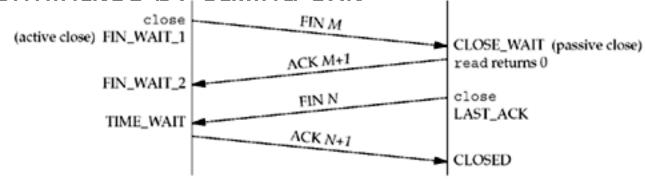
TCP Client/Server Example – part 2

Giảng viên: TS. Trần Hải Anh Bộ môn Truyền Thông & Mạng máy tính Khoa CNTT & TT

Intro

- In the previous practical work, after sending the EOF character => fgets() returns null pointer => the function str_cli returns => the client main function calls exit() => the client sends FIN to the server
- => str_echo function returns => server child terminates by calling exit



Issue

- Finally, the SIGCHLD signal is sent to the parent when the server child terminates.
- This occurs in this example, but we do not catch the signal in our code, and the default action of the signal is to be ignored. Thus, the child enters the zombie state.

```
linux % ps -t pts/6 -o pid,ppid,tty,stat,args,wchan
PID PPID TT STAT COMMAND WCHAN
22038 22036 pts/6 S -bash read_chan
17870 22038 pts/6 S ./tcpserv01 wait_for_connect
19315 17870 pts/6 Z [tcpserv01 <defu do_exit
```

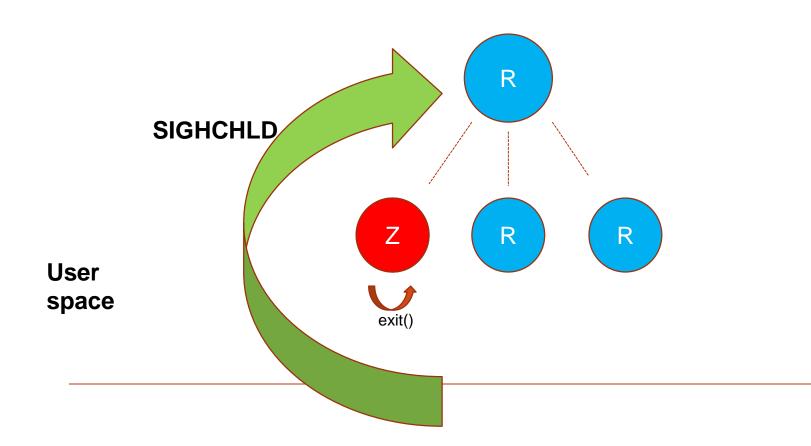
POSIX Signal Handling

- A signal is a notification to a process that an event has occurred (software interrupts).
- asynchronously
- Signals can be sent
 - by one process to another process (or to itself)
 - by the kernel to a process
- Example: The SIGCHLD signal is sent by the kernel whenever a process terminates, to the parent of the terminating process.

POSIX Signal Handling

- Every signal has a *disposition* (the *action* associated with the signal). We set the disposition of a signal by calling the sigaction function.
- 3 choices for the disposition:
 - We can provide a function that is called whenever a specific signal occurs. This function is called a signal handler and this action is called catching a signal.
 - We can *ignore* a signal by setting its disposition to SIG_IGN.
 - We can set the default disposition for a signal by setting its disposition to SIG_DFL.

- The purpose of the zombie state is to maintain information about the child for the parent:
 - the process ID of the child
 - its termination status
 - information on the resource utilization of the child (CPU time, memory, etc.).
- If a process terminates, and that process has children in the zombie state, the parent process ID of all the zombie children is set to 1 (the *init* process).
 - We do not want to leave zombies around:
 - They take up space in the kernel
 - We can run out of processes.
 - Whenever we fork children, we must wait for them to prevent them from becoming zombies.
 - Establish a signal handler



Kernel space

 We establish the signal handler by adding the function call after the call to listen function:

```
Signal (SIGCHLD, sig chld);
```

We define the function sig_chld

tcpcliserv/sigchldwait.c

```
1 #include "unp.h"

2 void
3 sig_chld(int signo)
4 {
5     pid_t    pid;
6     int     stat;

7     pid = wait(&stat);
8     printf("child %d terminated\", pid);
9     return;
10 }
```

Now, try to compile and run it!

```
solaris % tcpserv02 &

[2] 16939

solaris % tcpcli01 127.0.0.1

hi there

hi there

^D

child 16942 terminated

accept error: Interrupted system call
```

 To handle an interrupted accept, we change the call to accept:

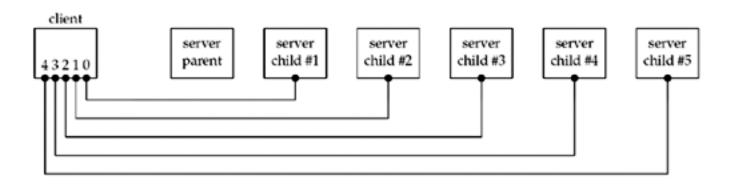
wait and waitpid functions

```
#include <sys/wait.h>
pid_t wait (int *statloc);
pid_t waitpid (pid_t pid, int *statloc,
int options);
```

- Both return: process ID if OK, 0 or–1 on error
- The waitpid gives more control:
 - which process to wait for (pid argument)
 - whether or not to block (options argument)

Difference between wait and waitpid

 Client with five established connections to same concurrent server.



tcpcliserv/tcpcli04.c

```
1 #include
                "unp.h"
 2 int
 3 main (int argc, char **argv)
 4 {
 5
        int
               i, sockfd[5];
 6
        struct sockaddr in servaddr;
 7
        if (argc != 2)
            err quit ("usage: tcpcli <IPaddress>";
        for (i = 0; i < 5; i++) {
10
            sockfd[i] = Socket (AF_INET, SOCK_STREAM, 0);
11
            bzero (&servaddr, sizeof (servaddr));
            servaddr.sin_family = AF_INET;
12
13
            servaddr.sin port = htons (SERV PORT);
14
            Inet_pton (AF_INET, argv[1], &servaddr.sin_addr);
15
            Connect (sockfd[i], (SA *) &servaddr, sizeof (servaddr));
16
       }
       str_cli (stdin, sockfd[0]); /* do it all */
17
18
       exit(0);
19 }
```

Problem!!!

```
linux % tcpserv03 &
[1] 20419
linux % tcpcli04 127.0.0.1
hello
hello
^D
child 20426 terminated
```

Only one child process is terminated

Why?

Now, we execute the ps command:

- Establishing a signal handler and calling wait from that handler are insufficient for preventing zombies
- The problem is that all five signals are generated before the signal handler is executed, and the signal handler is executed only one time because Unix signals are normally not queued.

Use waitpid

Final (correct) version of sig_chld function that calls waitpid

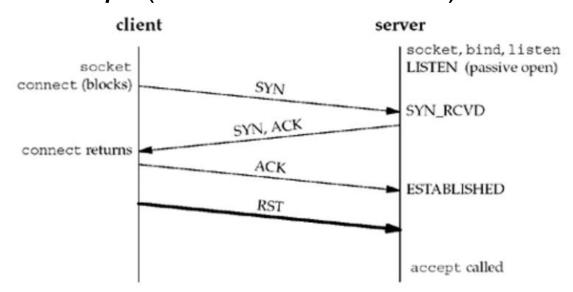
tcpcliserv/sigchldwaitpid.c

Conclusion

- We must catch the SIGCHLD signal when forking child processes.
- We must handle interrupted system calls when we catch signals.
- A SIGCHLD handler must be coded correctly using waitpid to prevent any zombies from being left around.

Connection Abort before accept Returns

- Receiving an RST for an ESTABLISHED connection before accept is called.
- The aborted connection completely within the kernel
- That returns an error to the process as the return from accept (ECONNABORTED)



Some another issues

- Termination of Server Process
- Crashing of Server Host
- Crashing and Rebooting of Server Host
- Shutdown of Server Host

