

Latent Variable Modelling with Hyperbolic Normalizing Flows

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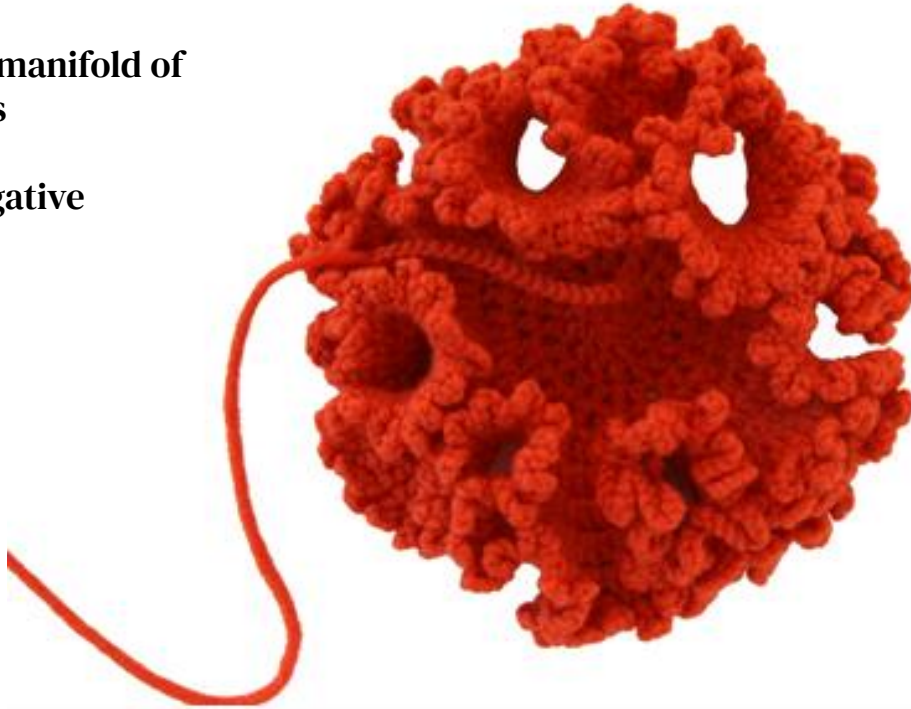
- 1. Why hyperbolic?**
- 2. Related work**
- 3. Hyperbolic normalizing flows**
- 4. Experiments**
- 5. Conclusion**

Why hyperbolic?

Hyperbolic space

Riemannian manifold of
 n dimensions

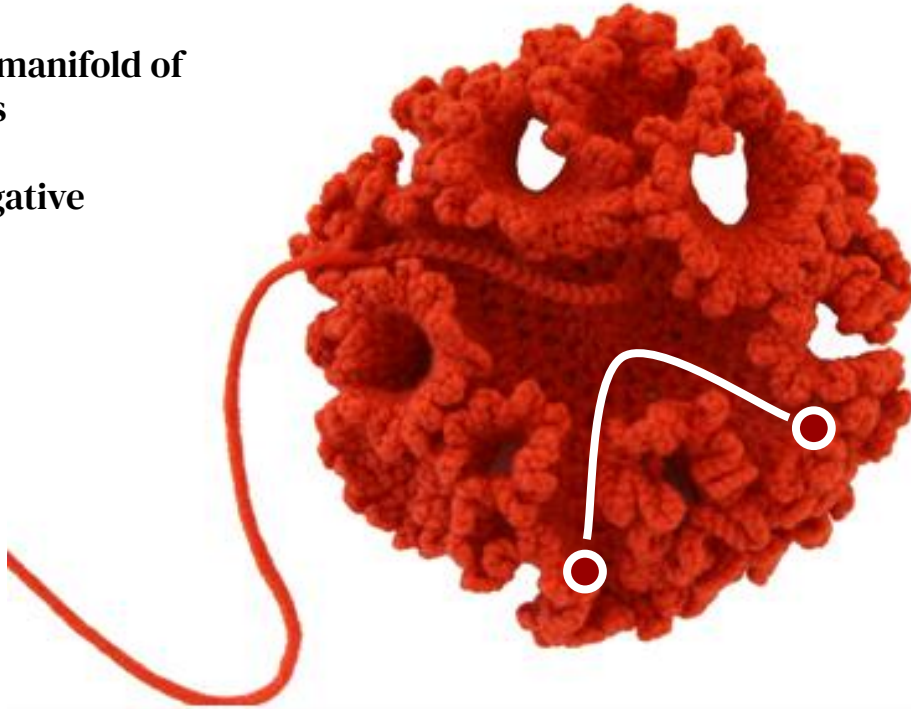
Constant negative
curvature K



Hyperbolic space

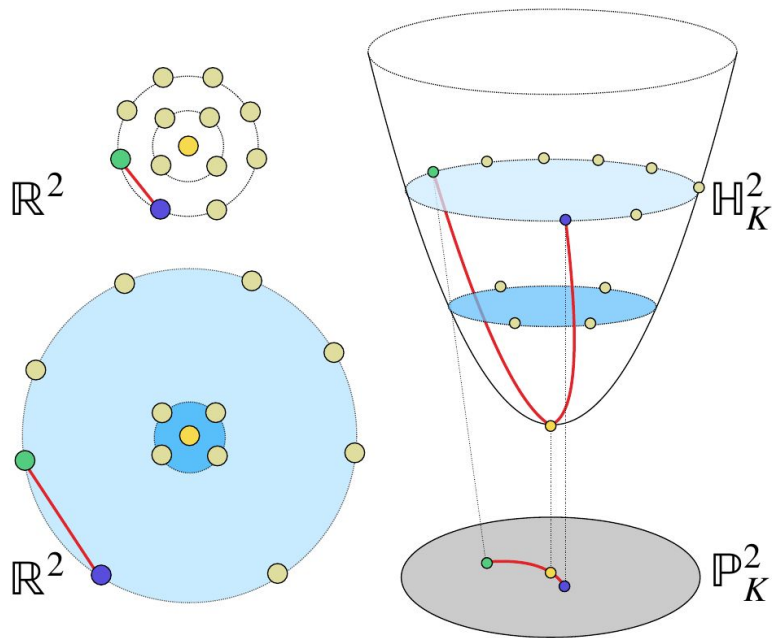
Riemannian manifold of
 n dimensions

Constant negative
curvature K



Hyperbolic space

Unlike Euclidean space,
geodesics go near origin

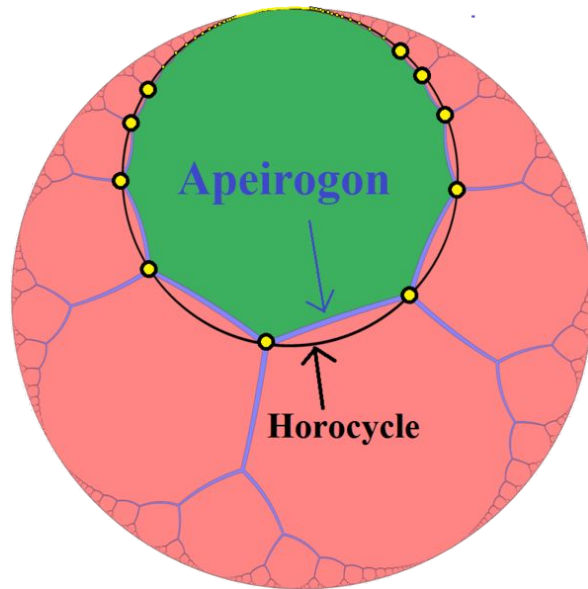


Hyperbolic space

Naturally models hierarchical structure:

- origin is close to everything
- the further you go, the more space there is
- non-intersecting lines are easy to draw

Good for embedding trees!



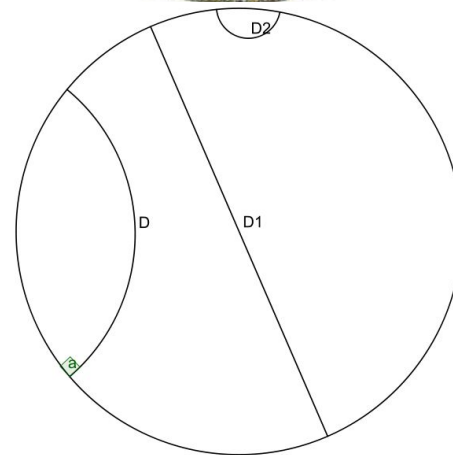
Poincaré ball model

Projects manifold onto unit ball of same dimension

- boundary is at infinity
- easy to visualize
- numerically unstable

Straight lines in 2D:

- circles orthogonal to boundary
- lines through origin



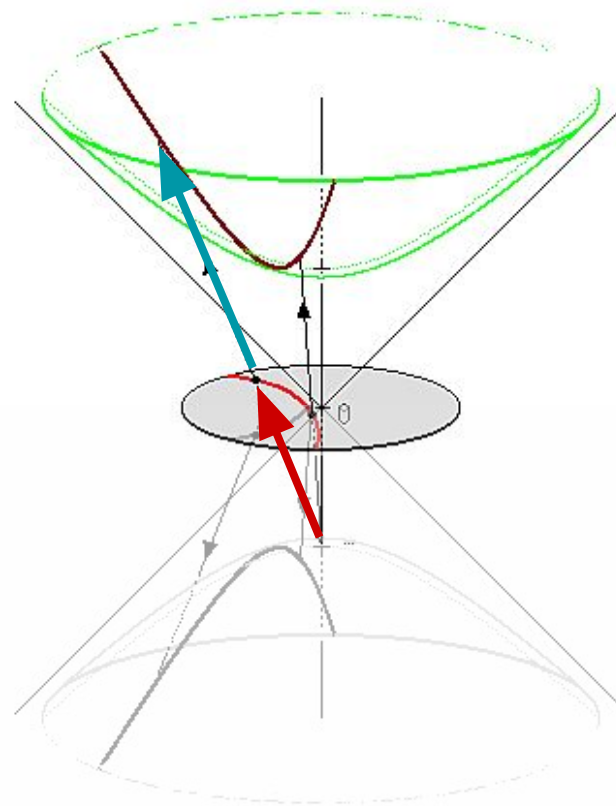
Lorentz model

Projects onto hyperboloid in Euclidean space ($d+1$)

- a.k.a. Minkowski space
- can project to Poincaré ball at origin along a line from the center of the opposite hyperboloid

Straight lines in 2D:

- planes intersecting hyperboloid and origin



Lorentz model

Lorentz (Minkowski) inner product over \mathbb{R}^{n+1} :

$$\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} := -\underbrace{x_0 y_0}_{\text{“special” 0}^{\text{th}} \text{ coordinate}} + x_1 y_1 + \cdots + x_n y_n$$

Lorentz model

Lorentz (Minkowski) inner product over \mathbb{R}^{n+1} :

$$\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} := -x_0 y_0 + x_1 y_1 + \cdots + x_n y_n$$

Points on the manifold satisfy:

$$\mathbb{H}_K^n := \{x \in \mathbb{R}^{n+1} : \langle \mathbf{x}, \mathbf{x} \rangle_{\mathcal{L}} = 1/K, x_0 > 0, K < 0\}.$$

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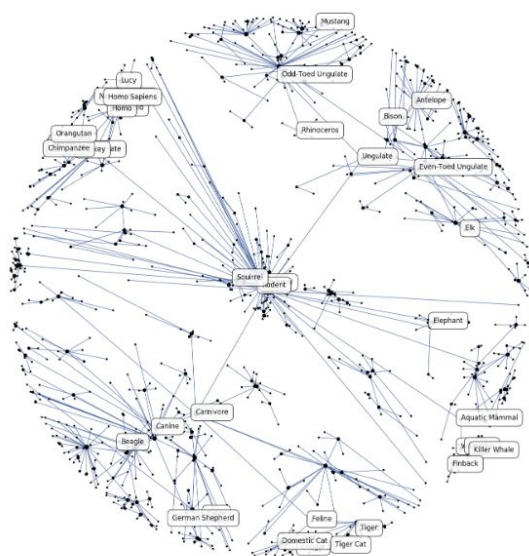
Induced distance on the manifold:

$$d(\mathbf{x}, \mathbf{y})_{\mathcal{L}} := \frac{1}{\sqrt{-K}} \operatorname{arccosh}(-K \langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}}).$$

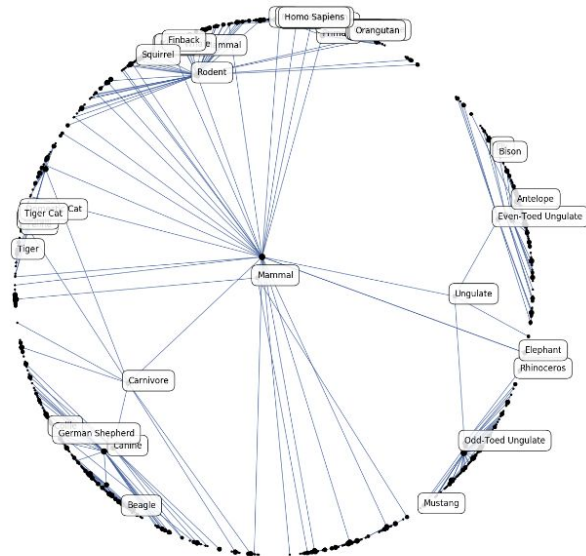
In the tangent space of the **origin**, norm is identical to Euclidean norm!

Related work

Hyperbolic embedding (Poincaré)

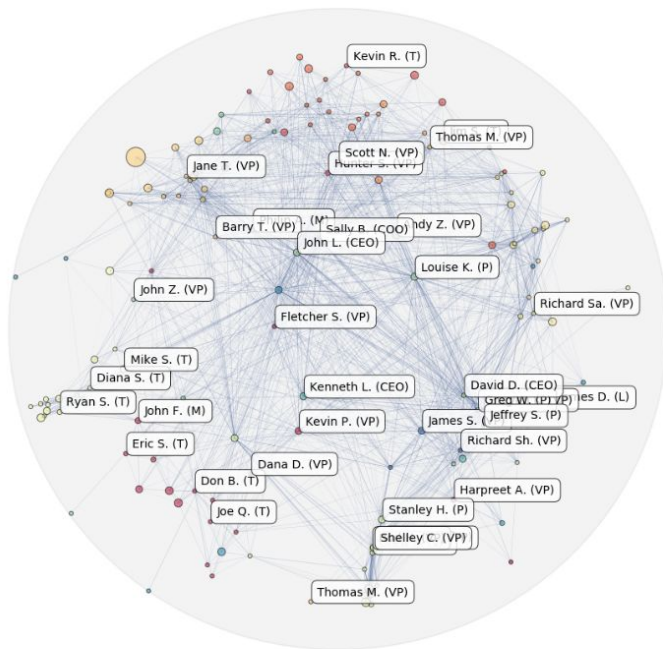


(a) Intermediate embedding after 20 epochs



(b) Embedding after convergence

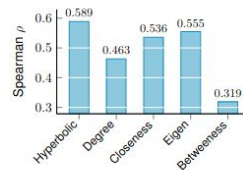
Hyperbolic embedding (Lorentz)



(a) Embedding of the Enron communication graph

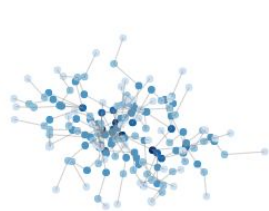


(b) Org. hierarchy

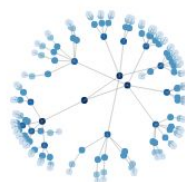
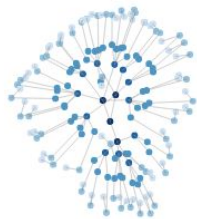
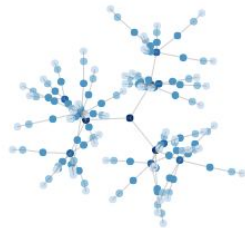


(c) Rank-order correlation

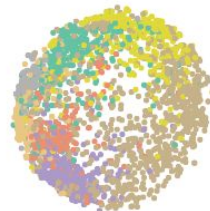
Hyperbolic graph neural networks



(a) GCN layers.



(b) HGCN layers.



(c) GCN (left), HGCN (right).

Hyperbolic VAEs

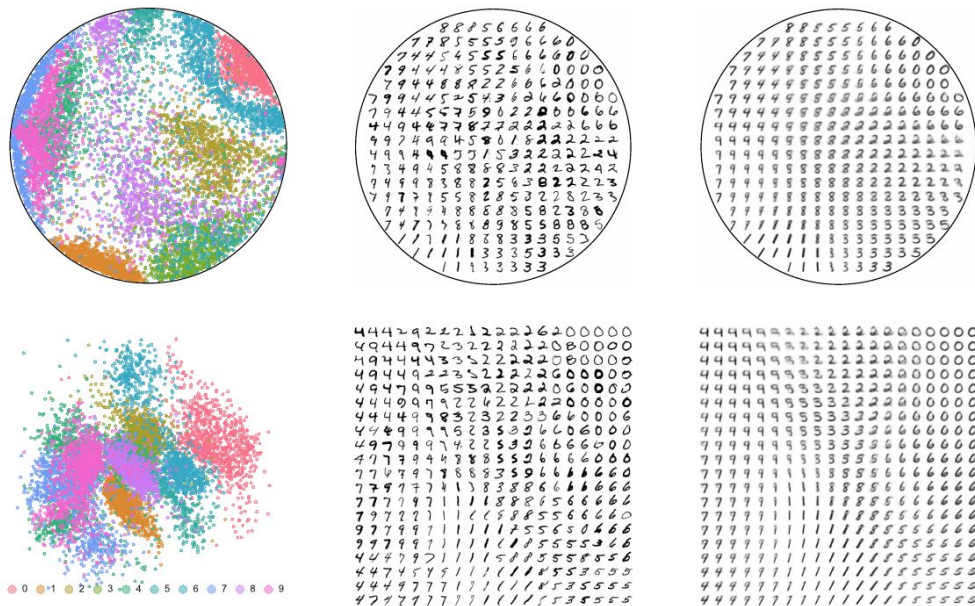


Figure 7: MNIST Posteriors mean (Left) sub-sample of digit images associated with posteriors mean (Middle) Model samples (Right) – for $\mathcal{P}^{1.4}$ -VAE (Top) and \mathcal{N} -VAE (Bottom).

Normalizing flows

Use invertible transforms to turn an initial probability density into a more complex target

- Need to efficiently compute determinant of Jacobian to change density

Normalizing flows

Use invertible transforms to turn an initial probability density into a more complex target

- Need to efficiently compute determinant of Jacobian to change density

Real non-volume-preserving (NVP) transform:

- affine transform half of input channels at a time, conditioning on other half
- triangular Jacobian (det = product of diagonal)

$$\tilde{f}^{TC}(\tilde{x}) = \begin{cases} \tilde{z}_1 & = \tilde{x}_1 \\ \tilde{z}_2 & = \tilde{x}_2 \odot \underbrace{\sigma(s(\tilde{x}_1))}_{\text{scale}} + \underbrace{t(\tilde{x}_1)}_{\text{translate}} \end{cases}$$

split input channels

non-linearity

scale

translate

Hyperbolic Normalizing Flows

Hyperbolic geometry

Projection: map vector in ambient space to manifold

$$\text{proj}_{\mathbb{H}_K^n}(x) = \frac{x}{\sqrt{-K} \|x\|_{\mathcal{L}}}$$



vector in \mathbb{R}^{n+1}

$$x_0 = \sqrt{\underbrace{\|\hat{x}\|_2^2 + \frac{1}{K}}_{\text{can also project from } \mathbb{R}^n \text{ by concatenating 0}^{\text{th}} \text{ coordinate}}}$$

can also project from \mathbb{R}^n by concatenating 0th coordinate

Hyperbolic geometry

Projection: map vector in ambient space to manifold

$$\text{proj}_{\mathbb{H}_K^n}(x) = \frac{x}{\sqrt{-K} \|x\|_{\mathcal{L}}}$$

vector in $\mathcal{T}_{\mathbf{x}}\mathbb{H}_K^n$

Exponential map: tangent space to manifold

$$\exp_{\mathbf{x}}^K(v) = \cosh\left(\frac{\|v\|_{\mathcal{L}}}{R}\right)\mathbf{x} + \sinh\left(\frac{\|v\|_{\mathcal{L}}}{R}\right)\frac{Rv}{\|v\|_{\mathcal{L}}}$$

point in \mathbb{H}_K^n

$$x_0 = \sqrt{\|\hat{x}\|_2^2 + \frac{1}{K}}$$

$$R = 1/\sqrt{-K}$$

generalized radius

Hyperbolic geometry

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$$R = 1/\sqrt{-K}$$

Logarithmic map: inverse of exp map (manifold to tangent space)

$$\log_{\mathbf{x}}^K \mathbf{y} = \frac{\text{arccosh}(\alpha)}{\sqrt{\alpha^2 - 1}}(\mathbf{y} - \alpha\mathbf{x})$$

$$\alpha = K\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}}$$


vector in \mathbb{H}_K^n

Hyperbolic geometry

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$$\alpha = K\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}}$$

Parallel transport: map from one tangent space to another

$$\underbrace{\text{PT}_{\mathbf{x} \rightarrow \mathbf{y}}^K(v)}_{\mathcal{T}_{\mathbf{y}}\mathbb{H}_K^n} = v + \frac{\langle \mathbf{y}, v \rangle_{\mathcal{L}}}{R^2 - \langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}}}(\mathbf{x} + \mathbf{y})$$


$$(\underbrace{\text{PT}_{\mathbf{x} \rightarrow \mathbf{y}}^K(v)}_{\text{swap x and y for inverse}})^{-1} = \text{PT}_{\mathbf{y} \rightarrow \mathbf{x}}^K(v)$$

swap x and y for inverse

Hyperbolic normal distributions

Riemannian normal: like Euclidean normal distribution, but replace norm with induced distance

$$p(z|\bar{z}, \gamma) = \frac{1}{Z(\gamma)} \exp \left(\frac{-\overbrace{d^2(z, \bar{z})}^{\text{distance}}}{2\gamma^2} \right)$$

Hyperbolic normal distributions

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Restricted normal: condition normal distribution in \mathbb{R}^{n+1} by whether a point is on the manifold

$$p(\mathbf{z}) = p(\underbrace{x \sim \mathcal{N}(\mathbf{0}, I)}_{\text{ambient space } \mathbb{R}^{n+1}} \mid \underbrace{\langle \mathbf{x}, \mathbf{x} \rangle_{\mathcal{L}} = 1/K}_{\text{Lorentzian metric condition for } \mathbb{H}_K^n})$$

Hyperbolic normal distributions

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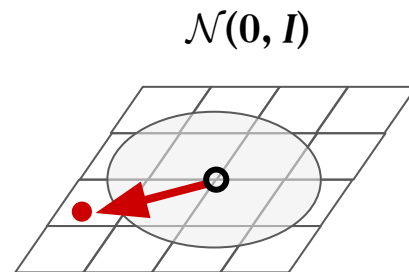
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Wrapped normal: reparameterize standard normal from tangent space at origin

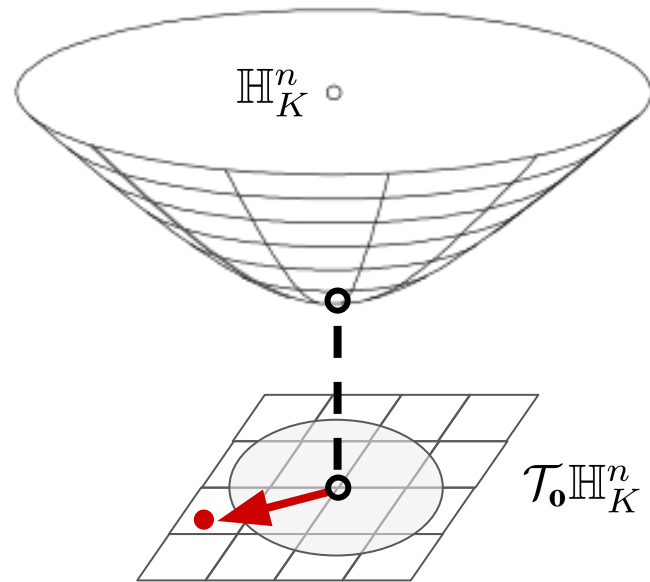
Wrapped normal

1. Sample from $\mathcal{N}(0, I)$



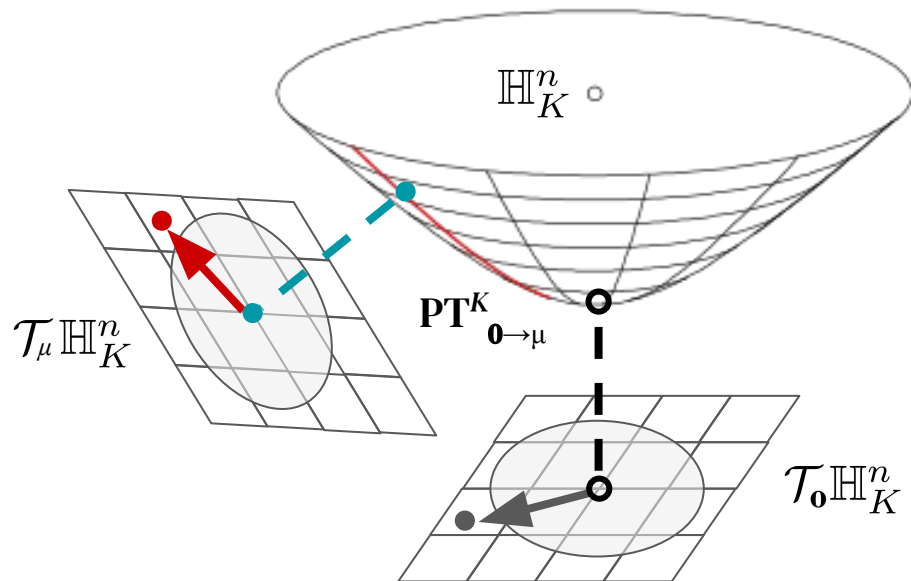
Wrapped normal

1. Sample from $\mathcal{N}(0, I)$
2. Put in tangent space at origin
(concatenate 0 at 0th coordinate)



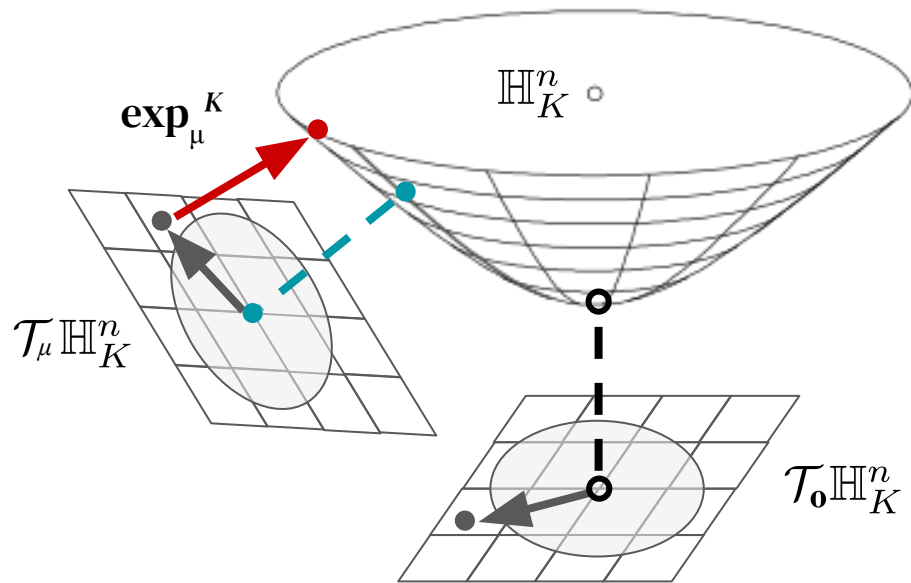
Wrapped normal

1. Sample from $\mathcal{N}(0, I)$
2. Put in tangent space at origin
(concatenate 0 at 0th coordinate)
3. Parallel transport to tangent space
of another point



Wrapped normal

1. Sample from $\mathcal{N}(0, I)$
2. Put in tangent space at origin
(concatenate 0 at 0th coordinate)
3. Parallel transport to tangent space
of another point
4. Map to manifold



Wrapped normal

Density is given by change of variable:

$$\log p(\mathbf{z}) = \log p(v) - (n - 1) \log \left(\frac{\sinh(\|u\|_{\mathcal{L}})}{\|u\|_{\mathcal{L}}} \right)$$

Hyperbolic normalizing flows

Base distribution is wrapped normal

Use RealNVP transform

$$\tilde{f}^{\mathcal{TC}}(\tilde{x}) = \begin{cases} \tilde{z}_1 & = \tilde{x}_1 \\ \tilde{z}_2 & = \tilde{x}_2 \odot \sigma(s(\tilde{x}_1)) + t(\tilde{x}_1) \end{cases}$$

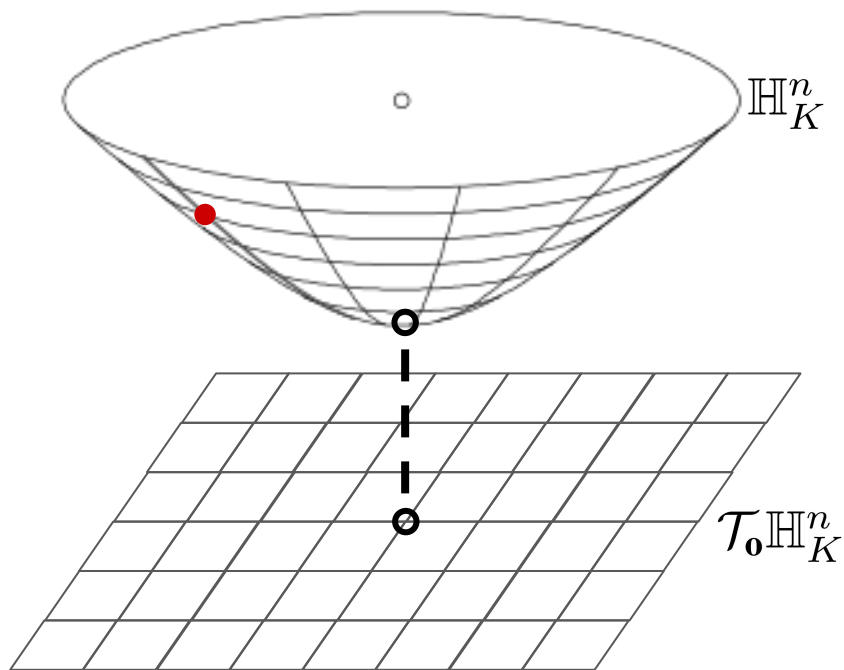
Two ways to make this hyperbolic:

1. Tangent coupling (simple, fast)
2. Wrapped hyperboloid coupling (not tied to origin, better results)

Tangent Coupling

For each layer:

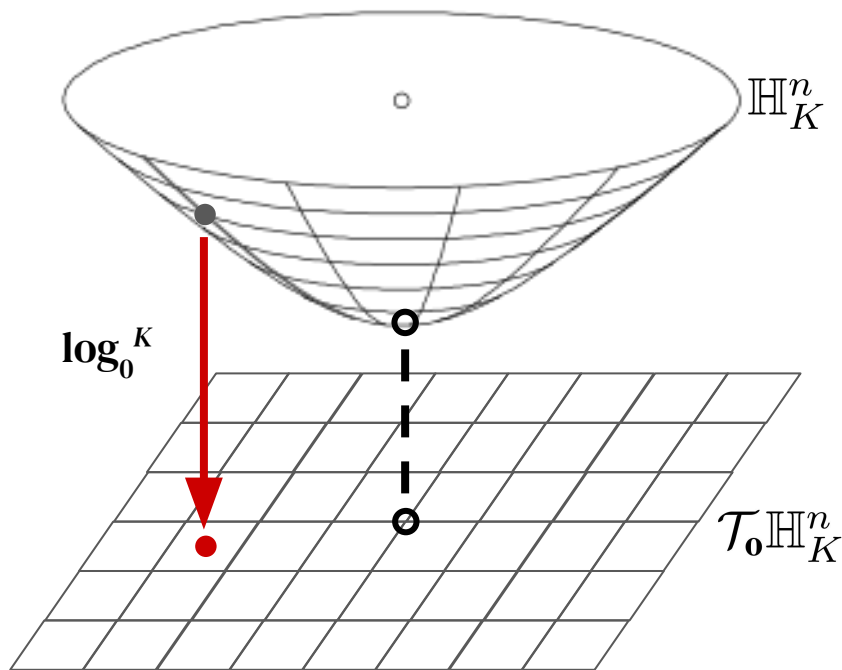
1. Sample point in manifold



Tangent Coupling

For each layer:

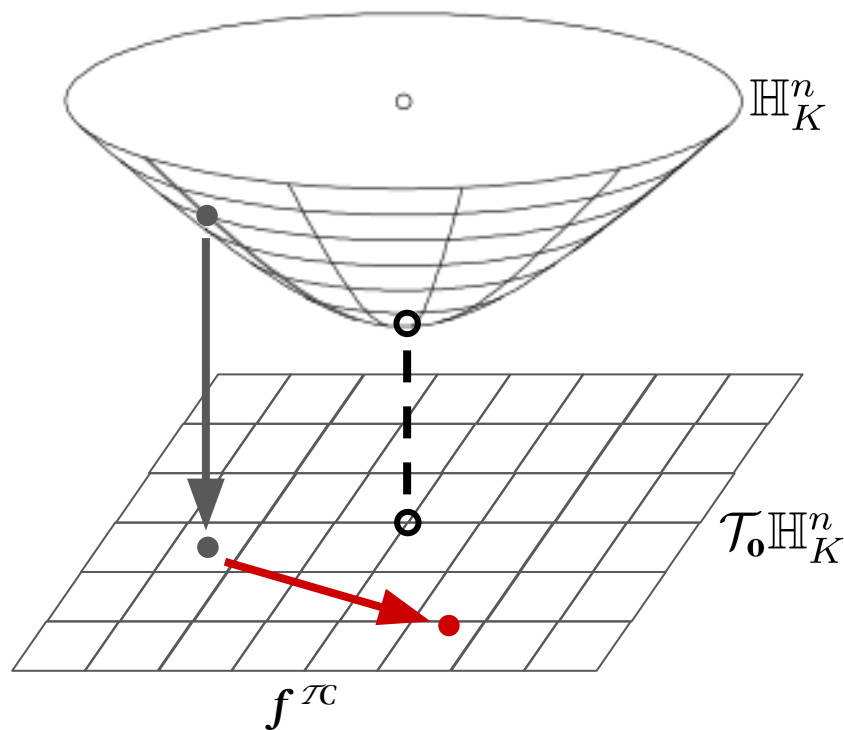
1. Sample point in manifold
2. Map to tangent space at origin



Tangent Coupling

For each layer:

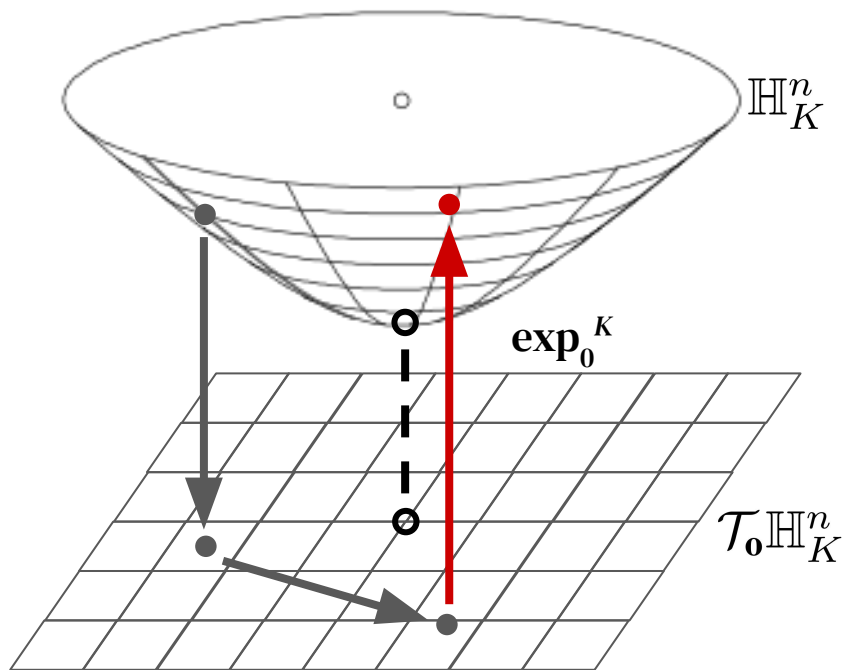
1. Sample point in manifold
2. Map to tangent space at origin
3. Apply Euclidean flow transform



Tangent Coupling

For each layer:

1. Sample point in manifold
2. Map to tangent space at origin
3. Apply Euclidean flow transform
4. Map back to manifold



Jacobian of \mathcal{TC} layer

$$\tilde{f}^{\mathcal{TC}}(\tilde{x}) = \begin{cases} \tilde{z}_1 &= \tilde{x}_1 \\ \tilde{z}_2 &= \tilde{x}_2 \odot \sigma(s(\tilde{x}_1)) + t(\tilde{x}_1) \end{cases}$$

$$f^{\mathcal{TC}}(\mathbf{x}) = \exp_{\mathbf{o}}^K(\tilde{f}^{\mathcal{TC}}(\log_{\mathbf{o}}^K(\mathbf{x}))),$$

$$\left| \det\left(\frac{\partial \mathbf{y}}{\partial \mathbf{x}}\right) \right| = \underbrace{\left(\frac{R \sinh(\frac{\|\mathbf{z}\|_{\mathcal{L}}}{R})}{\|\mathbf{z}\|_{\mathcal{L}}}\right)^{n-1}}_{\text{Exp map}} \times \underbrace{\prod_{i=d+1}^n \sigma(s(\tilde{x}_1))_i}_{\text{RealNVP transform}} \times \underbrace{\left(\frac{R \sinh(\frac{\|\log_{\mathbf{o}}^K(\mathbf{x})\|_{\mathcal{L}}}{R})}{\|\log_{\mathbf{o}}^K(\mathbf{x})\|_{\mathcal{L}}}\right)^{1-n}}_{\text{Log map}}$$

Exp map

RealNVP transform

Log map

Wrapped Hyperboloid Coupling

1. Sample point in manifold
2. Map to tangent space at origin
3. **Apply $\mathcal{W}\mathbb{H}C$ flow transform**
4. Map back to manifold

$$\begin{aligned}
 \tilde{f}^{\mathcal{W}\mathbb{H}C}(\tilde{x}) &= \begin{cases} \tilde{z}_1 &= \tilde{x}_1 \\ \tilde{z}_2 &= \log_{\mathbf{o}}^K \left(\exp_{t(\tilde{x}_1)}^K (\text{PT}_{\mathbf{o} \rightarrow t(\tilde{x}_1)}(v)) \right) \end{cases} \\
 &\quad v = \tilde{x}_2 \odot \sigma(s(\tilde{x}_1))
 \end{aligned}
 \quad \begin{array}{l} \text{same scaling} \\ \uparrow \end{array}$$

$$f^{\mathcal{W}\mathbb{H}C}(\mathbf{x}) = \exp_{\mathbf{o}}^K \left(\underbrace{\tilde{f}^{\mathcal{W}\mathbb{H}C}(\log_{\mathbf{o}}^K(\mathbf{x}))}_{\text{same as } TC} \right). \tag{13}$$

Wrapped Hyperboloid Coupling

1. Sample point in manifold
2. Map to tangent space at origin
3. **Apply $\mathcal{W}\mathbb{H}\mathbb{C}$ flow transform**
4. Map back to manifold

$\mathcal{W}\mathbb{H}\mathbb{C}$ transform:


1. Split inputs
2. Scale by non-linear factor
3. **Parallel transport to new tangent space** (instead of translating)
4. Map to manifold
5. Map back to tangent space at origin

$$\tilde{f}^{\mathcal{W}\mathbb{H}\mathbb{C}}(\tilde{x}) = \begin{cases} \tilde{z}_1 & = \tilde{x}_1 \\ \tilde{z}_2 & = \log_{\mathbf{o}}^K \left(\overbrace{\exp_{t(\tilde{x}_1)}^K (\text{PT}_{\mathbf{o} \rightarrow t(\tilde{x}_1)}(v))}^{\text{return to } \mathcal{T}_{\mathbf{o}} \mathbb{H}_K^n} \right) \end{cases}$$

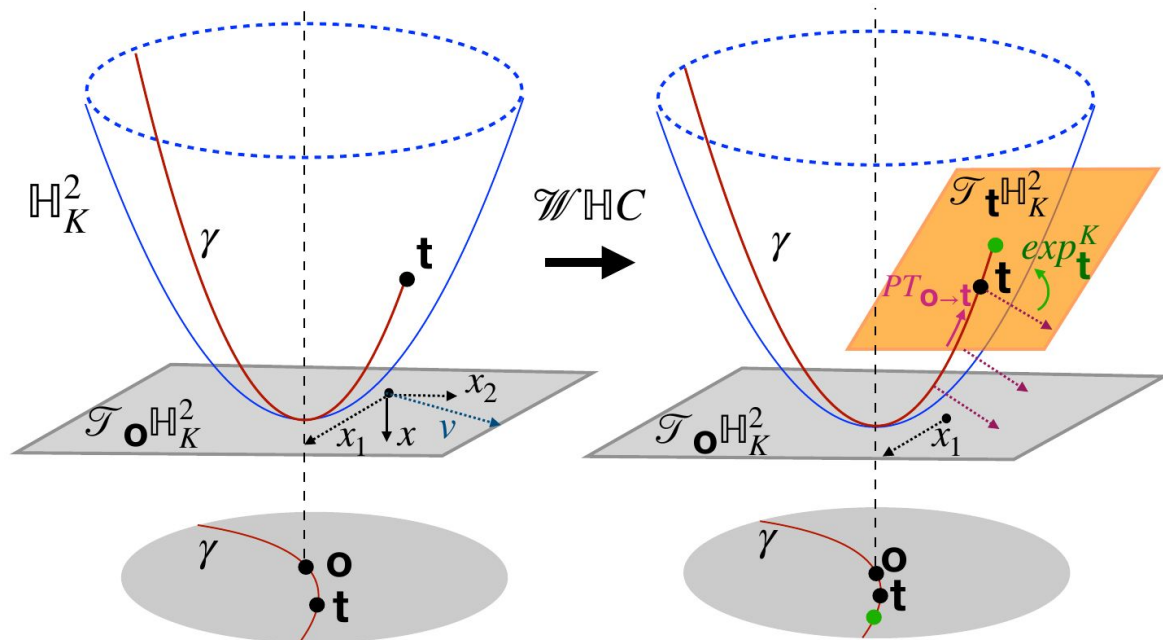
$$v = \tilde{x}_2 \odot \sigma(s(\tilde{x}_1))$$

$$f^{\mathcal{W}\mathbb{H}\mathbb{C}}(\mathbf{x}) = \exp_{\mathbf{o}}^K(\tilde{f}^{\mathcal{W}\mathbb{H}\mathbb{C}}(\log_{\mathbf{o}}^K(\mathbf{x}))). \quad (13)$$

“translation”



Wrapped Hyperboloid Coupling



Wrapped Hyperboloid Coupling

To guarantee \mathbf{x}_2 does not affect \mathbf{x}_1 :

- find the parallel transport target \mathbf{t} by explicitly setting components from \mathbf{x}_1 to 0

$$\mathbf{t} = [t_0, 0, \dots, 0, t_{d+1}, \dots, t_n]$$

- find t_0 using the trick to project from \mathbb{R}^n to the manifold:

$$t_0 = \sqrt{\|\mathbf{t}\|_2^2 + \frac{1}{K}}$$

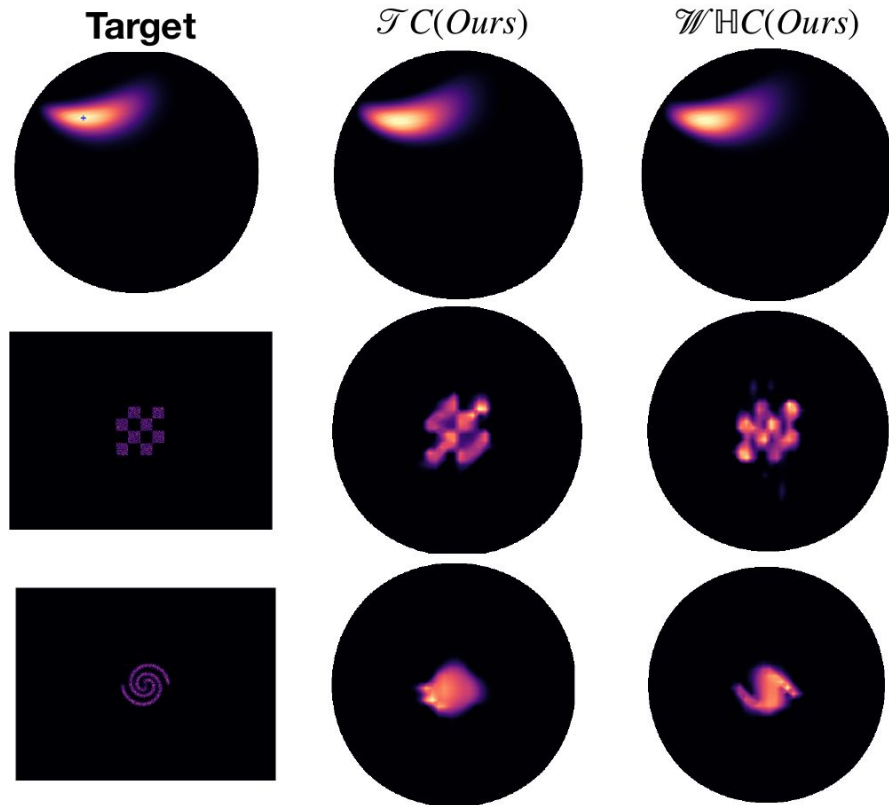
Jacobian of $\mathcal{W}\mathbb{H}\mathbb{C}$

$$\begin{aligned}
 & \text{RealNVP transform} \qquad \text{Four maps} \\
 \left| \det \left(\frac{\partial \mathbf{y}}{\partial \mathbf{x}} \right) \right| &= \prod_{i=d+1}^n \sigma(s(\tilde{x}_1))_i \times \left(\frac{R \sinh(\frac{\|q\|_{\mathcal{L}}}{R})}{\|q\|_{\mathcal{L}}} \right)^l \\
 & \times \underbrace{\left(\frac{R \sinh(\frac{\|\log_{\mathbf{o}}^K(\hat{q})\|_{\mathcal{L}}}{R})}{\|\log_{\mathbf{o}}^K(q)\|_{\mathcal{L}}} \right)^{-l}}_{\text{Four maps}} \times \underbrace{\left(\frac{R \sinh(\frac{\|\tilde{z}\|_{\mathcal{L}}}{R})}{\|\tilde{z}\|_{\mathcal{L}}} \right)^{n-1}}_{\text{Four maps}} \\
 & \times \underbrace{\left(\frac{R \sinh(\frac{\|\log_{\mathbf{o}}^K(\mathbf{x})\|_{\mathcal{L}}}{R})}{\|\log_{\mathbf{o}}^K(\mathbf{x})\|_{\mathcal{L}}} \right)^{1-n}}_{\text{Four maps}}, \quad (15)
 \end{aligned}$$

where $\tilde{z} = \text{concat}(\tilde{z}_1, \tilde{z}_2)$, the constant $l = n - d$, σ is a non-linearity, $q = \text{PT}_{\mathbf{o} \rightarrow t(\tilde{x}_1)}(v)$ and $\hat{q} = \exp_t^K(q)$.

Experiments

Density estimation



Density estimation

Branching diffusion process (BDP)

- sample from a “binary decision tree”

Dynamically binarized MNIST

- randomly threshold pixels to $\{0, 1\}$

Estimate likelihood of test data with importance sampling

Model	BDP-2	BDP-4	BDP-6
\mathcal{N} -VAE	-55.4 ± 0.2	-55.2 ± 0.3	-56.1 ± 0.2
\mathbb{H} -VAE	$-\mathbf{54.9} \pm 0.3$	-55.4 ± 0.2	-58.0 ± 0.2
$\mathcal{N}\mathcal{C}$	-55.4 ± 0.4	$-\mathbf{54.7} \pm 0.1$	$-\mathbf{55.2} \pm 0.3$
$\mathcal{T}\mathcal{C}$	$-\mathbf{54.9} \pm 0.1$	-55.4 ± 0.1	-57.5 ± 0.2
$\mathcal{W}\mathbb{H}\mathcal{C}$	$-\mathbf{55.1} \pm 0.4$	-55.2 ± 0.2	-56.9 ± 0.4

Table 1. Test Log Likelihood on Binary Diffusion Process versus latent dimension. All normalizing flows use 2-coupling layers.

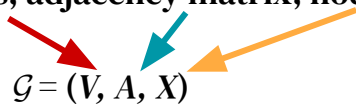
Model	MNIST 2	MNIST 4	MNIST 6
\mathcal{N} -VAE	-139.5 ± 1.0	-115.6 ± 0.2	-100.0 ± 0.02
\mathbb{H} -VAE	*	-113.7 ± 0.9	-99.8 ± 0.2
$\mathcal{N}\mathcal{C}$	-139.2 ± 0.4	-115.2 ± 0.6	$-\mathbf{98.7} \pm 0.3$
$\mathcal{T}\mathcal{C}$	*	$-\mathbf{112.5} \pm 0.2$	-99.3 ± 0.2
$\mathcal{W}\mathbb{H}\mathcal{C}$	$-\mathbf{136.5} \pm 2.1$	$-\mathbf{112.8} \pm 0.5$	-99.4 ± 0.2

Table 2. Test Log Likelihood on MNIST averaged over 5 runs versus latent dimension. * indicates numerically unstable settings.

Graph reconstruction

1. Disorders and disease genes: linked by known disorder-gene associations
2. SIR disease spreading model: nodes are individuals with varying susceptibility to disease

Nodes, adjacency matrix, node feature matrix:


$$\mathcal{G} = (V, A, X)$$

Encode nodes with variational graph autoencoder (VGAE):

$$q_{\phi}(Z \mid A, X)$$

Replace decoder with simple inner product:

$$p(A_{u,v} = 1 \mid z_u, z_v) = \sigma(\underbrace{z_u^T z_v}_{\text{inner product in hyperbolic space}})$$

Graph reconstruction

Model	Dis-I AUC	Dis-I AP	Dis-II AUC	Dis-II AP
\mathcal{N} -VAE	$0.90_{\pm 0.01}$	$0.92_{\pm 0.01}$	$0.92_{\pm 0.01}$	$0.91_{\pm 0.01}$
\mathbb{H} -VAE	$0.91_{\pm 5e-3}$	$0.92_{\pm 5e-3}$	$0.92_{\pm 4e-3}$	$0.91_{\pm 0.01}$
$\mathcal{N}C$	$0.92_{\pm 0.01}$	$0.93_{\pm 0.01}$	$0.95_{\pm 4e-3}$	$0.93_{\pm 0.01}$
$\mathcal{T}C$	$0.93_{\pm 0.01}$	$0.93_{\pm 0.01}$	$0.96_{\pm 0.01}$	$0.95_{\pm 0.01}$
WHC	$0.93_{\pm 0.01}$	$0.94_{\pm 0.01}$	$0.96_{\pm 0.01}$	$0.96_{\pm 0.01}$

Table 3. Test AUC and Test AP on Graph Embeddings where Dis-I has latent dimesion 6 and Dis-II has latent dimension 2.

Graph generation

Pretrain graph autoencoder on trees

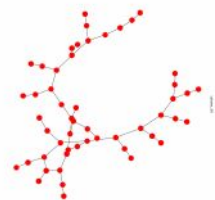
Decode edge probabilities with:

$$p(A_{u,v} = 1 \mid z_u, z_v) = \sigma(\underbrace{(-d_{\mathcal{G}}(u, v) - b)}_{\text{distance between nodes in latent space}} / \tau)$$

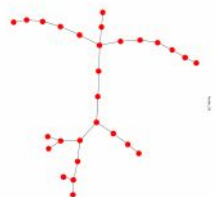
Annotations:

- Red arrow pointing to σ : sigmoid function
- Blue bracket under $d_{\mathcal{G}}(u, v)$: distance between nodes in latent space
- Orange arrows pointing to b and τ : learned bias, temperature

Lobster



Random Tree

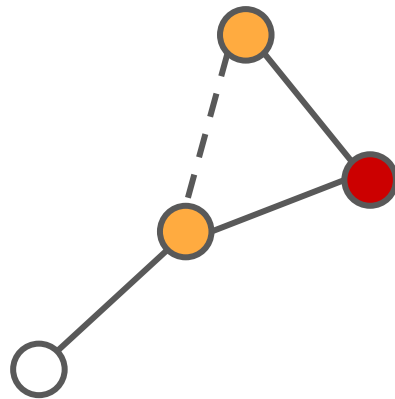


Evaluating generated graphs

Hard to evaluate graphs by likelihood, due to multiple isomorphic orderings

Compare statistics using maximum mean discrepancy (Wasserstein/earth mover's distance):

- degree (neighbours per node)
- local clustering coefficient (“triangles to neighbours” per node)
- global clustering coefficient (total triangles to triplets)
- spectrum (eigenvalues of graph Laplacian)
- accuracy (valid trees)



Evaluating generated graphs

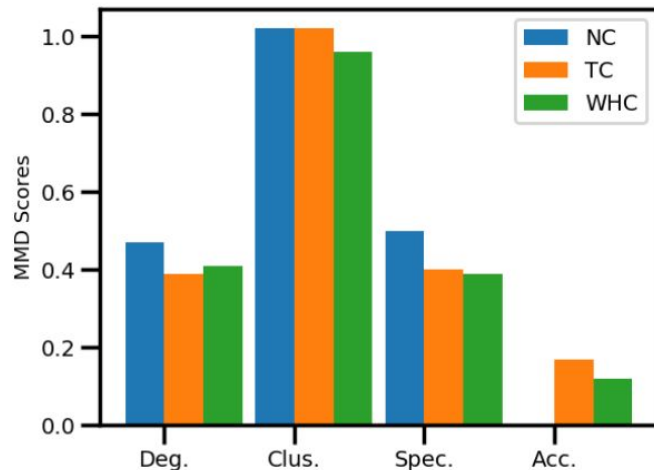


Figure 5. MMD scores for graph generation on Lobster graphs. Note, that \mathcal{NC} achieves 0% accuracy.

Graph generation results

Random Tree

Train

\mathcal{NC}

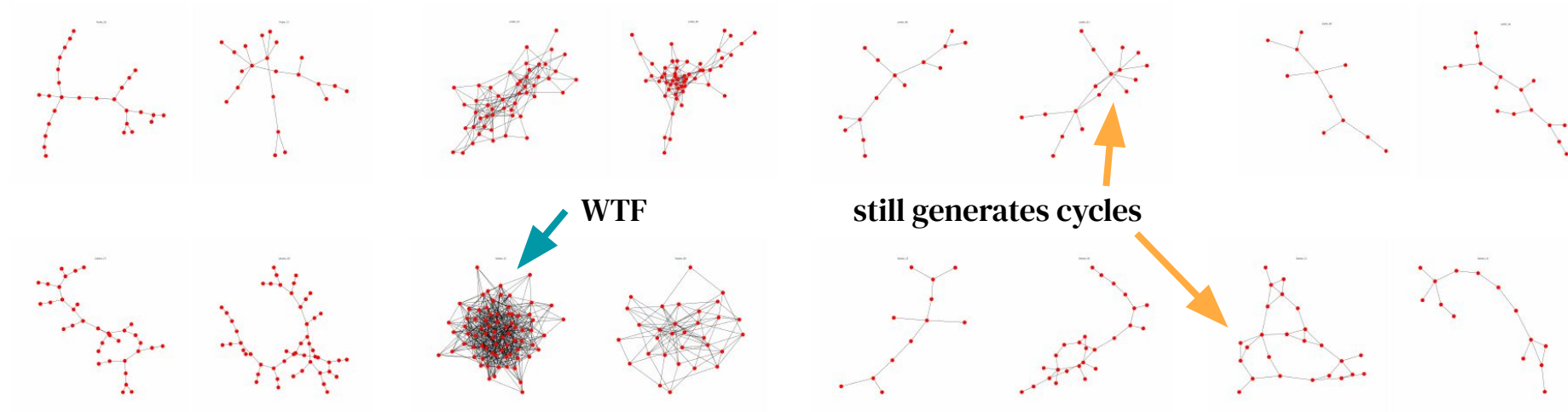
\mathcal{TC}

\mathcal{WHC}

Lobster

WTF

still generates cycles



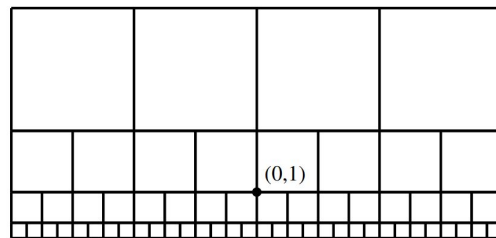
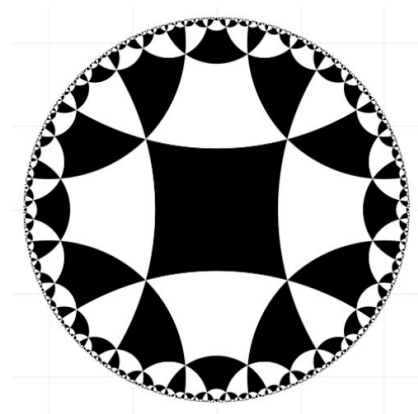
Conclusion

Advantages and disadvantages

- + Good at generating/reconstructing trees
- Less effective with more latent dimensions
- Clamping for numerical stability limits depth(?)

Further thoughts

- What problems benefit from high-dimensional hyperbolic spaces?
- How does performance and cost scale with increased model depth?
- Can tiling methods fix numerical instability?
- Hyperbolic diffusion when?



Thanks!