Collaboration Pattern: 025

ActionHuman25 2

hasNextActionHuman

ActionHuman25 0 hasAction: Stand still in <location> hasLocation: <Left> side of field

ActionHuman25 1

ActionRobot25 2

hasNextActionRobot

ActionRobot25 1

hasNextActionRobot

ActionRobot25 0 hasLocation: Top of rock pile hasObject: Large rock hasAction: Pick up <object> in <location>

hasActionRobot

hasParticipantNumber: 4082 hasTimeScore: 2251 hasCPLabel: Remove large rock top

hasCPNum: 25 hasRoundNumber: 3

hasSituation

Situation25 0 hasObject: Large rock hasLocation: Top of rock pile

hasNextSituation

Situation25 1

hasActionHuman

CP25

hasTicksLasted: 52