Collaboration Pattern: 032

ActionRobot32_0
hasObject: Brown rock
hasAction: Pick up <object> in <loca
hasLocation: Top of rock pile

ActionRobot32_2

hasNextActionRobot

hasNextActionRobot

ActionRobot32_1

hasActionRobot

CP32
hasTimeScore: 2830
hasRoundNumber: 7
hasParticipantNumber: 4082
hasCPNum: 32
hasCPLabel: Brown rock
hasTicksLasted: 2779

hasActionHuman

ActionHuman32_0
hasAction: Stand still in <location>
hasLocation: <Left> side of field

hasNextActionHuman

ActionHuman32_1

hasSituation

hasNextActionHuman

ActionHuman32_2

Situation32_0
location: <Right> side of rock pile
hasObject: Brown rock

hasNextSituation

Situation32_1