

Hunter Lybbert

Student ID: 2426454

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Homework 4

II

a) $\dot{x} = x - y, \dot{y} = x^2 - 4$

Find fixed points

$$\begin{aligned}\dot{x} = x - y &= 0 \Rightarrow x = y \\ \dot{y} = x^2 - 4 &= 0 \Rightarrow x^2 = 4\end{aligned}$$

More precisely the two fixed points are at
 $(x^*, y^*) = (-2, -2), (2, 2)$.

Next let's compute the Jacobian. Note $\dot{x} = f(x, y), \dot{y} = g(x, y)$.

$$\begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 2x & 0 \end{pmatrix}.$$

Now let's evaluate the Jacobian at the first fixed point $(-2, -2)$. Then we have the matrix that defines our linearized system:

$$\begin{pmatrix} 1 & -1 \\ -4 & 0 \end{pmatrix} \Rightarrow \text{let's get the eigenvalues}$$

$$(1-\lambda)(-1-\lambda) - 4 = 0$$

$$\lambda^2 - \lambda - 4 = 0$$

$$\lambda = \frac{1 \pm \sqrt{1-4(-4)}}{2} = \frac{1}{2} \pm \frac{\sqrt{17}}{2}$$

1a continued:

Now lets solve for the eigenvectors. starting with

$$\lambda = \frac{1+\sqrt{17}}{2} \text{ we have } \begin{pmatrix} 1 - \frac{1+\sqrt{17}}{2} & -1 \\ -4 & -\frac{1-\sqrt{17}}{2} \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \frac{2-1-\sqrt{17}}{2}x = y \Rightarrow -4x = \frac{1+\sqrt{17}}{2}y$$
$$\frac{1-\sqrt{17}}{2}x = y \Rightarrow -4x = \frac{1+\sqrt{17}}{2}\left(\frac{1-\sqrt{17}}{2}x\right)$$
$$-4x = \frac{1-17}{4}x = -\frac{16}{4}x = -4x. \text{ This is always true so we choose } \Rightarrow x = 1.$$

Therefore, $y = x \frac{1-\sqrt{17}}{2} = \frac{1-\sqrt{17}}{2}$. Thus the eigenvector is

$$\begin{pmatrix} 1 \\ \frac{1-\sqrt{17}}{2} \end{pmatrix}. \text{ Furthermore, for}$$

$$\lambda = \frac{1-\sqrt{17}}{2} \text{ we have } \begin{pmatrix} \frac{2-1+\sqrt{17}}{2} & -1 \\ -4 & -\frac{1+\sqrt{17}}{2} \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \frac{1+\sqrt{17}}{2}x = y, -4x = \frac{1-\sqrt{17}}{2}y$$

$$\Rightarrow -4x = \frac{1-\sqrt{17}}{2}\left(\frac{1+\sqrt{17}}{2}x\right) = \frac{1-17}{4}x = -\frac{16}{4}x = -4x \text{ which is always true so we pick } x = 1. \text{ Then } y = \frac{1+\sqrt{17}}{2}.$$

there we have the second eigenvector $\begin{pmatrix} 1 \\ \frac{1+\sqrt{17}}{2} \end{pmatrix}$.

On the next page we will classify this fixed point.

In summary for the fixed point $(x^*, y^*) = (-2, -2)$
 we have the following eigenvalue eigenvector pairs:

$$\lambda_1 = \frac{1 + \sqrt{17}}{2}, \begin{pmatrix} 1 \\ \frac{1-\sqrt{17}}{2} \end{pmatrix} \text{ and } \lambda_2 = \frac{1 - \sqrt{17}}{2}, \begin{pmatrix} 1 \\ \frac{1+\sqrt{17}}{2} \end{pmatrix}$$

Since we have two real valued eigenvalues with opposite signs this fixed point is a saddle node. I will draw its behavior after I do the other fixed point as well. Now ~~un~~sped to evaluate the jacobian at $(x^*, y^*) = (2, 2)$ to get $\begin{pmatrix} 1 & -1 \\ 4 & 0 \end{pmatrix}$.

The characteristic equation to solve for eigenvalues is

$$(1-\lambda)(-1-\lambda) + 4 = 0 \Rightarrow \lambda = \frac{1 \pm \sqrt{1-4(4)}}{2}$$

$$\lambda^2 + \lambda + 4 = 0 \quad \lambda = \frac{1 \pm \sqrt{-15}}{2}$$

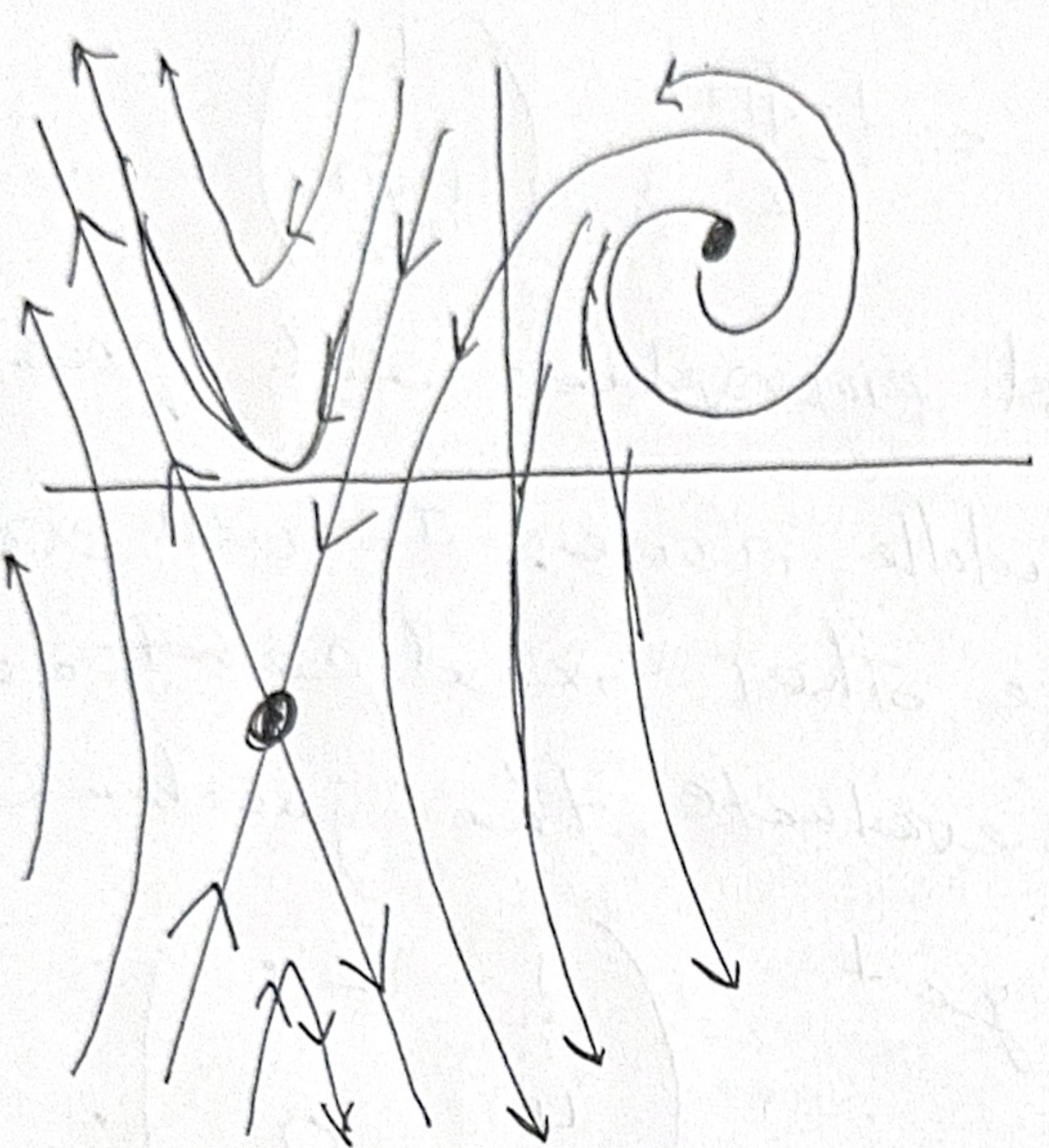
$$\lambda = \frac{1 \pm i\sqrt{15}}{2}$$

Now lets solve for eigenvectors. we notice the algebra will be nearly identical for these cases as there was before. After performing the same algebra we arrive at the conclusion

$$\lambda_1 = \frac{1+i\sqrt{15}}{2}, \begin{pmatrix} 1 \\ \frac{1-i\sqrt{15}}{2} \end{pmatrix} \text{ and } \lambda_2 = \frac{1-i\sqrt{15}}{2}, \begin{pmatrix} 1 \\ \frac{1+i\sqrt{15}}{2} \end{pmatrix}$$

Since both eigenvalues have positive real parts and also imaginary parts we have a spiraling source or repeller which is unstable f.p. $(2, 2)$.

Now the phase portrait would qualitatively behave as follows



fixed points are bolded
for emphasis not shaded
to depict stability.

1b

$$\begin{aligned} \dot{x} &= 1+y-e^{-x}, & \dot{y} &= x^3-y \\ \dot{x} &= f(x,y), & \dot{y} &= g(x,y) \end{aligned}$$

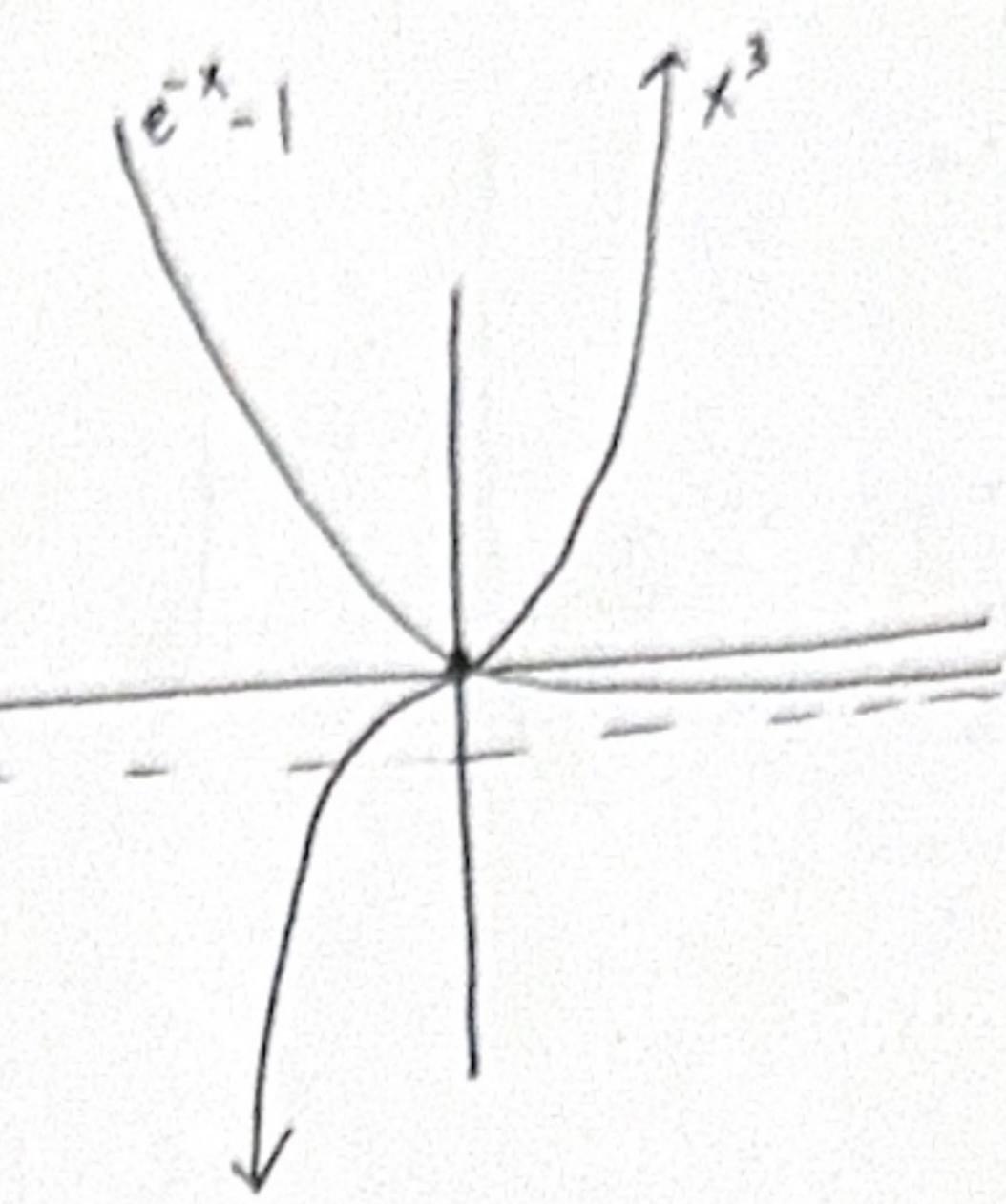
Fixed points

$$1+y-e^{-x}=0 \Rightarrow 1+x^3-e^x=0$$

$$x^3-y=0 \quad \text{alternatively}$$

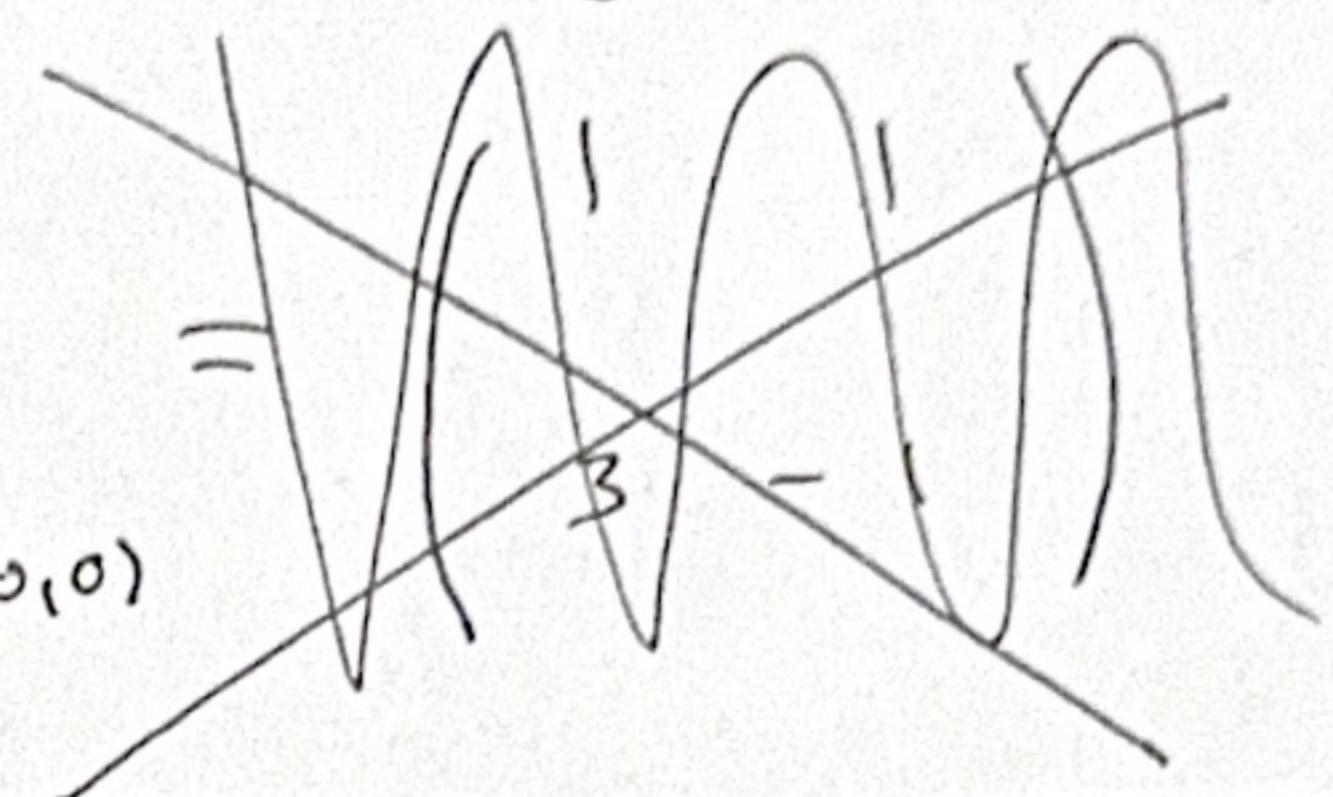
$$\Rightarrow x^3=e^x \quad x^3=e^x-1$$

$$x=0, y=0 \checkmark$$



We only have one fixed point at $(x^*, y^*) = (0,0)$.

$$\begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} \Rightarrow \begin{pmatrix} e^{-x} & 1 \\ 3x^2 & -1 \end{pmatrix} \Big|_{(x^*, y^*) = (0,0)}$$



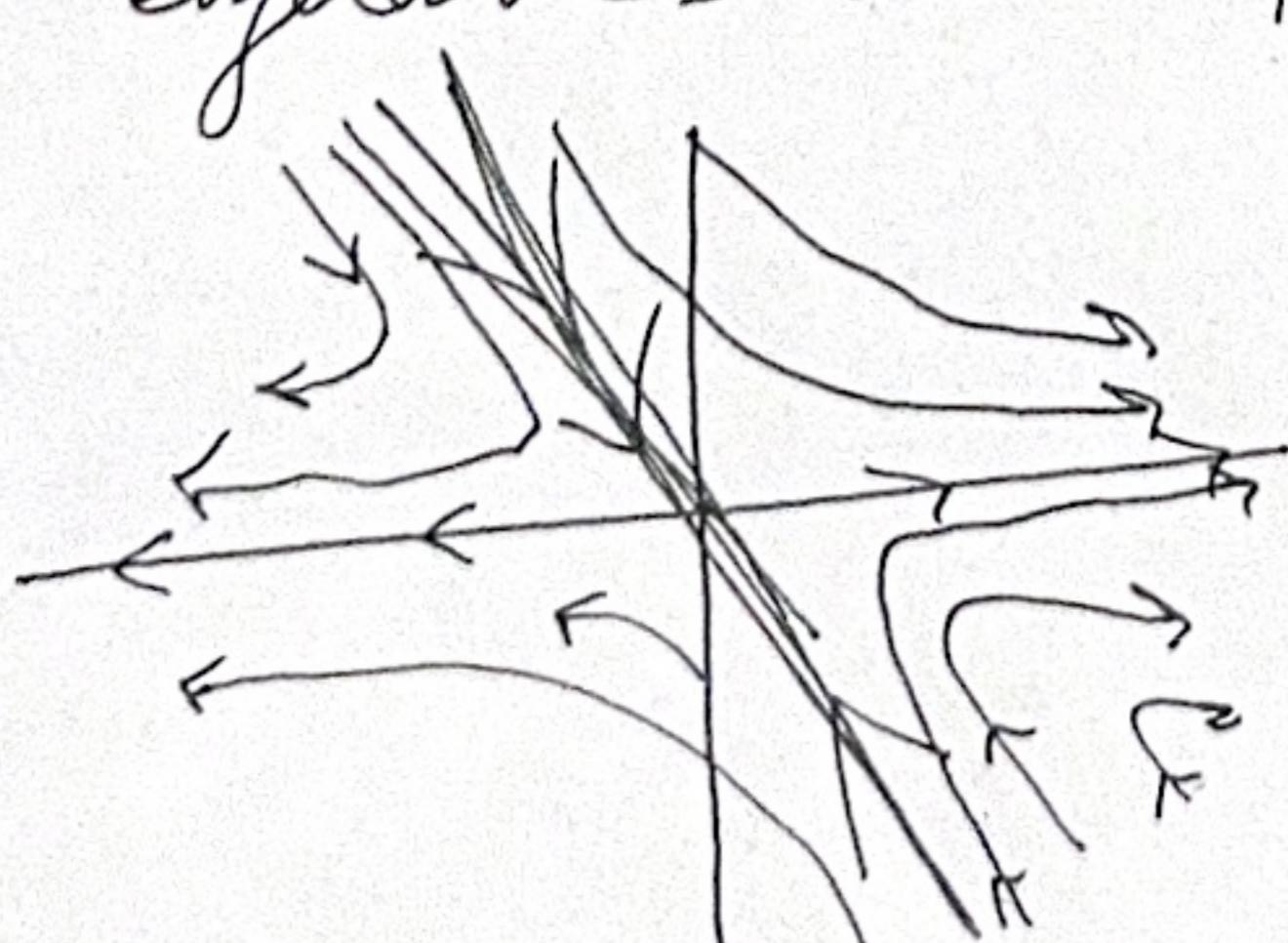
$$= \begin{pmatrix} 1 & 1 \\ 0 & -1 \end{pmatrix} \Rightarrow \begin{array}{l} \text{Characteristic equation} \\ (1-\lambda)(-1-\lambda) - 0 = 0 \\ \lambda^2 + \cancel{\lambda} - 1 = 0 \\ \lambda^2 - 1 = 0 \\ \lambda = \pm 1 \end{array}$$

eigenvectors:

$$\left(\begin{array}{cc|c} 0 & 1 & 0 \\ 0 & -2 & 0 \end{array} \right) \Rightarrow \begin{array}{l} 0x+y=0 \\ 0x-2y=0 \end{array} \quad \begin{array}{l} y=0 \\ \text{choose} \end{array} \quad \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\left(\begin{array}{cc|c} 2 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right) \Rightarrow \begin{array}{l} 2x+y=0 \\ 2x=-y \\ x=-\frac{1}{2}y \end{array} \Rightarrow \begin{pmatrix} -\frac{1}{2} \\ 1 \end{pmatrix}$$

Once again we have a saddle node f.p. since the eigenvalues are real and opposite signs.



[2] consider ODE $\dot{x} = y - x^2 + 2, \dot{y} = 2y^2 - 2xy$

$$\begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 4y - 2x \end{pmatrix}$$

$$y - x^2 + 2 = 0$$

$$2y^2 - 2xy = 0$$

$$2(x^2 - 2)^2 - 2x(x^2 - 2) = 0$$

$$2(x^4 - 4x^2 + 4) - 2x^3 + 4x = 0$$

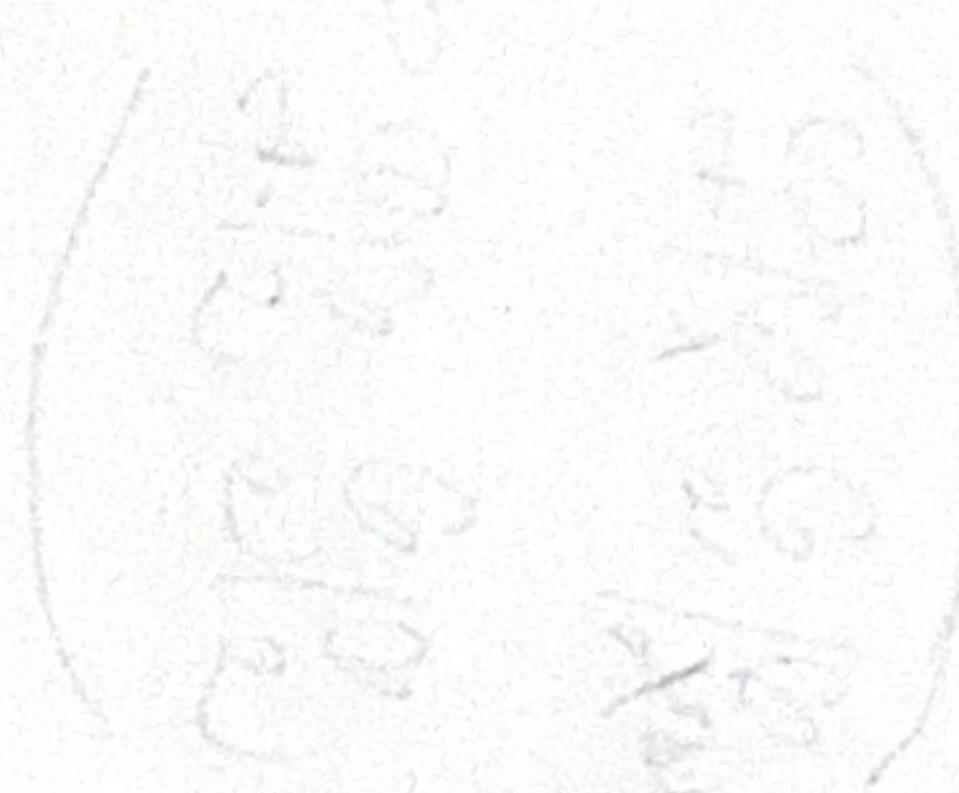
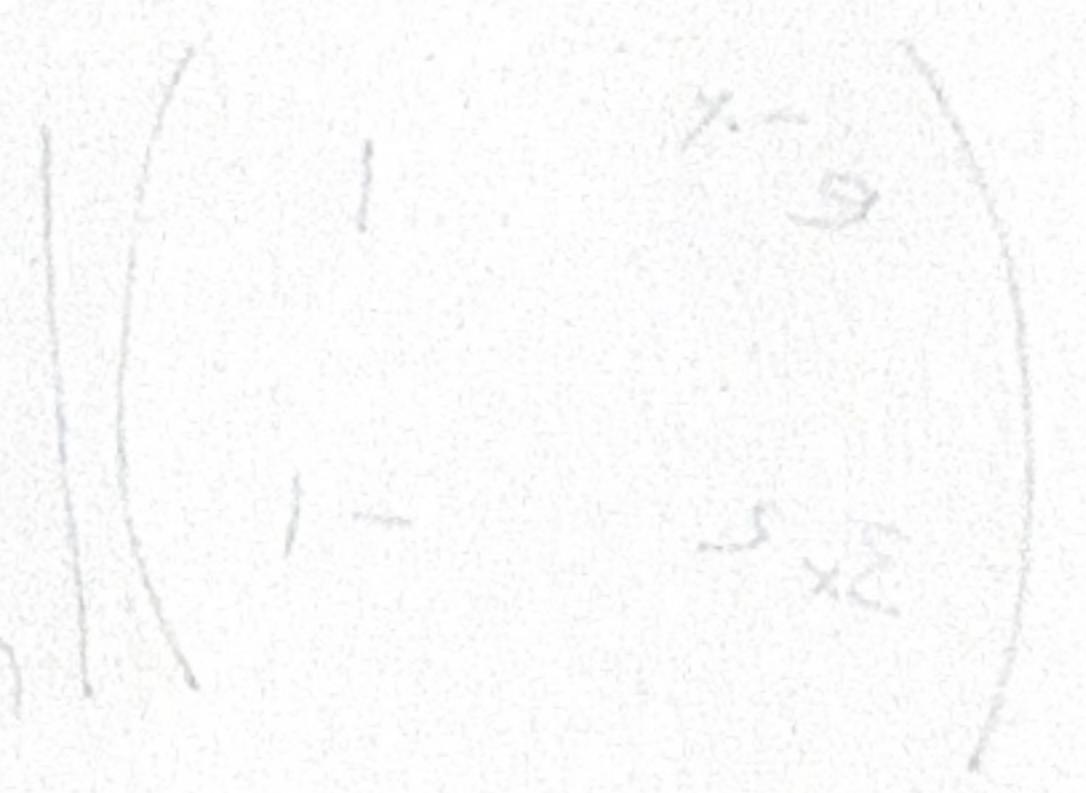
$$2x^4 - 8x^2 + 8 - 2x^3 + 4x = 0$$

$$2(x^4 - x^3 + 4x^2 + 2x + 4) = 0.$$

$(0,0) = (*y, *x)$ to what left we can get see



$$(0,0) = (*y, *x)$$



2) calculate 1st derivatives of $x(t), y(t)$

$$\text{rotating } (1) \leftarrow \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix} \text{ with } \theta = (\lambda_1 - \lambda_2)(t-1)$$

$$0 = \varepsilon - 1 - (\lambda_1 + \lambda_2)t$$

$$\text{rotating } (1) \leftarrow \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & -1 \\ 0 & -1 & 0 \end{pmatrix} \text{ with } s + t = \lambda$$

we will want when it has a small enough range of rotation this has a small enough