Collaboration Pattern: 017

ActionRobot17_1
hasAction: Drop <object> in <location>
ActionRobot17_22 extactionRobot Right side of field
hasObject: Brown rock
ActionRobot ActionRobot 17_0

hasAction: Pick up <object> in <location> hasObject: Brown rock hasLocation: Top of rock pile

Situation17_1

hasNextSituation

Situation17_0
hasObject: Brown rock
nasLocation: Top of rock pile

hasSituation _

hasActionRobot

CP17
hasParticipantNumber: 4081
hasTimeScore: 6200
hasTicksLasted: 1917
hasRoundNumber: 6
hasCPLabel: top brown
hasCPNum: 17

hasActionHuman

ActionHuman17_0 hasLocation: Above rock pile hasAction: Stand still in <locati

hasNextActionHuman

ActionHuman17_1

hasNextActionHuman

ActionHuman17_2