

## Chapter 6

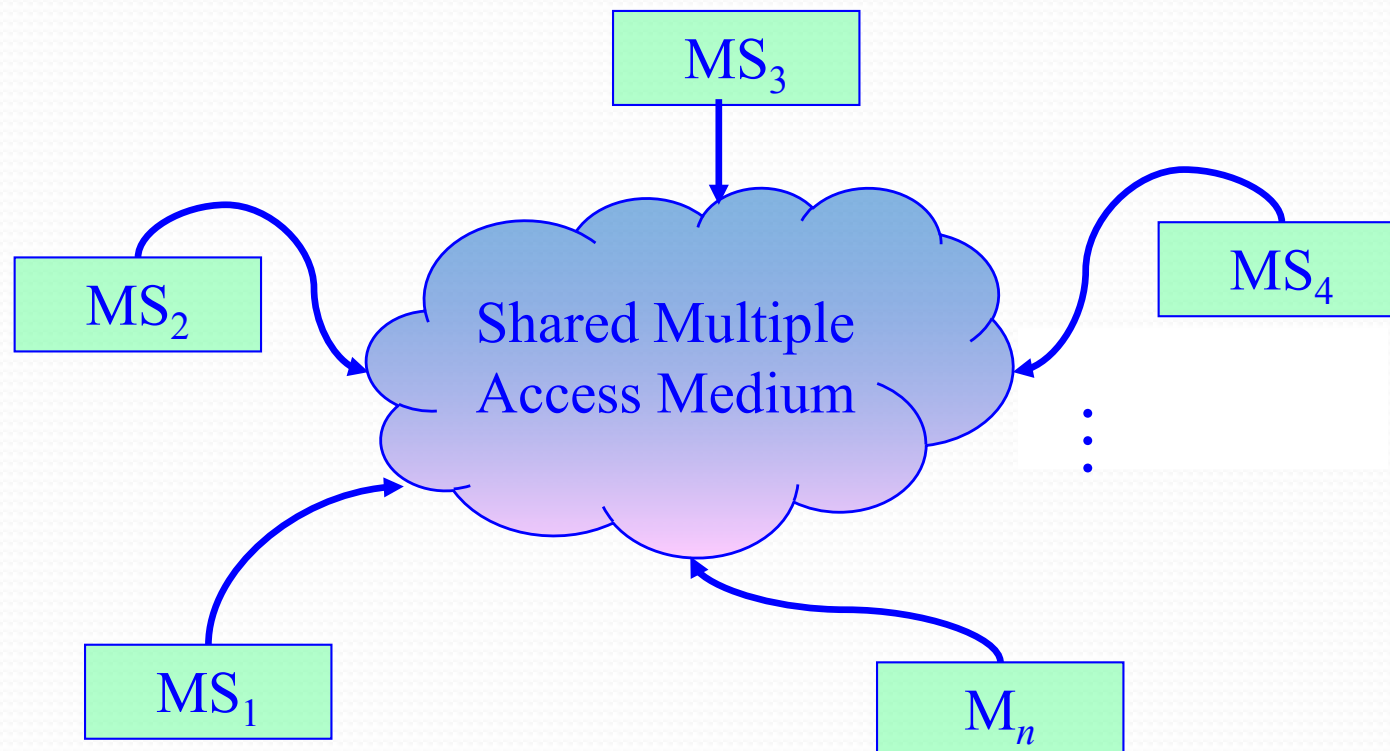
### Multiple Radio Access

# Outline

- Introduction
- Multiple Radio Access Protocols
- Contention-based Protocols
  - Pure ALOHA
  - Slotted ALOHA
  - CSMA (Carrier Sense Multiple Access)
  - CSMA/CD (CSMA with Collision Detection)
  - CSMA/CA (CSMA with Collision Avoidance)
- Summary

# Introduction

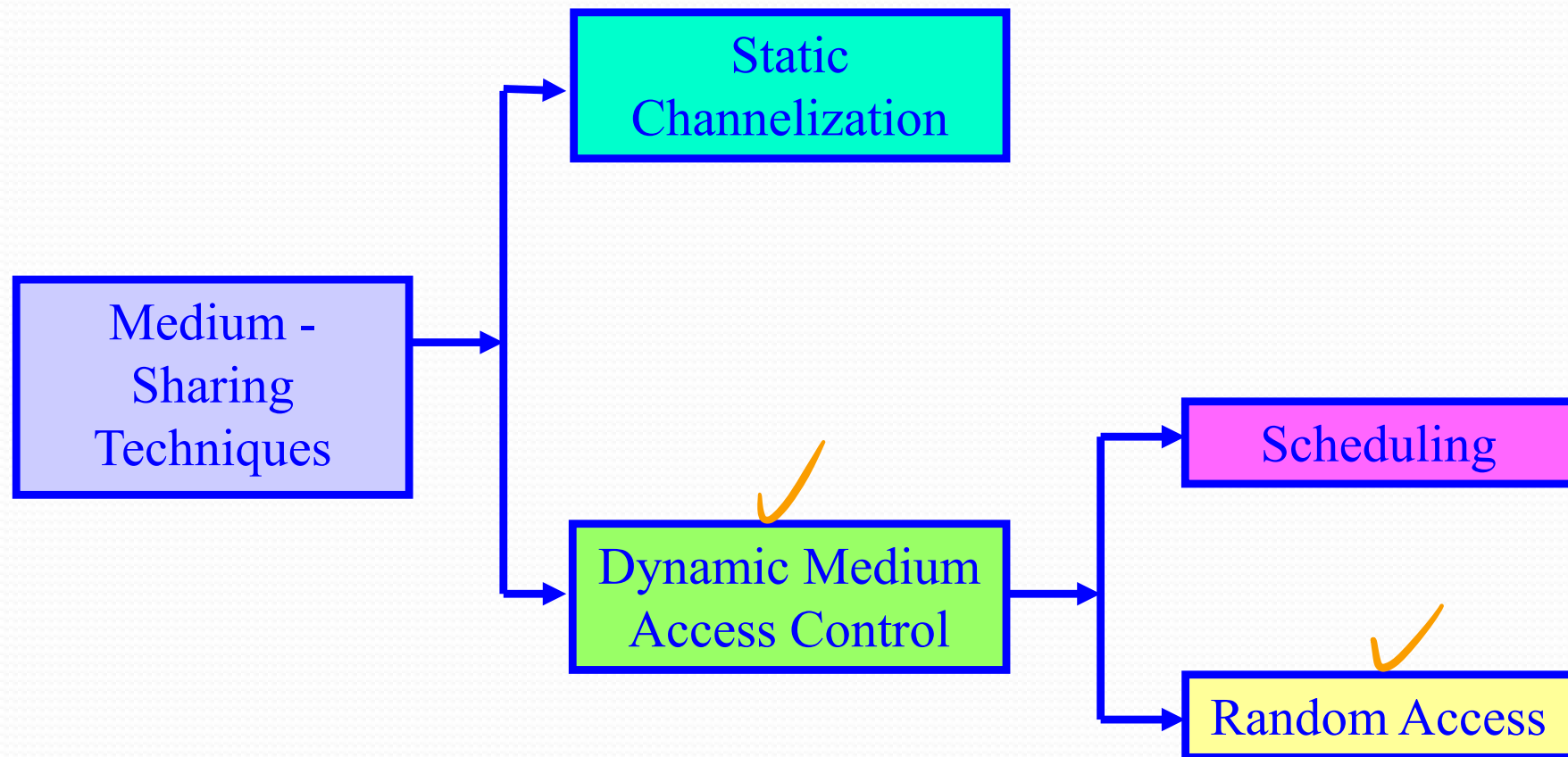
- Multiple access control channels
  - Each Mobile Station (MS) is attached to a transmitter or receiver which communicates via a channel shared by other nodes
  - Transmission from any MS is received by other MSs



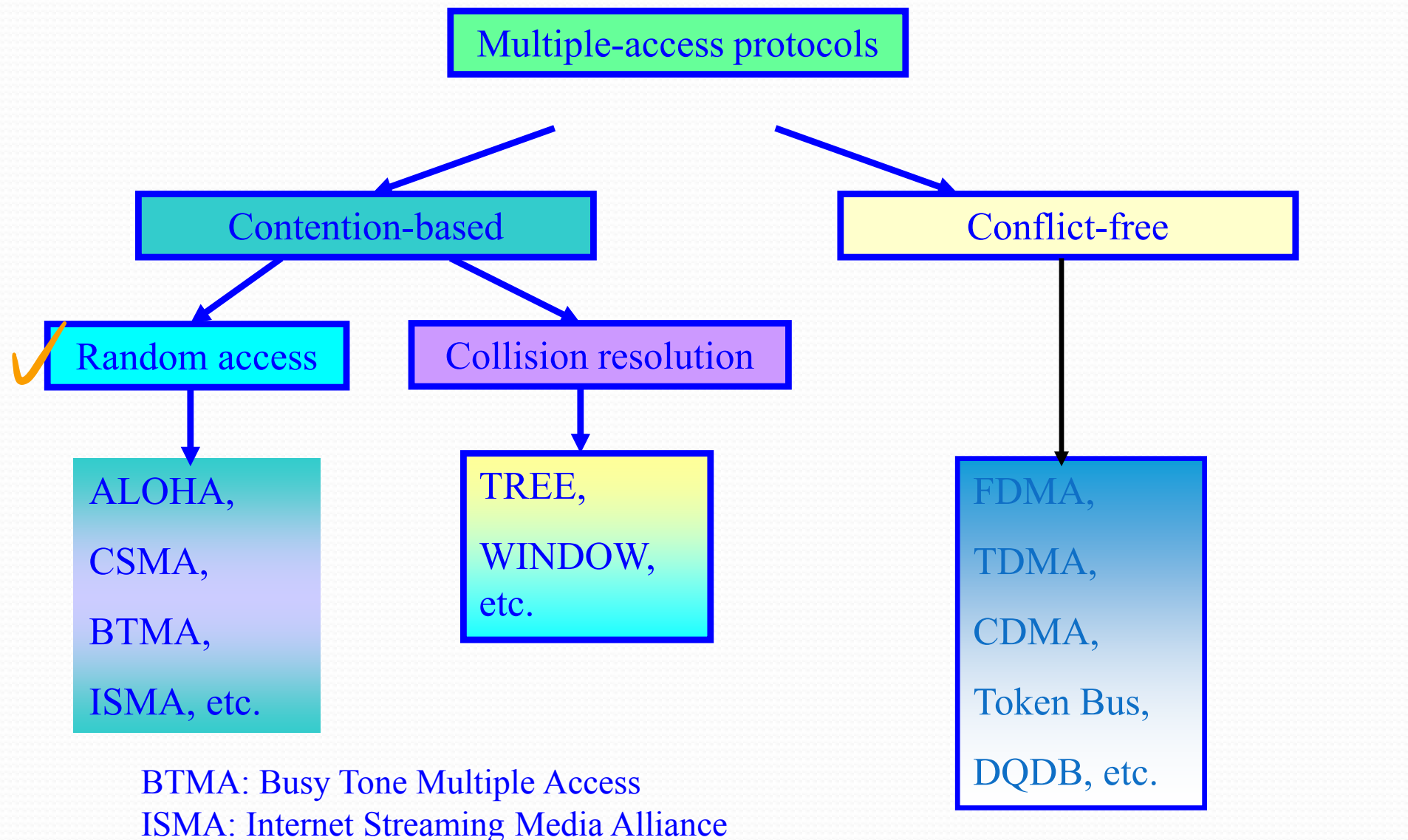
# Introduction (Cont'd)

- Multiple access issues
  - If more than one MS transmit at a time on the control channel to BS, a collision occurs
  - How to determine which MS can transmit to BS?
- Multiple access protocols
  - Solving multiple access issues
  - Different types:
    - ❖ Contention protocols resolve a collision after it occurs. These protocols execute a collision resolution protocol after each collision
    - ❖ Collision-free protocols (e.g., a bit-map protocol and binary countdown) ensure that a collision can never occur

# Channel Sharing Techniques



# Classification of Multiple Access Protocols



DQDB: Distributed Queue Dual Bus

# Contention-based Protocols

⊙ 有 data 就傳送

- **ALOHA** ⊙ 若 collision, 則等一時間後重傳

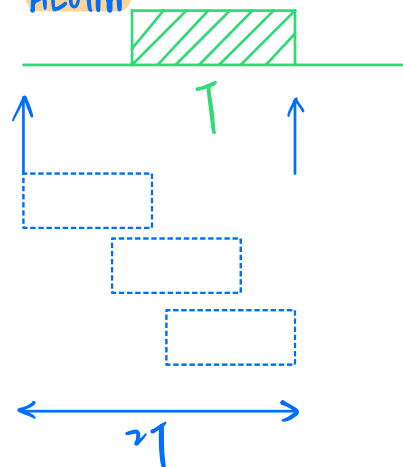
- Developed in the 1970s for a packet radio network by Hawaii University
- Whenever a terminal (MS) has data, it transmits. Sender finds out whether transmission was successful or experienced a collision by listening to the broadcast from the destination station. If there is a collision, sender retransmits after some random time

- **Slotted ALOHA**

- Improvement: Time is slotted and a packet can only be transmitted at the beginning of one slot. Thus, it can reduce the collision duration



## ★ Aloha



平均一秒有多少 package  
 $G = \frac{\lambda}{\mu} = \lambda T \cdot \text{offered load}$

$$P_n(t) = P_0(2T) \text{ 成功傳出的機率}$$

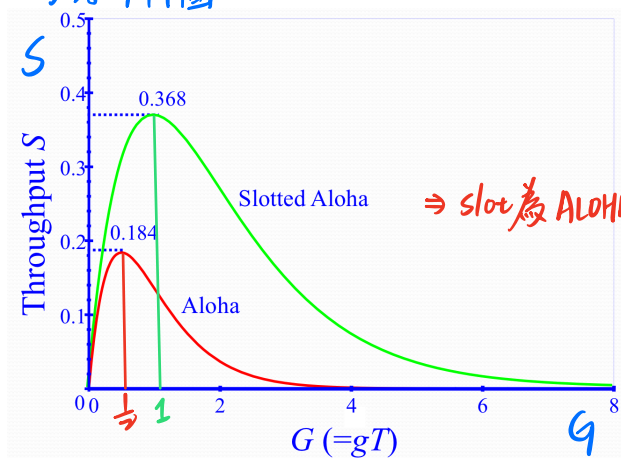
$$= \frac{e^{-\lambda T} (\lambda T)^0}{0!} = e^{-\lambda T} = e^{-G}$$

$$S = \text{throughput} = G \cdot e^{-2G}$$

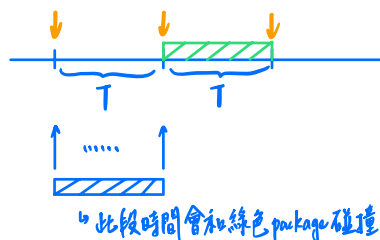
$$\frac{\partial S}{\partial G} = e^{-2G} - 2G e^{-2G} = 0 \Rightarrow G = \frac{1}{2} \text{ 極值}$$

$$\Rightarrow S = \frac{1}{2} \cdot e^{-1} = 0.184 \Rightarrow 18.4\%$$

\* S 對 G 作圖:



• Slotted ALOHA: 在指定的時間點才能傳資料



$$P_n(t) = P_0(T) = \frac{e^{-\lambda T} (\lambda T)^0}{0!} = e^{-G}$$

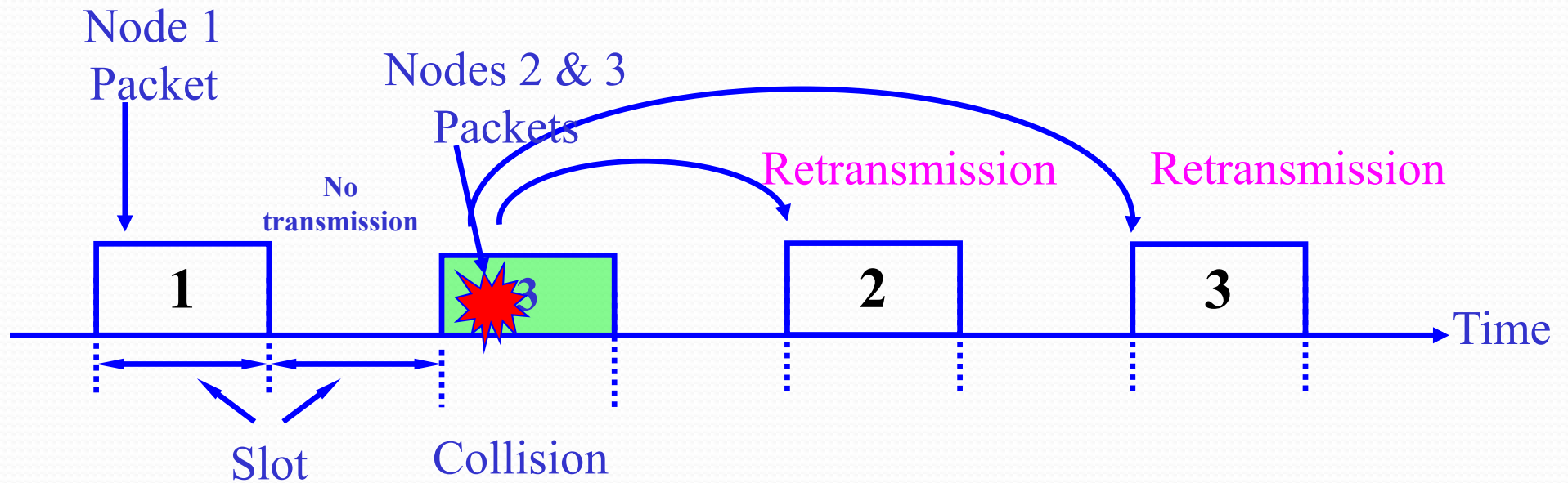
$$S_r = \text{throughput} = G \cdot e^{-G}$$

$$\frac{\partial S_r}{\partial G} = e^{-G} - G e^{-G} = 0 \text{ 極值} \Rightarrow G = 1$$

$$\Rightarrow S_r = e^{-1} = 0.368 = 36.8\%$$



# Slotted ALOHA



Collision mechanism in slotted ALOHA

# Throughput of Slotted ALOHA

- The probability of successful transmission  $P_s$  is the probability no other packet is scheduled in an interval of length  $T$

$$P_s = e^{-gT}$$

where  $g$  is the packet rate of the traffic

- The throughput  $S_{th}$  of pure Aloha as:

$$S_{th} = gTe^{-gT}$$

- Defining  $G = gT$  to normalize offered load, we have

$$S_{th} = Ge^{-G}$$

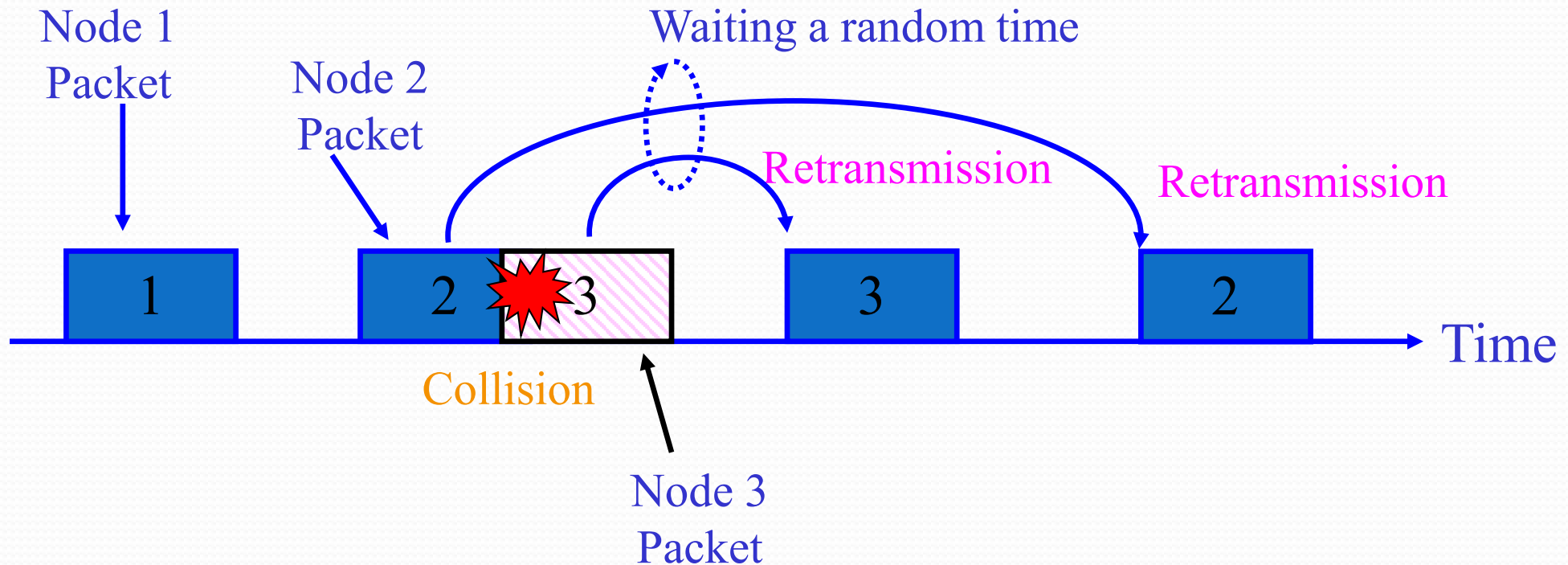
- Differentiating  $S_{th}$  with respect to  $G$  and equating to zero gives

$$\frac{dS_{th}}{dG} = -Ge^{-G} + e^{-G} = 0$$

- The Maximum throughput of ALOHA is

$$S_{\max} = \frac{1}{e} \approx 0.368$$

# Pure ALOHA



Collision mechanism in ALOHA

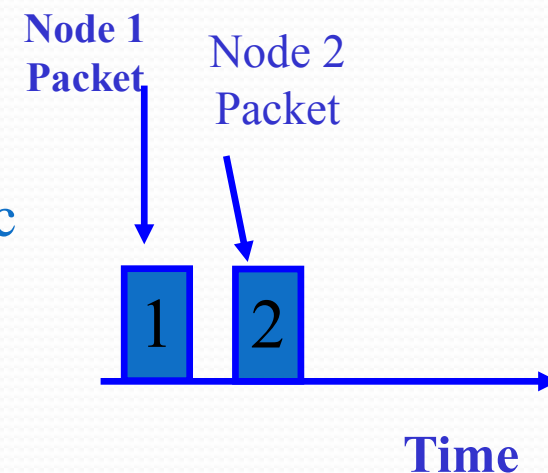
# Throughput of Pure ALOHA

- The probability of successful transmission  $P_s$  is the probability no other packet is scheduled in an interval of length  $2T$

$$P_s = P(\text{no\_collision})$$

$$= e^{-2gT}$$

where  $g$  is the packet rate of the traffic



- The throughput  $S_{th}$  of pure Aloha as:

$$S_{th} = gTe^{-2gT}$$

- Defining  $G = gT$  to normalize offered load, we have

$$S_{th} = Ge^{-2G}$$

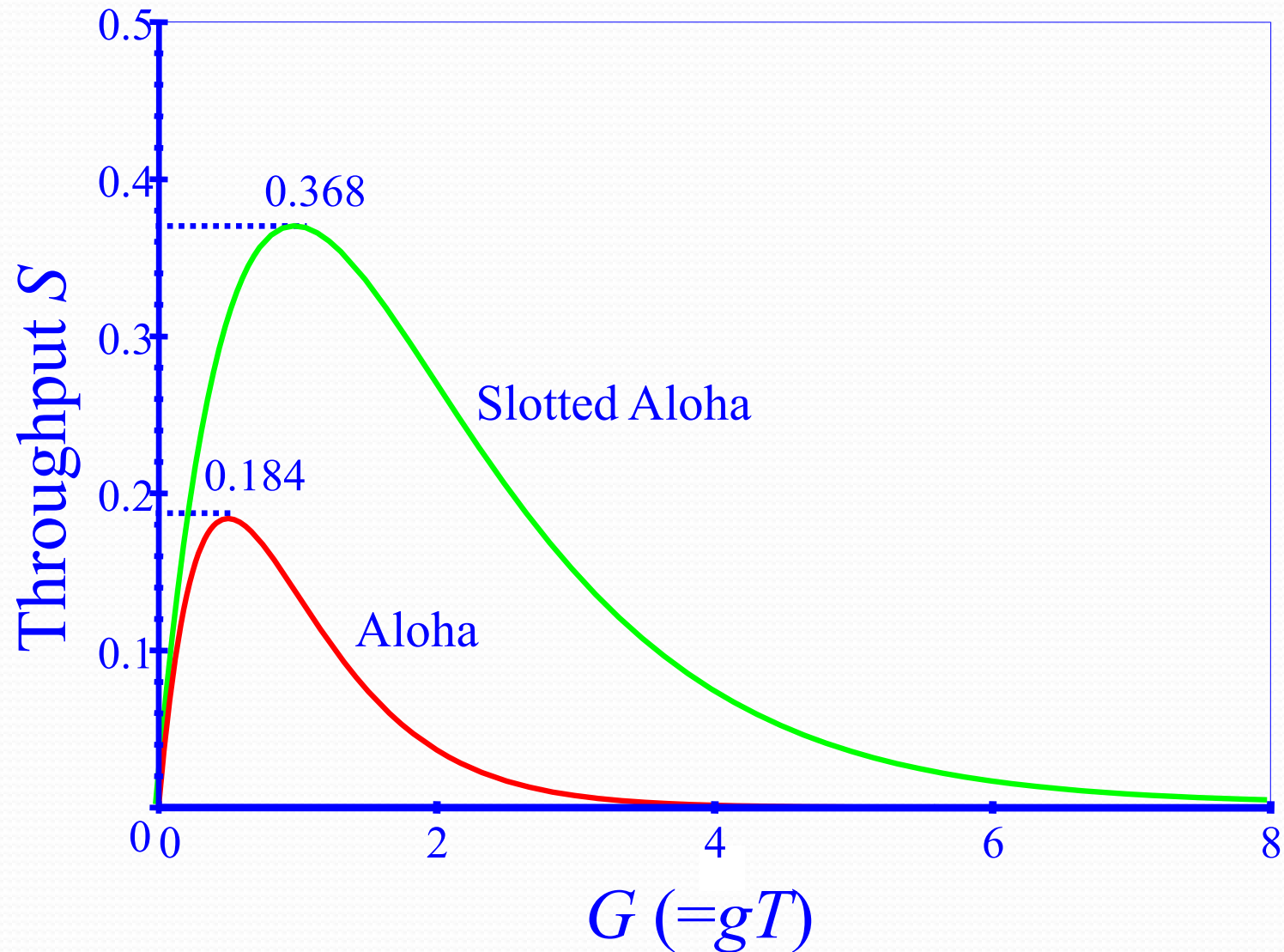
- Differentiating  $S_{th}$  with respect to  $G$  and equating to zero gives

$$\frac{dS_{th}}{dG} = -2Ge^{-2G} + e^{-2G} = 0$$

- The Maximum throughput of ALOHA is

$$S_{\max} = \frac{1}{2e} \approx 0.184$$

# Throughput



# Contention Protocols (Cont'd)

- **CSMA (Carrier Sense Multiple Access)**
  - Improvement: Start transmission only if no transmission is ongoing  
↳ 傳之前確定沒人在傳 (carrier sense)
- **CSMA/CD (CSMA with Collision Detection)**
  - Improvement: Stop ongoing transmission if a collision is detected
- **CSMA/CA (CSMA with Collision Avoidance)**
  - Improvement: Wait a random time and try again when carrier is quiet. If still quiet, then transmit
- **CSMA/CA with ACK**
- **CSMA/CA with RTS/CTS**

# CSMA (Carrier Sense Multiple Access)

- Max throughput achievable by slotted ALOHA is 0.368
- CSMA gives improved throughput compared to Aloha protocols
- Listens to the channel before transmitting a packet (avoid avoidable collisions)

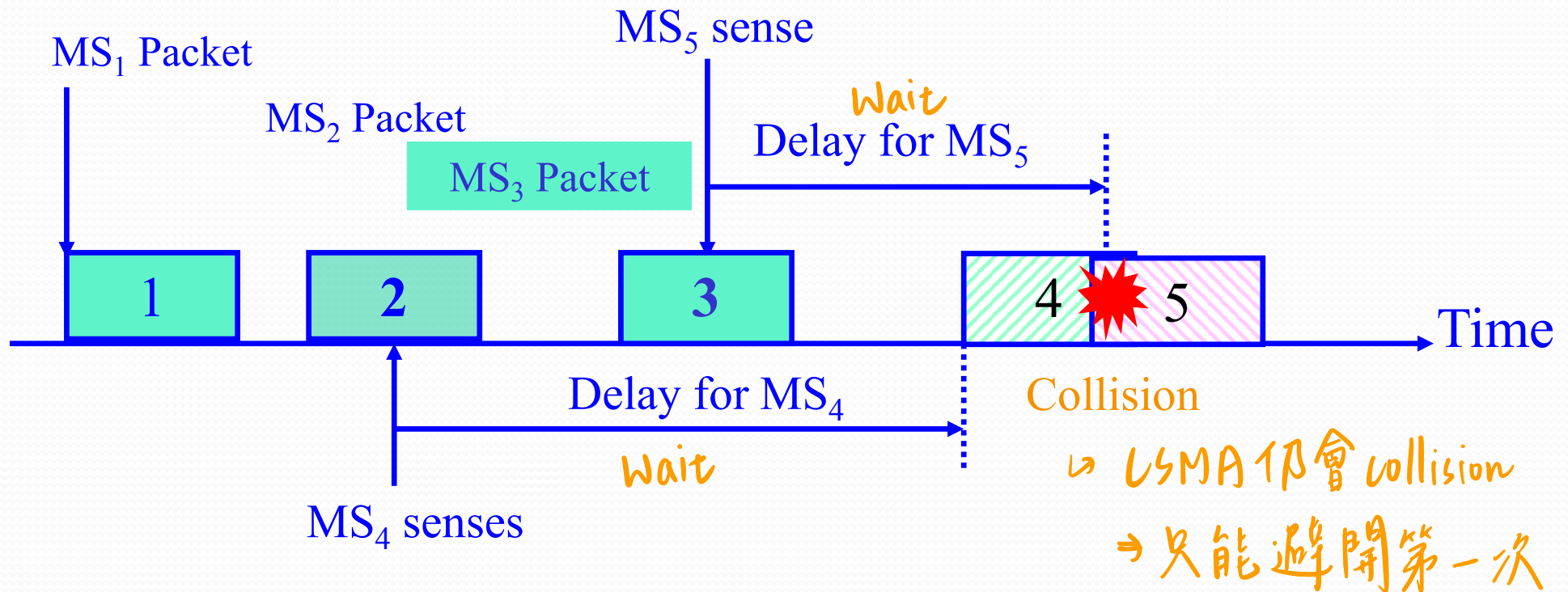
① 傳之前確定沒人在傳 (carrier sense), 否則就 wait

② 有 data 就傳送

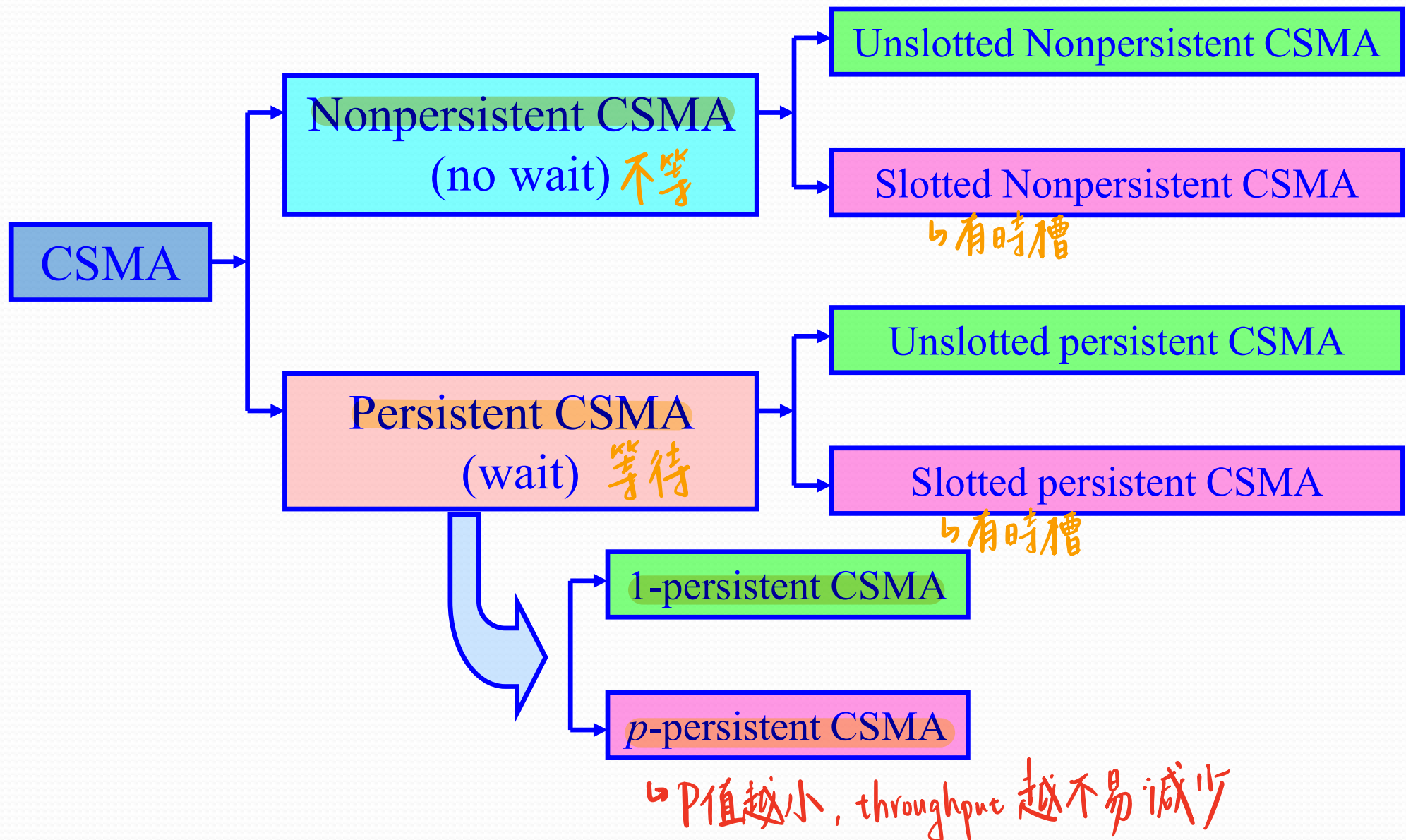
③ 若 collision, 則等一時間後重傳



# Collision Mechanism in CSMA



# Kinds of CSMA CSMA 家族



# $p$ -persistent CSMA Protocols

- $p$ -persistent CSMA Protocol:**

Step 1: If the medium is idle, transmit with probability  $p$ , and delay for worst case propagation delay by one packet with probability  $(1-p)$

↳ 等一個 slot ( $1-p$  的機率)

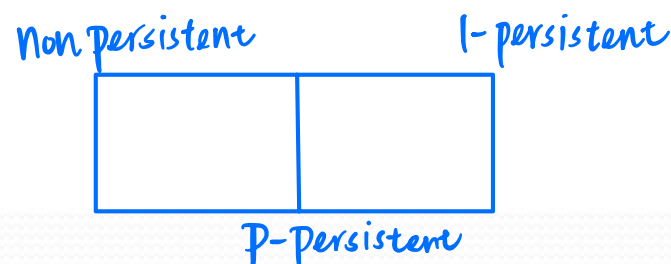
Special case of  $p=0$  and  $p=1$

Step 2: If the medium is busy, continue to listen until medium becomes idle, then go to Step 1

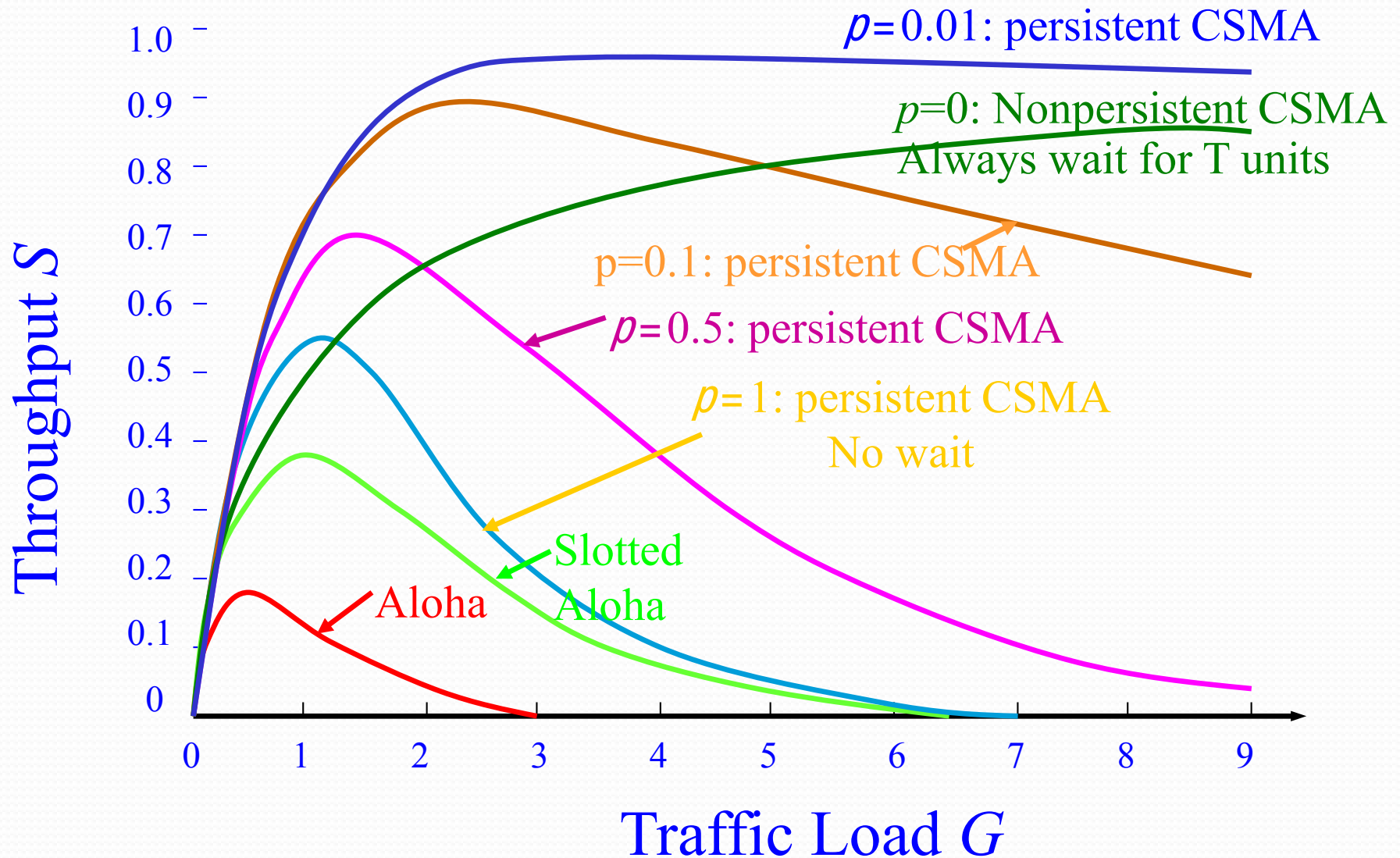
Step 3: If transmission is delayed by one time slot, continue with Step 1

➤  $p=0$ : nonpersistent and  $p=1$ : 1-persistent CSMA

➤ A good tradeoff between nonpersistent and 1-persistent CSMA



# Throughput



## Nonpersistent/ $p$ -persistent CSMA Protocols

### • Nonpersistent CSMA Protocol:

→ 用 carrier sense 判斷

Step 1: If the medium is idle, transmit immediately (same as  $p=1$ )

Step 2: If the medium is busy, wait a random amount of time and repeat Step 1

- Random backoff reduces probability of collisions
- Waste idle time if the backoff time is too long

參考

For unslotted nonpersistent CSMA, the throughput is given by:

$$S_{th} = \frac{Ge^{-2\alpha T}}{G(1+2\alpha) + e^{-\alpha G}} \quad \text{where } \alpha = \frac{\tau}{T} = \frac{\text{propagation delay}}{\text{packet transmission time}}$$

For slotted nonpersistent CSMA, the throughput is given by:

$$S_{th} = \frac{\alpha Ge^{-2\alpha T}}{(1 - e^{-\alpha G} + \alpha)}$$

# 1-persistent CSMA Protocols

## 1-persistent CSMA Protocol:

Step 1: If the medium is idle, transmit immediately

Step 2: If the medium is busy, continue to listen until medium becomes idle, and then transmit immediately 一等 idle 就馬上傳

- There will always be a collision if two nodes want to retransmit (usually you stop transmission attempts after few tries)

參考

若遇到 2 個人同時在等待，則必會碰撞

For unslotted 1-persistent CSMA, the throughput is given by

$$S_{th} = \frac{G[1 + G + \alpha G(1 + G + \alpha G / 2)]e^{-G(1+2\alpha)}}{G(1 + 2\alpha) - (1 - e^{-\alpha G}) + (1 + \alpha G)e^{-G(1+\alpha)}}$$

For slotted 1-persistent CSMA, the throughput is given by

$$S_{th} = \frac{G(1 + \alpha - e^{-\alpha G})e^{-G(1+\alpha)}}{(1 + \alpha)(1 - e^{-\alpha G}) + \alpha e^{-G(1+\alpha)}}$$

# How to Select Probability $p$ ?

- Assume that  $N$  nodes have a packet to send and the medium is busy
- Then,  $Np$  is the expected number of nodes that will attempt to transmit once the medium becomes idle
- If  $Np > 1$ , then a collision is expected to occur

Therefore, network must make sure that  $Np \leq 1$  to avoid collision, where  $N$  is the maximum number of nodes that can be active at a time



# $p$ -persistent CSMA Protocol

If  $N$  terminals have packets to send,  $Np$  terminals will attempt to transmit once the medium becomes idle. If  $Np > 1$ , then collision is expected. Therefore,  $Np \leq 1$ .  
Throughput  $S$  as:

参考 
$$S_{th}(G, p, \alpha) = \frac{(1 - e^{-\alpha G}) [P'_s \pi_0 + P_s (1 - \pi_0)]}{(1 - e^{-\alpha G}) [\alpha \bar{t}' \pi_0 + \alpha \bar{t} (1 - \pi_0) + 1 + \alpha] + \alpha \pi_0}$$

where  $G$  is offered traffic rate

$\alpha = \tau/T =$  **propagation delay/packet transmission time**

where  $P'_s, P_s, \bar{t}', \bar{t}$  and  $\pi_0$  are given by the following equations:

$$P'_s = \sum_{n=1}^{\infty} P_s(n) \pi'_n \quad P_s = \sum_{n=1}^{\infty} P_s(n) \frac{\pi_n}{1 - \pi_0}$$

$$\bar{t}' = \sum_{n=1}^{\infty} \bar{t}_n \pi'_n \quad \bar{t} = \sum_{n=1}^{\infty} \bar{t}_n \frac{\pi_n}{1 - \pi_0}$$

# $p$ -persistent CSMA Protocol

**Where:**

$$\pi_n = \frac{[(1+\alpha)G]^n}{n!} e^{-(1+\alpha)G}, n \geq 0, \quad P_s(n) = \sum_{l=n}^{\infty} \frac{lp(1-p)^{l-1}}{1-(1-p)^l} \Pr\{L_n = l\}$$

$$\pi'_n = \frac{g^n e^{-g}}{n!(1-e^{-g})}, n \geq 1 \quad \bar{t}_n = \sum_{k=0}^{\infty} \Pr\{\bar{t}_n > k\}$$

$$\text{where } \Pr\{L_n = l\} = \sum_{k=1}^{\infty} \frac{(kg)^{l-n}}{(l-n)!} e^{-kg} \quad \Pr\{t_n = k\} + [1-(1-p)^n] \delta_{l,n}, l \geq n$$

and  $\delta_{i,j}$  is the Kronecker delta.

# ★ CSMA/CD (CSMA with Collision Detection)

In CSMA, if 2 terminals begin sending packet at the same time, each will transmit its complete packet (although collision is taking place)

Wasting medium for an entire packet time

**CSMA/CD:** ⇒ Ethernet (乙太網路) IEEE 802.3 (token bus)

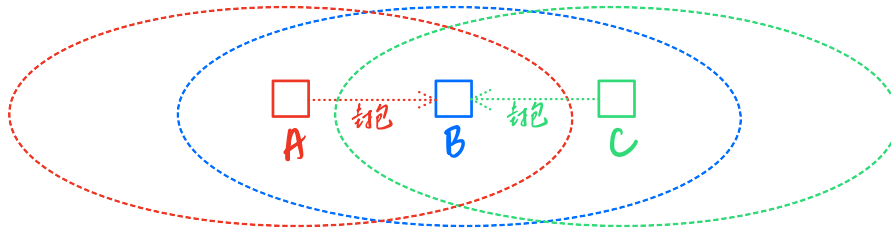
Step 1: If the medium is idle, transmit

Step 2: If the medium is busy, continue to listen until the channel is idle then transmit

Step 3: If a collision is detected during transmission, cease transmitting (detection not possible by wireless devices) ↳ 偵測碰撞 (一碰就停)

Step 4: Wait a random amount of time and repeats the same algorithm ↳ 等一下再用

## § Hidden terminal problem (HTP)



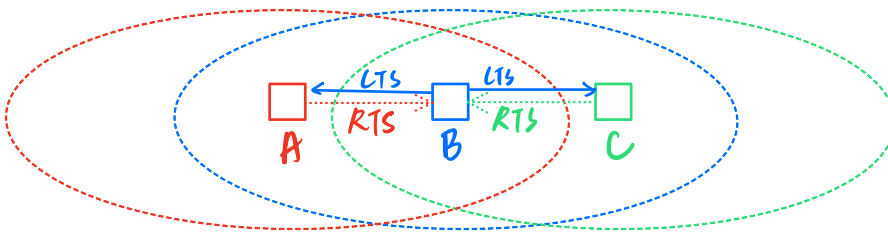
- \* A & C in B's range
- \* B is in A range, but not C
- \* B is in C range, but not A

When  $A \rightarrow B$  &  $C \rightarrow B$  at same time, collision occur!

(B一直收到A和C互相干擾的封包, 且A和C互為 hidden terminal)

↳ CSMA/CD failed

### • Solution



\* RTS: request to send (註明 sender, receiver)  
A B

\* CTS: clear to send (註明 sender, receiver)  
B A

### • Priority waiting:

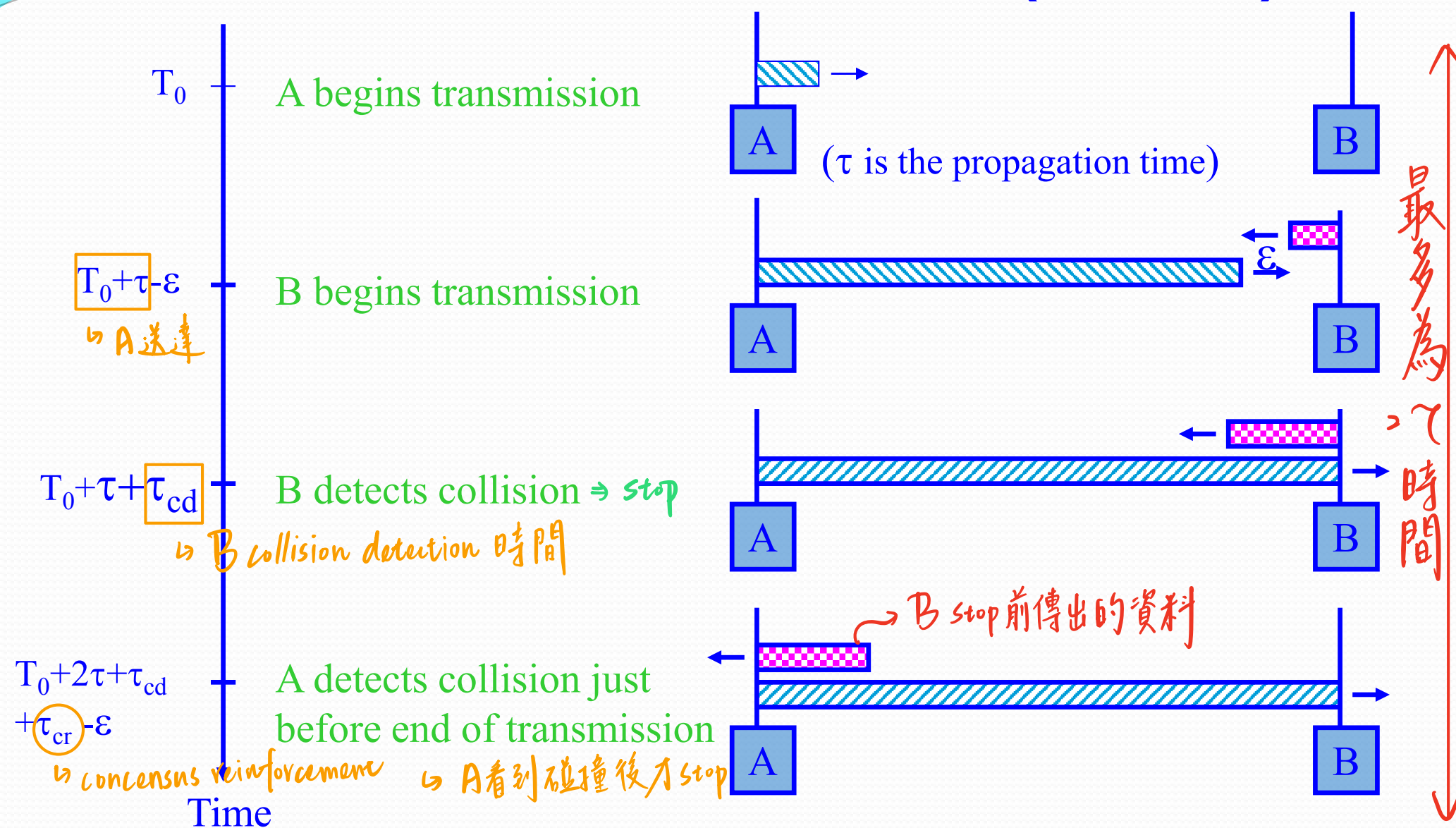
- PIFS (priority interframe space)
- SIFS (small interframe space)
- DIFS (distributed interframe space)
- EIFS (extended interframe space)

↑ 高優先權

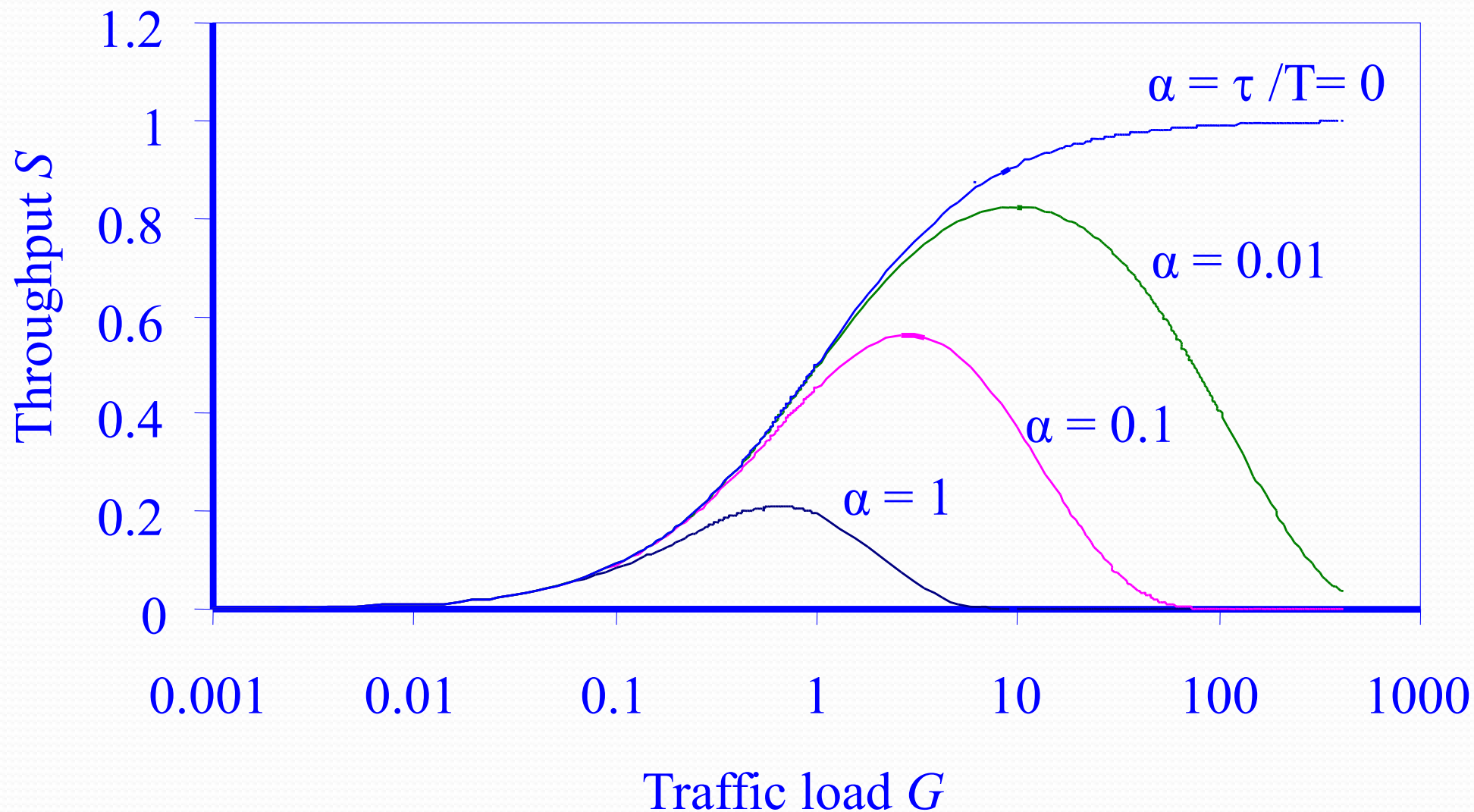
### • Acknowledgement

### • Back off: Freeze + resume

# CSMA/CD in Ethernet (Cont'd)



# Throughput of Slotted Nonpersistent CSMA/CD



# CSMA/CA (CSMA with Collision Avoidance)

↳ 802.11 = WiFi

All terminals listen to the same medium as CSMA/CD

Terminal ready to transmit senses the medium

If medium is busy it waits until the end of current transmission

It again waits for an additional predetermined time period DIFS (Distributed inter frame Space)

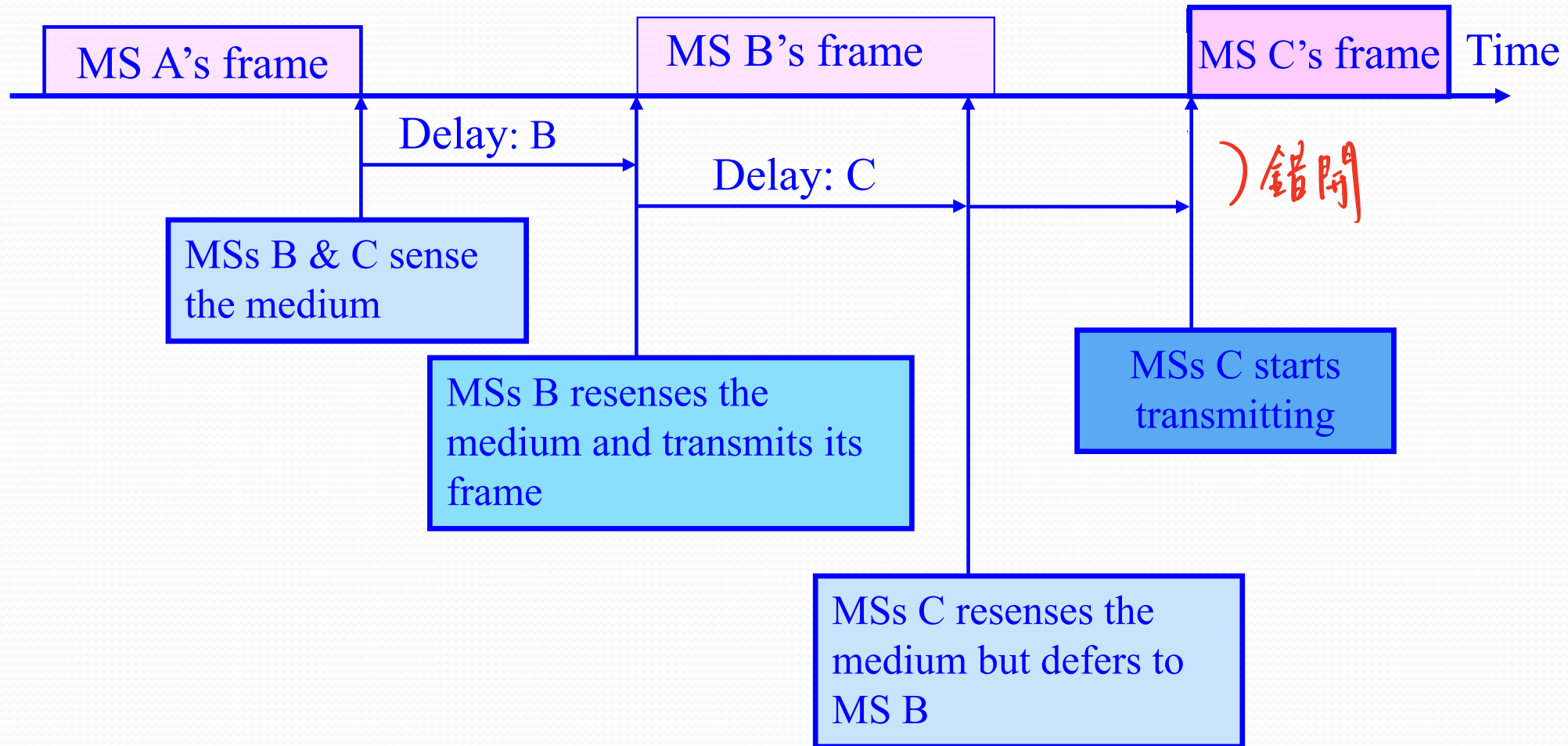
Then picks up a random number of slots (the initial value of backoff counter) within a contention window to wait before transmitting its frame

If there are transmissions by other MSs during this time period (backoff time), the MS freezes its counter

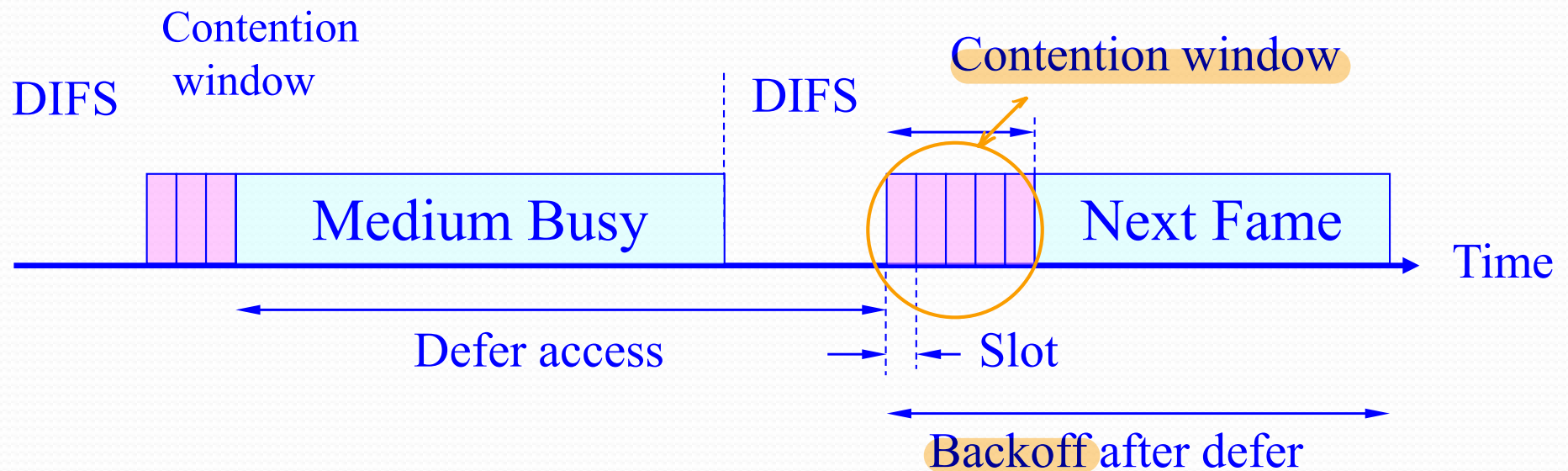
It resumes count down after other MSs finish transmission plus DIFS. The MS can start its transmission when the counter reaches to zero



# CSMA/CA (Cont'd)

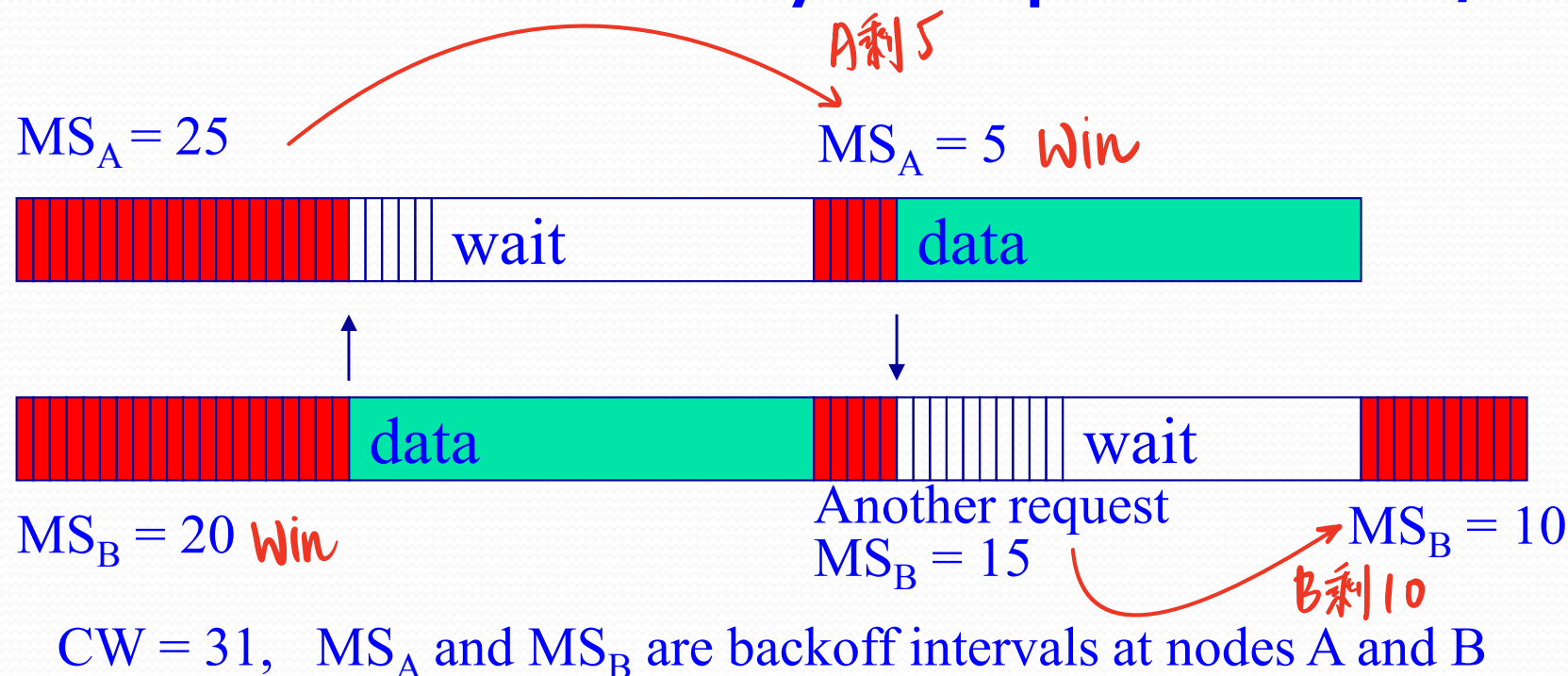


# CSMA/CA Explained



DIFS – Distributed Inter Frame Spacing

# Random Delay helps CSMA/CA



- ❑  $MS_A$  and  $MS_B$  are the backoff intervals of  $MS_A$  and  $MS_B$
- ❑ We assume for this example that  $CW = 31$
- ❑  $MS_A$  and  $MS_B$  have chosen a backoff interval of 25 and 20, respectively
- ❑  $MS_B$  will reach zero before five units of time earlier than  $MS_A$
- ❑ When this happens,  $MS_A$  will notice that the medium became busy and freezes its back-off interval currently at 5 (A倒数剩5)
- ❑ As soon as the medium becomes idle again,  $MS_A$  resumes its backoff countdown and transmits its data once the backoff interval reaches zero

# CSMA/CA with ACK for ad hoc networks

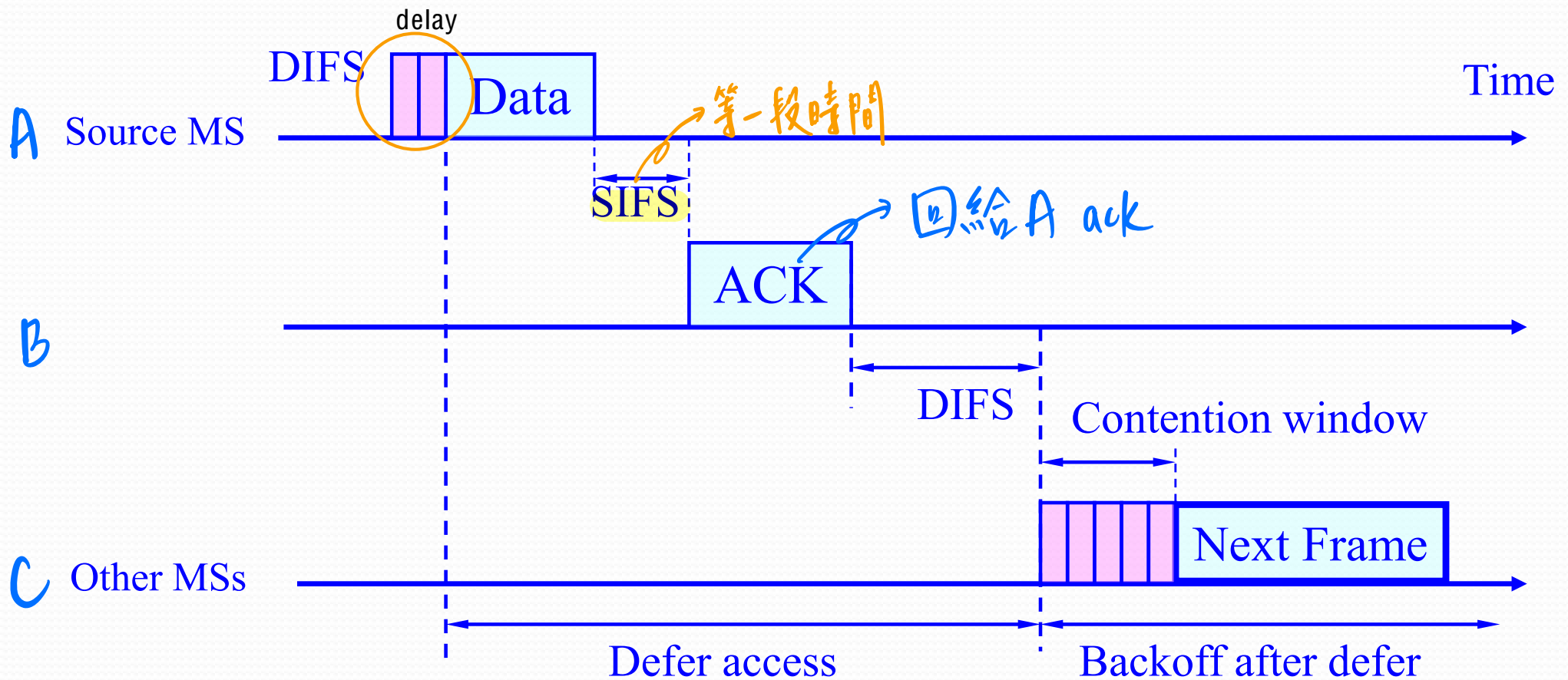
Immediate Acknowledgements from receiver upon reception of data frame without any need for sensing the medium

ACK frame transmitted after time interval SIFS (*Short Inter-Frame Space*) ( $SIFS < DIFS$ )

Receiver transmits ACK without sensing the medium

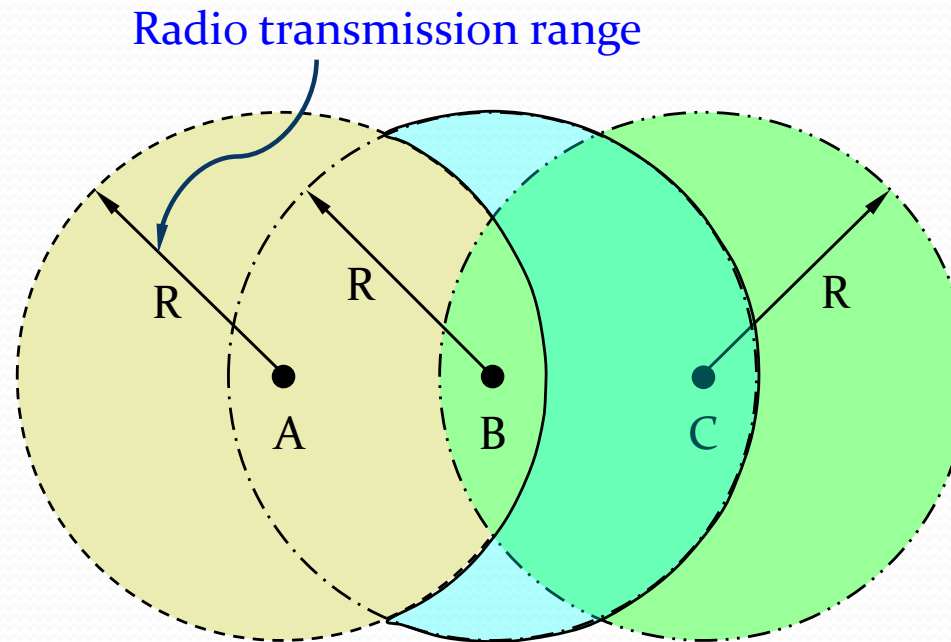
If ACK is lost, retransmission done

# CSMA/CA/ACK



SIFS – Short Inter Frame Spacing

# Hidden Terminal Problem



Nodes A and C are hidden with respect to each other

# CSMA/CA with RTS/CTS

Transmitter sends an RTS (request to send) after medium has been idle for time interval more than DIFS

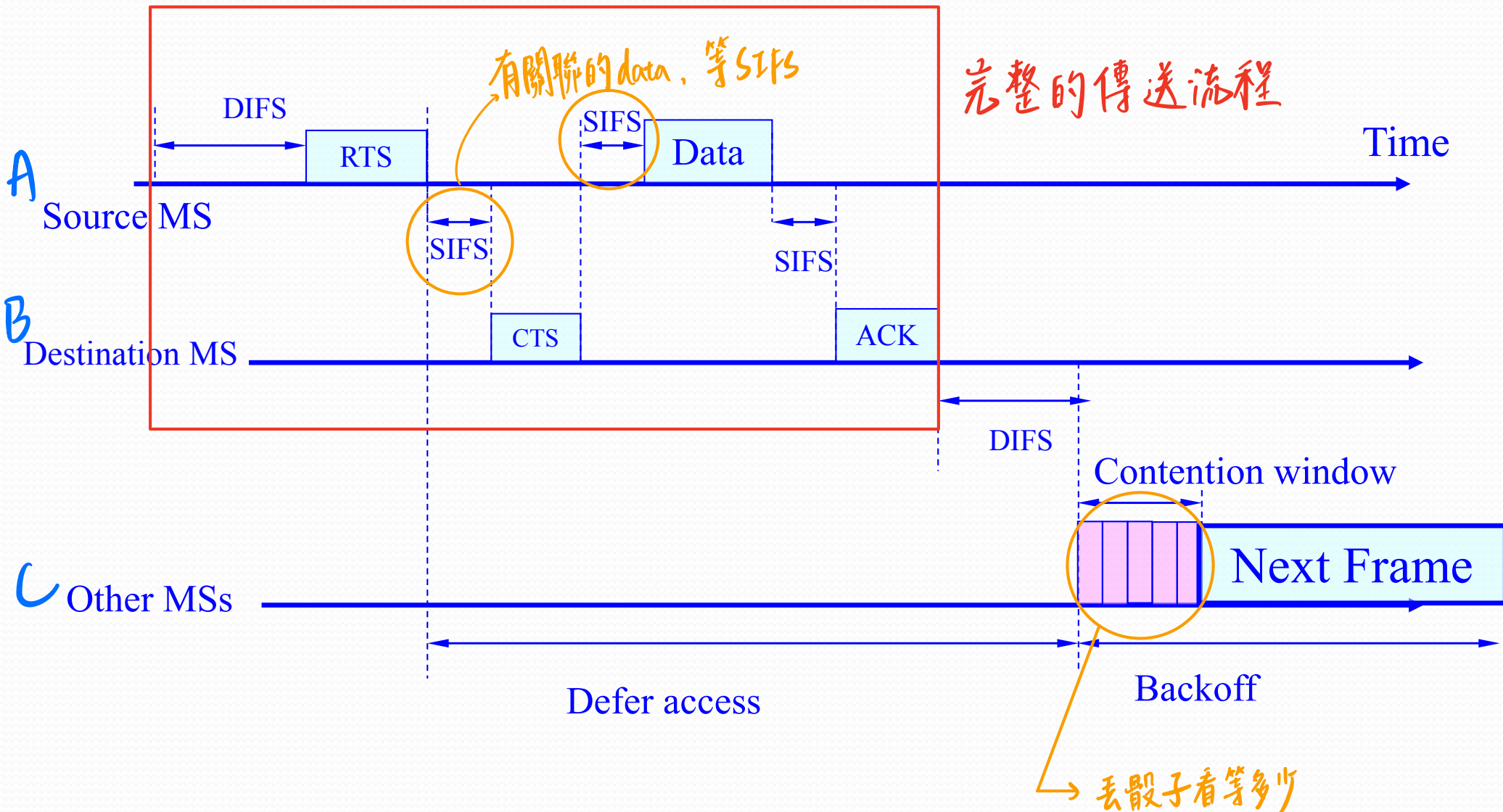
Receiver responds with CTS (clear to send) after medium has been idle for SIFS

Then Data is exchanged

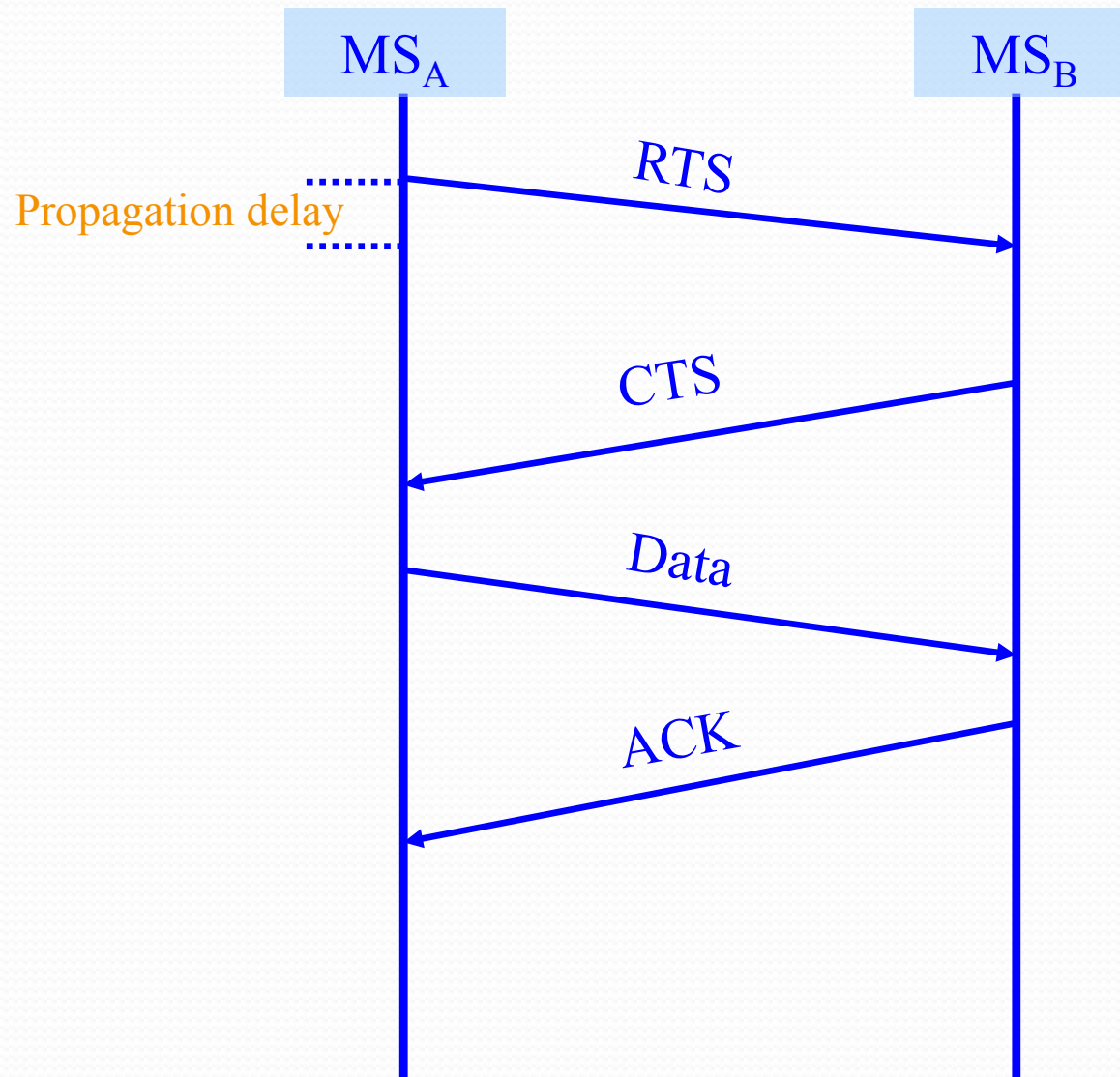
RTS/CTS is used for reserving channel for data transmission so that the collision can only occur in control message



# CSMA/CA with RTS/CTS

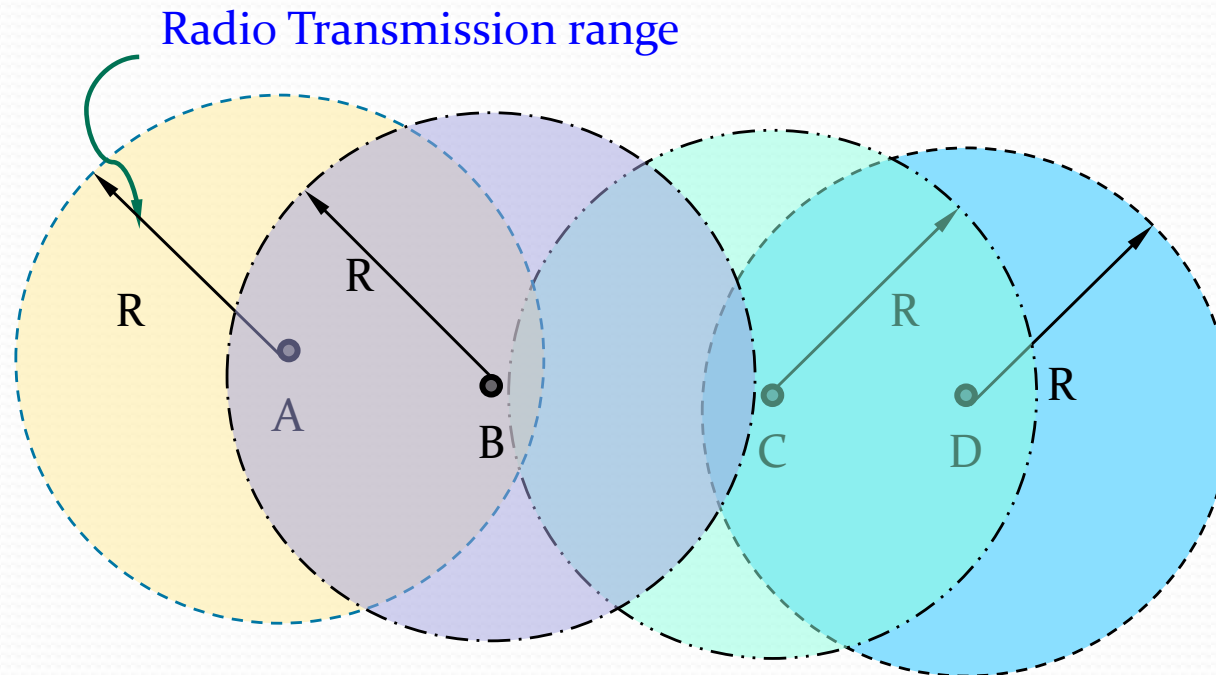


# RTS/CTS



This helps avoid **hidden terminal** problem in Ad hoc networks

# Exposed Terminal Problem



Transmission at Node A forces Node C (Exposed) to stop transmission to Node D