Collaboration Pattern: 104

Situation104 1 hasNextSituation Situation104_0 hasLocation: Top of rock pile hasObject: Large rock ActionHuman104 2 hasNextActionHuman hasSituation ActionHuman104_1 hasNextActionHuman CP104 hasParticipantNumber: 4092 ActionHuman104_0 hasActionHuman nasHukasasses. hasCPLabel: Big rocks hasTimeScore: 2828 hasCPNum: 104 hasRoundNumber: 5 hasActionRobot ActionRobot104_0 hasObject: Large rock hasAction: Move to <Object> hasNextActionRobot ActionRobot104_1 hasObject: Large rock hasAction: Pick up <object> in <location> hasLocation: Bottom of rock pile hasNextActionRobot

ActionRobot104_2
hasAction: Drop <object> in <loc
hasLocation: <Left> side of file
hasObject: Large rock