Collaboration Pattern: 075

ActionRobot75 2

hasNextActionRobot

ActionRobot75 1 hasActor: Human hasLocation: On top of <Actor> hasAction: Break <object> in <location> haasObject: Large rock ActionRobot75_0

hasAction: Move to <Actor> hasActor: Human

hasActionRobot

CP75

hasVictimHarm: 0 hasTimeStamp: 2024-07-02T15:32:48

hasCPNum: 75 hasTicksLasted: 2753 hasUnixTimeStamp: 1719927168 hasParticipantNumber: 4086 hasCPLabel: Breaking large rocks hasRemainingRocks: 41

hasRoundNumber: 2 hasActionHuman hasRemainingTime: 3000

ActionHuman75 0 hasObject: Large rock hasAction: Move to <Object>

hasNextActionHuman

ActionHuman75_1

hasNextActionHuman

ActionHuman75_2

Situation75 1

sNextSituation

Situation75 0 hasObject: Large rock hasSituation