

Algorithms for Data Science Data Streams I

April 2, 2023

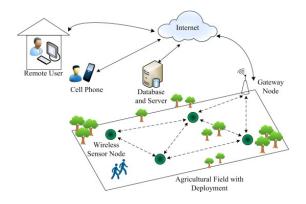
Table of contents

Data Streams

Sampling Items from Streams

Filtering Elements in a Stream

Sensor Data / Internet of Things



High-Speed Trading



Offline vs. online

Databases assume that the entirety of datasets are available offline

This is not always true – sometimes data is only **online**:

- · Twitter status updates, queries on search engines
- · data from sensor networks
- · telephone calls
- · IP packets on the Internet
- high-speed trading data

Data Stream Characteristics

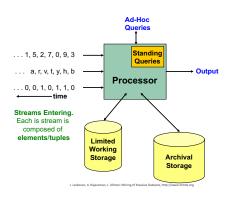
Input rate is **controlled externally** – so the data processor has no control over the speed of the data

Data streams are:

- · infinite one does not know the size of the data
- non-stationary the distributions of the data can change (seasonally, daily, hourly)

Model: infinite sequence of items $S = (i_1, i_2, \dots, i_k \dots)$

Stream Processing Model



Objective: asking **queries** on the stream – standing and ad-hoc

Restrictions: **storage space** and **processing time** – have to process it or we lose it forever!

Implementation Issues

If we had enough memory/time – data streams would be easy

With restrictions:

- more efficient to get approximate answers
- use space-saving techniques such as hashing

Problems Studied

- · Sample data from a stream
- · Filtering items
- Counting distinct elements
- Estimating moments
- Queries over sliding windows

Table of contents

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Sampling Problem

Objective: keeping a **representative** sample of the items in the stream – to deal with the limited space issues

Sub-problems:

- · sample a fixed proportion of elements
- · keep a sample of fixed size

Sampling a Fixed Proportion of Elements

Objective keep a proportion p of items in a stream

First solution:

- · say, e.g., we want to keep 1 in 10 elements
- \cdot for each item, we can generate a random number from **o** to **9**
- keep the item only we generate o

Motivating example

Stream: tuples of (user, query, time) – queries of users on a search engine

Problem: how often does an user run the same query – what fraction of queries are duplicates

Motivating example

Issue of the above solution (assume we have space for **10**% of the stream):

- suppose a queries are only once, b queries are double, total a+2b correct answer is b/(a+b)
- prob. we see the singleton queries a/10
- · prob. we see a double query twice $b/100 = b \times 1/10 \times 1/10$
- prob. we see a double query only once $18b/100 = (1/10 \times 9/10 + 9/10 \times 1/10)b$
- hence the sample-based answer (our wrong estimation) is

$$\frac{\frac{b}{100}}{\frac{a}{10} + \frac{b}{100} + \frac{18b}{100}} = \frac{b}{10a + 19b}$$

A Better Solution

It is better to sample the **users**, instead of the queries – so we sample **all the queries** of a proportion of the users

- · this can be done by hashing strings to integers
- get a sample of a/b fraction of the stream:
 - hash each tuple's key uniformly into b buckets
 - pick the tuple if its hash value is at most a
 - thus, how to generate a 30% sample?

Takeaway: one has to be careful what sample one keeps, depending on the applications

Fixed-Size Samples

Assume we have **to keep a sample of exactly** *s* **items** – i.e., max space in memory

Objective: each item in the stream S should be in the s with equal probability – after n items prob. should be s/n

Reservoir Sampling

Reservoir Sampling Algorithm [?]

- 1. store first s elements in the stream in the sample
- 2. when element n arrives (n > s)
 - with probability s/n keep the element, else discard
 - if the element is kept, it replaces one element in the sample (chosen randomly)

Reservoir Sampling – Proof

Claim the algorithm maintains a sample s with the desired property – each item is in s with probability s/n

Proof (induction):

- base case: first s elements are in the sample with probability s/s=1
- inductive hypothesis: after n elements, the sample contains each element with prob. s/n

Reservoir Sampling – Proof

Claim the algorithm maintains a sample s with the desired property – each item is in s with probability s/n

Proof (induction):

- inductive step: element n + 1 arrives
 - \cdot probability that it is kept in s is

$$\left(1 - \frac{\mathsf{s}}{\mathsf{n} + \mathsf{1}}\right) + \frac{\mathsf{s}}{\mathsf{n} + \mathsf{1}} \cdot \frac{\mathsf{s} - \mathsf{1}}{\mathsf{s}} = \frac{\mathsf{n}}{\mathsf{n} + \mathsf{1}}$$

- at time n tuples are in the sample with prob. s/n, and are kept with probability n/n+1
- so the probability that they "survive" in the sample at time n+1 is

$$\frac{s}{n} \cdot \frac{n}{n+1} = \frac{s}{n+1}$$

Table of contents

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Filtering Streams

Problem: we want to let only some items in the stream, but we do not have the space to store the keys for comparison

Motivating example - e-mail filtering

- large numbers of emails come every minute, a few of them are spam
- we cannot keep the list of good emails in main memory (to compare), but we still want to keep only non-spam emails
- solution: hashing

Using Hashing to Filter Items

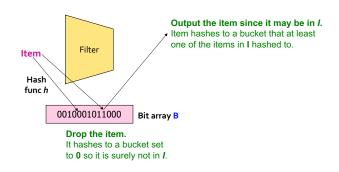
- 1. Set of item keys I that we want to keep / filter
- 2. Keep a **bit array B** of **n** bits, initialized to **o**
- 3. Choose a hash function h with range [0, n), and hash each $i \in I$ to one of the n buckets; i.e., set B[h(i)] = 1

Process: for each item s in the stream S, output it only if B[h(s)] = 1

Using Hashing to Filter Items

No false negatives, but some false positives

· some spam emails might still get through



Probability of False Positives

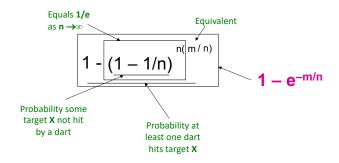
A good hash function – each item in the stream S is **equally likely** to hash to one of the n buckets

Assume *m* unique items (e.g., e-mails addresses)

What is the probability that a spam email hashes to a good email bit?

 equivalent: throwing m darts at n target – what is the probability that a target gets at least one dart?

Probability of False Positives



Fraction of 1 in the array B is Probability of false positives $1 - e^{-m/n}$

Example

$$|B|$$
 – 1GB = 8 billion bits (targets)

False positive rate: $1 - e^{-1/8} = 0.1175$

 \cdot 11% of the spam email passes through

Can we do better?

Bloom Filters [?]

Structure:

- an array B of n bits, set to o
- a **collection** of hash function h_1, h_2, \dots, h_k each mapping to the same n buckets
- set I of keys of item

Initialization:

• take each key $i \in I$ and hash it using each h_j ; set to 1 each bit in B that has $h_j(i) = 1$

Function:

• for each item s from the stream, check that $h_1(s), h_2(s), \ldots, h_k(s)$ all map to 1 in B; discard it otherwise

Bloom Filter Analysis

Equivalent: throwing *km* darts at *n* targets; fraction of 1 is

$$1-e^{\frac{-km}{n}}$$

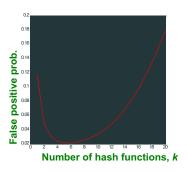
We have k independent hash functions; elements s only passes if all k hash to a bucket of 1

False Positive Probability

$$\left(1-e^{-\frac{km}{n}}\right)^k$$

Bloom Filter Analysis

The false positive probability changes with the number *k* of hash functions!



Optimal Number of Hash Functions

$$k = \frac{n}{m} \ln 2$$

Bloom Filters – Takeaways

Can **optimize** the space taken, while having **no false negatives** and minimizing **false positives**

Can be implemented efficiently – parallel hash functions

Can divide **B** in **k** parts – **equivalent** but simpler to keep one bit array



The contents and some figures are taken from Chapter 4 of [?].

http://www.mmds.org/

References i