

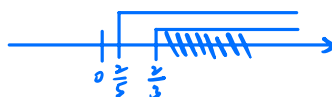
7.5 Determine the z-transform and its ROC for

$$x[n] = 2\left(\frac{2}{3}\right)^n u[n] - \left(\frac{2}{5}\right)^n u[n]$$

$$\text{令 } x_1[n] = 2\left(\frac{2}{3}\right)^n u[n], \quad x_2[n] = \left(\frac{2}{5}\right)^n u[n]$$

$$\text{則 } X_1(z) = \frac{2z}{z - \frac{2}{3}} \Rightarrow |z| > \frac{2}{3}$$

$$X_2(z) = \frac{z}{z - \frac{2}{5}} \Rightarrow |z| > \frac{2}{5}$$



$$\therefore X(z) = X_1(z) - X_2(z) = \frac{2z}{z - \frac{2}{3}} - \frac{z}{z - \frac{2}{5}} = \frac{6z}{3z - 2} - \frac{5z}{5z - 2}, \quad |z| > \frac{2}{3} *$$

7.6 Find the z-transform of the following signals:

(a)  $u[n - m]$

(b)  $na^n u[n]$

(c)  $a^n \cos \pi n u[n]$

$$\begin{aligned} e^{j\omega} &= \cos \omega + j \sin \omega \\ e^{-j\omega} &= \cos \omega - j \sin \omega \Rightarrow \cos \omega = \frac{e^{j\omega} + e^{-j\omega}}{2} \end{aligned}$$

(a)

$$X(z) = z^{-m} \frac{z}{z-1} = \frac{z}{z^m(z-1)} *$$

(c)

$$\begin{aligned} X(z) &= \frac{1}{2} \left( \frac{e^{j\pi} z}{e^{j\pi} z - a} + \frac{e^{-j\pi} z}{e^{-j\pi} z - a} \right) \\ &= \frac{1}{2} \left( \frac{z^2 - a e^{-j\pi} z + z^2 - a e^{j\pi} z}{z^2 - (e^{j\pi} z + e^{-j\pi} z) a + a^2} \right) \\ &= \frac{1}{2} \left( \frac{2z^2 - a z \cdot 2 \cos \pi}{z^2 - a z \cdot 2 \cos \pi + a^2} \right) \quad \text{且 } \cos \pi = -1 \\ &= \frac{z^2 + a z}{z^2 + 2a z + a^2} * \end{aligned}$$

(b)

$$\begin{aligned} X(z) &= -z \cdot \frac{d}{dz} z \{ a^n u[n] \} \\ &= -z \cdot \frac{d}{dz} \left( \frac{z}{z-a} \right) \\ &= \frac{a z}{(z-a)^2} * \end{aligned}$$

7.20 The z-transform of a discrete-time signal is

$$X(z) = \frac{2z}{z^2 + 3z + 1}$$

Find the z-transform of the following signals:

(a)  $y[n] = x[n-1]u[n-1]$

(b)  $y[n] = \sin(\pi n/4) x[n]$   $\Omega = \frac{\pi}{4}$

(c)  $y[n] = n^2 x[n]$

(d)  $y[n] = 2x[n]^* x[n]$

(a)

$$\begin{aligned} Y(z) &= z^{-1} X(z) \\ &= \frac{2}{z^2 + 3z + 1} * \end{aligned}$$

$$\begin{aligned}
 \text{b)} \quad y(z) &= \frac{j}{2} \left[ X(e^{\frac{\pi j}{4}} z) - X(e^{-\frac{\pi j}{4}} z) \right] \\
 &= \frac{j}{2} \left[ \frac{ze^{\frac{\pi j}{4}} z}{e^{\frac{\pi j}{2}} z^2 + 3e^{\frac{\pi j}{4}} z + 1} - \frac{ze^{-\frac{\pi j}{4}} z}{e^{-\frac{\pi j}{2}} z^2 + 3e^{-\frac{\pi j}{4}} z + 1} \right] *
 \end{aligned}$$

$$\begin{aligned}
 \text{c)} \quad y(z) &= -z \frac{d}{dz} \left( -z \frac{d}{dz} X(z) \right) \\
 &= -z \left( -\frac{d}{dz} X(z) + (-z) \frac{d^2}{dz^2} X(z) \right) \\
 &= z \frac{d}{dz} X(z) + z^2 \frac{d^2}{dz^2} X(z) \\
 &= z \cdot \frac{-2z^2 + 2}{(z^2 + 3z + 1)^2} + z^2 \cdot \frac{4z^3 - 12z - 12}{(z^2 + 3z + 1)^3} \\
 &= \frac{2z^5 - 6z^4 - 12z^3 - 6z^2 + 2z}{(z^2 + 3z + 1)^3} *
 \end{aligned}$$

$$\begin{aligned}
 \text{d)} \quad y(z) &= z \cdot \frac{2z}{z^2 + 3z + 1} \cdot \frac{2z}{z^2 + 3z + 1} \\
 &= \frac{4z^2}{(z^2 + 3z + 1)^2} *
 \end{aligned}$$

7.21 Using the z-transform, determine the convolution of these sequences:

$$x[n] = [1, -1, 3, 2], \quad h[n] = [1, 0, 2, 1, -3].$$

$$X(z) = 1 - z^{-1} + 3z^{-2} + 2z^{-3}$$

$$H(z) = 1 + 0z^{-1} + 2z^{-2} + 1z^{-3} - 3z^{-4}$$

$$\begin{aligned}
 Y(z) &= X(z)H(z) = 1 + 1z^{-2} + 1z^{-3} - 3z^{-4} - z^{-1} - 2z^{-3} - z^{-4} + 3z^{-5} + 5z^{-2} + 6z^{-4} + 3z^{-5} - 9z^{-6} \\
 &\quad + 2z^{-3} + 4z^{-5} + 2z^{-6} - 6z^{-7} \\
 &= 1 - z^{-1} + 5z^{-2} + z^{-3} + 2z^{-4} + 10z^{-5} - 7z^{-6} - 6z^{-7} \\
 \Rightarrow y[n] &= [1, -1, 5, 1, 2, 10, -7, -6] *
 \end{aligned}$$

7.24 Find the inverse z-transform of the following functions:

(a)  $X(z) = \frac{2z}{z^2 - z + 1}$

(b)  $Y(z) = \frac{z(z+2)}{(z+1)(z-1)}$

(c)  $H(z) = \frac{4z}{(z^2 + z + 1)(z + 1/2)}$

$$\mathcal{Z}\{a^n \sin(\omega n) u[n]\} = \frac{a z \sin \omega}{z^2 - 2a z \cos \omega + a^2}$$

(a)  $a=1 \quad 2 \cos \omega = 1 \Rightarrow \omega = 60^\circ \quad \sin 60^\circ = 0.866$

$$X(z) = \frac{0.866z}{z^2 - z + 1} \cdot \frac{z}{0.866} \Rightarrow x[n] = 2 \cdot 30^\circ \sin(60^\circ n) u[n]_{**}$$

(b)

$$Y_1(z) = \frac{Y(z)}{z} = \frac{A}{z+1} + \frac{B}{z-1}$$

$$A = (z+1) Y_1(z) \Big|_{z=-1} = \frac{1}{-2} = -\frac{1}{2}$$

$$B = (z-1) Y_1(z) \Big|_{z=1} = \frac{3}{2}$$

$$Y(z) = \frac{-1}{2} \frac{z}{z+1} + \frac{3}{2} \frac{z}{z-1} \Rightarrow y[n] = -\frac{1}{2} (-1)^n u[n] + \frac{3}{2} u[n]_{**}$$

(c)

$$H_1(z) = \frac{H(z)}{z} = \frac{4}{(z^2 + z + 1)(z + \frac{1}{2})} = \frac{A z + B}{z^2 + z + 1} + \frac{C}{z + \frac{1}{2}} \Rightarrow A = -\frac{16}{3}, B = -\frac{8}{3}, C = \frac{16}{3}$$

$$\begin{aligned} \therefore H(z) &= -\frac{8}{3} \left( \frac{2z^2 + z}{z^2 + z + 1} \right) + \frac{16}{3} \left( \frac{z}{z + \frac{1}{2}} \right) \\ &= -\frac{16}{3} \left( \frac{z^2 + \frac{1}{2}z}{z^2 + z + 1} \right) + \frac{16}{3} \left( \frac{z}{z + \frac{1}{2}} \right) \end{aligned}$$

$$\mathcal{Z}\{a^n \cos(\Omega n) u[n]\} = \frac{z^2 - a z \cos \Omega}{z^2 - 2a z \cos \Omega + a^2}$$

$$\Rightarrow a=1 \quad \cos \Omega = -\frac{1}{2} \Rightarrow \Omega = 120^\circ$$

$$\Rightarrow h[n] = -\frac{16}{3} \cos(120^\circ n) u[n] + \frac{16}{3} \left(-\frac{1}{2}\right)^n u[n]_{**}$$

7.27 Invert each of the following z-transform:

$$(a) X_1(z) = \frac{1 - z^{-1}}{1 - z^{-1} - 0.75z^{-2}}$$

$$\mathcal{Z}\{a^n \cos(\Omega n) u[n]\} = \frac{z^2 - a z \cos \Omega}{z^2 - 2a z \cos \Omega + a^2}$$

$$(b) X_2(z) = \frac{1 + z^{-1}}{1 - 0.8z^{-1} + 0.64z^{-2}}$$

(a)

$$X_1(z) = \frac{z^2 - z}{z^2 - z - 0.75} = \frac{4z^2 - z}{(2z+1)(2z-3)}$$

$$\frac{X_1(z)}{z} = \frac{A}{2z+1} + \frac{B}{2z-3} \Rightarrow A = \frac{3}{2}, B = \frac{1}{2}$$

$$X_1(z) = \frac{\frac{3}{2}z}{2z+1} + \frac{\frac{1}{2}z}{2z-3} = \frac{3}{2} \cdot \frac{1}{2} \left( \frac{z}{z+\frac{1}{2}} \right) + \frac{1}{2} \cdot \frac{3}{2} \left( \frac{z}{z-\frac{3}{2}} \right)$$

$$X_1[n] = \frac{3}{4} \left(-\frac{1}{2}\right)^n u[n] + \frac{3}{4} \left(\frac{3}{2}\right)^n u[n] \quad *$$

$$(b) a^2 = 0.64 \Rightarrow a = 0.8$$

$$2a \cos \Omega = 0.8 \Rightarrow \Omega = \cos^{-1} \frac{1}{2} = 60^\circ$$

$$a \sin \Omega = 0.8 \sin 60^\circ = 0.6928$$

$$X_2(z) = \frac{z^2 - 0.4z}{z^2 - 0.8z + 0.64} + \frac{1.4z}{z^2 - 0.8z + 0.64} \times \frac{0.6928}{0.6928}$$

$$\Rightarrow X_2[n] = (0.8)^n \cos(60^\circ n) u[n] + 2.02 (0.8)^n \sin(60^\circ n) u[n] \quad *$$

7.31 Using the z-transform, solve the following difference equation:

$$y[n+1] - 2y[n] = (1.5)^n, \quad y[0] = 1.$$

$$\mathcal{Z}\{y[n+1]\} = zY(z) - zy[0]$$

$$(zY(z) - zy[0]) - 2Y(z) = \frac{z}{z-1.5}$$

$$Y(z)(z-2) = \frac{z}{z-1.5} + z = \frac{z^2 - 0.5z}{z-1.5}$$

$$Y(z) = \frac{z(z-0.5)}{(z-1.5)(z-2)}$$

$$Y_1(z) = \frac{Y(z)}{z} = \frac{A}{z-1.5} + \frac{B}{z-2}$$

$$A = (z - 1.5)Y_1(z) \Big|_{z=1.5} = \frac{1}{-0.5} = -2$$

$$B = (z - 2)Y_1(z) \Big|_{z=2} = \frac{1.5}{0.5} = 3$$

$$\therefore Y(z) = \frac{-2z}{z-1.5} + \frac{3z}{z-2}$$

$$\Rightarrow y[n] = -2(1.5)^n u[n] + 3(2)^n u[n] \quad \#$$

7.36 The transfer function of a discrete-time system is

$$H(z) = \frac{1 + 2z^{-1}}{1 - z^{-1} + z^{-2}}$$

Find the system response  $y[n]$  when the input is a unit step function  $u[n]$ .

$$Y(z) = H(z)X(z) = \frac{1 + 2z^{-1}}{1 - z^{-1} + z^{-2}} \left( \frac{z}{z-1} \right) = \frac{z(z+2z)}{(z-1)(z^2-z+1)}$$

$$\text{令 } Y_1(z) = \frac{Y(z)}{z} = \frac{z+2z}{(z-1)(z^2-z+1)} = \frac{A}{z-1} + \frac{Bz+C}{z^2-z+1}$$

$$A = (z-1)Y_1(z) \Big|_{z=1} = 3$$

通分比較係數  $\Rightarrow B = -2, C = 3$

$$\therefore Y(z) = \frac{3z}{z-1} - \frac{2(z-1.5z)}{z^2-z+1} \quad \text{令 } -z = -2z \cos \Omega \Rightarrow \Omega = \cos^{-1}(0.5) = 60^\circ, A=1, A \sin \Omega = 0.866$$

$$= \frac{3z}{z-1} - \frac{2(z-0.5z)}{z^2-z+1} + \frac{2}{0.866} \cdot \frac{0.866z}{z^2-z+1}$$

$$\Rightarrow y[n] = 3u[n] - 2\cos(60^\circ n)u[n] + 2.309 \sin(60^\circ n)u[n] \quad \#$$

7.38 Determine the transfer function of the feedback system represented in Figure 7.14.

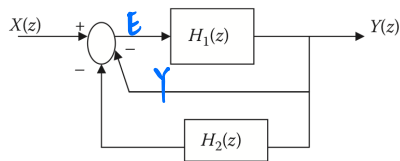


FIGURE 7.14 For Problem 7.38.

$$E = X - Y - H_2 Y$$

$$Y = H_1 E = H_1 X - H_1 Y - H_1 H_2 Y \quad \therefore H = \frac{Y}{X} = \frac{H_1(z)}{1 + H_1(z) + H_1(z)H_2(z)} *$$

$$(1 + H_1 + H_1 H_2) Y = H_1 X$$

7.43 Obtain the impulse and step responses of the discrete-time system with transfer function

$$H(z) = \frac{0.8z}{(z-0.6)(z-2)}$$

(1) impulse response:  $\delta[n] \xrightarrow{z} 1$

$$Y(z) = H(z)X(z) = H(z)$$

$$A: (z-0.6)Y_1(z) \Big|_{z=0.6} = \frac{0.8}{-1.4} = -0.5714$$

$$B: (z-2)Y_1(z) \Big|_{z=2} = \frac{0.8}{1.4} = 0.5714$$

$$Y_1(z) = \frac{Y(z)}{z} = \frac{A}{z-0.6} + \frac{B}{z-2}$$

$$\therefore Y(z) = \frac{-0.5714z}{z-0.6} + \frac{0.5714z}{z-2} \Rightarrow y[n] = -0.5714(0.6)^n u[n] + 0.5714(2)^n u[n] *$$

(2) step response:  $u[n] \xrightarrow{z} \frac{z}{z-1}$

$$Y(z) = H(z)X(z) = \frac{0.8z^2}{(z-0.6)(z-2)(z-1)}$$

$$Y_1(z) = \frac{Y(z)}{z} = \frac{0.8z}{(z-0.6)(z-2)(z-1)} = \frac{A}{z-0.6} + \frac{B}{z-2} + \frac{C}{z-1}$$

$$A: (z-0.6)Y_1(z) \Big|_{z=0.6} = \frac{0.48}{(-1.4)(-0.4)} = 0.8571$$

$$B: (z-2)Y_1(z) \Big|_{z=2} = \frac{1.6}{1.4 \times 1} = 1.143 \Rightarrow y[n] = (0.8571(0.6)^n + 1.143(2)^n - 2) u[n] *$$

$$C: (z-1)Y_1(z) \Big|_{z=1} = \frac{0.8}{0.4(-1)} = -2$$

7.45 Use MATLAB to find the inverse z-transform of

$$X(z) = \frac{z}{z - 0.6}$$

```
1 syms z; % 聲明為符號，而不是数值
2 X = z / (z - 0.6);
3
4 x = iztrans(X); % reverse z-transform
5
6 disp(x); % 打印结果
```

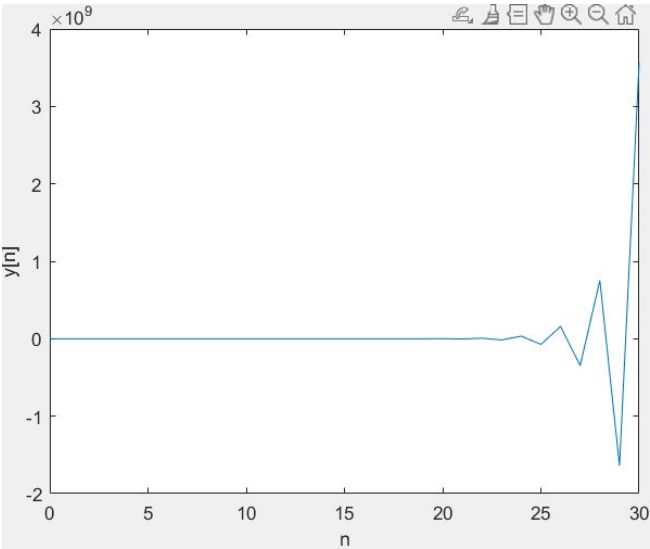
Command Window

```
>> HW4_45
(3/5)^n
```

7.46 A linear discrete-time system is represented by the transfer function

$$H(z) = \frac{z + 1}{z^3 + 2z^2 + z + 3}$$

Use MATLAB to plot the step response of the system.



7.47 Determine the poles and zeros of the transfer function

$$H(z) = \frac{z^2 + 6z + z}{z^4 + 3z^3 + 4z + 10}$$

```
zeros =  
  -5.8284  
  -0.1716  
  
poles =  
  -3.0794 + 0.0000i  
   0.7401 + 1.3305i  
   0.7401 - 1.3305i  
  -1.4009 + 0.0000i
```

7.50 Check the stability of a system described by the following transfer function:

$$H(z) = \frac{z^{-3} - 2z^2 + 6z + 1}{z^5 - 2z^4 + 5z^2 - z + 4}$$

```
p =  
  
  1.6969 + 1.1485i  
  1.6969 - 1.1485i  
 -1.4722 + 0.0000i  
  0.0391 + 0.8035i  
  0.0391 - 0.8035i
```

} 長度超過單位圓之半徑  
⇒ unstable \*