Collaboration Pattern: 000

ActionRobot0_2

hasNextActionRobot

ActionRobot0_1

hasNextActionRobot

ActionRobot0_0
on: Break <object> in <location>
hasObject: Brown rock

hasActionRobot

ActionHuman0_0
hasAction: Stand still in <location>
hasActor: Human
hasLocation: <Left> side of field

ActionHuman0_1   *hasNextActionHuman*   ActionHuman0_2

hasNextActionHuman

hasActionHuman

CP0
hasRemainingTime: 2336
hasTicksLasted: 117
hasRoundNumber: 3
hasRemainingRocks: 0
hasCPNum: 0
hasVictimHarm: 400
hasTimeStamp: 2024-05-03T13:41:23
hasUnixTimeStamp: 1714736483
hasParticipantNumber: 4069
hasCPLabel: Label

hasSituation

Situation0_0

hasNextSituation

Situation0_1