Collaboration Pattern: 067

ActionHuman67\_1 ActionHuman67\_2 hasNextActionHuman ActionHuman67\_0 ActionRobot67\_2 hasObject: Large rock
hasLocation: <Right> side of field
hasAction: Drop <object> in <location>
ActionRoboto 7\_0
hasObject: Large rock
hasLocation: Top of rock pile hasActionHuman ion: Pick up <object> in <location> hasActionRobot CP67 hasTimeScore: 1598 hasRoundNumber: 2 hasParticipantNumber: 4087 hasCPNum: 67 hasCPLabel: Move hasTicksLasted; 183

> Situation67\_0 hasObject: Large rock hasLocation: Top of rock pile hasNextSituation

hasSituation