Collaboration Pattern: 037

ActionRobot37\_2

hasNextActionRobot

ActionRobot37 1

nasNextActionRobot ActionRobot37\_0

hasAction: Pick up <object> in <location> hasObject: Large rock hasLocation: Top of rock pile

## ActionHuman37 2 hasNextActionHuman ActionHuman37 0 hasAction: Stand still in <location> hasLocation: <Left> side of field hasActionHuman CP37 hasCPNum: 37 hasTicksLasted: 52 hasRoundNumber: 8 hasTimeScore: 5300 hasCPLabel: Remove large rock to hasSituation hasParticipantNumber: 4082 Situation37\_0 hasObject: Large rock hasLocation: Top of rock pile hasNextSituation Situation37 1 hasActionRobot