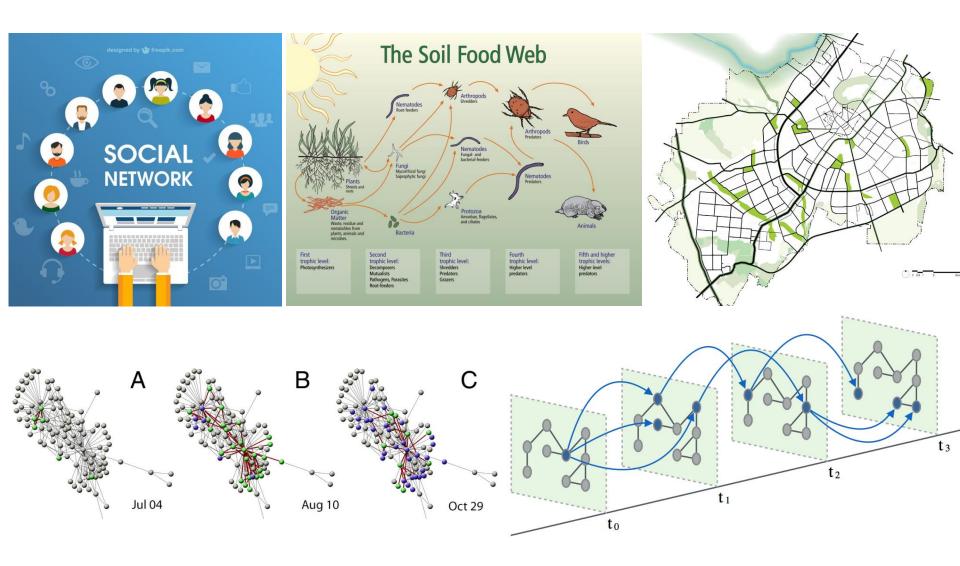
## Fast Computation of Dense Temporal Subgraphs

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### Graphs are dynamic

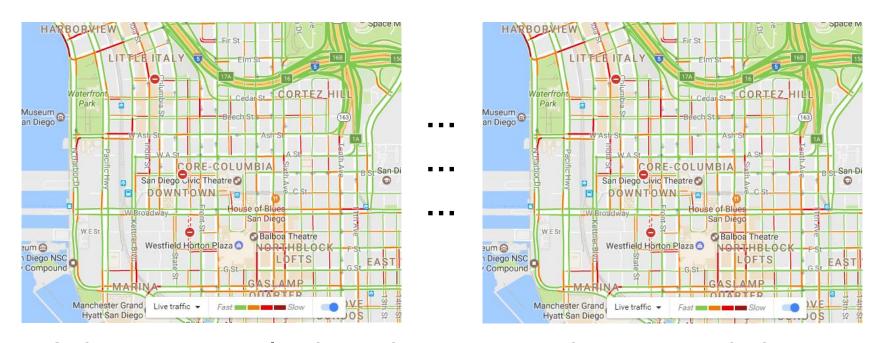


\*All images are downloaded from Google.

#### **Motivation**

**Temporal graph:** a continuous sequence of snapshots (each snapshot records the status of a graph at a specific timestamp)

**Dense temporal subgraph:** a subgraph having heavy edge weights over a continuous time period



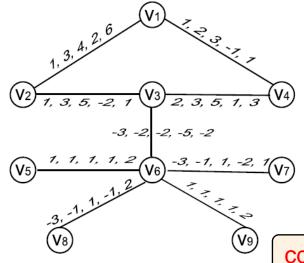
A dense temporal subgraphs corresponds to a crowded area spanning over a continuous time period.

#### **Outline**

> The FDS problem: analyses and challenges

- A data-driven approach
- Experimental study
- Summary

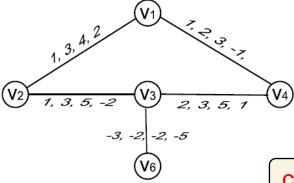
#### Temporal graphs and subgraphs



Temporal graph G(V, E, F) with T timestamps

- nodes and edges keep unchanged
- edge weights constantly and regularly vary with timestamps
- T snapshots: G<sub>1</sub>(V, E, F<sup>1</sup>), G<sub>2</sub>(V, E, F<sup>2</sup>), ..., G<sub>T</sub>(V, E, F<sup>T</sup>)

cdensity(G)=36



Temporal subgraph H(V<sub>s</sub>, E<sub>s</sub>, F<sub>s</sub>, i, j)

- time interval [i, j] ⊆ [1, T]
- subgraph (V<sub>s</sub>, E<sub>s</sub>) of (V, E)
- denote H(V, E, F<sub>s</sub>, i, j) as G[i, j]

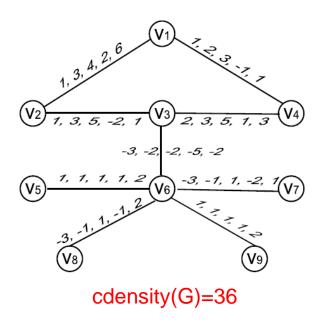
cdensity(H)=21

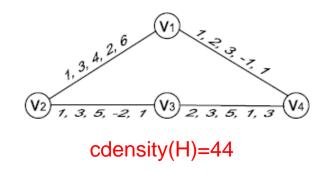
Cohesive density cdensity(G)

sum of edge weights among all snapshots

### Problem statement and complexity analysis

- > FDS: finding dense subgraphs
  - find a connected temporal subgraph with the greatest cohesive density





### Problem statement and complexity analysis

- > FDS: finding dense subgraphs
  - find a connected temporal subgraph with the greatest cohesive density
- Problem hardness<sup>[Bogdanov et al. 11]</sup>
  - the FDS problem is NP-complete, even for a temporal network with a single snapshot and with +1 or -1 edge weights only.
- Our approximation hardness result
  - the cohesive density of the optimal dense temporal subgraph is NP-hard to approximate within any constant factor.
    - ✓ proof sketch: building an approximation factor preserving reduction from the net worth maximization problem, which is NPhard to approximate within any constant factor.

### Challenges

find a dense temporal subgraph

determine a time interval [i, j]

find a dense subgraph given [i, j]

- ➤ Filter-and-Verification<sup>[Bogdanov et al. 11]</sup>
  - consider all time intervals [i, j] and find dense subgraphs by fixing [i, j] each time
  - filter [i, j] if its upper bound of cohesive density is worse than the best cohesive density achieved
  - prune 99% of a total of T\*(T+1)/2 time intervals

Т	141	447	1,414	•••	14,142
T*(T+1)/2	104	<b>10</b> <sup>5</sup>	10 <sup>6</sup>	•••	108
# unpruned	10 <sup>2</sup>	<b>10</b> <sup>3</sup>	104		<b>10</b> <sup>6</sup>

Filter-and-Verification is insufficient for large temporal graphs!

A new and better algorithm design philosophy is needed.

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#### Main ideas

Big graph friendly

- Employ hidden data statistics to explore k time intervals
  - k is typically a small constant independent of T, e.g., 10

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T*(T+1)/2	104	<b>10</b> <sup>5</sup>	10 <sup>6</sup>	•••	108
# unpruned	10 <sup>2</sup>	10 <sup>3</sup>	$10^{4}$	•••	10 <sup>6</sup>
our approach	k	k	k		k

- Our data-driven approach FIDES
  - **step 1:** identify k time intervals involved with dense subgraphs
    - employing hidden data statistics and drawing characteristics of targeted time intervals
  - step 2: compute dense subgraphs given time intervals
    - ✓ building the connections with the NWM problem, and exploiting effective and efficient optimization techniques

1000x faster while remain comparable quality of dense subgraphs

#### Step 1: Hidden data statistics

#### Convergent evolution

 organisms not closely related independently evolve similar traits as a result of having to adapt to similar environments







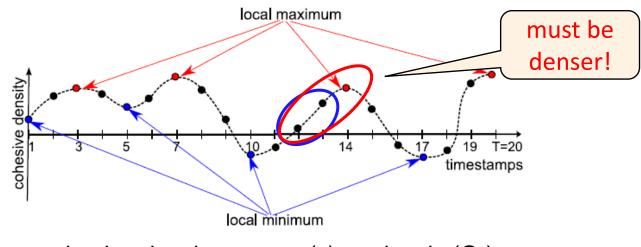


- Evolving convergence phenomenon (ECP)
  - edge weights evolve in a convergent way
  - not completely realistic, but admit a nice mathematical development

ECP assures an important characteristic of targeted time intervals.

#### Step 1: Characteristics of time intervals

C1: To find the dense subgraph, we only need to consider the time intervals [i, j] such that the cohesive density curve has a local maximum at certain points between i and j under ECP.



top-k for better

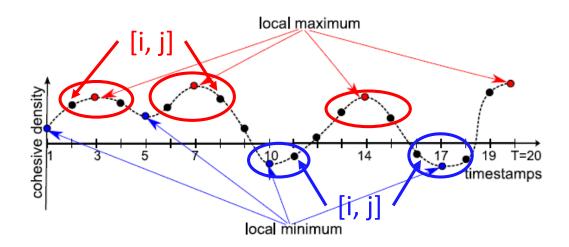
cohesive density curve,  $y(x) = cdensity(G_x)$ 

C2: All dense subgraph have a non-negative cohesive density.

C3: G[i, j] with a higher positive cohesive density has a higher probability of containing a dense subgraph.

### Step 1: Identifying k time intervals

- 1. compute local maxima/minima of the cohesive density curve;
- 2. extend local maxima/minima to peaks/valleys of the curve;
- 3. generate time intervals containing local maxima;
- 4. find the top-k time intervals having the largest positive cdensity;



Time complexity:  $O((T+h^2)|E|)$ , h is the # of local maxima/minima

### FIDES recap

- step 1: identify k time intervals involved with dense subgraphs
  - ✓ hidden data statistics: evolving convergence phenomenon.
  - ✓ three characteristics of targeted time intervals
  - ✓ top-k time intervals containing a local maximum and having the largest positive cohesive density

- step 2: compute dense subgraphs given time intervals (referred to as computeADS)
  - ✓ building the connections with the NWM problem
  - ✓ exploiting effective and efficient optimization techniques

#### Step 2: The NWM problem

- Net worth maximization
  - input: a graph with non-negative node and edge weights
  - output: a subtree that maximizes the net worth
    - ✓ net worth = sum of node weights sum of edge weights

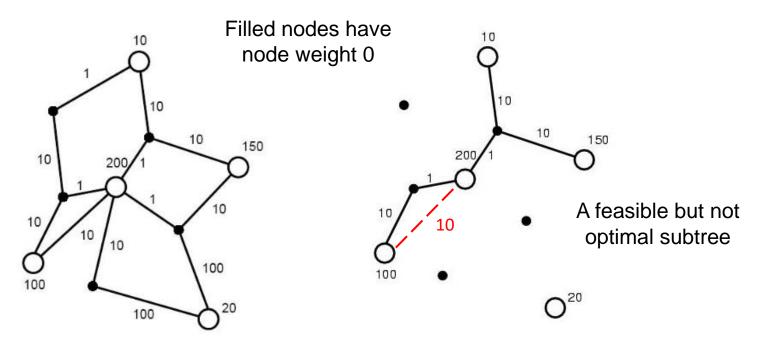


Image credit: Ivana Ljubic, https://homepage.univie.ac.at/ivana.ljubic/research/pcstp/

### Step 2: Connections with the NWM problem

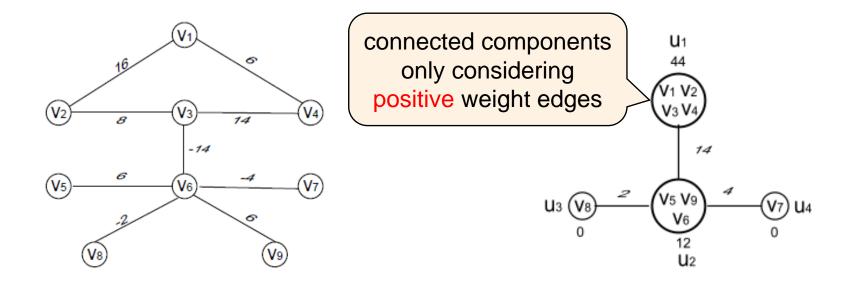
temporal subgraph G[i, j]



aggregate graph G'(V, E, f) where  $f(e)=\sum F^{t}(e)$ ,  $t\in[i, j]$ 



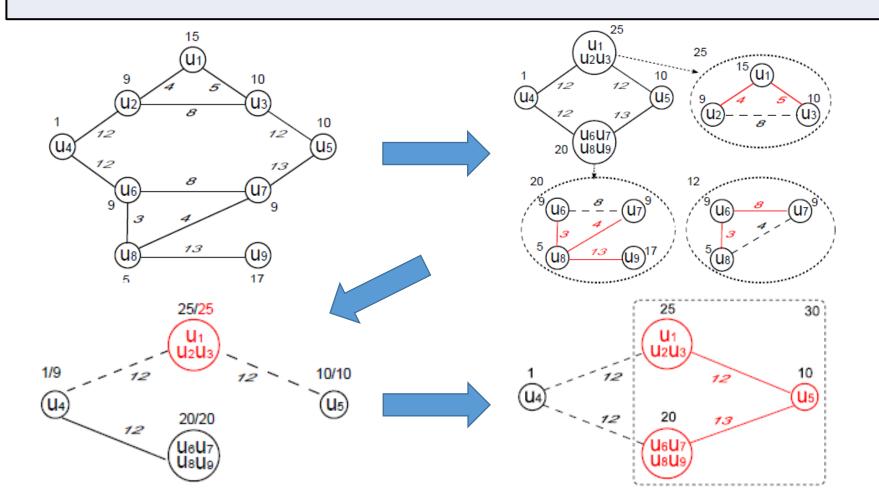
converted graph G'<sub>c</sub>(V<sub>c</sub>, E<sub>c</sub>) with node and edge weights



dense subgraph in G' is equivalent to NWM subtree in G'c

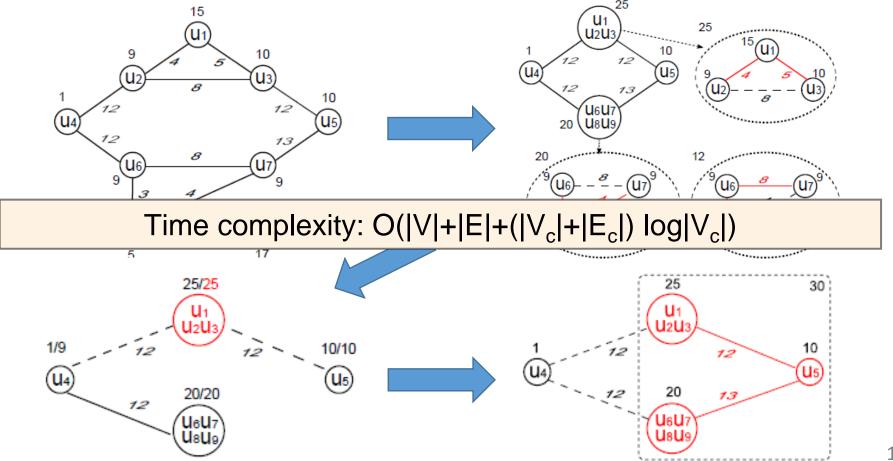
#### Step 2: Optimization techniques

strong merging: merge nodes that belong to the same NWM subtree; strong pruning: compute an optimal subtree ST on the MST; bounded probing: optimize ST by probing nodes in bounded distance;



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#### Experimental setups

#### Data sets

Data sets	V	E	Т	ad <sub>r</sub>	Description
BJData	82,093	108,238	289	0.44	real-life Beijing road network with traffic status
SYNData	50,000 ~ 400,000	2 V	200 ~ 2,000	0.05 ~ 0.35	synthetic temporal network used in [Bogdanov et al. 11]

- activation density ad<sub>r</sub>: ratio of positive weight edges
- Algorithms
  - FDS given time intervals: computeADS & topDown [Bogdanov et al., 11]
  - FDS on temporal graphs: FIDES & MEDEN [Bogdanov et al., 11]
- Experimental goals
  - verify the rationale behind evolving convergence phenomenon
  - test the quality of dense subgraph found by computeADS and FIDES
  - test the efficiency of computeADS and FIDES

#### Verification of ECP

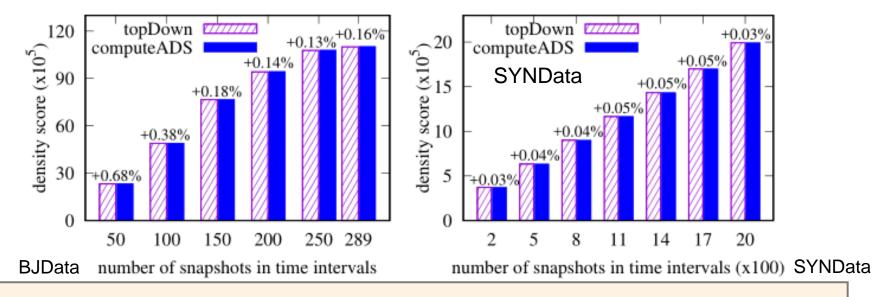
- Edge weights evolve in a convergent way
  - to what degree does ECP hold in temporal graphs?
- Proportion of edges that satisfy ECP
  - 96% on BJData
  - 90% on average on SYNData

$$p_{EC} = \frac{\sum_{t=2}^{T} \max(|E^{\geq}(t)|, |E^{\leq}(t)|)}{|E|(T-1)}$$

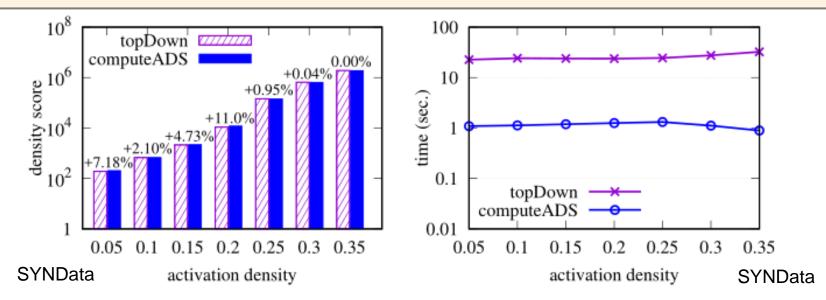
ECP is quite common on both real-life and synthetic temporal graphs.

The characteristics based on ECP work, though ECP is not completely satisfied.

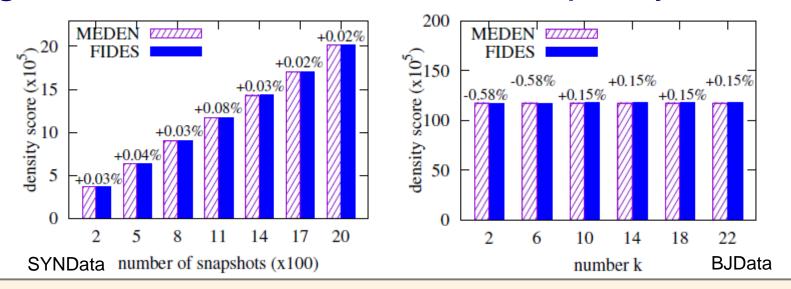
#### Algorithms computeADS vs. topDown



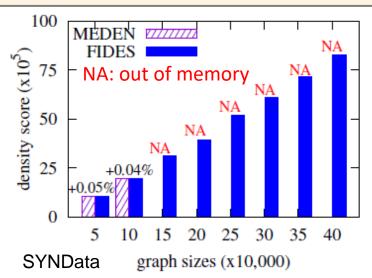
Algorithm computeADS is better than topDown in both quality and efficiency.

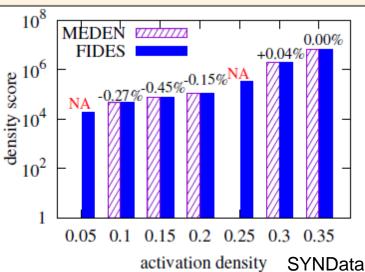


#### Algorithms FIDES vs. MEDEN: quality

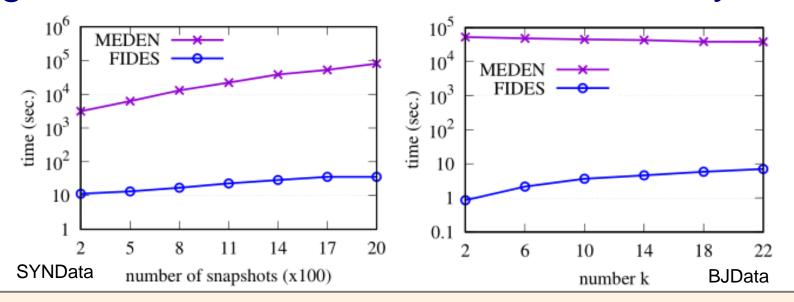


Dense subgraphs found by FIDES are (+0.28%, -0.16%) better than those found by MEDEN on (BJData, SYNData).

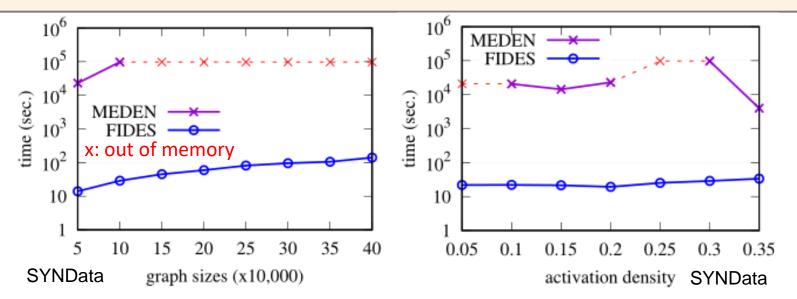




#### Algorithms FIDES vs. MEDEN: efficiency



FIDES is (2,980, 1,079) times faster than MEDEN on (BJData, SYNData).



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#### Summary

- Find dense subgraphs on large temporal graphs
  - NP-complete and NP-hard to approximate
  - Filter-and-Verification is insufficient for large temporal graphs
- A data-driven approach (big graph friendly)
  - identify k time intervals by employing hidden data statistics
  - build the connection between FDS and NWM
  - three algorithm optimization techniques
- Comparison with the state-of-the-art solution on both real-life and synthetic data
  - comparable in quality of dense subgraphs found
  - three orders of magnitude faster

# Thanks!

Q & A

Welcome to tomorrow afternoon's poster session!

## Synthetic data generator[Bogdanov et al., 11]

- Random graphs as underlying graphs
- Step 1: all edges in every snapshots have weight -1
- Step 2: randomly activate an edge in a specific snapshot (+1), and activate its neighboring edges and the same edge in the next snapshots with certain probabilities. Later activated edge will perform the same activation process.
- Step 3: repeat step 2 until a prefixed ad<sub>r</sub> is satisfied