Collaboration Pattern: 109

ActionRobot109_2
hasAction: Drop <object> in <location>
hasLocation: <Left> side of field
hasObject: Small rock

hasNextActionRobot

ActionRobot109_0
hasLocation; Top of rock pile1
hasAction; Stanck tip Vobject in <10
hasLocation: Top of rock pile
hasLocation: Top of rock pile
hasObject: Small rock

ActionHuman109 2

hasActionRobot

hacNextActionhuman

ActionHuman109 1

hasNextActionHuman

ActionHuman109_0

hasActionHuman

CP109
hasCPNum: 109
hasCPLabel: Something
hasTimeScore: 2363
hasParticipantNumber: 4092
hasRoundNumber: 8
hasTicksLasted: 951

hasSituation

Situation109 1

hasNextSituation

Situation109_0 hasObject: Small rock hasLocation: Top of rock pile