Collaboration Pattern: 179

ActionRobot179\_2 hasAction: Pick up <object> in <location> hasLocation: Top of rock pile hasObject: Small rock

## hasNextActionRobot

ActionRobot179 1 hasLocation: Top of rock pile hasObject: Small rock ion: Pick up <object> in <location>

## hasNextActionRobot

ActionRobot179 0 on: Pick up <object> in <location> nasLocation: Top of rock pile hasObject: Small rock

hasActionRobot

CP179 hasCPLabel: PickUpMultipleSmall hasParticipantNumber: 4099 hasTicksLasted: 366

hasCPNum: 179 hasTimeScore: 1662 hasRoundNumber: 3

ActionHuman179\_1 hasActionHuman —

ActionHuman179\_0

hasNextActionHuman

ActionHuman179\_2

hasSituation

Situation179 0 hasLocation: Top of rock pile hasObject: Small rock hasNextSituation

Situation179 1