ActionHuman147_2

hasNextActionHuman

hasActionHuman

ActionHuman147_0 hasAction: Pick up <object> in <lo
ActionHuman147_5

ActionHuman147_5

ActionHuman147_5

hasObject: Brown rock

Situation147 1

hasNextSituation

Situation147 0 hasLocation: Top of rock pile

hasSituation

CP147 hasCPNum: 147 hasTicksLasted: 1 hasParticipantNumber: 4097 hasRoundNumber: 6 hasCPLabel: 1 hasTimeScore: 4900

hasActionRobot

ActionRobot147_1 hasObject: Brown rock hasAction: Move to <Object onRobot147_0

has Next Action Robot

ActionRobot147_2 hasLocation: <Left> side of field hasObject: Brown rock hasAction: Drop <object> in <location>