Collaboration Pattern: 169

ActionRobot169_0
hasObject: Large rock
hasAction: Pick up <object> in <location>
hasLocation: Bottom of rock pile

hasNextActionRobot

ActionRobot169_1
hasObject: Large rock
hasAction: Drop <object> in <location>
hasLeccationRoLeft> side of rock pile

ActionRobot169_2

hasActionRobot CP169 hasTicksLasted: 905 hasVictimHarm: 0 hasRemainingRocks: 24 hasCPNum: 169 hasRoundNumber: 7 Situation169 1 hasTimeStamp: 2024-07-22T09:53:10 hasCPLabel: 3 hasUnixTimeStamp: 1721634790 hasParticipantNumber: 4097Situation hasNextSituation hasRemainingTime: 3000 Situation169 0 hasActor: Robot hasActionHuman ActionHuman169_1 ActionHuman169_0 hasAction: Move to <Object> hasObject: Large rock hasNextActionHuman

ActionHuman169 2