Collaboration Pattern: 058

Situation58 1

hasNextSituation

Situation58_0 hasObject: Large rock hasLocation: Top of rock pile

hasSituation

ActionRobot58 0 hasLocation: Top of rock pile hasAction: Move to <Location>

CP58 hasCPLabel: Large rock on top of pile hasRoundNumber: 3 hasCPNum: 58 hasParticipantNumber: 4086 hasNeasTicksLasted: 3018

hasTimeScore: 6800

ActionRobot58 4 sLocation: <Left> side of field hasObject: Large rock ion: Drop <object> in <location>

ActionRobot58 1

hasActionHuman

ActionHuman58 1 hasObject: Large rock

hasNextActionRobot

hasNextActionRobot

ActionRobot58 2 hasLocation: On top of <Actor> ActionHuman58 4 hasAction: Pick up <object> in <location>

hasActor: Human

hasNextActionHuman

hasAction: Move to Sabject in Human 58_0 hasLocation: Top of rock pile hasAction: Stand still in <locati

hasNextActionRobot 2: Large rock

ActionHuman58_2
ActionHuman58_3

ActionRobot58 3 hasLocation: <Left> side of field hasAction: Move to <Location>