Collaboration Pattern: 169

ActionRobot169_2

hasNextActionRobot

ActionRobot169_0
hasObject: Small rock
hasLocation: On top of <Object>
ActionRobot169_1
hasObject: Large rock
hasAction: Pick up <object> in <location>

hasActionRobot

CP169
hasRoundNumber: 7
hasCPLabel: Move small rocks off large rocks
hasTicksLasted: 282
hasTimeScore: 4600
hasCPNum: 169
hasParticipantNumber: 4098

hasSituation

hasActionHuman

Situation169_0
hasObject: Large rock
hasLocation: On top of <Object>
hasObject: Small rock

hasNextSituation

Situation169_1

ActionHuman169_1
ActionHuman169_0
hasNextActionHuman

hasNextActionHuman

ActionHuman169_2