Collaboration Pattern: 011

ActionRobot11 2 hasNextActionRobot ActionRobot11_1 hasAction: Drop <object> in <location> hasLocation: <Right> side of field hasObject: Large rock hasNextActionRobot ActionRobot11 0 hasAction: Pick up <object> in <location>
hasObject: Large rock
hasLocation: Top of rock pile ActionHuman11 0 hasAction: Stand still in <location> hasLocation: <Left> side of field hasNextActionHuman ActionHuman11_1
NextActionHuman11_2 hasActionRobot hasActionHuman CP11 hasParticipantNumber: 4073 hasTicksLasted: 896 hasRoundNumber: 8 hasCPNum: 11 hasCPLabel: large rocks on top V5 hasTimeScore: 5057

> Situation11_0 hasObject: Small rock hasObject: Brown rock hasObject: Large rock habastocation: Top of rock pile

Situation11_1

hasSituation