Collaboration Pattern: 181

ActionRobot181_0 hasLocation: Top of rock pile hasObject: Large rock ActionHuman181_2 hasAction: Pick up <object> in <location> hasNextActionRobot ActionRobot181_2 hasNextActionRobot hasNextActionHuman ActionRobot181 1 ActionHuman181_1 hasActionRobot hasNextActionHuman ActionHuman181_0 hasActionHuman CP181/ hasCPLabel: PickBigTop hasCPNum: 181 hasParticipantNumber: 4099 hasTimeScore: 1306 hasRoundNumber: 4

hasTicksLasted: 1564

hasSituation

Situation181_0 hasObject: Largeneosts its at uation181_1 hasLocation: Top of rock pile