hasActionRobot

ActionRobot52_0 hasAction: Pick up <object> in <location>

hasObject: Large rock

hasLocation: Top of rock pile
hasNextActionRobot
ActionRobot52_1

hasObject: Large rock
hasLocation: <Left> side of field
hasAction: Drop <object> in <location>
hasNextActionRobot

hasNextActionHuman ActionHuman52_1 hasNextActionHuman ActionHuman52 0 hasActionHuman CP52 hasParticipantNumber: 4085 hasCPLabel: large rock robot hasCPNum: 52 hasTimeScore: 4700 hasRoundNumber: 6 hasTicksLasted: 25 hasSituation Situation52_0 hasLocation: Top of rock pile hasObject: Large rock hasNextSituation

Situation52 1

ActionHuman52 2

ActionRobot52 2