Collaboration Pattern: 002

ActionRobot2_0

ActionRobot2_2
hasObject: Large rock
ion: Drop <object> in <location>
Location: <Right> side of field

hasNextActionRobot

ActionRobot2_1
hasObject: Large rock
hasLocation: Top of rock pile
hasAction: Pick up <object> in <location>

NextAction

hasActionRobot

CP2
hasTimeScore: 5800
hasTicksLasted: 546
hasCPLabel: Large rocks on top
hasCPNum: 2
hasParticipantNumber: 4073
hasRoundNumber: 3

hasSituation

Situation2_0
hasObject: Large rock
hasLocation: Top of rock pile

hasNextSituati

Situation2_1

hasActionHuman

ActionHuman2_0
hasAction: Stand still in <location>
hasActor: Human
hasLocation: <Left> side of field

hasNextActionHuman

ActionHuman2_1

hasNextActionHuman

ActionHuman2_2