Collaboration Pattern: 161

ActionRobot161_2
hasNextActionRobot
ActionRobot161_1
hasNextActionRobot
ActionRobot161_0
hasAction: Pick up <object> in <location>
hasLocation: <Left> side of rock pile
hasObject: Large rock

hasActionRobot

CP161
hasParticipantNumber: 4097
hasRemainingTime: 3000
hasVictimHarm: 0
hasTimeStamp: 2024-07-22T09:23:00
hasUnixTimeStamp: 1721632980
hasRemainingRocks: 24
hasRoundNumber: 3
hasCPLabel: Large rock
hasCPNum: 161
hasTicksLasted: 3018

Situation161_1
hasNextSituation
Situation161_0
hasLocation: Top of rock pile
hasObject: Large rock

hasSituation

hasActionHuman

ActionHuman161_0
hasAction: Pick up <object> in <locatio
hasLocation: <Left> side of rock pile
hasObject: Large rock
hasNextActionHuman
ActionHuman161_1
hasNextActionHuman
ActionHuman161_2