Collaboration Pattern: 110

ActionRobot110_3

ActionRobot110_2
hasAction: Drop <object> in <location>
hasLocation: <Right> side of field
hasObject: Large rock

hasNextActionRobot

ActionRobot110_1
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: <Right> side of rock pile

hasNextActionRobot

ActionRobot110_0
asAction: Move to <Object>
hasObject: Large rock

hasNextActionRobot

hasActionRobot

CP110
hasTimeScore: 2363
hasCPNum: 110
hasTicksLasted: 1013
hasParticipantNumber: 4092
hasCPLabel: Big rocks
hasRoundNumber: 8

hasActionHuman

ActionHuman110_0

hasNextActionHuman

ActionHuman110_1

hasNextActionHuman

ActionHuman110_2

hasNextActionHuman

ActionHuman110_3

hasSituation

Situation110_0
hasObject: Large rock
hasLocation: <Right> side of rock pile

hasNextSituation

Situation110_1