## **Hunter Ellis**

## **Electrical & Computer Engineer**

(703) 953-6963 hunterellis@vt.edu

Engineer with an interest in control theory and embedded systems.  $\hookrightarrow$  Currently working on my thesis in an Accelerated Master's Program at Virginia Tech. github.com/hunterwellis ellishw.tech

**Skills** 

Software: C/C++, Python, MATLAB, GNU/Linux, Simulink, Git, ROS2, Gazebo, Make, CMake, Labview, Qt,

PyTorch, OpenCV, 3D-Printing, LaTeX, Verilog, FreeRTOS, Autodesk Inventor, SolidWorks, Rhino

Hardware: SMD Soldering, PCB Design and Assembly, Oscilloscope, Multimeter, 3D-Printing

Education

**Master of Science in Computer Engineering** 

Virginia Tech - Focused on Control Theory - GPA: 3.8

Advisers: Dr.Thinh Doan (UT Austin) and Dr.Michael Hsiao(Virginia Tech)

Bachelor of Science in Electrical & Computer Engineering (double major)

Virginia Tech - Control Systems and Machine Learning - GPA: 3.7

**Experience** 

Control Theory (Reinforcement Learning) Research | M.S. Thesis Virginia Tech · Graduate Researcher

• Undergraduate and graduate research developing neuro-symbolic algorithms

• Developing robotic hardware and software tools for testing algorithms

Working on merging symbolic programming with deep RL for multi-task agents

• Building ROS2 workspaces and packages for training custom RL agents

• Designed and implemented RL methods to beat Atari games

**Graduate Teaching Assistant | Continuous & Discrete Systems** Virginia Tech · Teaching Assistant

Assisting Professors in teaching fundamental concepts in linear systems theory and DSP

• Holding office hours and preparing recitation sessions for students

Thrust Vector Control | Mars Ascent Vehicle (MAV) Jacobs Space Exploration Group · TVC Intern

• TVC for Mars Sample Return Mission and EUS at the NASA Marshall Space Flight Center

• Developed software and hardware systems for NASA's Active Inertial Load Simulator

• Characterized dynamic systems for MAV's TVC test stand using Python and MATLAB

Derived a non-linear model and control architecture for a load simulating actuator

• Traveled to Kennedy Space Center for the Space Launch System's (Booster) TVC Testing

**Control Systems Research | Microgrid Inverters** 

Grenoble Electrical Engineering Laboratory · Research Intern

• Researched "microgrids" – designed to avoid infastructure problems on the French Grid

• Simulated neutral point balancing control methods using 4-leg inverters in Simulink

Investigated NPC inverters with unbalanced network conditions for islanding events

Naval Concept Design Research | Hospital Sea Trains

Naval Surface Warfare Center (Carderock Division) · Concept Research Intern

• Developed concept hospital sea-train design at the Center for Innovative Ship Design

• Estimated fuel consumption and electrical power loads of concept sea-trains

**Projects** 

FOC Stepper Motor (github.com/hunterwellis)

• Backdrivable stepper motor driver using FOC and a magnetic encoder for feedback

• 4-layer PCB mounts to the back of the motor with CAN and power connections

**Computer Vision | OCR Capstone Project** (capstone brochure.pdf)

• IOS application capable of detecting coins of interest/value

Trained OCR and ResNet-50 models on a dataset of real and augmented coin images

Design Teams | Solar Car & Human Powered Submarine (solarcaratvt.org)

• Overall E/E architecture of the Solar Car

• Single board computer and LCD to display relevant data to the submarine pilot

May 2024

May 2025

Blacksburg, Virginia

Blacksburg, Virginia

Aug 2023 – Present

Blacksburg, Virginia

Aug 2024 – Present

Blacksburg, Virginia

May 2024 - Aug 2024

Huntsville, Alabama (Merrit Island, Florida)

June 2023 – Aug 2023

Grenoble, France

June 2022 - Aug 2022

West Bethesda, Maryland

Dec 2023 - Present

Aug 2023 - May 2024

Oct 2020 - Mar 2023