

Input:



Panoramic
Video at Frame $t+1$



Panoramic
Video at Frame t



Ground-truth HM
Scan-path till Frame t

Observation

Observation

FoV Extractor



Reward Estimator
Equation (2)(3)

Reward

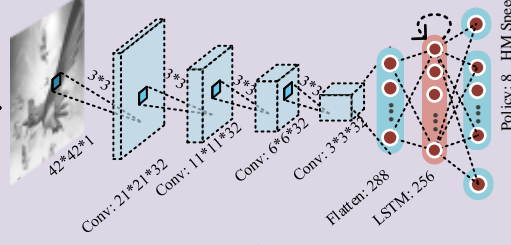
FoV Extractor



Reward Estimator
Equation (2)(3)

Reward

DRL Network for On-line Model



Load

DRL Network for Off-line Model

Output:



Predicted HM
Position at Frame $t+1$

Action

Action

Train

Predict