Collaboration Pattern: 050

Situation50 1 hasNextSituation Situation50_0 hasObject: Large rock hasLocation: Top of rock pile hasSituation CP50 hasTicksLasted: 305 hasTimeScore: 4200 hasRoundNumber: 4 hasParticipantNumber: 4085 hasCPLabel: large rock robot hasCPNum: 50 hasActionHuman ActionHuman50 2 hasNextActionHuman ActionHuman50_1 hasNextActionHuman ActionHuman50_0 hasActionRobot ActionRobot50 0 hasAction: Pick up <object> in <lo hasObject: Large rock hasLocation: Top of rock pile hasNextActionRobot ActionRobot50_1 hasAction: Drop <object> in <location> hasObject: Large rock hasLocation: <Left> side of field ActionRobot50 2