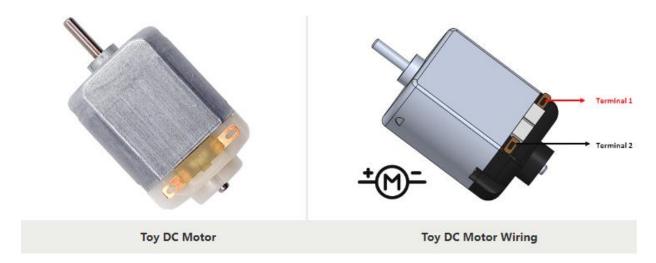
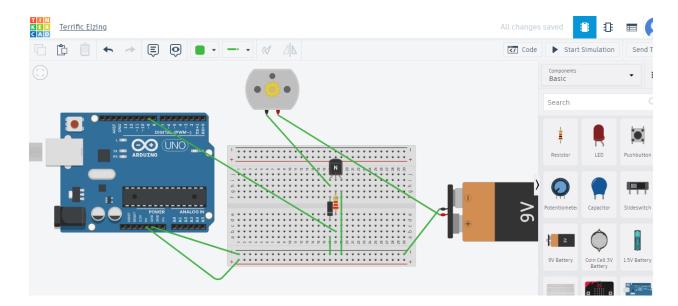
# Program to demonstrate DC motor using Arduino uno in tinkercad step by step in a simple and easy way





**Step 1: Set Up Tinkercad** 

- 1. **Log in** to Tinkercad.
- 2. Click on "Circuits" and then "Create new Circuit."

# **Step 2: Add Components**

- 1. **Arduino Uno**: Drag it onto the workspace.
- 2. **DC Motor**: Add it to the workspace.

- 3. **9V Battery**: Drag it into the circuit.
- 4. NPN Transistor (e.g., 2N2222): Add it.
- 5. **Diode** (e.g., 1N4007): Add it.
- 6. **Resistor** (220 $\Omega$ ): Place it in the workspace.
- 7. (Optional) **Breadboard**: Add it for organization.

### **Step 3: Wire the Components**

#### 1. Motor:

- o Connect one terminal to the **collector** of the NPN transistor.
- o Connect the other terminal to the **positive** terminal of the battery.

#### 2. **Diode**:

- o Connect the **anode** (no stripe) to the collector.
- o Connect the **cathode** (stripe) to the **negative** terminal of the battery.

#### 3. Transistor:

- o Connect the **emitter** to the **ground (GND)** rail.
- Connect the base to one end of the resistor; connect the other end to digital pin 9
  on the Arduino.

#### 4. Power Connections:

- o Connect the **negative terminal** of the battery to the GND rail.
- o Connect the **GND** pin of the Arduino to the GND rail.

# **Step 4: Write the Arduino Code**

- 1. Click the "Code" button.
- 2. Replace the default code with:

```
int motorPin = 9; // Motor control pin

void setup() {
  pinMode(motorPin, OUTPUT); // Set pin as output
}

void loop() {
  digitalWrite(motorPin, HIGH); // Turn motor ON
  delay(2000); // Wait for 2 seconds
  digitalWrite(motorPin, LOW); // Turn motor OFF
  delay(2000); // Wait for 2 seconds
}
```

# **Step 5: Simulate the Circuit**

- 1. Click "Start Simulation."
- 2. Observe the motor: it should turn on for 2 seconds and then off for 2 seconds, repeating this cycle.

### **Step 6: Debugging (if needed)**

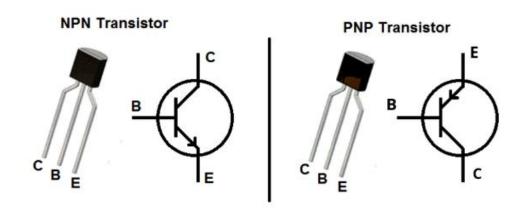
- Check connections: Ensure they are correct.
- **Verify code**: Ensure there are no syntax errors.

#### **Conclusion**

You've successfully set up a DC motor controlled by an Arduino Uno! The motor will turn on and off in a loop as programmed. Enjoy experimenting!

An **NPN transistor** is a device that can control a larger electrical current using a smaller one.

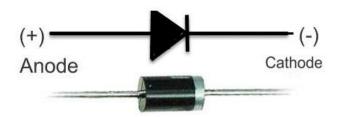
You can think of an NPN transistor like a water faucet. When you turn the handle (the base), it allows a larger flow of water (current) to come out from the pipe (collector) to the drain (emitter). A little twist controls a much bigger flow! a small turn (input current) controls a larger flow of water (output current) from the pipe.



- base terminal; E - emitter terminal; C - collector terminal

o A **diode** is a semiconductor device that allows current to flow in one direction only, acting as a one-way valve for electrical current. It consists of a p-n junction and is used in various

applications like rectification, voltage regulation, and signal demodulation. In circuits, diodes protect components from reverse polarity and voltage spikes.



# 1N4007 Diode Pinout



# **1N4007 Diode Electronic Symbol**



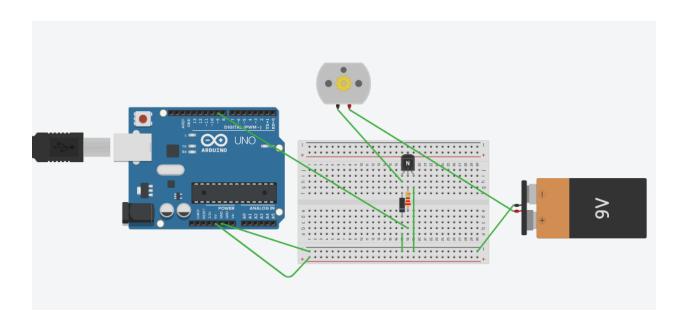
int motorPin = 9; // Motor control pin

void setup() {

 $pinMode(motorPin,\,OUTPUT);\,/\!/\,\,Set\,\,pin\,\,as\,\,output$ 

}

}



int motorPin = 9; // Motor control pin

void setup() {