Collaboration Pattern: 003

Situation3_1

hasNextSituation

Situation3_0
hasObject: Small rock
hasLocation: Top of rock pile

hasSituation

ActionRobot3_2

hasNextActionRobot

ActionRobot3_1

hasNextActionRobot

ActionRobot3_0
hasLocation: <Right> side of field
hasAction: Stand still in <location>

hasActionRobot

CP3
hasParticipantNumber: 4073
hasCPNum: 3
hasRoundNumber: 3
hasTicksLasted: 2470
hasCPLabel: Small rocks on top
hasTimeScore: 5800

hasActionHuman

ActionHuman3_0

hasNextActionHuman

ActionHuman3_1
hasAction: Pick up <object> in <location>
hasObject: Small rock
hasLocation: Top of rock pile

hasNextActionHuman

ActionHuman3_2
hasAction: Drop <object> in <location>
hasObject: Small rock
hasLocation: <Left> side of field