## Numerical Analysis

## **Linear Systems**

- 1. For n = 2, 3, ..., 10, generate a Hilbert Matrix H of order n. Note that H is symmetric positive definite matrix. Use Matlab built-in function **hilb(n)** to check the output of the code.
- 2. In Matlab,  $\mathbf{R} = \mathbf{chol}(\mathbf{A})$  factorizes the symmetric positive definite matrix A into an upper triangular R that satisfies A = R' \* R. Use the built-in function  $\mathbf{chol}$  to decompose H into lower and upper triangular R' and R, respectively.
- 3. Generate the n-vector b = Hx, where x is an n-vector with all of its components equal to 1. Using the factorization of H, solve the linear system Hx = b using forward and backward substitution to obtain an approximate solution  $\hat{x}$ .
- 4. Compute for the  $\infty$ -norm of the residual  $r = b H\hat{x}$  and the error  $\Delta x = \hat{x} x$ , where the n-vector x consisting of ones is the true solution of the linear system. Compute also for the condition number of H.
- 5. Plot n vs the error  $\Delta x$ , residual r, and the condition number in one figure. For the condition number, use the **semilogy** plot function.