Collaboration Pattern: 013

ActionRobot13\_2 hasAction: Drop <object> in <location> hasLocation: <Right> side of rock pile hasObject: Large rock

hasNextActionRobot

ActionRobot13 1 hasObject: LargexrectionRobot13\_0
hasAction: Pick up <object> in <location>
hasLocation: Bottom of rock pile

has Action Robot

CP13 hasRoundNumber: 6 hasParticipantNumber: 4071 hasCPNum: 13

hasCPLabel: move break big rock bottom hasUnixTimeStamp: 1724939682 hasRemainingRocks: 16 hasVictimHarm: 100 hasTicksLasted: 193 hasTimeStamp: 2024-08-29T15:54:42

hasActionhasRemainingTime: 3000

ActionHuman13 0 hasAction: Move back and forth in <location> asNextAstionation: Bottom of rock pile ActionHuman13 1

hasNextActionHuman

ActionHuman13 2

hasSituation

Situation13 0 hasLocation: <Left> side of fig hasActor: Human

hasNextSituation

Situation13 1 hasObject: Large rock hasLocation: Bottom of rock pile