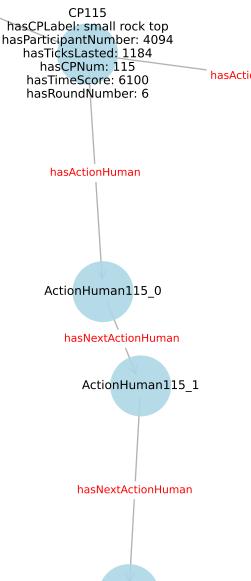
Situation115 1

hasNextSituation

Situation115_0 hasObject: Small rock hasLocation: Top of rock pile

hasSituation



ActionHuman115_2

has Action Robot

ActionRobot115_0
hasObject: Small rock
hasAction: Move to <Object>

hasNextActionRobot

ActionRobot115_1
hasAction: Pick up <object> in <location>
hasObject: Small rock

hasNextActionRobot

ActionRobot115_2
hasAction: Drop <object> in <loc
hasObject: Small rock
hasLocation: <Left> side of fire