Blacksburg, Virginia (703) 953-6963 hunterellis@vt.edu

Hunter Ellis

Electrical & Computer Engineer

ellishw.tech github.com/hunterwellis linkedin.com/in/ellishw

Electrical/Computer Engineer with interests in control systems and signal processing.

Skills

Software: C/C++, Python, MATLAB, GNU/Linux, Simulink, Git, ROS2, Gazebo, Make, CMake, Labview, Qt,

PyTorch, OpenCV, LaTeX, Verilog, FreeRTOS, Autodesk Inventor, SolidWorks, Rhino

Hardware: PCB Design and Assembly, Breadboarding, Computer Architecture, Oscilloscope, Multimeter, 3D-Printing

Education

May 2025 **Master of Science in Computer Engineering** Virginia Tech – Focused on Control Theory – GPA: 3.8 Blacksburg, Virginia

Advisers: Dr.Thinh Doan (UT Austin) and Dr.Michael Hsiao (Virginia Tech)

Bachelor of Science in Electrical & Computer Engineering (double major) May 2024 Virginia Tech - Control Systems and Machine Learning - GPA: 3.7 Blacksburg, Virginia

Technical Experience

Control Theory (Reinforcement Learning) Research | M.S. Thesis Aug 2023 - Present Virginia Tech · Graduate Researcher Blacksburg, Virginia

• Undergraduate and graduate research developing neuro-symbolic algorithms with The C.O.O.L Autonomy Lab at The University of Texas at Austin.

 Developing hardware for a 6-axis robot arm and software for a ROS2 simulation environment used to test custom Reinforcement Learning algorithms.

Continuous and Discrete Systems · Graduate Teaching Assistant

Aug 2024 - Dec 2024 · Taught fundamental concepts in linear systems theory and digital signal processing, including Laplace Blacksburg, Virginia Transforms, Z-Transforms, system stability, and FIR & IIR filter design.

 Assisted with hands-on projects to illustrate and integrate analog and digital filter design and application on breadboards and TI MSP432 development boards.

Thrust Vector Control (TVC) | Mars Ascent Vehicle (MAV) Jacobs Space Exploration Group · TVC Intern

• Developed thrust vector control testing hardware and software as part of NASA's Active Inertial Load Simuator at the Marshall Space Flight Center.

• Characterized and created a model of an electro-mechanical actuator including internal viscous and (non-linear) coloumb friction components.

· Derived control systems for load simulating actuators - used to simulate external loads placed on the Mars Ascent Vehicle's thrust vector control actuators during flight.

 Designed and integrated a 3rd order IIR filter to remove high frequency noise from a load cell and linear variable differential transformer (LVDT).

Control Systems Research | Microgrid Inverters Grenoble Electrical Engineering Laboratory · Research Intern

Researched inverter control systems – designed to be robust to islanding events and avoid future

infastructure problems on the French power grid.

• Simulated neutral point capacitive and balancing control methods using 4-leg inverters in Simulink. Tested PI control, PR control, Clarke and Park Transforms with HIL simulations.

Naval Concept Design Research | Hospital Sea Trains

Naval Surface Warfare Center (Carderock Division) · Concept Research Intern

 Developed concept hospital sea-train designs at the Center for Innovation in Ship Design and estimated fuel consumption and electrical power loads of concept sea-trains.

June 2022 - Aug 2022 West Bethesda, Maryland

June 2023 - Aug 2023

Grenoble, France

May 2024 - Aug 2024

(Merrit Island, Florida)

Huntsville, Alabama

Projects

FOC Stepper Motor (github.com/hunterwellis)

Backdrivable stepper motor driver using FOC and a magnetic encoder for feedback

• 4-layer PCB mounts to the back of the motor with CAN and power connections

Computer Vision | OCR Capstone Project (capstone brochure.pdf)

IOS application capable of detecting coins of interest/value

Trained OCR and ResNet-50 models on a dataset of real and augmented coin images

Design Teams | Solar Car & Human Powered Submarine (solarcaratvt.org)

• Overall E/E architecture of the Solar Car

· Single board computer and LCD to display relevant data to the submarine pilot

Oct 2020 - Mar 2023

Aug 2023 - May 2024

Dec 2023 - Present