Collaboration Pattern: 169

Situation169_1

hasNextSituation

Situation169_0
hasObject: Large rock
hasLocation: On top of <Object>
hasObject: Small rock

hasSituation

ActionRobot169_0
hasAction: Pick up <object> in <location>
hasObject: Small rock
hasLocation: On top of <Object>
hasObject: Large rock

CP169
hasTicksLasted: 282
hasCPNum: 169
hasRoundNumber: 7
hasParticipantNumber: 4098
hasCPLabel: Move small rocks off large rocks
hasTimeScore: 4600

hasActionRobot

hasNextActionRobot

ActionRobot169_1

hasNextActionRobot

ActionRobot169_2

hasActionHuman

ActionHuman169_0

hasNextActionHuman

ActionHuman169_2

hasNextActionHuman

ActionHuman169_1