ActionRobot40_2

hasNextActionRobot

ActionRobot40_1
:tion: Drop <object> in <location>
hasObject: Small rock
asLocation: <Left> side of field

hasNextActionRobot

ActionRobot40_0
on: Pick up <object> in <location>
nasLocation: Top of rock pile
hasObject: Small rock

ActionHuman40_2

hasNextActionHuman

hasActionHuman

hasActionRobot

CP40
hasParticipantNumber: 4083
hasTimeScore: 3900
hasCPNum: 40
hasCPLabel: Only small rocks
hasTicksLasted: 371
hasRoundNumber: 5

has Situation

Situation40_0
Situation40_1hasNextSituhasObject: Small rock
hasLocation: Top of rock pile