

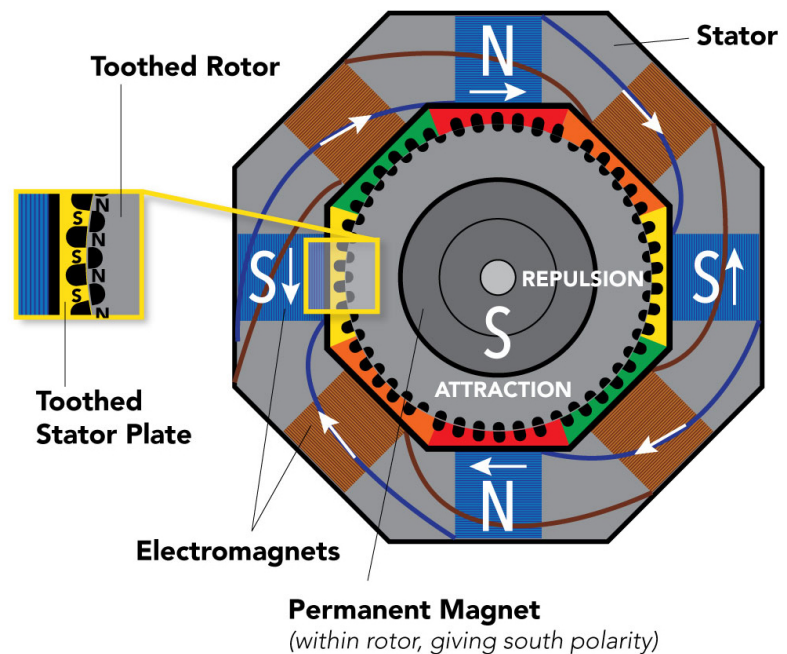
Names: _____

Arduino Stepper Motor

Background:

The stepper motor is a device that is capable of producing large torque with a high level of precision. Stepper motors contain a toothed rotor that spins based on its attraction and repulsion to 4 surrounding electromagnets. We can control the exact angle that the motor spins by turning on and off the four electromagnets. You can learn more about how a stepper motor works [here](#).

Due to their ability to rotate exact angles, stepper motors are used in a wide range of applications. For example, stepper motors drive the hands of analog clocks (rotating the second hand 6° every second) and in 3-D printers.



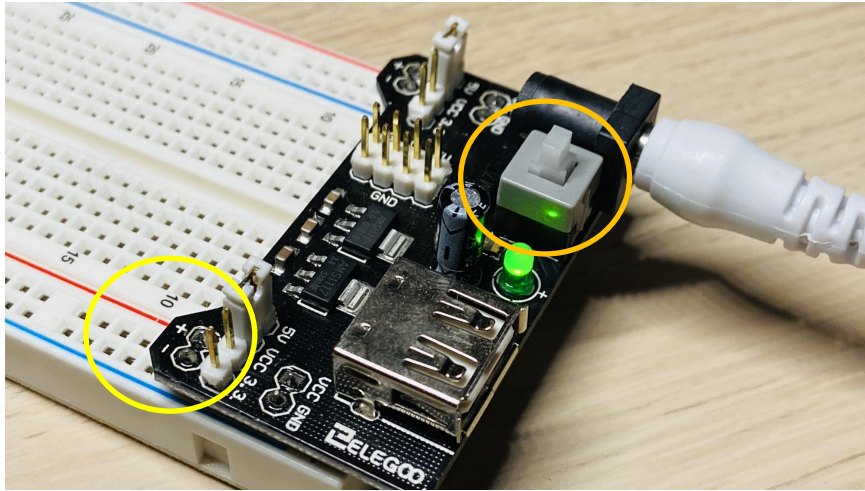
Question: What is another possible application for stepper motors?

Part 1: Hardware

Materials: Arduino Uno, breadboard, stepper motor, stepper motor driver board, power supply module, 9V battery, battery wire, jumper wires, USB cable

The stepper motor is a device that needs a large amount of current to operate. This much current would fry the delicate circuitry of the Arduino, so the motor must be powered separately using a 9V battery and power supply module. The Arduino also does not produce the correct frequency signal in order to communicate directly with the stepper motor, so they must both communicate through the stepper motor driver board. The stepper motor driver board is connected to the 9V power supply *and* the Arduino. It contains an IC chip that translates the Arduino's signal into the correct pattern to rapidly turn the four electromagnets inside the motor on and off, connecting them in turn to the power from the battery in order to drive it.

1. Draw an arrow on a small piece of paper and attach it to the stepper motor axle. (This makes it easier to see exactly how far the motor has rotated)
2. Plug the power supply module into the breadboard, as shown below. Make sure to align the positive and negative markings with the correct rails of your breadboard (circled in yellow).



3. Connect a 9V battery to a battery wire and plug it into the power supply. When you press down the button (circled in orange) the green LED should light.
4. Verify that the white jumper is set to 5V rather than 3.3V for the power rail that you plan to use (circled in green below).



5. Connect the GND pin on the Arduino to the ground rail of the breadboard in order to ensure a common ground.
6. Plug the stepper motor into the stepper motor driver board.
7. Connect the 4 input pins on the stepper motor driver board to the Arduino as listed:

Driver pin	Arduino pin
IN1	8
IN2	9
IN3	10
IN4	11

8. Connect the bottom left pin (labeled “-”) to the ground rail and the bottom right pin (labeled “+”) to the power rail

Part 2: Software

Open a new program in the Arduino code editor. Copy the starter code below:

Starter code:

```

#include <Stepper.h>
const int stepsPerRevolution = 2048; //based on the physical hardware of the stepper motor

// initialize the stepper library on pins 8 through 11:
Stepper myStepper(stepsPerRevolution, 8, 10, 9, 11);

void setup() {
  // set the speed at 5 rpm:
  myStepper.setSpeed(5);
  // initialize the serial port:
  Serial.begin(9600);
}

void loop() {
  // step one revolution in one direction:
  Serial.println("clockwise");
  myStepper.step(stepsPerRevolution);
  delay(500);
  // step one revolution in the other direction:
  Serial.println("counterclockwise");
  myStepper.step(-stepsPerRevolution);
  delay(500);
}

```

Run the code and check that it works! The motor should rotate in one full circle, wait half a second, then rotate one full circle in the other direction.

Video: Take a video of your circuit. Include your names. Paste it here or upload it to this Google Classroom assignment.

Experiment: Play around with the code; try changing parameters in order to answer the questions below. Don't change the stepsPerRevolution variable (this is based on the physical number of teeth on the rotor inside the stepper motor).

Questions	Answers
1. How can we make the stepper motor spin faster?	
2. What happens if you change the number of steps: <i>myStepper.step(200);</i> <i>delay(500);</i> instead of <i>myStepper.step(stepsPerRevolution);</i> <i>delay(500);</i>	

3. What does the negative sign inside of <i>myStepper.step(-stepsPerRevolution)</i> ; do?	
4. How can we make the stepper motor rotate 90°?	

Part 3: Extras

Task 1: Modify the code so that motor spins 180° clockwise, then spins counterclockwise in three 60° increments.

Paste your code here:

Take a video of your circuit. Include your name. Paste it here or upload it to this Google Classroom assignment.

Task 2: Add a slide switch to your circuit. Program the Arduino so that when the slide switch is up, the motor spins clockwise, and when the slide switch is down, the motor spins counterclockwise.

Paste your code here:

Take a video of your circuit. Include your name. Paste it here or upload it to this Google Classroom assignment.

Task 3: Add a button switch to your circuit. Program the Arduino so that when the button is pressed, the motor starts/stops spinning (if it was stopped, it starts, and if it was spinning, it stops). Challenge: Modify your code so that whether the user holds the button down for a long or short period of time doesn't matter

Paste your code here:

Take a video of your circuit. Include your name. Paste it here or upload it to this Google Classroom assignment.

Task 4: Modify the code so that when the button is pressed once, the motor spins slowly. When the button is pressed again it spins more quickly. When the button is pressed a third time, it turns off. (When the button is pressed again, it spins slowly again, etc.)

Paste your code here:

Take a video of your circuit. Include your name. Paste it here or upload it to this Google Classroom assignment.

Task 5: Watch the video about how stepper motors work [here](#) (make sure to wear headphones). Write a paragraph summarizing how a stepper motor is able to achieve such a high degree of precision.

Paragraph:

Extra Resources:

If you are stuck, check out [this YouTube tutorial](#).