Collaboration Pattern: 102

Situation102 1

nasNextSituation Situation102_0 hasObject: Small rock hasLocation: Top of rock pile

hasSituation

CP102 hasRoundNumber: 4 hasTimeScore: 5300 hasCPNum: 102

ActionRobot102_2

hasCPLabel: Something Action Robot Action Robot 102 0 hasNext Action Robot has Participant Number: 4092 has Action: Move to Hospital Processing Robot 102 1 has Action: Pick up < object > in < location > hasTicksLasted: 2232

hasActionHuman

ActionHuman102_0 hasAction: Move to <Object>

hasNextActionHuman

ActionHuman102_1
hasAction: Pick up <object