Collaboration Pattern: 065

Situation65_1

hasNextSituation

Situation65_0
hasLocation: <Right> side of rock pile
hasObject: Large rock

hasSituation

ActionRobot65_0
hasActor: Victim
hasAction: Move to <Actor>

hasNextActionRobot

ActionRobot65_1
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: <Right> side of rock pile

hasNextActionRobot

ActionRobot65_2
hasAction: Move to <Location>
hasLocation: <Right> side of field

hasCPNum: 65
hasParticipantNumber: 4086
hasTimeScore: 4219
hasTicksLasted: 1110
hasCPLabel: Rock on the right side of the victim
hasRoundNumber: 8

hasNextActionRobot

ActionRobot65_3
hasObject: Large rock
hasLocation: <Right> side of field
hasAction: Drop <object> in <location>

hasNextActionRobot

ActionRobot65_4

hasActionHuman

ActionHuman65_0
hasAction: Move to <Actor>
hasActor: Victim

hasNextActionHuman

ActionHuman65_1
hasLocation: <Right> side of rock pile
hasAction: Move to <Location>

hasNextActionHuman

ActionHuman65_2
hasLocation: <Right> side of field
hasAction: Move to <Location>

ActionHuman65_3

hasNextActionHuman

ActionHuman65_4