Collaboration Pattern: 160

Situation160_0
hasObject: Large rock
hasLocation: On top of <Object>
hasObject: Small rock

Situation160_1

hasNextSituation

ActionRobot160_2

hasNextActionRobot

ActionRobot160_1

hasNextActionRobot

ActionRobot160_0
hasAction: Pick up <object> in <location>
hasObject: Small rock
hasLocation: On top of <Object>
hasObject: Large rock

hasSituation

CP160
hasTicksLasted: 282
hasCPNum: 160
hasTimeScore: 3293
hasRoundNumber: 4
hasCPLabel: Move small rocks off large rocks
hasParticipantNumber: 4098

hasActionRobot

hasActionHuman

ActionHuman160_0

hasNextActionHuman

ActionHuman160_1

hasNextActionHuman

ActionHuman160_2