Collaboration Pattern: 016

ActionRobot16\_0 hasLocation: Top of rock pile hasAction: Pick up <object> in <location> hasObject: Large rock

hasNextActionRobot

ActionRobot16\_2 ActionRobot16\_1
hasAction: Drop <object> in <location> hasLocation: <Left> side of field hasObject: Large rock

ActionHuman16\_0 ActionHuman16\_1

hasNextActionHuman

ActionHuman16\_2

hasActionRobot

CP16

hasTicksLasted: 330 hasParticipantNumber: 4081 hasCPNum: 16

hasRoundNumber: 5 hasCPLabel: top large hasTimeScore: 922

hasSituation

Situation16 0 hasLocation: Top of rock pile hasObject: Large rock hasNextSituation

Situation16\_1

hasActionHuman