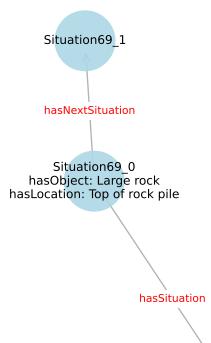
Collaboration Pattern: 069



ActionRobot69 0 hasAction: Pick up <object > in <location > hasLocation: Top of rock pile

hasCPNum: 69 hasObject: Large rock hasActionRobot hasRemainingRocks: 12 hasRoundNumber: 4 hasCPLabel: large rock robot hasUnixTimeStamp: 1717144631 hasRemaining Time: 3000 hasTimeStamp: 2024-05-31T10:37:11

CP69

hasParticipantNumber: 4085

hasVictimHarm: 0 hasTicksLasted: 305

has Next Action Robot

ActionRobot69 1 hasObject: Large rock hasAction: Drop <object> in <location> hastocation: <Left> side of field ActionRobot69 2

hasActionHuman

ActionHuman69 0

hasNextActionHuman

ActionHuman69 1

hasNextActionHuman

ActionHuman69\_2