Collaboration Pattern: 112

ActionRobot112_3
hasAction: Stand still in <location>
hasLocation: <Left> side of field

has Next Action Robot

ActionRobot112_2
hasLocation: <Left> side of field
hasAction: Drop <object> in <location>

hasNextActionRobot

ActionRobot112_1
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: Top of rock pile

hasNextActionRobot

ActionRobot112_0 hasObject: Large rock

CP112 hasAction: Move to <Object Situation 112_0

hasCPNum: 142ActionRobot hasObject: Large rockhasNextSituation — Situation112_1

hasParticipantNumber: 4094 hasSituation hasLocation: Top of rock pile

hasTicksLasted: 1397 hasCPLabel: remove large rock top

hasActionHuman hasTimeScore: 1415 hasRoundNumber: 3

ActionHuman112 0

has Next Action Human

ActionHuman112 1

hasNextActionHuman

ActionHuman112_2

hasNextActionHuman

ActionHuman112_3