Collaboration Pattern: 060

ActionRobot60_3 hasObject: Large rock hasLocation: <Left> side of rock pile hasAction: Drop <object> in <location> hasNextActionRobot ActionRobot60 2 hasLocation: <Left> side of rock pile
hasherIBAPM60elo stocation>
hasLocation: Top of rock pile hasObject: Large rock hasAction: Pick up <object> in <location> has Next Action RobotActionRobot60 0 hasActionRobot Situation60 0 CP60 hasObject: Large rock hasCPNum: 60 hasLocation: Top of rock pile hasSituation hasCPLabel: Large rock in top of pile hasParticipantNumber: 4086 Situation60 1 hasTicksLasted: 250 ActionHuman60 3 hasTimeScore: 4098 hasRoundNumber: 5 hasNextActionHuman ActionHuman60_2 hasActionHuman hasNextActionHuman ActionHuman60 1 hasNextActionHuman ActionHuman60 0 hasAction: Move to <Location> hasLocation: Top of rock pile