Collaboration Pattern: 060

ActionRobot60_3
hasLocation: <Left> side of rock pile
hasAction: Drop <object> in <location>
hasObject: Large rock

hasNextActionRobot

ActionRobot60_2
hasAction: Move to <Location
hasLocation: <Left> side of rock

hasNextActionRobot

ActionRobot60_1
hasAction: Pick up <object> in <loca
hasObject: Large rock
hasLocation: Top of rock pile

hasNextActionRobot

ActionRobot60_0

hasActionRobot

ActionHuman60_0
hasAction: Move to <Location>
hasLocation: Top of rock pile

hasActionHuman

CP60
hasCPLabel: Large rock in top of pile
hasParticipantNumber: 4086
hasRoundNumber: 5
hasCPNum: 60
hasTimeScore: 4098
hasTicksLasted: 250

hasNextActionHuman

ActionHuman60_1

hasNextActionHuman

ActionHuman60_2

hasNextActionHuman

ActionHuman60_3

hasSituation

Situation60_0
hasObject: Large rock
hasLocation: Top of rock pile

hasNextSituation

Situation60_1