## **Hunter Ellis**

## **Electrical & Computer Engineer**

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Engineer with an interest in control theory and embedded systems. github.com/hunterwellis → Currently, working on my Master's Thesis in Dr. Thinh Doan's Research Group. ellishw.tech Skills Languages: C++, Python, MATLAB, Embedded C, LaTeX, Verilog Tools: Simulink, Soldering, PCB Design and Assembly, GNU/Linux, Git, ROS2, Gazebo, PyTorch, OpenCV, 3D-Printing, SciKit-Learn, Make, CMake, LabView, Ot, KiCAD, FreeRTOS, Autodesk Inventor, SolidWorks, Rhino Education **Master of Science in Computer Engineering** May 2025 Blacksburg, Virginia Virginia Tech – Focused on Control Theory Advisers: Dr.Thinh Doan (UT Austin) and Dr.Michael Hsaio (Virginia Tech) Bachelor of Science in Electrical & Computer Engineering (double major) May 2024 Virginia Tech – Control Systems and Machine Learning Blacksburg, Virginia **Experience** Robotics & Control Theory Research | M.S. Thesis Aug 2023 – Present Blacksburg, Virginia Virginia Tech · Graduate Researcher • Undergraduate and graduate research developing neuro-symbolic algorithms • Developing robotic hardware and software tools for testing algorithms Working on merging symbolic programming with deep RL for multi-task agents • Building ROS2 workspaces and packages for training custom RL agents • Designed and implemented symbolic RL methods to beat Atari games Graduate Teaching Assistant | Continuous & Discrete Systems Aug 2024 – Present Blacksburg, Virginia Virginia Tech · Teaching Assistant Assisting Professors in teaching fundamental concepts in linear systems theory and DSP • Holding office hours and preparing recitation sessions for students Thrust Vector Control | Mars Ascent Vehicle (MAV) May 2024 - Aug 2024 Jacobs Space Exploration Group • TVC Intern Huntsville, Alabama • TVC for Mars Sample Return Mission and EUS at the NASA Marshall Space Flight Center (Merrit Island, Florida) • Developed software and hardware systems for NASA's Active Inertial Load Simulator • Characterized dynamic systems for MAV's TVC test stand using Python and MATLAB. Derived a non-linear model and control architecture for a load simulating actuator • Traveled to Kennedy Space Center for the Space Launch System's (Booster) TVC Testing **Control Systems Research | Microgrid Inverters** June 2023 – Aug 2023 *Grenoble Electrical Engineering Laboratory* • *Research Intern* Grenoble, France • Researched "microgrids" - designed to avoid infastructure problems on the French Grid • Simulated neutral point balancing control methods using 4-leg inverters in Simulink Investigated NPC inverters with unbalanced network conditions for islanding events Naval Concept Design Research | Hospital Sea Trains June 2022 – Aug 2022 Naval Surface Warfare Center (Carderock Division) · Concept Research Intern West Bethesda, Maryland • Developed concept hospital sea-train design at the Center for Innovative Ship Design • Estimated fuel consumption and electrical power loads of concept sea-trains **Projects** FOC Stepper Motor (github.com/hunterwellis) Dec 2023 - Present • Widely applicable stepper motor driver using FOC and a magnetic encoder for feedback • 4-layer PCB mounts to the back of stepper with CAN and power connection

Design Teams | Solar Car & Human Powered Submarine (solarcaratvt.org)

• Overall E/E architecture of the Solar Car

Computer Vision | OCR Capstone Project (capstone brochure.pdf)

• IOS application capable of detecting coins of interest/value

Oct 2020 - Mar 2023

Aug 2023 - May 2024

• Single board computer and LCD to display relevant data to the submarine pilot

Trained OCR and ResNet-50 models on dataset of real and augmented coin images