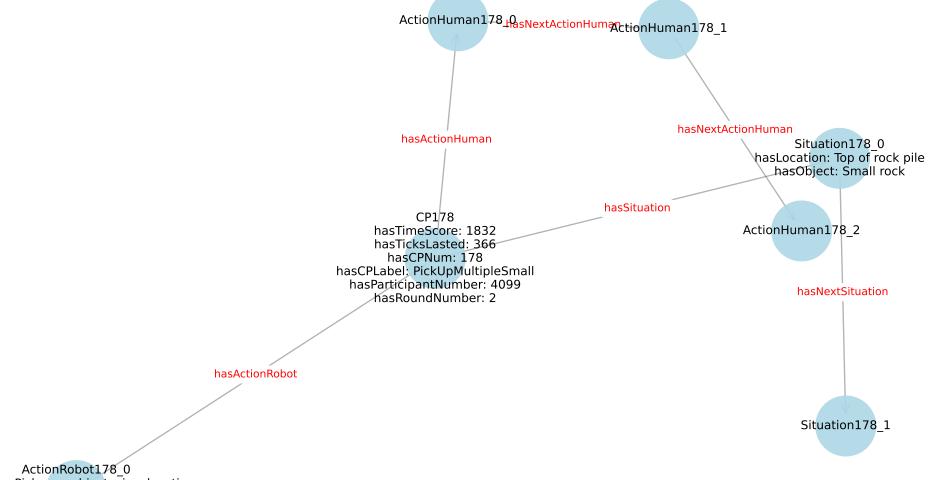
Collaboration Pattern: 178



ActionRobot178_0
on: Pick up <object> in <location>
nasLocation: Top of rock pile
hasObject: Small rock

hasNextActionRobot

ActionRobot178_1
hasObject: Small rock
hasAction: Pick up <object> in <location>
hasLocation: Top of rock pile

hasNextActionRobot

ActionRobot178_2
hasAction: Pick up <object> in <location>
hasLocation: Top of rock pile
hasObject: Small rock