# **Homework 2**

linshuangquan

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### **No.3**

Because  $X_k \sim N(\mu_k, \sigma_k)$ , Thus

$$\begin{split} Pr(Y=k|X=x) &= \frac{\Pi_k f_k(c)}{\sum_{l=1}^k \pi_l f_l(x)} \propto \Pi_k f_k(c) \\ log(Pr) &\propto log(\pi_k) + log(\frac{1}{\sqrt{(2\pi)\sigma_k}} \exp(-\frac{(x-\mu_k)^2}{2\sigma_k^2})) \\ log(Pr) &\propto log(\pi_k) - log(\sigma_k) - \frac{(x-\mu_k)^2}{2\sigma_k^2} \end{split}$$

Thereforce the discriminant function:

$$\delta_k(x) = -\frac{1}{2\sigma_k}x^2 + x \cdot \frac{\mu_k}{\sigma_k^2} - \frac{\mu_k^2}{2\sigma_k^2} + \log(\frac{\pi_k}{\sigma_k})$$

So the it is not linear, means quadratic.

### **No.5**

a

If the Bayes decision boundary is linear, on the training set, QDA is more flexiblity so perform better. On the test set, LDA perform better than QDA because QDA will cause overfitting now.

## b

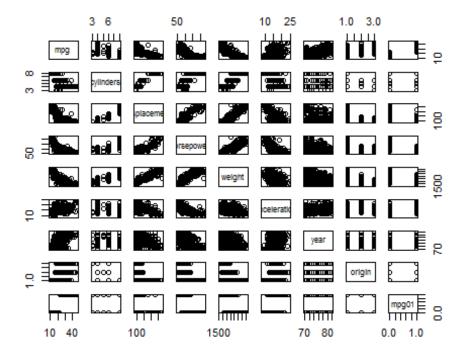
If the Bayes decision bounary is non-linear, we expect QDA to perform better both on the training and test sets.

Yes, when the sample size n increases, the boundary will be more complicate due to variance of data. So QDA will has better fit effect because it is more flexiblity than LDA.

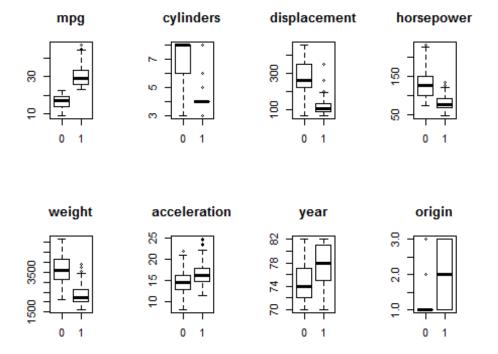
### d

False. QDA will cause overfitting when the Bayes boundary is linear, thus will has higher test rate than LDA.

```
No.11
library(ISLR)
attach(Auto)
a
Auto$mpg01 <- ifelse(mpg>=median(mpg),1,0)
b
cor(Auto$mpg01,Auto[,1:8])
##
              mpg cylinders displacement horsepower
                                                         weight acceler
ation
## [1,] 0.8369392 -0.7591939
                               -0.7534766 -0.6670526 -0.7577566
                                                                   0.34
68215
##
                     origin
             year
## [1,] 0.4299042 0.5136984
pairs(Auto[,-9])
```



```
par(mfrow=c(2,4))
for(i in 1:8){
          boxplot(Auto[,i]~Auto$mpg01,main=colnames(Auto)[i])
}
```



From the sed for

correlation and the picture, we can find that these variables can be used for predicting "mpg01":mpg,cylinders,displacement,horsepower,weight,

```
C
set.seed(123)
sample <- sample(rep(c(1:4),length=dim(Auto)[1]))</pre>
trainset<- Auto[sample!=4,]</pre>
testset <- Auto[sample==4,]</pre>
d
library(MASS)
lda.fit = lda(mpg01 ~ cylinders + weight + displacement + horsepower, d
ata = trainset)
lda.pred = predict(lda.fit, testset)
mean(lda.pred$class != testset$mpg01)
## [1] 0.05102041
e
qda.fit = qda(mpg01 ~ cylinders + weight + displacement + horsepower, d
ata = trainset)
qda.pred = predict(qda.fit, testset)
mean(qda.pred$class != testset$mpg01)
```

## [1] 0.06122449

```
f
glm.fit <- glm(mpg01 ~ cylinders + weight + displacement + horsepower,
data = trainset, family="binomial")
summary(glm.fit)
##
## Call:
## glm(formula = mpg01 ~ cylinders + weight + displacement + horsepower,
      family = "binomial", data = trainset)
##
##
## Deviance Residuals:
                    Median
##
      Min
                10
                                 30
                                        Max
## -2.1555 -0.2520
                    0.1314
                                     3,2805
                             0.3949
## Coefficients:
##
                Estimate Std. Error z value Pr(>|z|)
## (Intercept) 11.5346829 1.9126948
                                     6.031 1.63e-09 ***
## cylinders
               0.1435739 0.3856374
                                     0.372 0.70967
## weight
               ## displacement -0.0127788 0.0089016 -1.436
                                            0.15113
## horsepower
              ## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## (Dispersion parameter for binomial family taken to be 1)
##
##
      Null deviance: 406.90 on 293 degrees of freedom
## Residual deviance: 170.24 on 289 degrees of freedom
## AIC: 180.24
##
## Number of Fisher Scoring iterations: 7
#remove the variable that p-value bigger than 0.05
glm.fit2 <- glm(mpg01 ~ displacement + horsepower, data = trainset,fami
ly="binomial")
summary(glm.fit2)
##
## Call:
## glm(formula = mpg01 ~ displacement + horsepower, family = "binomial",
##
      data = trainset)
##
## Deviance Residuals:
##
      Min
                10
                                 3Q
                    Median
                                        Max
## -2.1116 -0.3315
                    0.1649
                             0.4749
                                     3.3755
##
## Coefficients:
                Estimate Std. Error z value Pr(>|z|)
```

```
## (Intercept) 9.049458 1.326893 6.820 9.10e-12 ***
## displacement -0.022111
                            0.003843 -5.754 8.74e-09 ***
                            0.015131 -3.703 0.000213 ***
## horsepower -0.056033
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for binomial family taken to be 1)
##
##
       Null deviance: 406.90 on 293 degrees of freedom
## Residual deviance: 177.64 on 291 degrees of freedom
## AIC: 183.64
##
## Number of Fisher Scoring iterations: 7
glm.probs = predict(glm.fit2, testset, type = "response")
glm.pred = ifelse(glm.probs>0.5,1,0)
mean(glm.pred != testset$mpg01)
## [1] 0.07142857
library(class)
errorrate \leftarrow rep(0,5)
set.seed(1234)
for(i in 1:10){
        knn.pred=knn(trainset[,2:5],testset[,2:5],trainset$mpg01,k=i)
        errorrate[i]<- mean(knn.pred != testset$mpg01)</pre>
}
names(errorrate) <- 1:10</pre>
errorrate
##
                       2
                                  3
## 0.10204082 0.09183673 0.06122449 0.07142857 0.06122449 0.07142857
                       8
                                  9
## 0.07142857 0.06122449 0.06122449 0.08163265
detach(Auto)
```

So when K=3 performes the best.

\*\*\*