Collaboration Pattern: 168

Situation168_1

hasNextSituation

Situation168_0
hasActor: Robot

ActionHuman168_2

hasNextActionHuman

ActionHuman168_1

hasNextActionHuman

ActionHuman168_0
hasObject: Large rock
hasAction: Move to <Object>

hasSituation

hasActionHuman

CP168
hasRemainingTime: 3000
hasUnixTimeStamp: 1721634460
hasTicksLasted: 905
hasTimeStamp: 2024-07-22T09:47:40
hasVictimHarm: 400
hasRoundNumber: 6
hasCPNum: 168
hasCPLabel: 3
hasRemainingRocks: 19
hasParticipantNumber: 4097

hasActionRobot

ActionRobot168_0
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: Bottom of rock pile

ActionRobot168_1
hasObject: Large rock
hasLocation: <Left> side of rock pile
hasAction: Drop <object> in <location>

hasNextActionRobot

ActionRobot168_2