Collaboration Pattern: 105

Situation105_1

nasNextSituation

hasSituation

Situation105_0 hasObject: Small rock hasLocation: Top of rock pile

ActionHuman105 2

hasNextActionHuman

ActionHuman105_1

hasNextActionHuman

ActionHuman105 0

CP105
hasCPLabel: Something
hasTimeScore: 4300
hasParticipantNumber: 4092
hasTicksLasted: 951
hasRoundNumber: 6
hasCPNum: 105

has Action Human

hasActionRobotCtionRobot105_1
hasObject: Small rock
hasLocation: Top of rock pile
hasAction: Pick up <object> in <location>

hasNextActionRobot

ActionRobot 105ctonRobot hasLocation: Top of rock pile hasAction: Stand still in <location>

ActionRobot105_2
hasLocation: <Left> side of file
hasAction: Drop <object> in <loc
hasObject: Small rock