Collaboration Pattern: 015

Situation15_0 hasObject: Large rock hasLocation: Top of rock pile Situation15 1 hasSituation hasRoundNumber: 4 hasCPLabel: top large hasTimeScore: 1123 hasTicksLasted: 330 hasParticipantNumber: 4081

ActionHuman 15_1 ActionHuman 15_0 ActionHuman 15_0

ActionRobot15 1 hasObject: Large rock hasAction: Drop <object> in <location> hasLocation: <Left> side of field

CP15 hasCPNum: 15

hasActionRobot

has Next Action Robot

ActionRobot15 0 hasLocation: Top of rock pile hasAction: Pickhup <objectmin <location> hasObject: Large rock

hasNextActionRobot

ActionRobot15_2