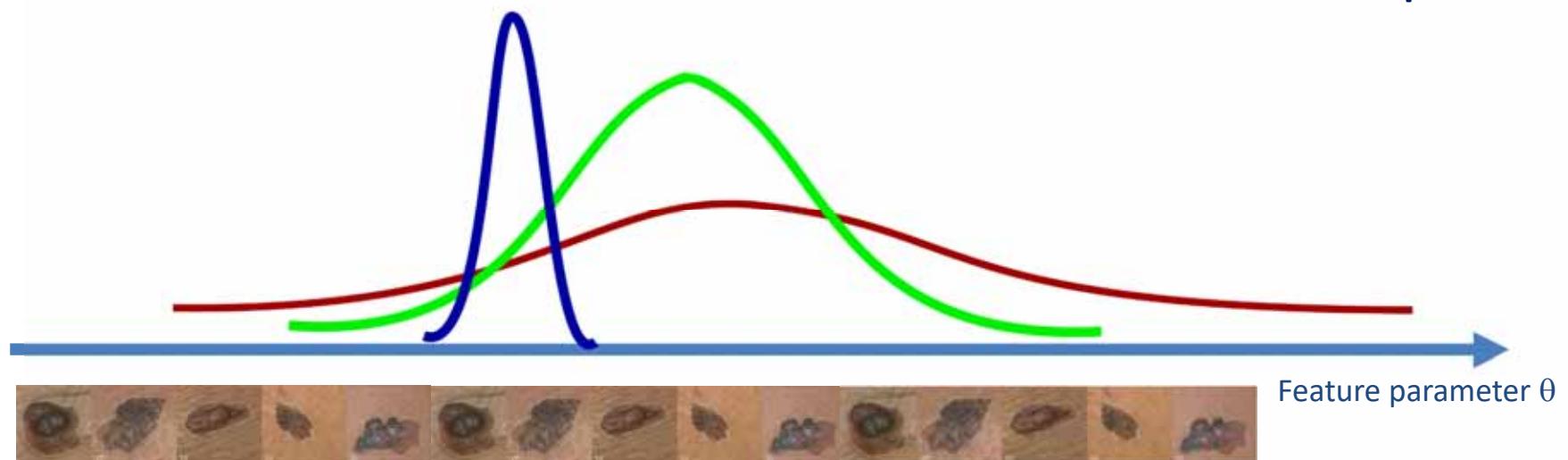
$$p(h|d) = \frac{p(d|h) * p(h)}{\sum_{h \in H} p(d|h') p(h')}$$

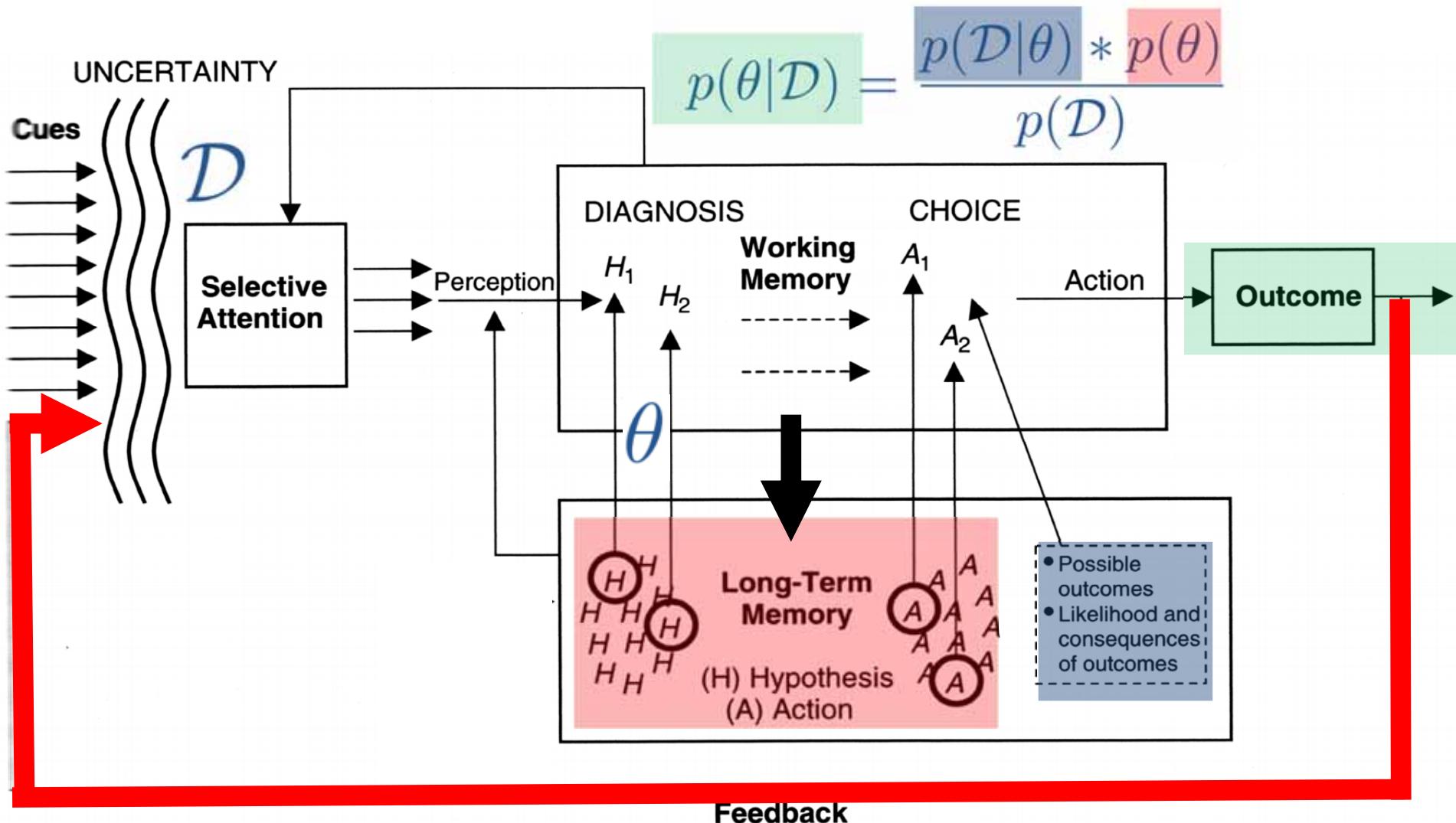
Likelihood

Prior Probability

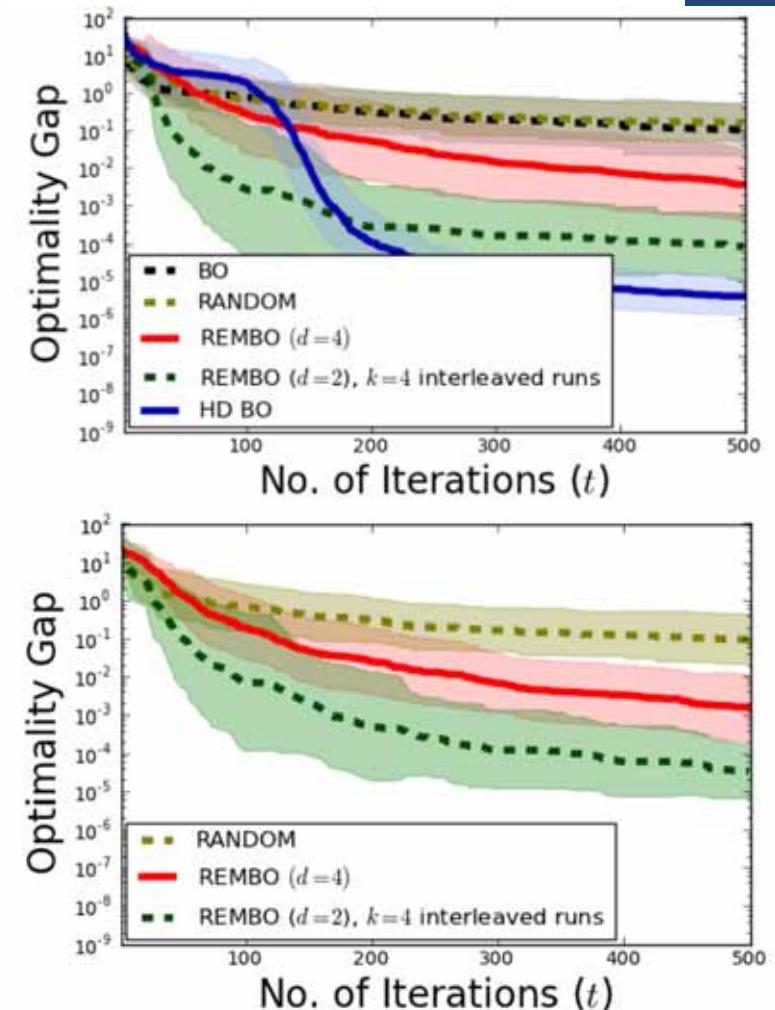
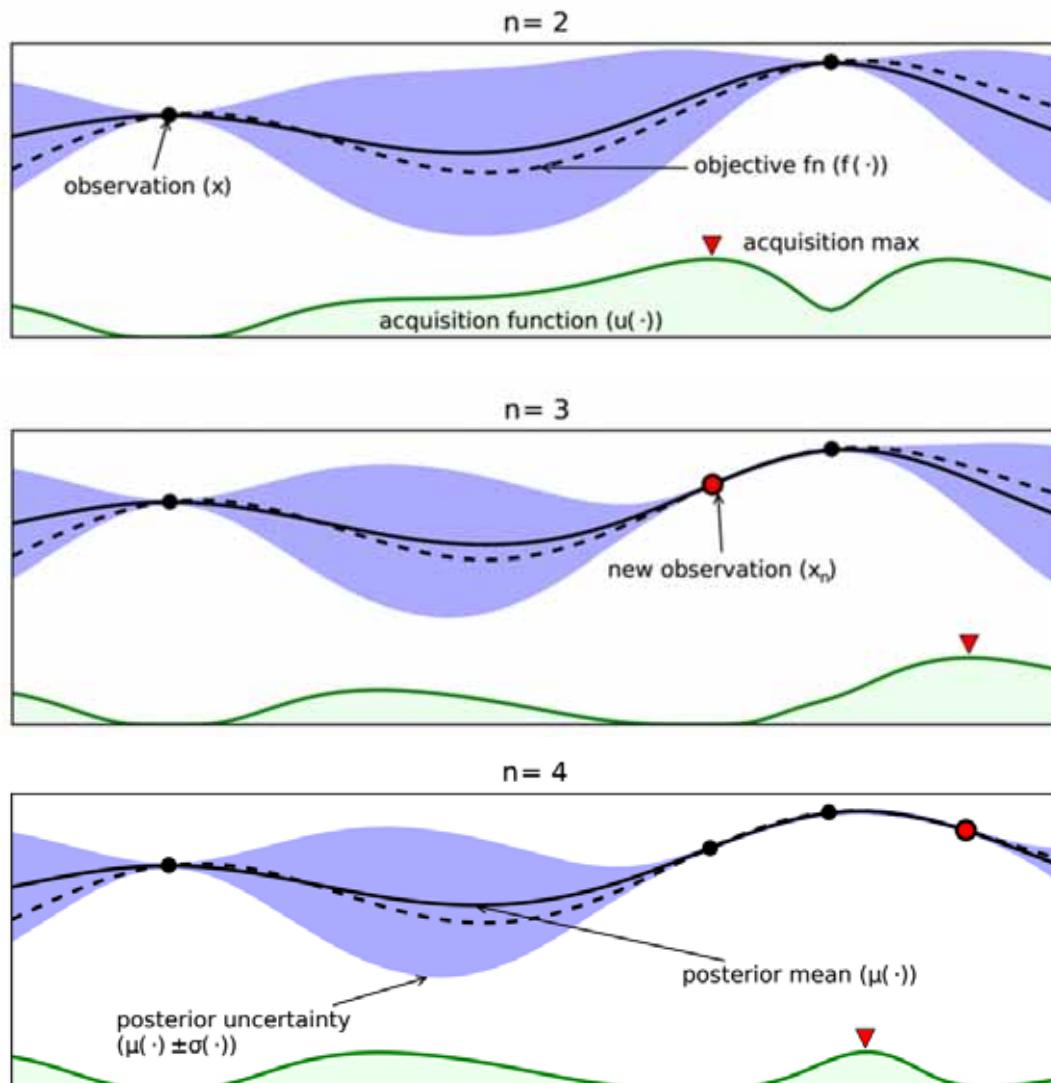
Posterior Probability

Problem in  $\mathbb{R}^n \rightarrow$  complex





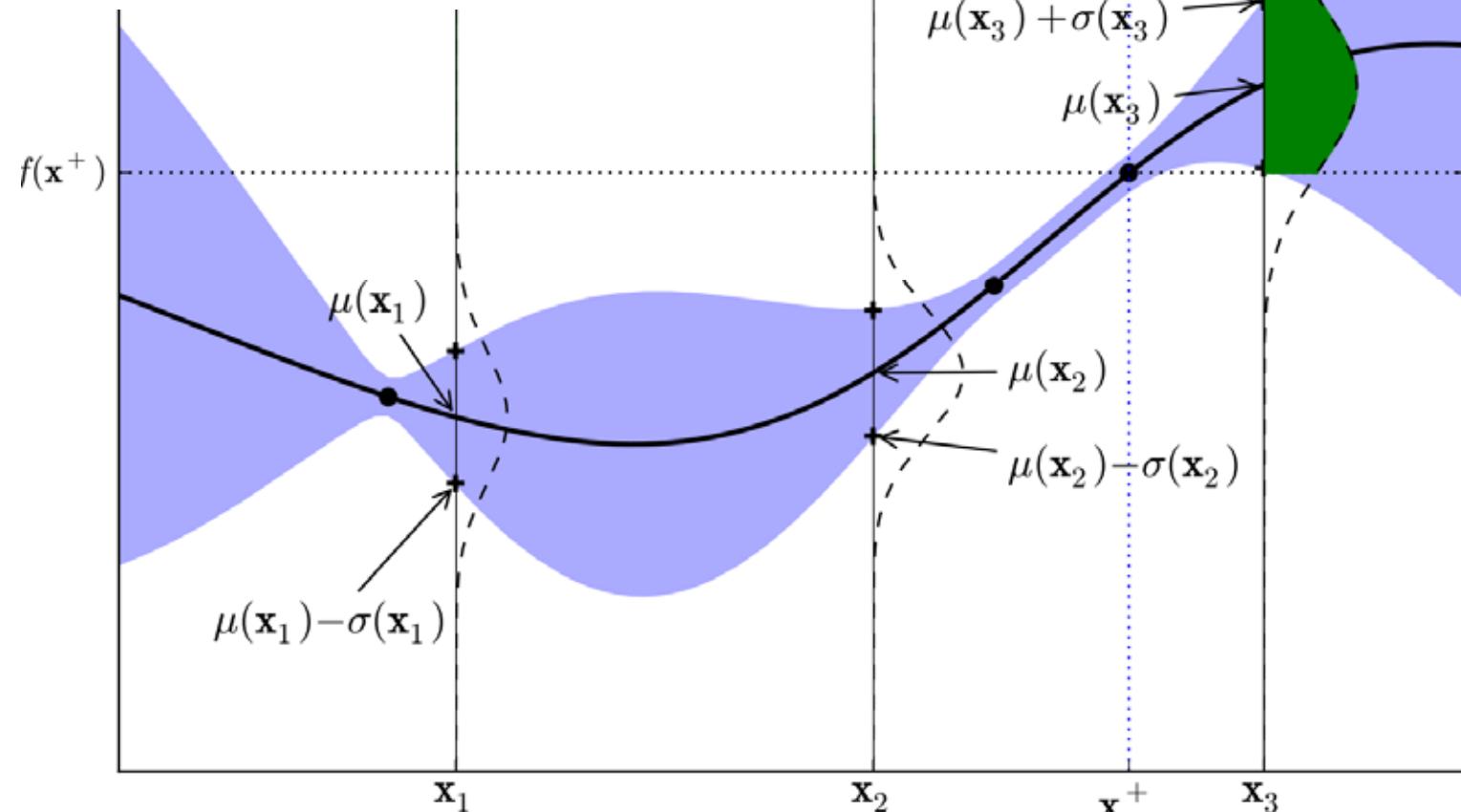
Wickens, C. D. (1984) *Engineering psychology and human performance*.  
Columbus (OH), Charles Merrill, modified by Holzinger, A.



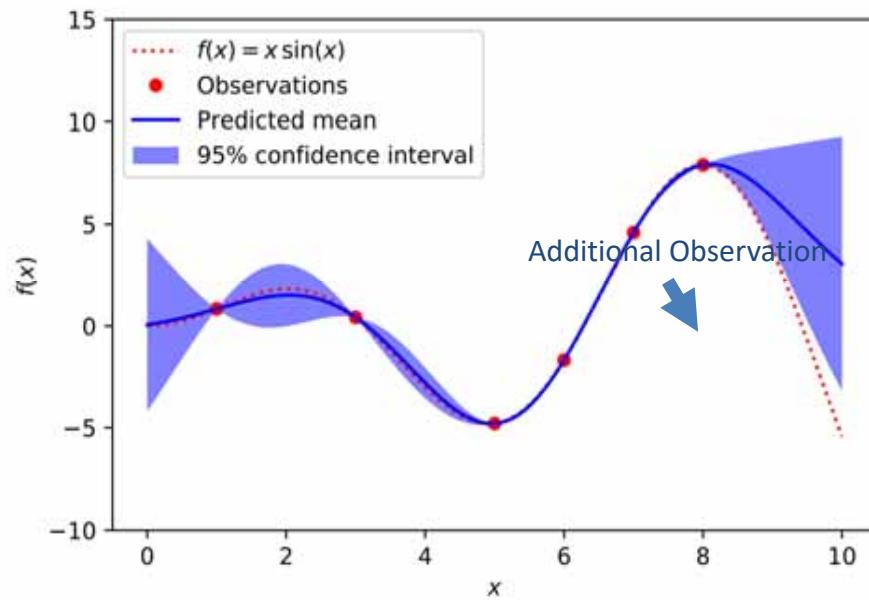
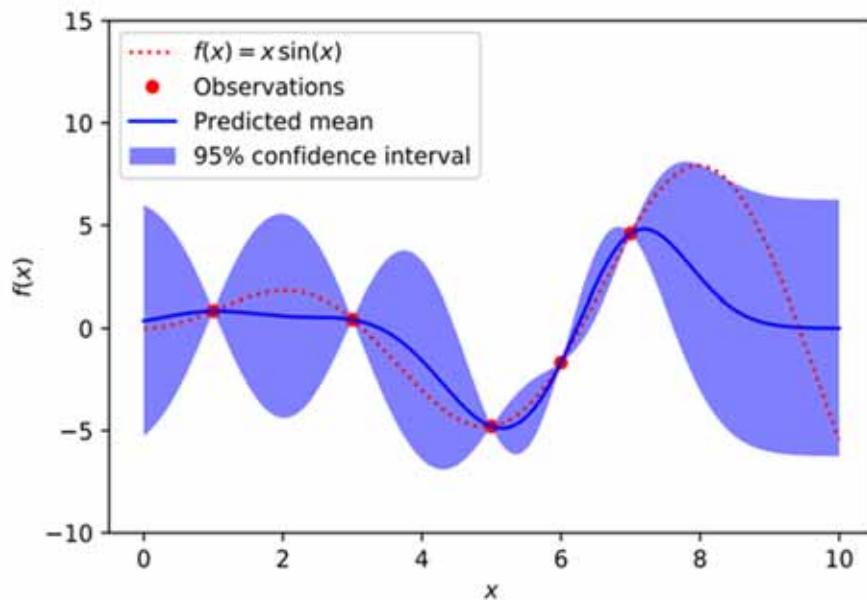
Wang, Z., Hutter, F., Zoghi, M., Matheson, D. & De Feitas, N. 2016. Bayesian optimization in a billion dimensions via random embeddings. Journal of Artificial Intelligence Research, 55, 361-387, doi:10.1613/jair.4806.

GP posterior      Likelihood      GP prior

$$\overbrace{p(f(x)|\mathcal{D})} \propto \overbrace{p(\mathcal{D}|f(x))} p(f(x))$$



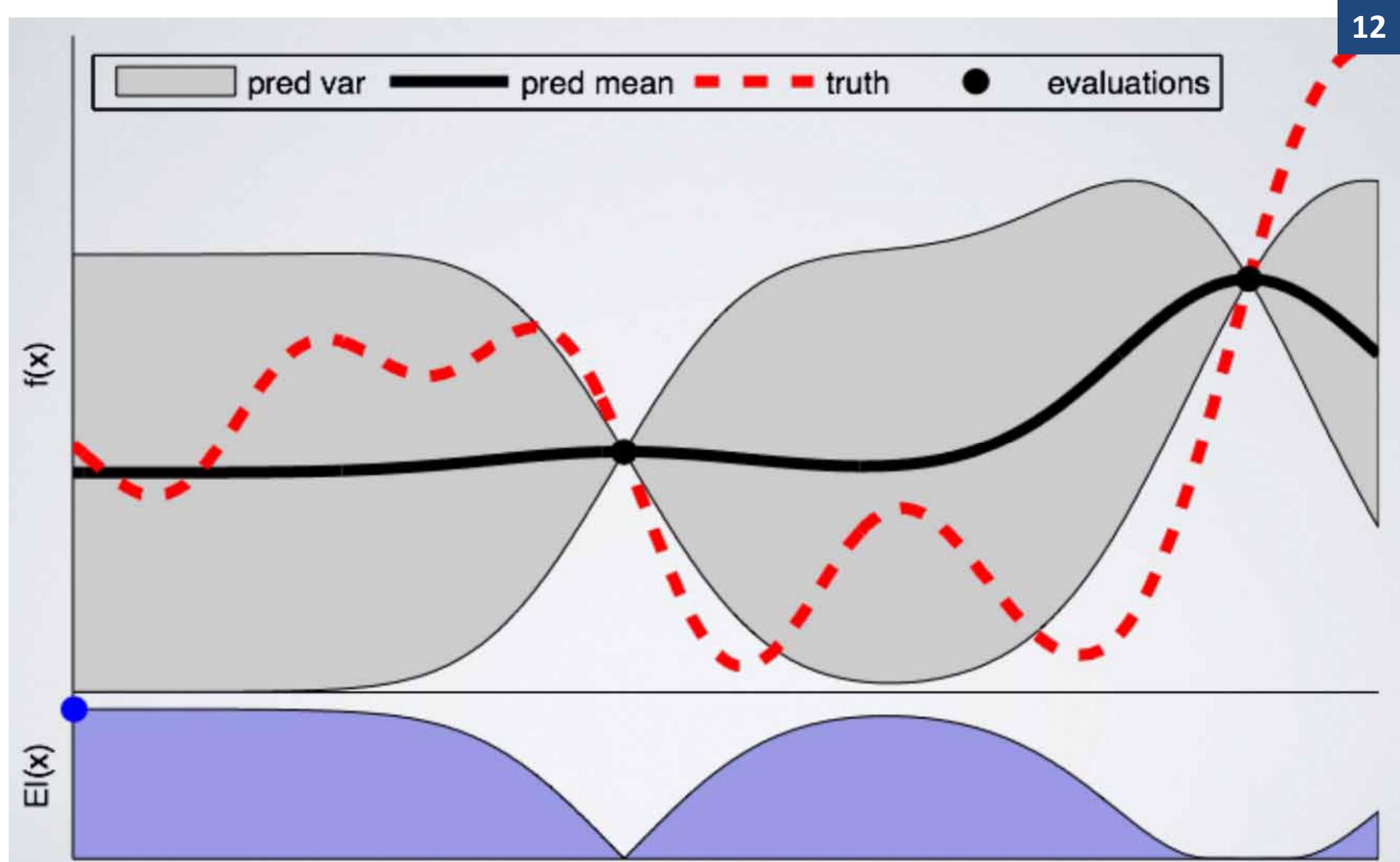
Brochu, E., Cora, V. M. & De Freitas, N. 2010. A tutorial on Bayesian optimization of expensive cost functions, with application to active user modeling and hierarchical reinforcement learning. arXiv:1012.2599.



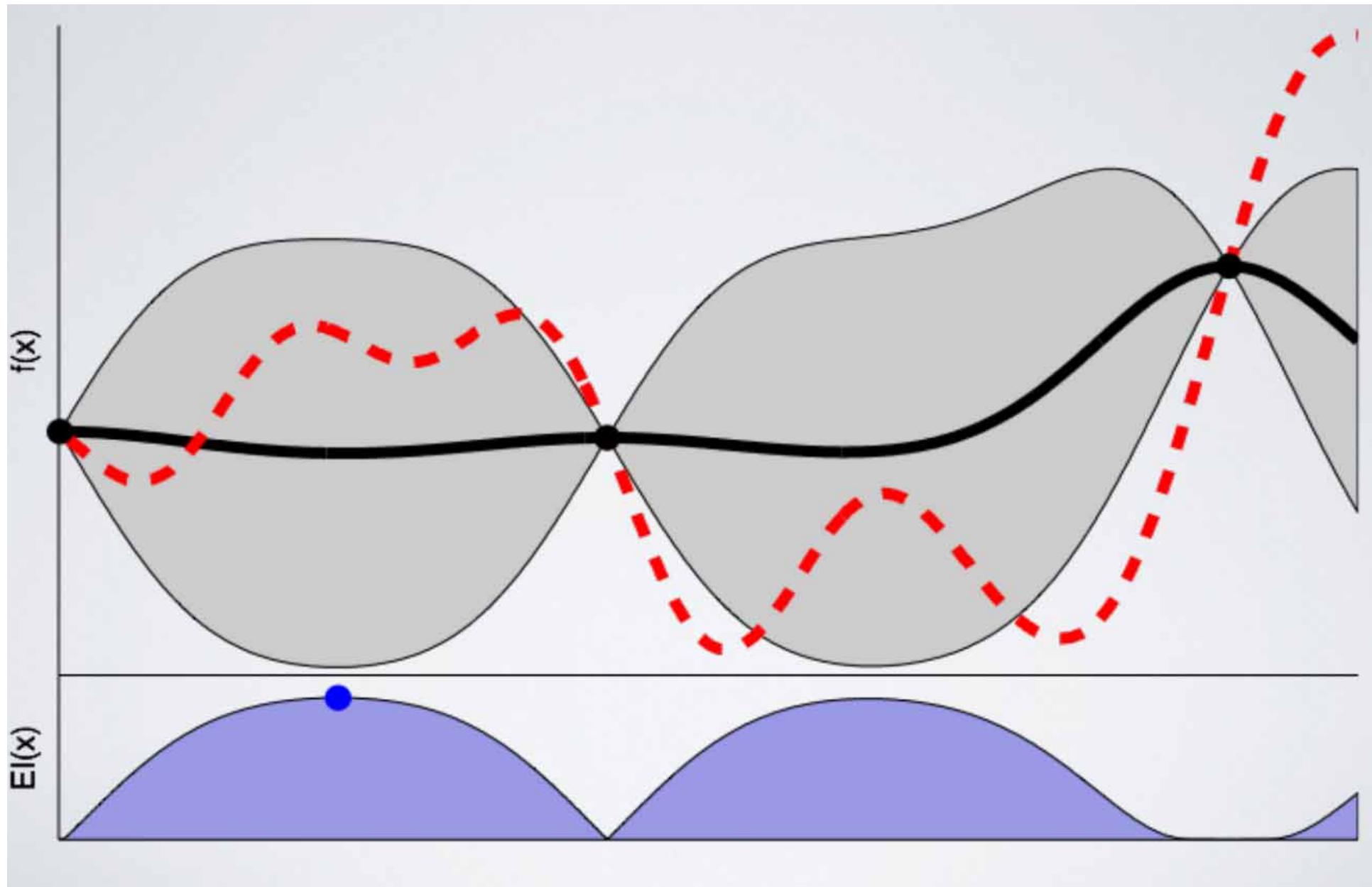
$$\mathbb{E}[f] = \int p(x)f(x) dx$$

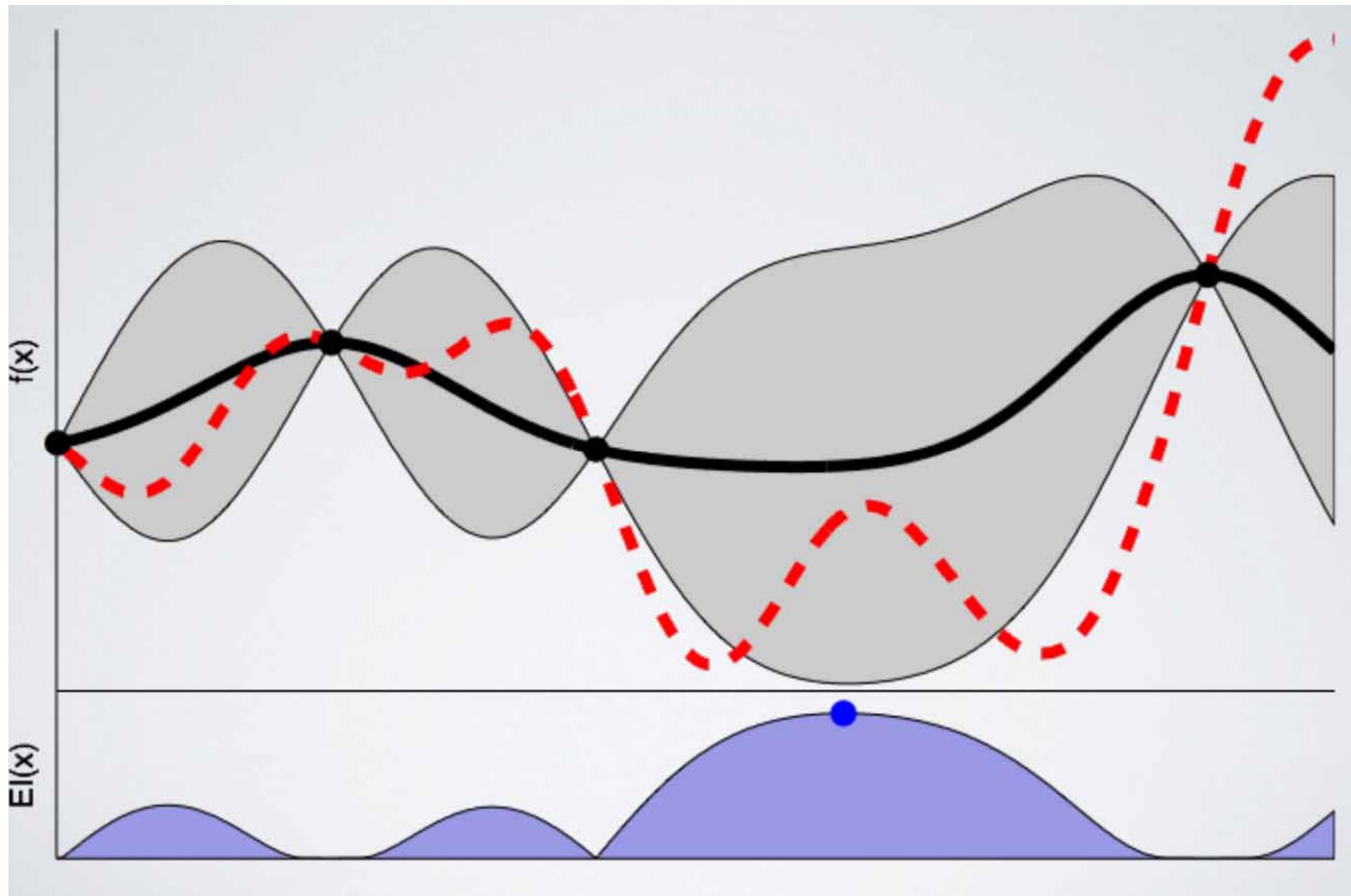
$$\mathbb{E}[f] \simeq \frac{1}{N} \sum_{n=1}^N f(x_n)$$

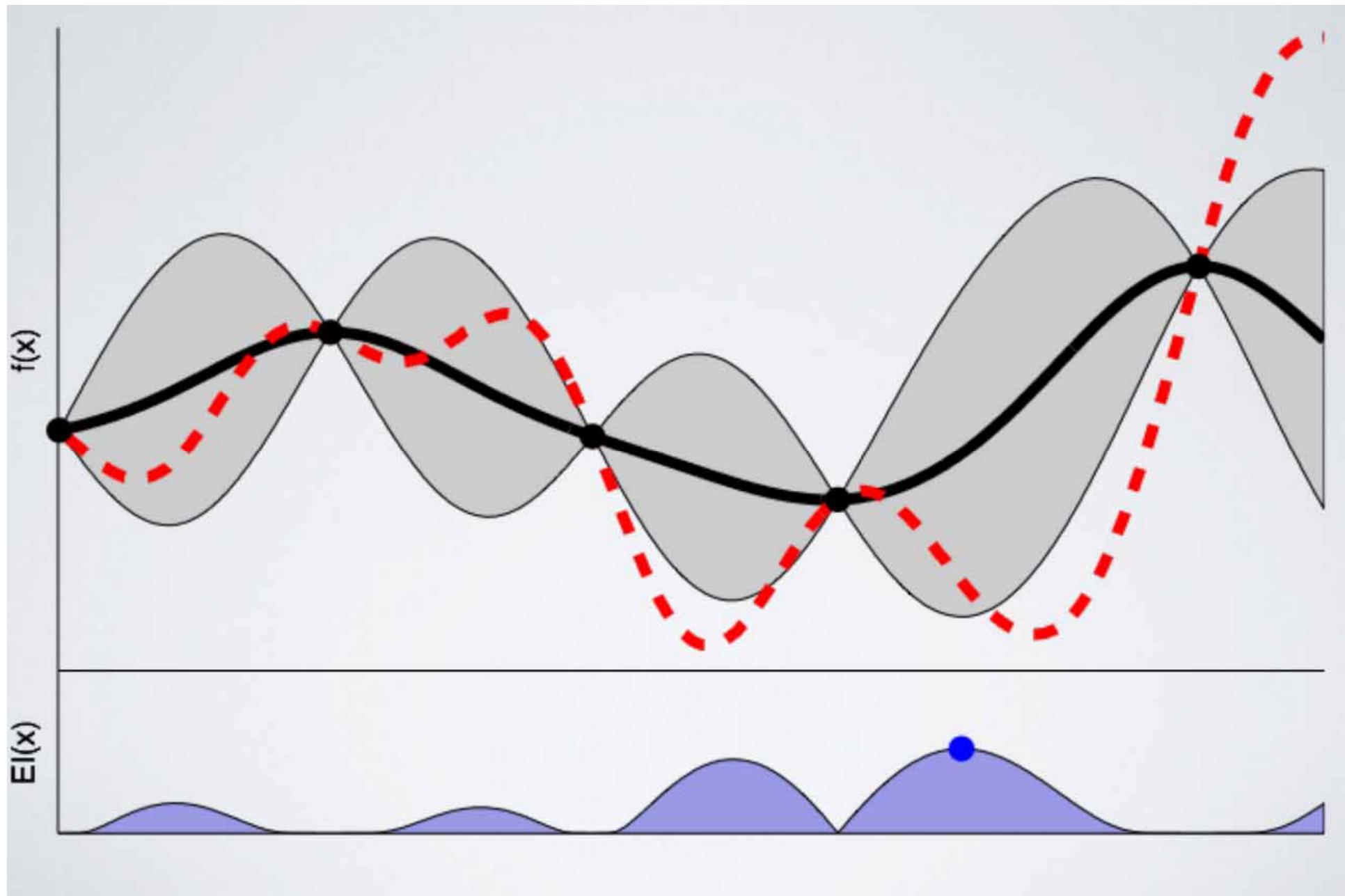
Holzinger, A. 2017. Introduction to Machine Learning and Knowledge Extraction (MAKE). Machine Learning and Knowledge Extraction, 1, (1), 1-20, doi:10.3390/make1010001.

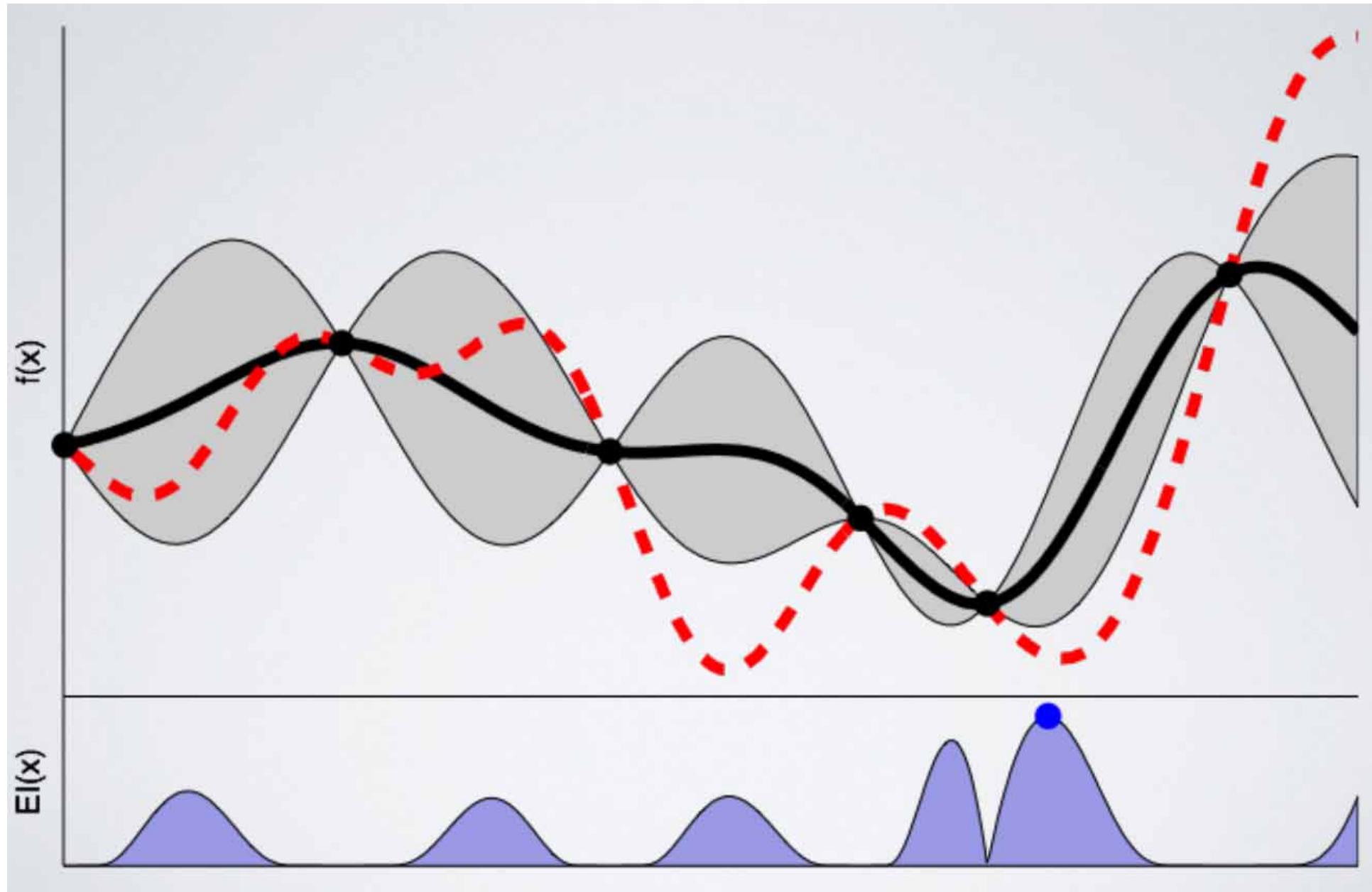


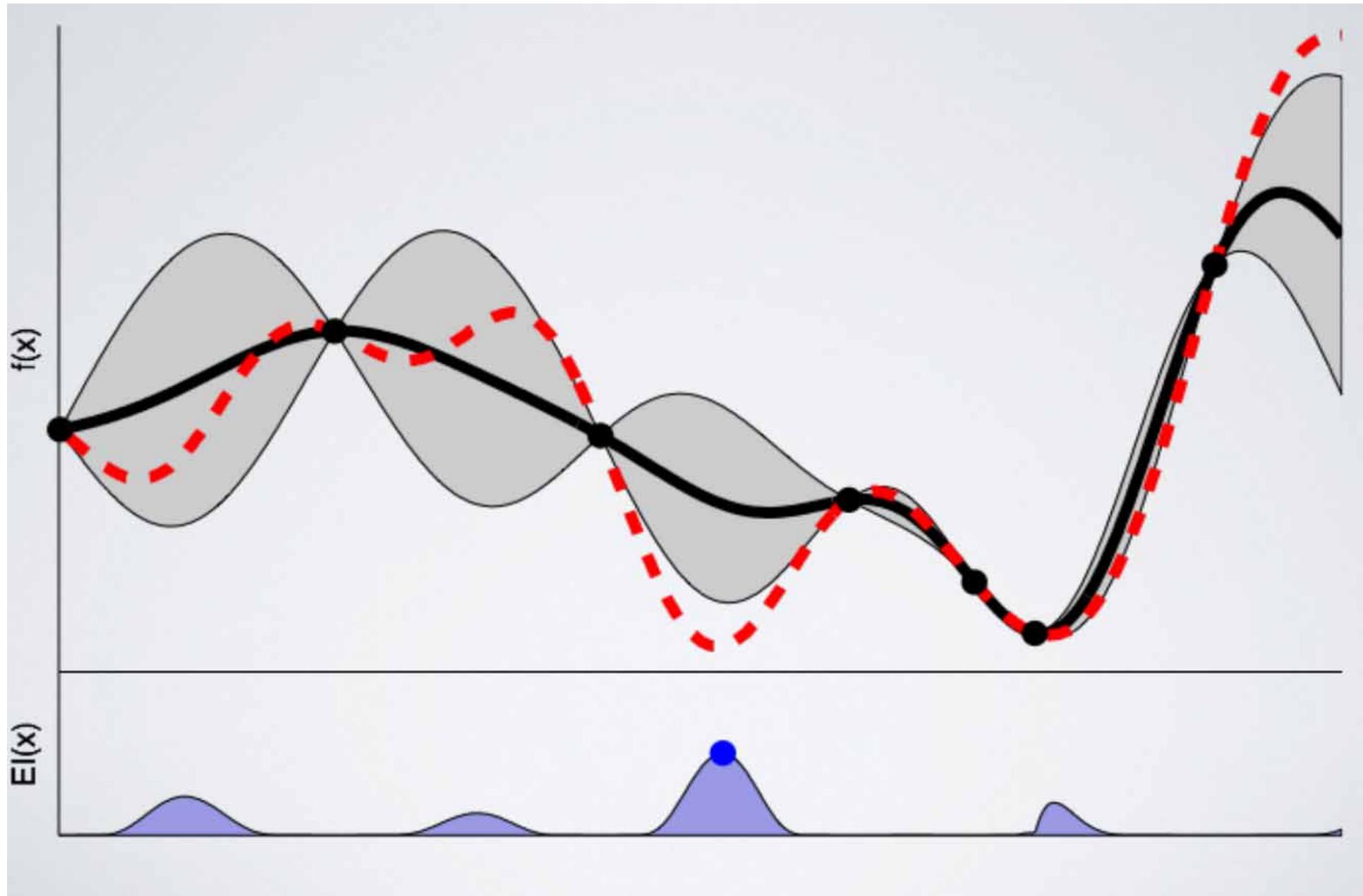
Snoek, J., Larochelle, H. & Adams, R. P. Practical Bayesian optimization of machine learning algorithms.  
Advances in neural information processing systems, 2012. 2951-2959.

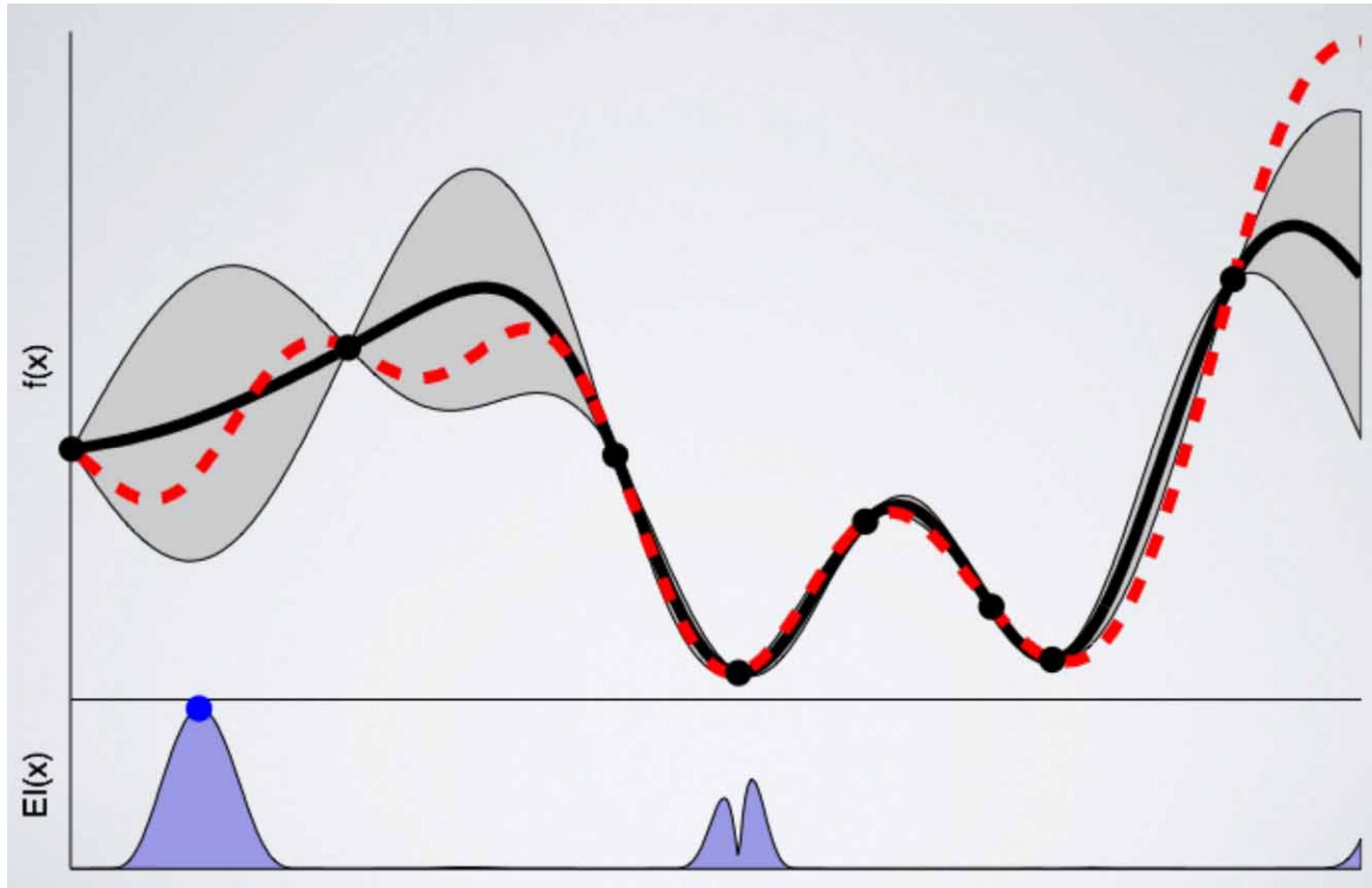


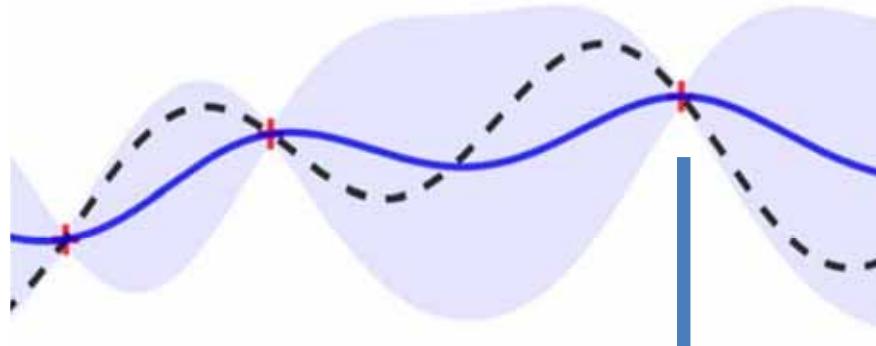












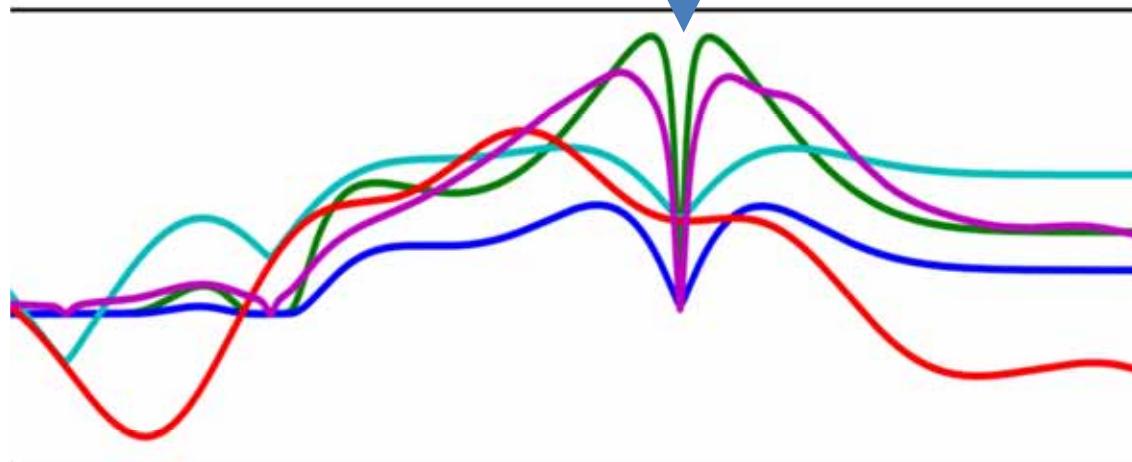
**Algorithm 1** Bayesian optimization

```

1: for  $n = 1, 2, \dots$  do
2:   select new  $\mathbf{x}_{n+1}$  by optimizing acquisition function  $\alpha$ 
      
$$\mathbf{x}_{n+1} = \arg \max_{\mathbf{x}} \alpha(\mathbf{x}; \mathcal{D}_n)$$

3:   query objective function to obtain  $y_{n+1}$ 
4:   augment data  $\mathcal{D}_{n+1} = \{\mathcal{D}_n, (\mathbf{x}_{n+1}, y_{n+1})\}$ 
5:   update statistical model
6: end for

```



- PI Probability of Improvement
- EI Expected Improvement
- UCB Upper Confidence Bound
- TS Thompson Sampling
- PES Predictive Entropy Search

Shahriari, B., Swersky, K., Wang, Z., Adams, R. P. & De Freitas, N. 2016.  
**Taking the human out of the loop:** A review of Bayesian optimization.  
*Proceedings of the IEEE*, 104, (1), 148-175, doi:10.1109/JPROC.2015.2494218.

# 04 aML

# Best practice examples of aML ...

amazon.co.uk All glass cutter circular

Shop by Department Your Amazon.co.uk Today's Deals Gift Cards & Top Up Sell Help

Hello You

Amazon.co.uk Today's Deals Warehouse Deals Outlet Subscribe & Save Vouchers Amazon Family Amazon Prime Amazon Video Amazon Student Mobile Apps An

Showing results for "glass cutter circular"

Show results for

**DIY & Tools** >

- Glass Cutters
- Cold Chisels
- Power Tools

**Sports & Outdoors** >

- Compasses

+ See All 13 I

Refine by

**Delivery Opt**

- Prime
- Free UK De

**Brand**

- sourcingm
- SODIAL(R)



**Silverline 101228 Circular Glass Cutter with 65-300 mm Diameter** 10 Oct 2014  
by Silverline

**£7.81** £10.02 ✓Prime  
Get it by Tomorrow, Sep 5  
Eligible for FREE UK Delivery

More buying choices  
**£6.40** new (22 offers)



**Highlander 3 Hole Thinsulate Balaclava**  
by Highlander

**£1.99 - £7.00** ✓Prime  
More buying choices  
**£1.99** new (5 offers)



**Sanwood® Outdoor Motorcycle Cycling Ski Neck Protecting Lycra Balaclava Full Face Mask**  
by Phoenix B2C UK

**£1.74 - £3.57**  
More buying choices  
**£0.01** new (4 offers)

 42

**DIY & Tools:** See all 162 items

 163

**Sports & Outdoors:** See all 5,918 items

 73

**Sports & Outdoors:** See all 5,918 items



Guizzo, E. 2011. How google's self-driving car works. IEEE Spectrum Online, 10, 18.



a woman riding a horse on a  
dirt road



an airplane is parked on the  
tarmac at an airport



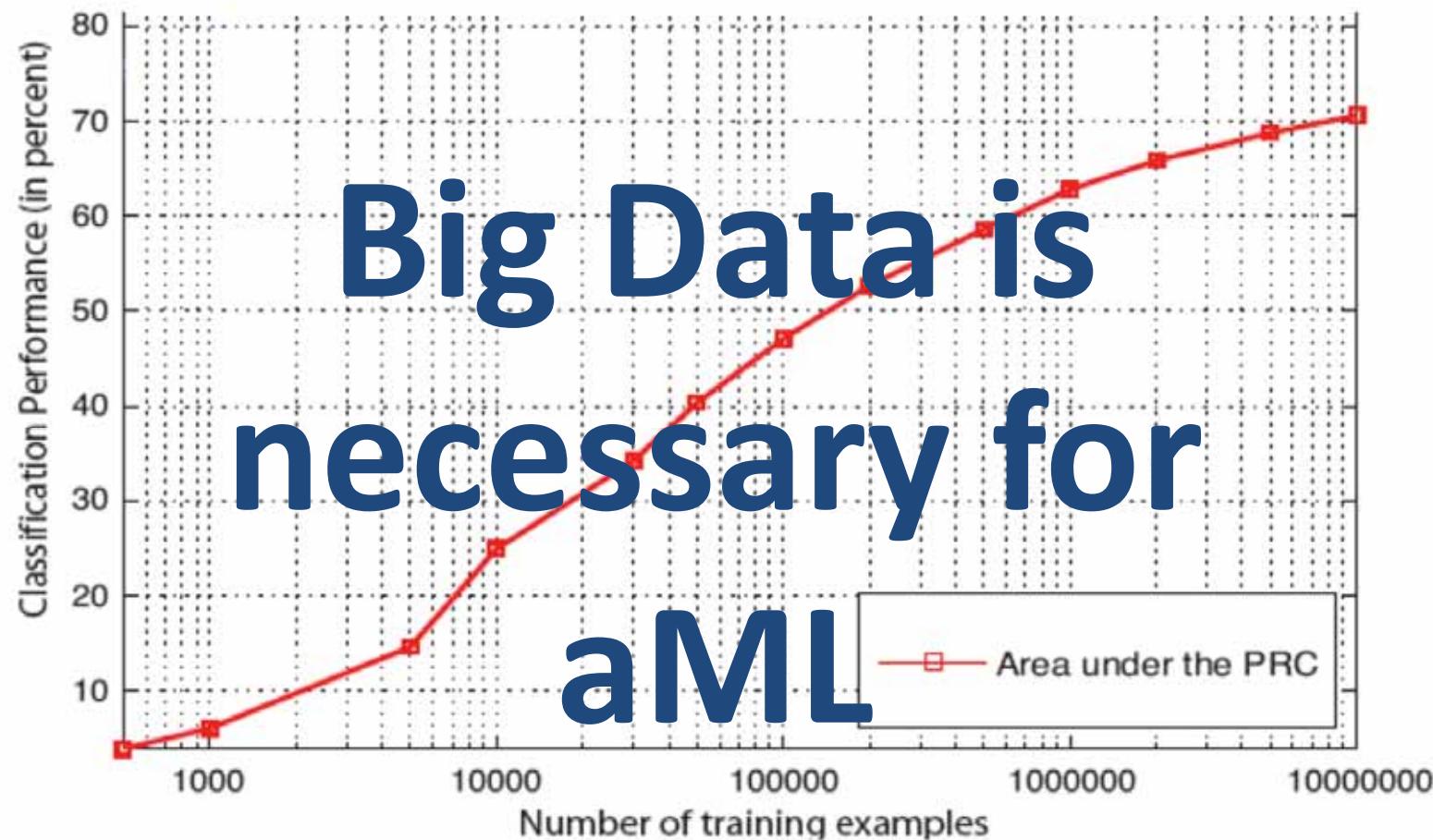
a group of people standing on  
top of a beach

<https://cs.stanford.edu/people/karpathy/deepimagesent/>

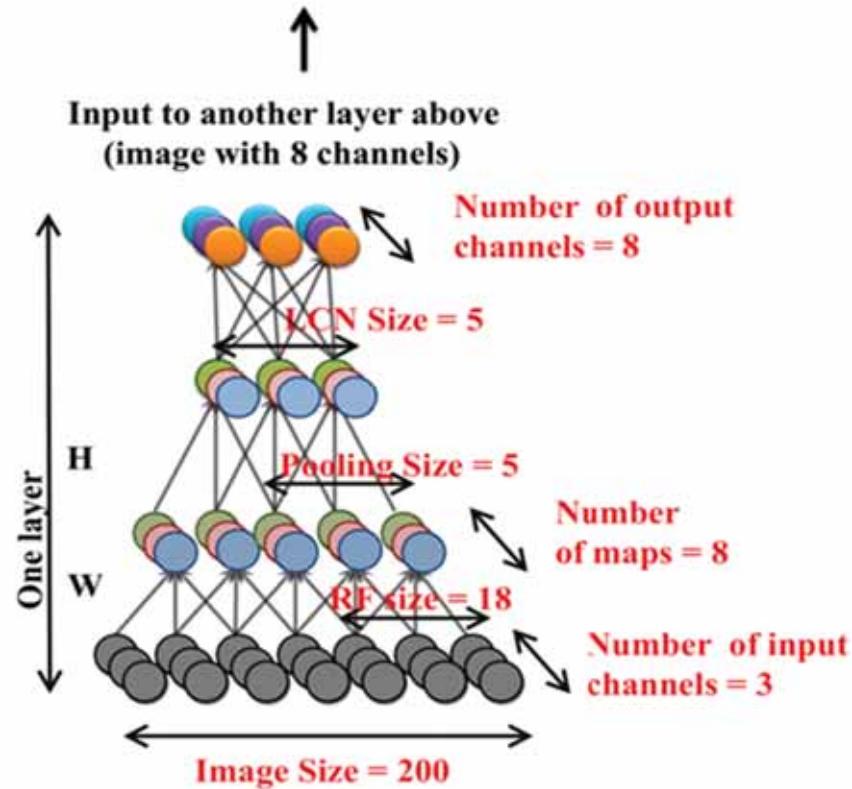
Andrej Karpathy & Li Fei-Fei. Deep visual-semantic alignments for generating image descriptions. Proceedings of the IEEE conference on computer vision and pattern recognition, 2015. 3128-3137.



"a young boy is holding a  
baseball bat."



Sonnenburg, S., Rätsch, G., Schäfer, C. & Schölkopf, B. 2006. Large scale multiple kernel learning. Journal of Machine Learning Research, 7, (7), 1531-1565.

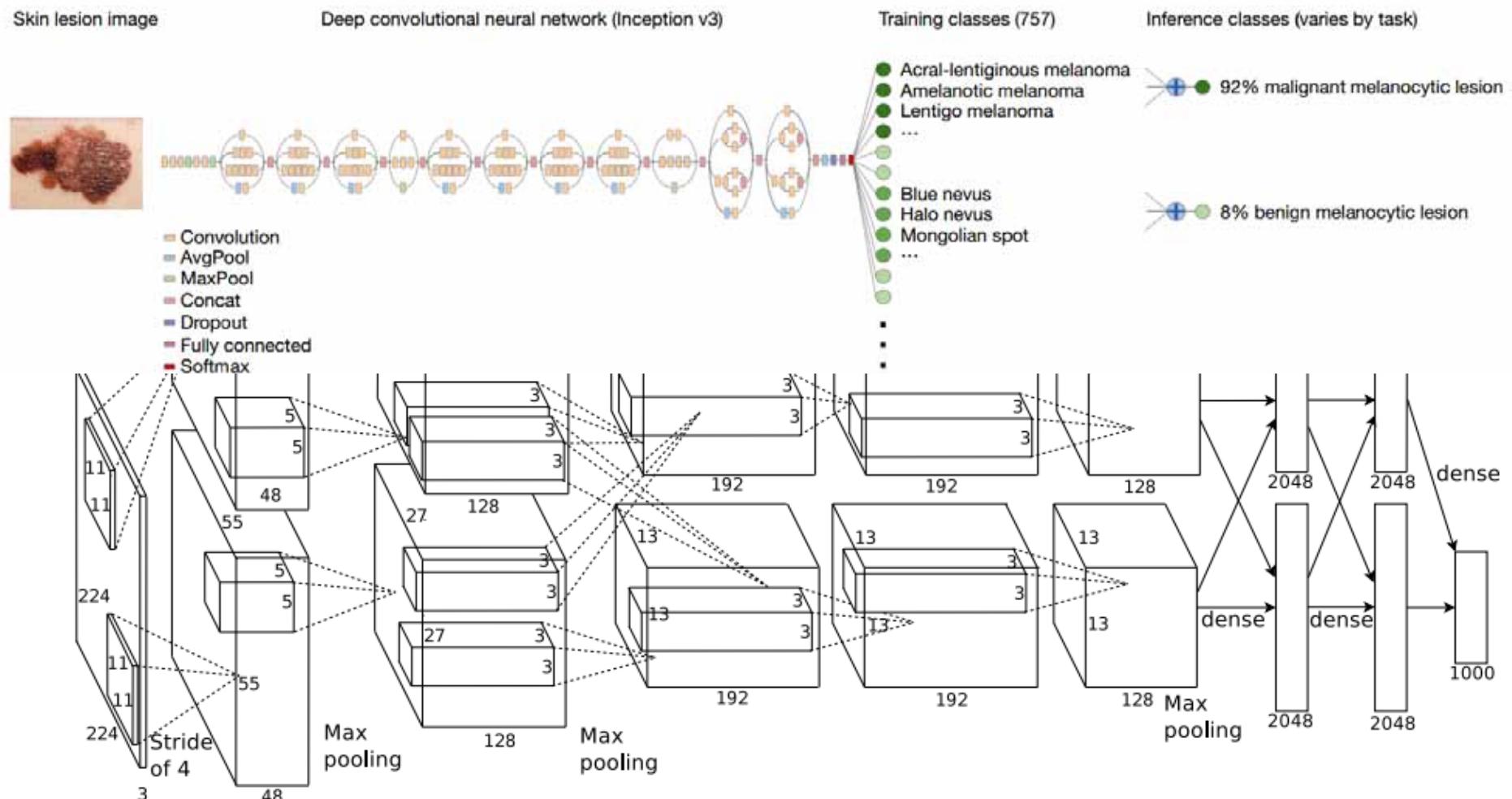


$$x^* = \arg \min_x f(x; W, H), \text{ subject to } \|x\|_2 = 1.$$

Le, Q. V., Ranzato, M. A., Monga, R., Devin, M., Chen, K., Corrado, G. S., Dean, J. & Ng, A. Y. 2011.  
Building high-level features using large scale unsupervised learning. arXiv preprint arXiv:1112.6209.

Le, Q. V. 2013. Building high-level features using large scale unsupervised learning. *IEEE Intl. Conference on Acoustics, Speech and Signal Processing ICASSP*. IEEE. 8595-8598, doi:10.1109/ICASSP.2013.6639343.

Esteva, A., Kuprel, B., Novoa, R. A., Ko, J., Swetter, S. M., Blau, H. M. & Thrun, S. 2017. Dermatologist-level classification of skin cancer with deep neural networks. Nature, 542, (7639), 115-118, doi:10.1038/nature21056.

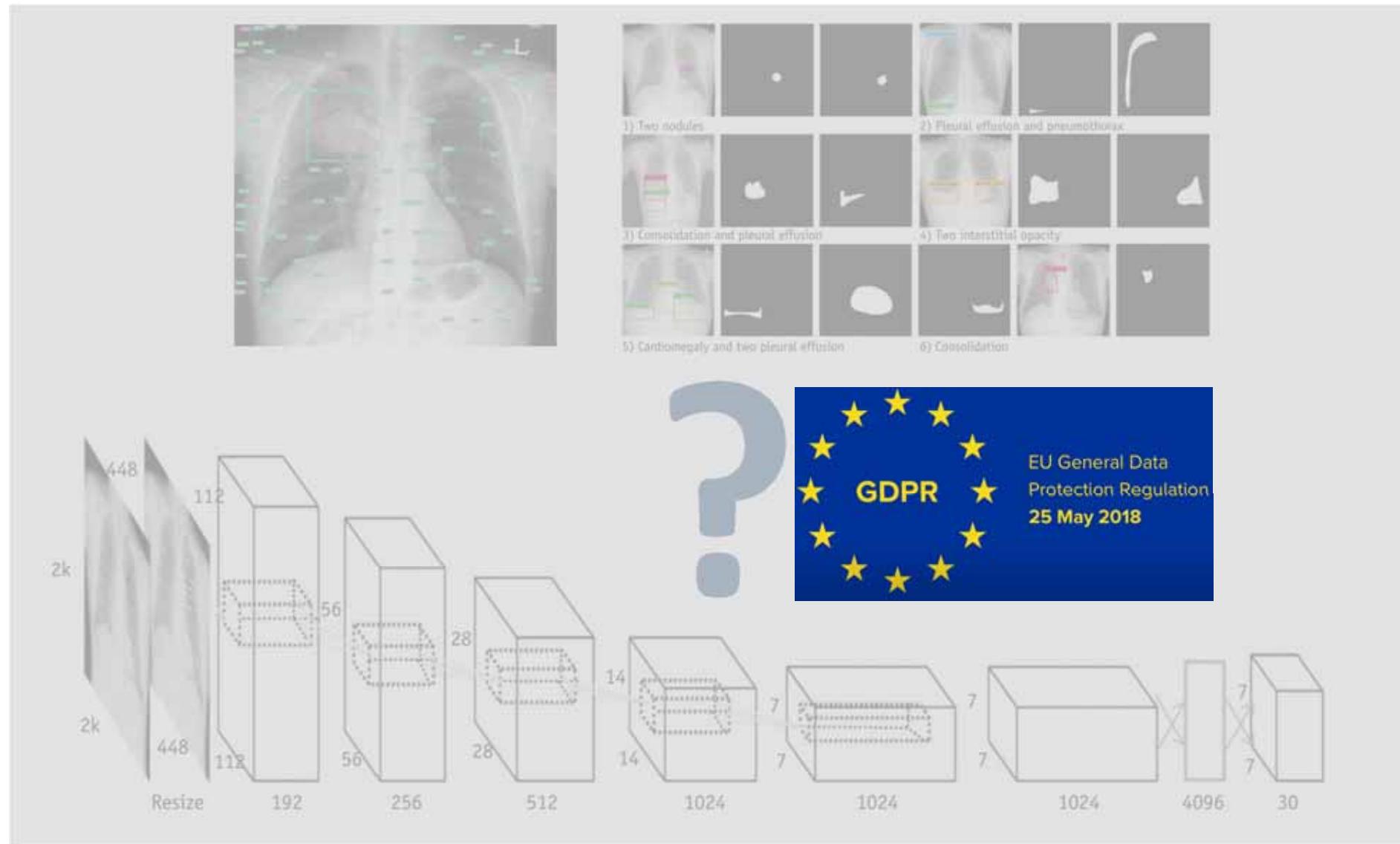


Krizhevsky, A., Sutskever, I. & Hinton, G. E. Imagenet classification with deep convolutional neural networks. In: Pereira, F., Burges, C. J. C., Bottou, L. & Weinberger, K. Q., eds. Advances in neural information processing systems (NIPS 2012), 2012 Lake Tahoe. 1097-1105.

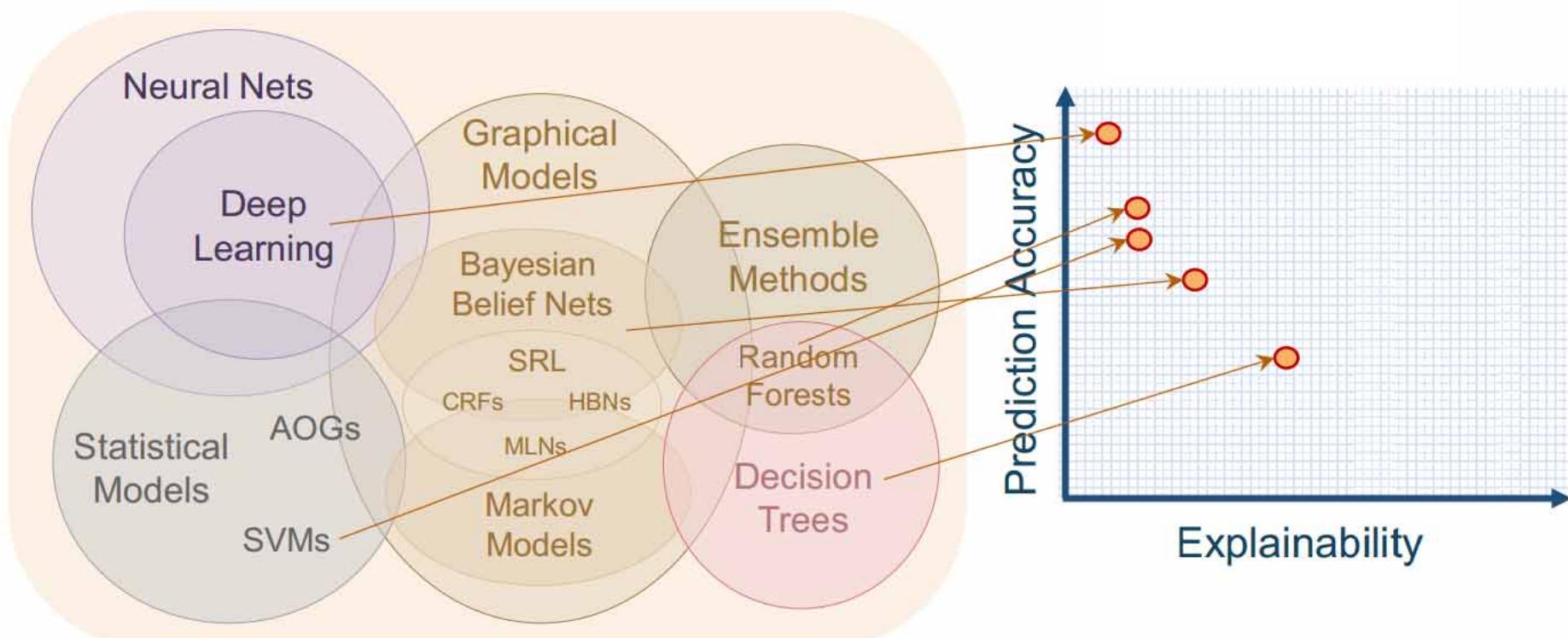


Source: NASA, Image is in the public domain

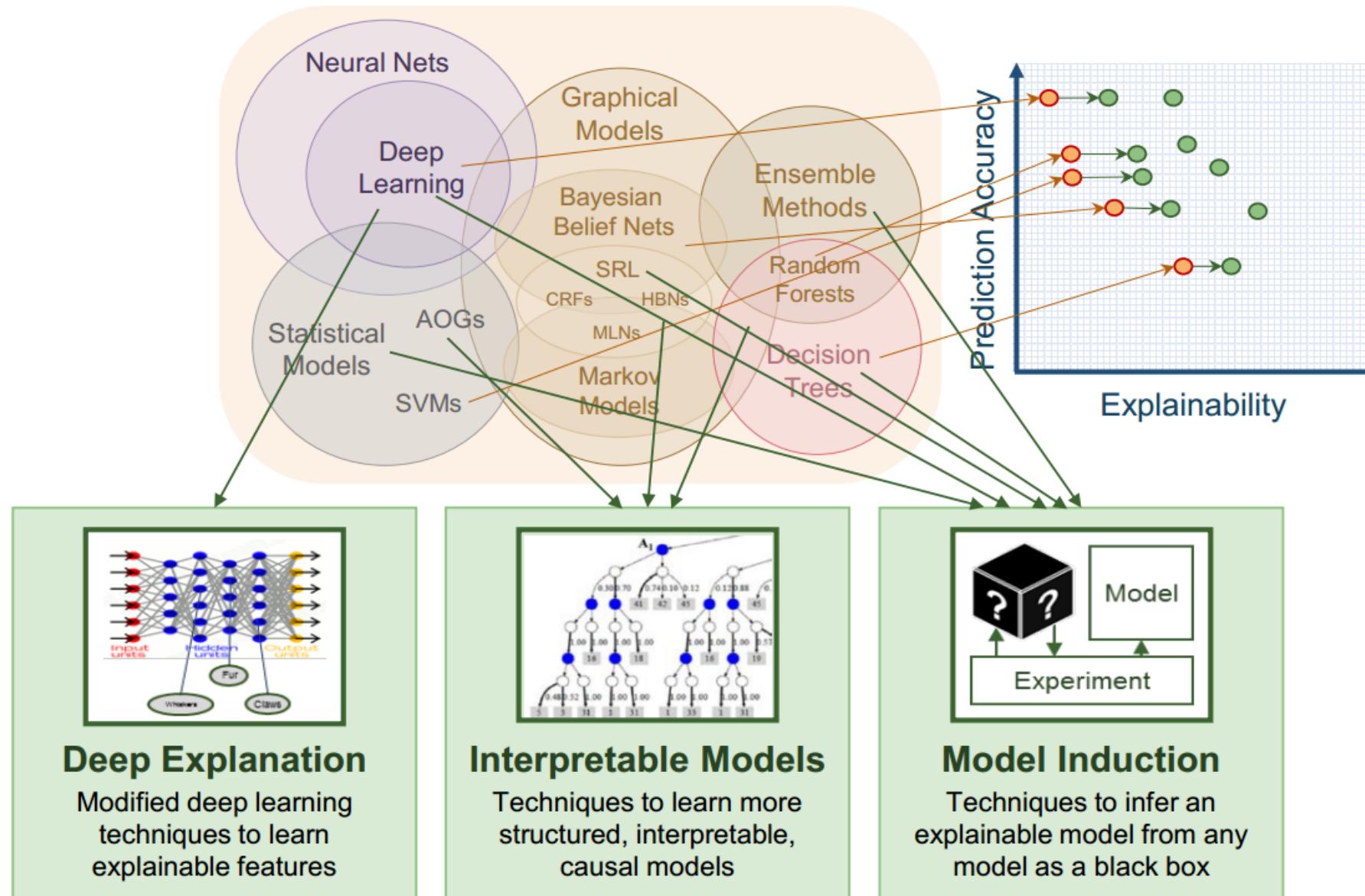
# The need for explainability



June-Goo Lee, Sanghoon Jun, Young-Won Cho, Hyunna Lee, Guk Bae Kim, Joon Beom Seo & Namkug Kim 2017. Deep learning in medical imaging: general overview. Korean journal of radiology, 18, (4), 570-584, doi:10.3348/kjr.2017.18.4.570.

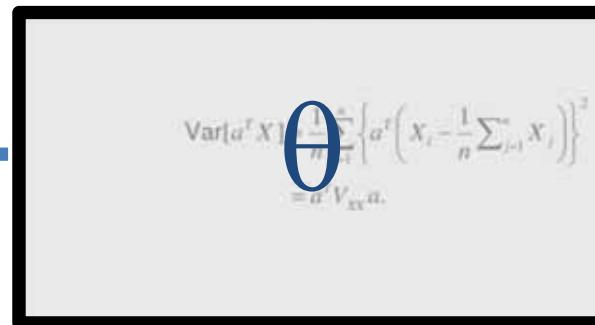


David Gunning 2016. Explainable artificial intelligence (XAI): Technical Report Defense Advanced Research Projects Agency DARPA-BAA-16-53, Arlington, USA, DARPA.



David Gunning 2016. Explainable artificial intelligence (XAI): Technical Report Defense Advanced Research Projects Agency DARPA-BAA-16-53, Arlington, USA, DARPA.

*Why did the algorithm do that?  
Can I trust these results?  
How can I correct an error?*



Input data

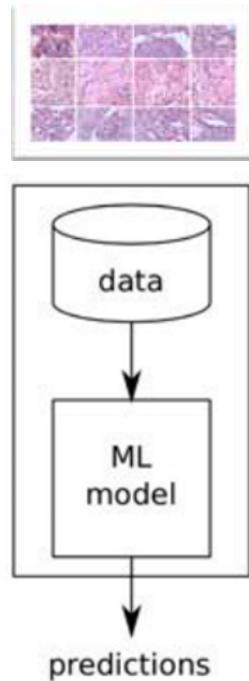
### A possible solution



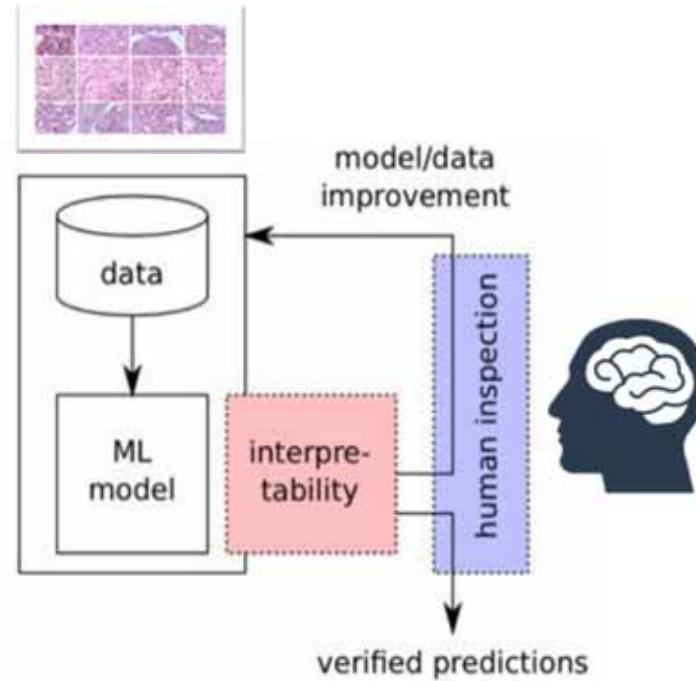
*The domain expert can understand why ...  
The domain expert can learn and correct errors ...  
The domain expert can re-enact on demand ...*

# 05

# iML



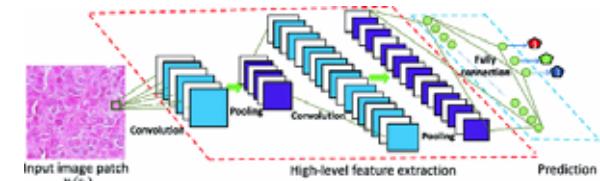
Generalization Error



Generalization Error + Human Experience

Andreas Holzinger 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? *Brain Informatics*, 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.

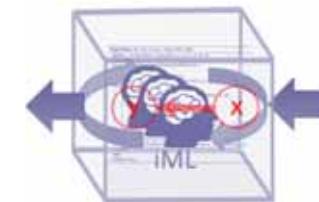
**Verify that algorithms/classifiers work as expected**  
Wrong decisions can be costly and dangerous



**Understanding the weaknesses and errors of the ML-Model - Detection of bias in both directions**



**Scientific interpretability, replicability, causality**  
The “why” is often more important than the prediction



**Enable re-traceability, re-enactivity**  
Compliance to legislation “right for explanation”,  
retain human reliability, fosters trust and acceptance



Hans Holbein d.J., 1533,  
The Ambassadors,  
London: National Gallery

Lopez-Paz, D., Muandet, K., Schölkopf, B. & Tolstikhin, I. 2015. Towards a learning theory of cause-effect inference. Proceedings of the 32nd International Conference on Machine Learning, JMLR, Lille, France.

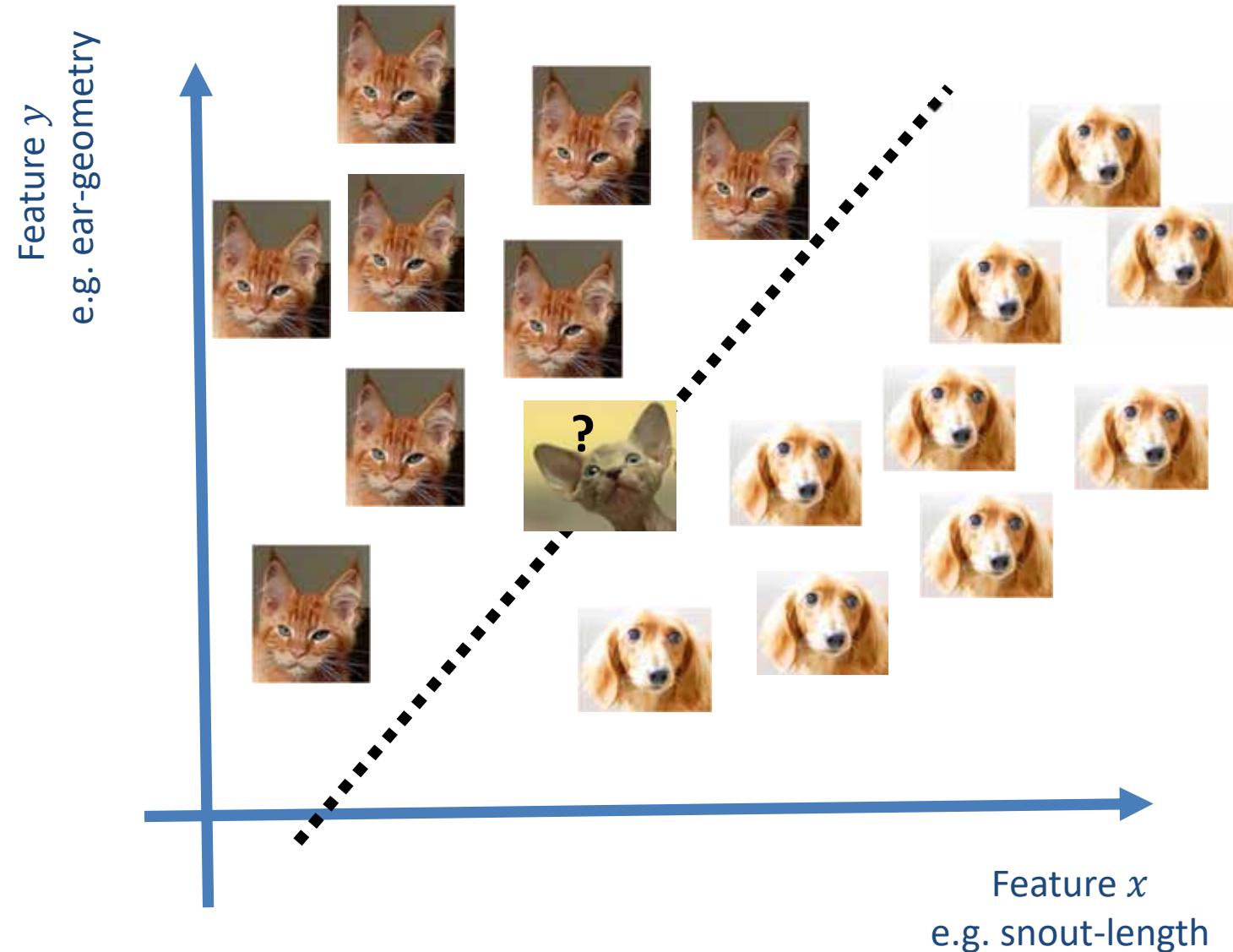


<https://www.youtube.com/watch?v=9KiVNIUMmCc>

- “How do humans generalize from so few examples?”
  - Learning relevant representations
  - Disentangling the explanatory factors
  - Finding the shared underlying explanatory factors, in particular between  $P(x)$  and  $P(Y|X)$ , with a causal link between  $Y \rightarrow X$

Bengio, Y., Courville, A. & Vincent, P. 2013. Representation learning: A review and new perspectives. *IEEE transactions on pattern analysis and machine intelligence*, 35, (8), 1798-1828, doi:10.1109/TPAMI.2013.50.

Tenenbaum, J. B., Kemp, C., Griffiths, T. L. & Goodman, N. D. 2011. How to grow a mind: Statistics, structure, and abstraction. *Science*, 331, (6022), 1279-1285, doi:10.1126/science.1192788.



# Even Children can make inferences from little data ...

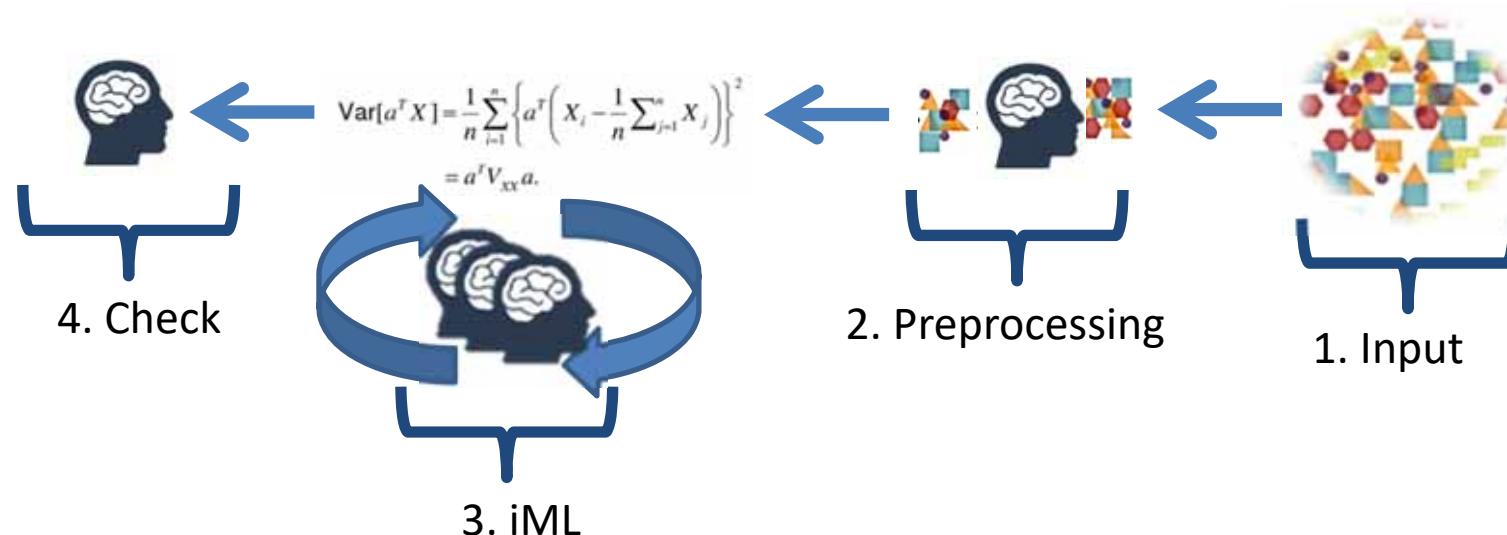


Tenenbaum, J. B., Kemp, C., Griffiths, T. L. & Goodman, N. D. 2011. How to grow a mind: Statistics, structure, and abstraction. *Science*, 331, (6022), 1279-1285, doi:10.1126/science.1192788.



See also: Ian J. Goodfellow, Jonathon Shlens & Christian Szegedy 2014. Explaining and harnessing adversarial examples. arXiv:1412.6572, and see more examples: <https://imgur.com/a/K4RWn>

**Interactive Machine Learning:** Human is seen as an agent involved in the actual learning phase, step-by-step influencing measures such as distance, cost functions ...



Holzinger, A. 2016. Interactive Machine Learning for Health Informatics: When do we need the human-in-the-loop? Brain Informatics (BRIN), 3, (2), 119-131, doi:10.1007/s40708-016-0042-6.

---

```
Input : ProblemSize,  $m$ ,  $\beta$ ,  $\rho$ ,  $\sigma$ ,  $q_0$ 
Output:  $P_{best}$ 
 $P_{best} \leftarrow \text{CreateHeuristicSolution(ProblemSize);}$ 
 $P_{best\_cost} \leftarrow \text{Cost}(P_{best});$ 
 $Pheromone_{init} \leftarrow \frac{1.0}{\text{ProblemSize} \times P_{best\_cost}};$ 
 $Pheromone \leftarrow \text{InitializePheromone}(Pheromone_{init});$ 
while  $\neg \text{StopCondition}()$  do
    for  $i = 1$  to  $m$  do
         $S_i \leftarrow \text{ConstructSolution}(Pheromone, \text{ProblemSize}, \beta, q_0);$ 
         $S_{i\_cost} \leftarrow \text{Cost}(S_i);$ 
        if  $S_{i\_cost} \leq P_{best\_cost}$  then
             $P_{best\_cost} \leftarrow S_{i\_cost};$ 
             $P_{best} \leftarrow S_i;$ 
        end
         $\text{LocalUpdateAndDecayPheromone}(Pheromone, S_i, S_{i\_cost}, \rho);$ 
    end
     $\text{GlobalUpdateAndDecayPheromone}(Pheromone, P_{best}, P_{best\_cost}, \rho);$ 
    while  $\text{isUserInteraction}()$  do
         $\text{GlobalAddAndRemovePheromone}(Pheromone, P_{best}, P_{best\_cost}, \rho);$ 
    end
end
return  $P_{best};$ 
```

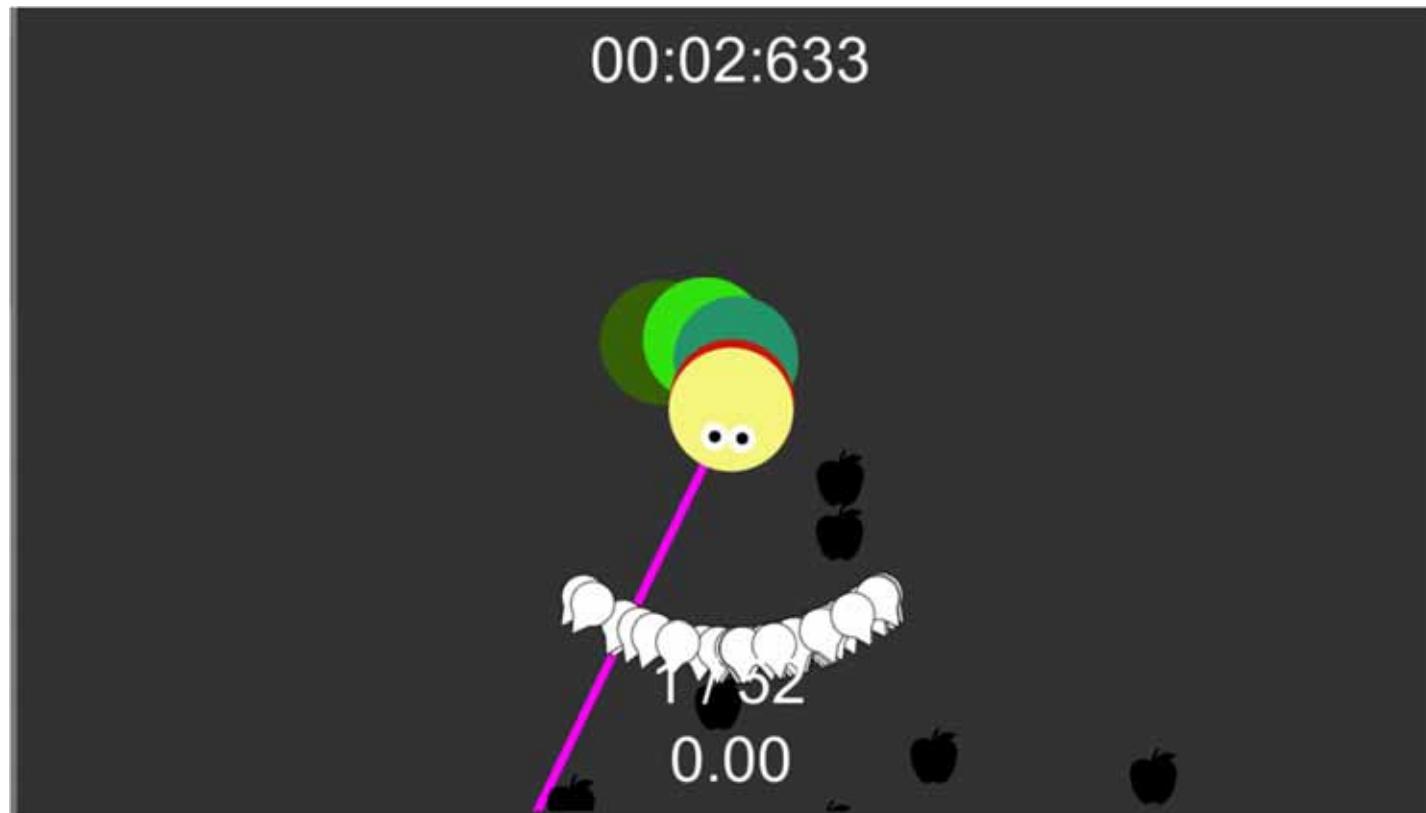
---

Holzinger, A., Plass, M., Holzinger, K., Crisan, G., Pintea, C. & Palade, V. 2016. Towards interactive Machine Learning (iML): Applying Ant Colony Algorithms to solve the Traveling Salesman Problem with the Human-in-the-Loop approach. Springer Lecture Notes in Computer Science LNCS 9817. 81-95, doi:10.1007/978-3-319-45507-56.

$$p_{ij} = \frac{[\tau_{ij}]^\alpha \cdot [\eta_{ij}]^\beta}{\sum_{l \in J_i^k} [\tau(t)]^\alpha \cdot [\eta]^\beta}$$

- $p_{ij}$  ... **probability** of ants that they, at a particular node  $i$ , select the route from node  $i \rightarrow j$  ("heuristic desirability")
- $\alpha > 0$  and  $\beta > 0$  ... the **influence parameters** ( $\alpha$  ... history coefficient,  $\beta$  ... heuristic coefficient) usually  $\alpha \approx \beta \approx 2 < 5$
- $\tau_{ij}$  ... the **pheromone value** for the components, i.e. the amount of pheromone on edge  $(i, j)$
- $k$  ... the set of usable components
- $J_i$  ... the set of nodes that ant  $k$  can reach from  $v_i$  (tabu list)
- $\eta_{ij} = \frac{1}{dij}$  ... attractiveness computed by a heuristic, indicating the "a-priori **desirability**" of the move

<http://hci-kdd.org/gamification-interactive-machine-learning/>



# LIVE DEMO

(<https://iml.hci-kdd.org/imlTspSolver/>)

ANDROID:

<https://play.google.com/store/apps/details?id=com.hcikdd.imlacosolver>

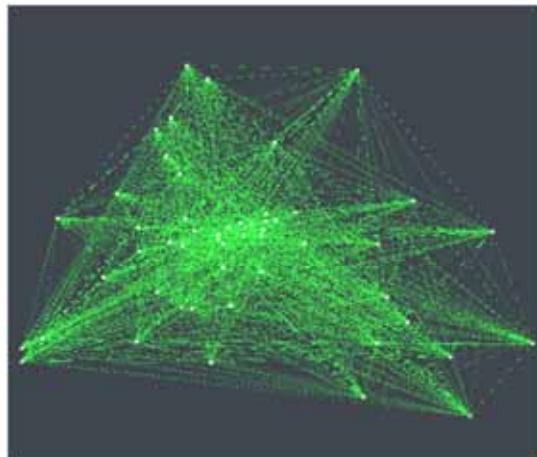


<http://hci-kdd.org/gamification-interactive-machine-learning/>



- **Ant algorithm:** Swarm algorithm driven by pheromones. Ants deposit pheromones on trails, which helps other ants decide, which trail to choose. *In our example we use the algorithm to find the shortest tour in a point set. (Traveling Salesman Problem)*
  - visualization of pheromones is a good interpretation of the ant algorithm

- The pheromones are showing “the state” (high or low frequented paths of ants) of the algorithm.



initial pheromone distribution



pheromones after 100 iterations



pheromones after 500 iterations

<http://iml.hci-kdd.org/imlTspSolver/>

### parameter settings

Algorithm:	MMAS
TSP-File:	berlin52.ts
#ants:	51
alpha:	1
beta:	2
Reload	EXIT

choose TSP file  
 choose number of Ants  
 choose alpha value (influence of pheromone)  
 choose beta value (influence of distances)  
 click "RunAnt"  
**ITERATION:**  
 choose number of iterations  
 hit enter button  
 EXIT  
 choose number of cities  
 hit enter button

ACO TSP Solver v0.1 09.12.2017

Made with Python from: www.pythontutor.com, licensed  
 by CC 3.0 BY

instructions for users

### model view

### perform step or iterations

	Step	Iteration
100		

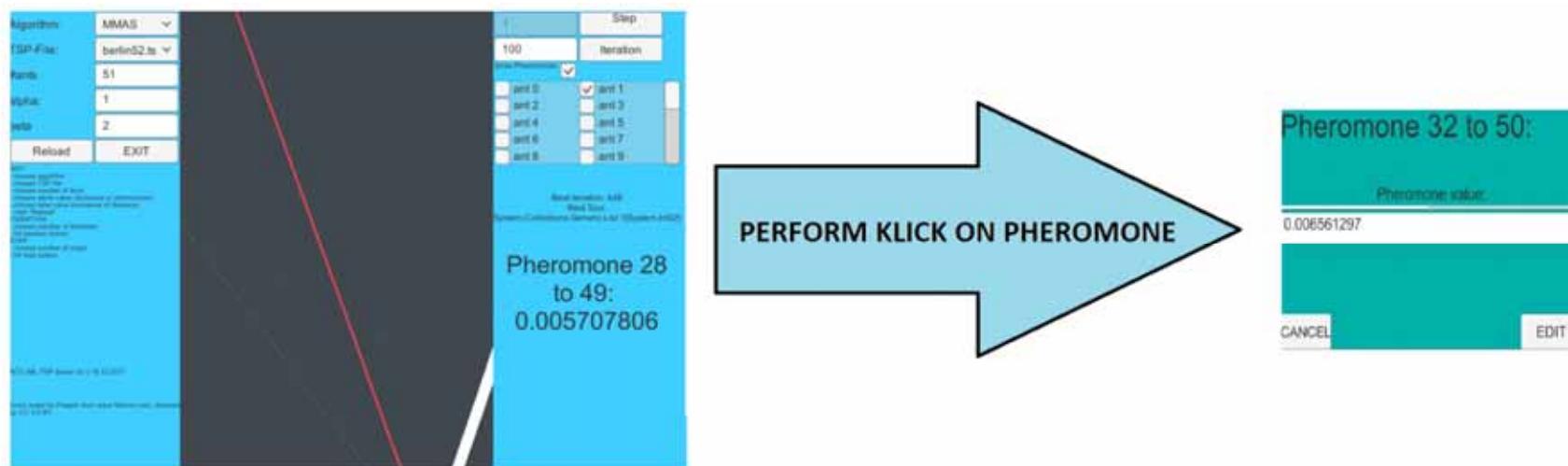
Best iteration: 448  
 Best tour:  
 System.Collections.Generic.List`1[System.Int32]

Pheromone 13  
 to 38:  
 1.572088E-05

display paticular  
ants (at any state)

additional information  
about the current state

- iteration vs. step: look inside the iteration
- make the ant algorithm interactive
  - change pheromones at any time
  - *change routes of certain ants in the current iteration (future work)*



# 06

# Causality and

# Causability



David Hume (1711-1776)

Causation is a matter of perception

*We remember seeing the flame, and feeling a sensation called heat; without further ceremony, we call the one cause and the other effect*



Statistical ML

*Forget causation! Correlation is all you should ask for.*



Judea Pearl (1936-)

A mathematical definition of causality

*Forget empirical observations! Define causality based on a network of known, physical, causal relationships*

8

# Dependence vs. Causation

**Storks Deliver Babies ( $p=0.008$ )**

Robert Matthews

Article first published online: 25 DEC 2001

DOI: 10.1111/1467-9639.00013

Teaching Statistics Trust, 2000



Teaching Statistics  
Volume 22, Issue 2  
38, June 2000

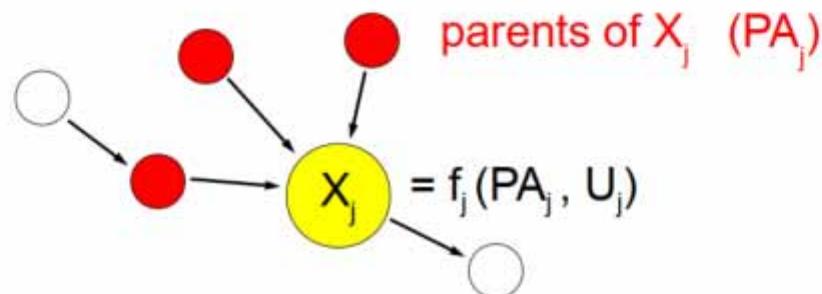
Country	Area (km <sup>2</sup> )	Storks (pairs)	Humans (10 <sup>6</sup> )	Birth rate (10 <sup>3</sup> /yr)
Albania	28,750	100	3.2	83
Austria	83,860	300	7.6	87
Belgium	30,520	1	9.9	118
Bulgaria	111,000	5000	9.0	117
Denmark	43,100	9	5.1	59
France	544,000	140	56	774
Germany	357,000	3300	78	901
Greece	132,000	2500	10	106
Holland	41,900	4	15	188
Hungary	93,000	5000	11	124
Italy	301,280	5	57	551
Poland	312,680	30,000	<a href="mailto:rajm@compuserve.com">mailto:rajm@compuserve.com</a>	
Portugal	92,390	1500	10	120
Romania	237,500	5000	23	367
Spain	504,750	8000	39	439
Switzerland	41,290	150	6.7	82
Turkey	779,450	25,000	56	1576

**Table 1.** Geographic, human and stork data for 17 European countries

## Functional Causal Model (*Pearl et al.*)



- Set of observables  $X_1, \dots, X_n$
- directed acyclic graph  $G$  with vertices  $X_1, \dots, X_n$
- Semantics: parents = direct causes
- $X_i = f_i(\text{ParentsOf}_i, \text{Noise}_i)$ , with independent  $\text{Noise}_1, \dots, \text{Noise}_n$ .
- “Noise” means “unexplained” (or “exogenous”), we use  $U_i$
- Can add requirement that  $f_1, \dots, f_n, \text{Noise}_1, \dots, \text{Noise}_n$  “independent”  
(cf. Lemeire & Dirkx 2006, Janzing & Schölkopf 2010 — more below)

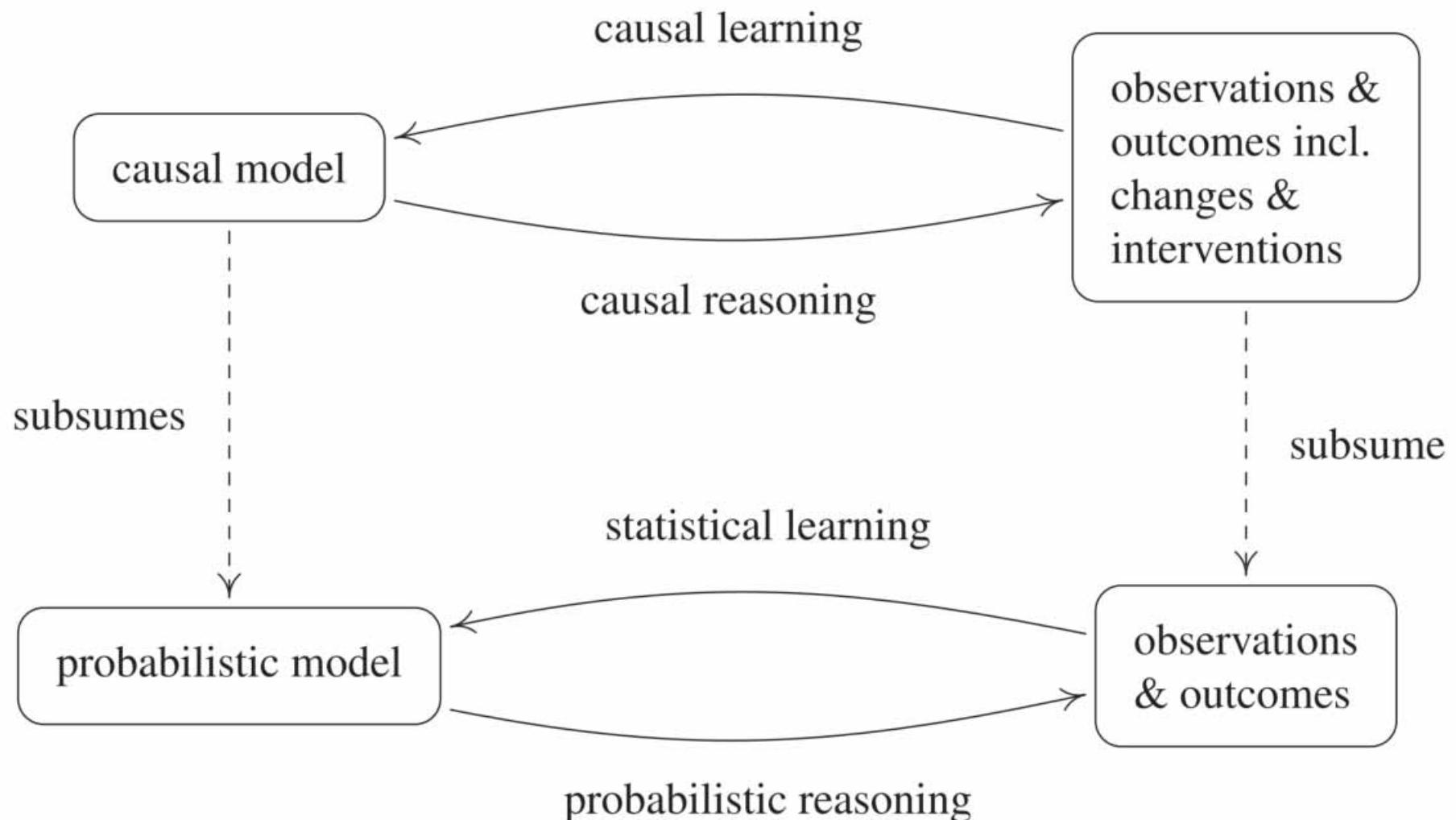


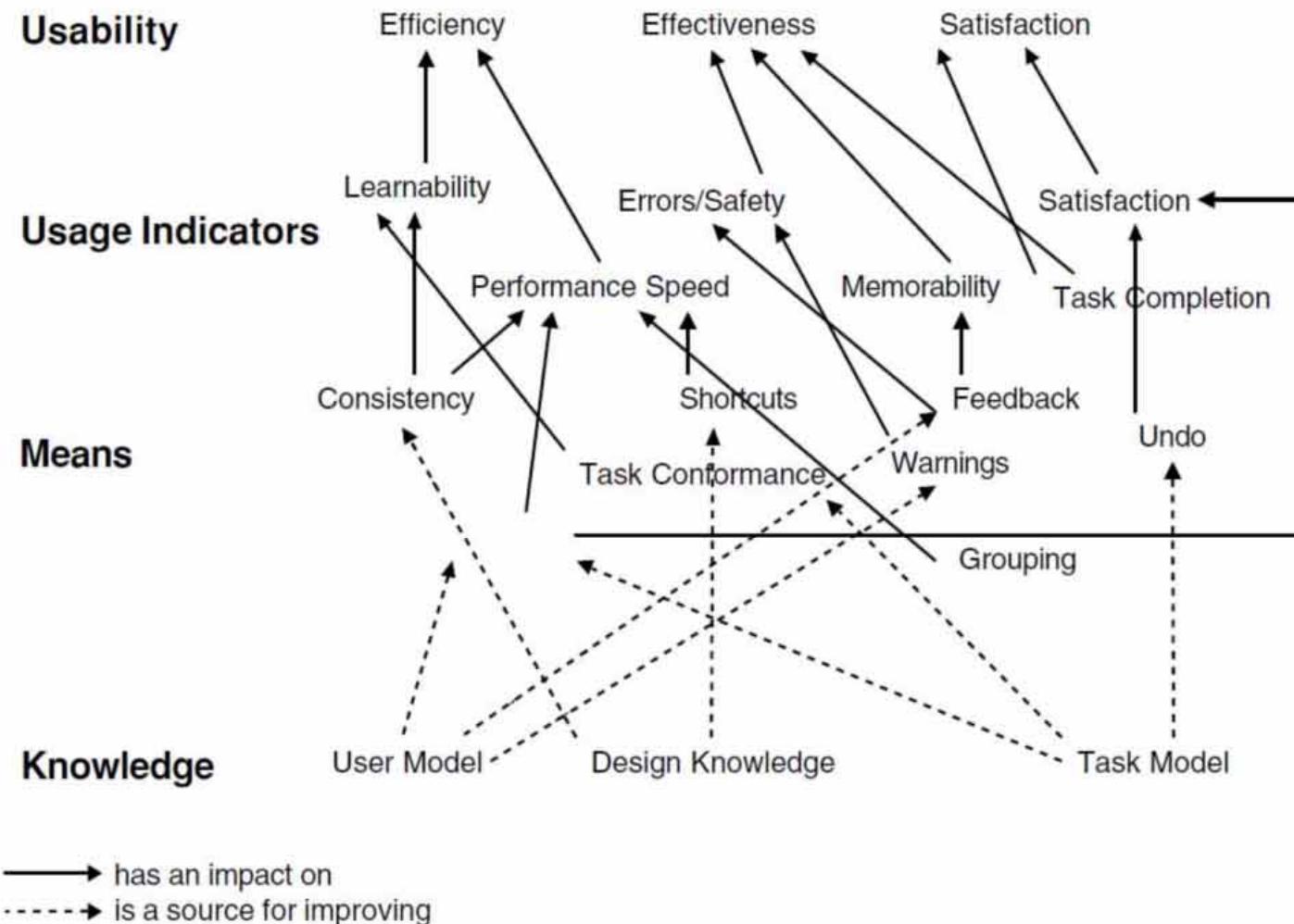
Explainability	in a technical sense highlights decision-relevant parts of the used representations of the algorithms and active parts in the algorithmic model, that either contribute to the model accuracy on the training set, or to a specific prediction for one particular observation. It does not refer to an explicit human model.
Causability	as the extent to which an explanation of a statement to a human expert achieves a specified level of causal understanding with effectiveness, efficiency and satisfaction in a specified context of use.

- **Causability := a property of a person, while**
- **Explainability := a property of a system**

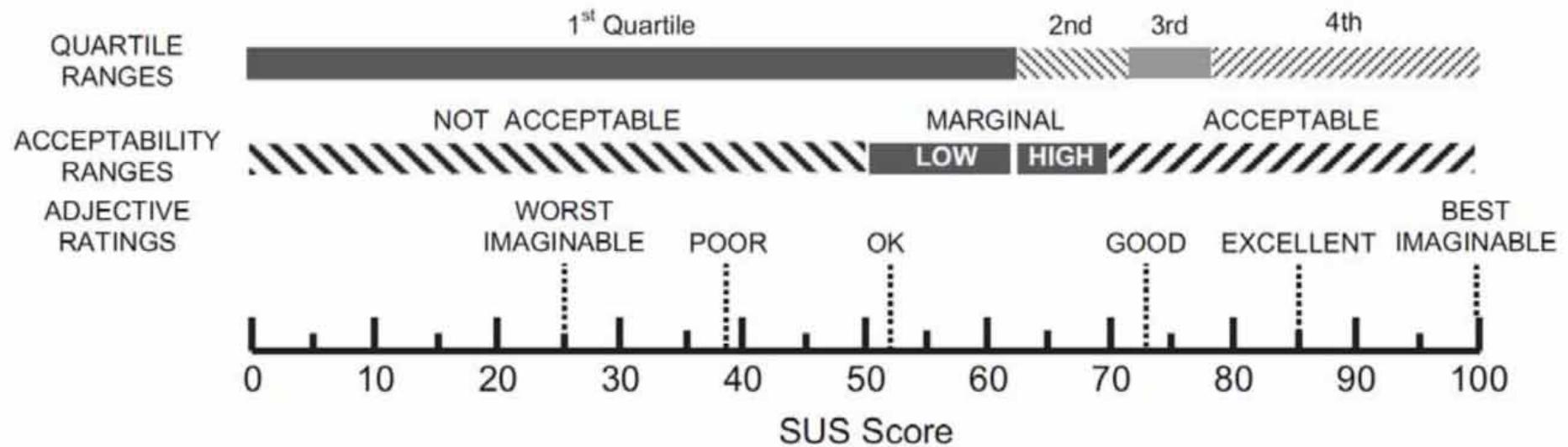
07

# Measuring Causality?





Veer, G. C. v. d. & Welie, M. v. (2004) DUTCH: Designing for Users and Tasks from Concepts to Handles. In: Diaper, D. & Stanton, N. (Eds.) *The Handbook of Task Analysis for Human-Computer Interaction*. Mahwah (New Jersey), Lawrence Erlbaum, 155-173.



Bangor, A., Kortum, P. T. & Miller, J. T. (2008) An empirical evaluation of the System Usability Scale. *International Journal of Human-Computer Interaction*, 24, 6, 574-594.

The System Usability Scale Standard Version		Strongly Disagree	Strongly Agree			
		1	2	3	4	5
1	I think that I would like to use this system frequently.		0	0	0	0
2	I found the system unnecessarily complex.		0	0	0	0
3	I thought the system was easy to use.		0	0	0	0
4	I think that I would need the support of a technical person to be able to use this system.		0	0	0	0
5	I found the various functions in this system were well integrated.		0	0	0	0
6	I thought there was too much inconsistency in this system.		0	0	0	0
7	I would imagine that most people would learn to use this system very quickly.		0	0	0	0
8	I found the system very awkward to use.		0	0	0	0
9	I felt very confident using the system.		0	0	0	0
10	I needed to learn a lot of things before I could get going with this system.		0	0	0	0

# Our Goal in this AK: design, develop & test a System Causability Scale