Collaboration Pattern: 105

ActionRobot105_2
hasObject: Small rock
hasLocation: <Left> side of field
hasAction: Drop <object> in <location>

hasNextActionRobot

ActionRobot105_1
hasAction: Pick up <object> in <location>
hasLocation: Top of rock pile
hasObject: Small rock

hasNextActionRobot

ActionRobot105_0
hasAction: Stand still in <locati
hasLocation: Top of rock pile

hasActionRobot

Situation105_1

hasNextSituation

Situation105_0
hasLocation: Top of rock pile
hasObject: Small rock

hasSituation

CP105
hasTimeScore: 4300
hasTicksLasted: 951
hasCPLabel: Something
hasCPNum: 105
hasRoundNumber: 6
hasParticipantNumber: 4092

hasActionHuman

ActionHuman105_0

hasNextActionHuman

ActionHuman105_1

hasNextActionHuman

ActionHuman105_2