Collaboration Pattern: 070

Situation70_1

Situation70_0
hasObject: Large rock
hasLocation: Top of rock pile

hasNextSituation

hasSituation

CP70
hasCPLabel: Move
hasParticipantNumber: 4087
hasTimeScore: 5700
hasTicksLasted: 183
hasCPNum: 70
hasRoundNumber: 5

hasActionRobot

hasActionHuman

ActionRobot70_0
hasAction: Pick up <object> in <location>
hasLocation: Top of rock pile
hasObject: Large rock

hasNextActionRobot

ActionRobot70_1
hasAction: Drop <object> in <location>
hasObject: Large rock
hasLocation: <Right> side of field

hasNextActionRobot

ActionRobot70_2

ActionHuman70_2

ActionHuman70_1

ActionHuman70_0

hasNextActionHuman

hasNextActionHuman