Collaboration Pattern: 103

ActionRobot103 2

## hasNextActionRobot

ActionRobot103\_1
hasAction: Move to <Actor on Robot103\_0
hasActor: Human Sobject: Large rock
hasAction: Pick up <object> in <loc
hasLocation: Top of rock pile

hasActionRobot

hasActionHuman

ActionHuman103 2

hasNextActionHuman

ActionHuman103 1

hasNextActionHuman

ActionHuman103\_0

CP103
hasRemainingTime: 3000
hasUnixTimeStamp: 1720618520
hasVictimHarm: 0
hasRemainingRocks: 27
hasCPNum: 103
hasRoundNumber: 4
hasTicksLasted: 1914
hasParticipantNumber: 4090
hasTimeStamp: 2024-07-10T15:35:20
hasCPLabel: Top of the pile improved

hasSituation

Situation103\_0 hasLocation: Top of rock pile hasObject: Large rock

hasNextSituation

Situation103 1