Collaboration Pattern: 058

ActionHuman58 4 nasNextActionHuman ActionHuman58 3 hasNextActionHuman ActionHuman58 2 hasNextActionHuman ActionHuman58_1 hasAction: Move to < Object> hasObject: Large rackinHuman58_0 hasAction: Stand still in <location> hasLocation: Top of rock pile hasActionHuman CP58 hasTicksLasted: 3018 Situation58 0 hasCPNum: 58 hasObject: Large rock hasSituation hasTimeScore: 6800 hasLocation: Top of rock pile hasRoundNumber: 3 hasCPLabel: Large rock on top of pile Situation58 1 hasParticipantNumber: 4086 ActionRobot58_2 hasObject: Large rock hasAction: Pick up <object> in <location> hasActor: Human on Robot 58 3 hastocationio has Aletofn Mode to < Location> hasLocation: <Left> side of field ActionRobot58 1

ActionRobot58_0
hasAction: Move to <Location>
hasLocation: Top of rock pile

hasNextActionRobot

ActionRobot58_4
hasLocation: <Left> side of file
hasAction: Drop <object> in <loc
hasObject: Large rock

hasNextActionRobot