## Collaboration Pattern: 016

Situation16 1 hasObject: Large rock hasLocation: Bottom of rock pile

hasNextSituation

Situation16 0 hasLocation: <Left> side of field hasActor: Human

ActionHuman16\_2

hasNextActionHuman

ActionHuman16\_1

hasNextActionHuman

ActionHuman16 0 hasLocation: <Left> side of field hasActionHuman hasAction: Stand still in <location>

**dP16** hasRoundNumber: 7

hasSituation

hasTimeStamp: 2024-08-29T16:03:13 hasRemainingTime: 3000

hasCPNum: 16 hasTicksLasted: 250 hasVictimHarm: 0

hasCPLabel: move break big rock bottom hasParticipantNumber: 4071 hasUnixTimeStamp: 1724940193 hasRemainingRocks: 19

hasActionRobot

ActionRobot16 0

ActionRobot16 1

hasAction: Pick up <object> in <location> hasLocation: Bottom of rock pile hasObject: Large rock

hasNextActionRobot

ActionRobot16\_2 hasAction: Drop <object> in <loc hasLocation: <Right> side of roc hasObject: Large rock