Collaboration Pattern: 100

ActionHuman100_2

hasNextActionHuman

ActionHuman100_1
Action: Pick up <object> in <location>

hasNextActionHuman

ActionHuman100_0
hasAction: Move to <Object>

hasActionHuman

ActionRobot100_0
hasAction: Move to <Object>

hasNextActionRobot

ActionRobot100_1
hasAction: Pick up <object> in <location>

hasNextActionRobot

ActionRobot100_2

hasActionRobot

CP100
hasCPLabel: Something
hasParticipantNumber: 4092
hasTicksLasted: 2232
hasCPNum: 100
hasRoundNumber: 1
hasTimeScore: 5900

hasSituation

Situation100_0
hasLocation: Top of rock pile
hasObject: Small rock

hasNextSituation

Situation100_1