MLA Data Challenge – Group 37



Anomaly Detection in Pneumatic Cylinder Production



Motivation and Goals



- Background is a manufacturing process of a pneumatic cylinder by a CNC-Milling machine
- Task is to develop a machine learning model, that uses internal and external machine data to classify the bottom parts into:

False: Anomaly, True: No Anomaly





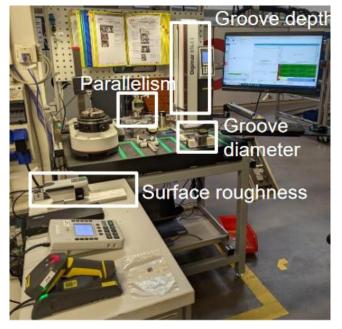


Motivation and Goals



In this way, the required quality can be ensured before the next production steps and the functionality of the product can be guaranteed at an early stage





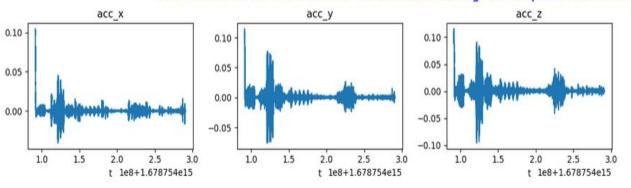


Data and Feature Exploration

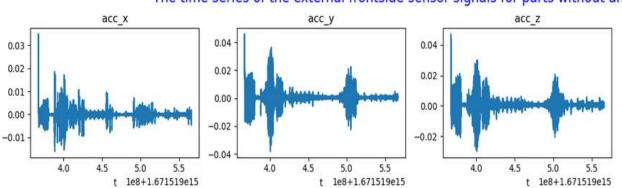


- Seperating true and false parts
- Investigation of time series for different sensors

The time series of the external frontside sensor signals for parts with anomalies



The time series of the external frontside sensor signals for parts without anomalies

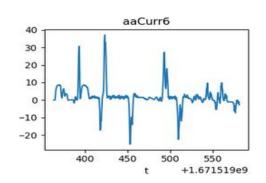


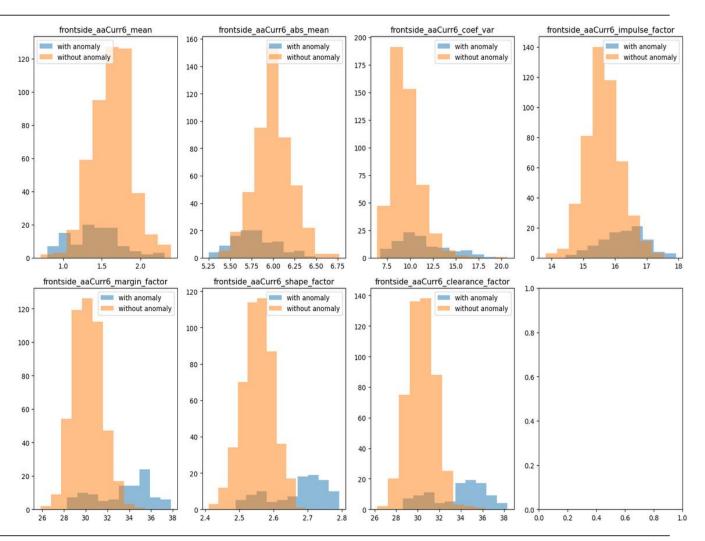


Data and Feature Exploration



 Deriving features as input data for further processing







Concept and Methodology



Data Preparation:

Feature Extraction Feature Selection Data Split Class Imbalance Scaling

Machine Learning Models:

MLP

SVM

RF



Data Preparation



Feature Extraction

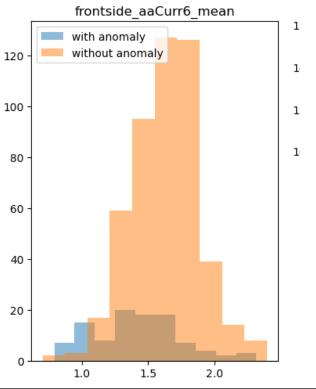


Feature Extraction



- Computed various statistical measures for each sensor
- Measures included mean, root mean square, kurtosis, skewness, etc.
- Chosen for their ability to describe time series characteristics.
- Assist in understanding patterns and variations.
- Resulted in 900 features per data point.

frontside_aaCurr6_margin_factor
frontside_aaCurr6_abs_mean
frontside_aaCurr6_impulse_factor
frontside_aaCurr6_coef_var





Data Preparation



Feature Extraction

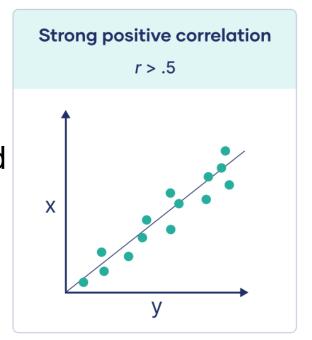
Feature Selection

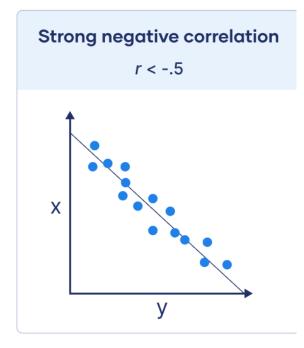


Feature Selection



- Feature selection reduces data dimensionality.
- A correlation-based method was used.
- Pearson correlation coefficient measured relationship strength.
- Features with correlation < 0.1 were filtered out.
- Reduced features from 900 to 161, significantly.







Data Preparation



Feature Extraction

Feature Selection

Data Split



Data Split



- Data split into training and validation sets.
- Training set for model training.
- Validation set for model performance evaluation.
- Ratio: 80% training, 20% validation.
- Stratified to preserve class distribution.





Data Preparation



Feature Extraction

Feature Selection

Data Split

Class Imbalance



Class Imbalance



Oversampled data:

- Data c class imbalance.
- Addressed using SMOTE technique.
- SMOTE generates new minority class samples.
- Parameters: sampling_strategy.

Number of Anomaly Classes Number of Anomaly Classes 400 400 350 350 300 300 250 250 200 · ਰੂ 200 150 150 100 100 50 50



Data Preparation



Feature Extraction

Feature Selection

Data Split

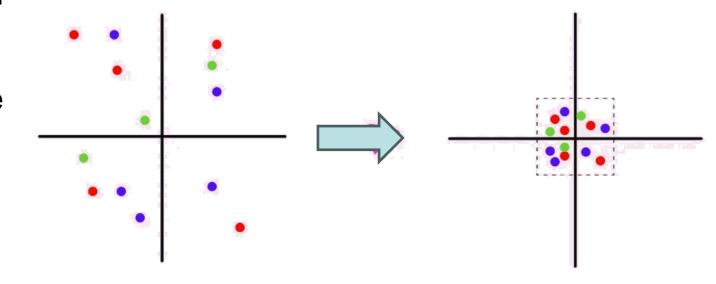
Class Imbalance Feature Scaling



Feature Scaling



- Data scaled using standard scaler.
- Transforms features to have mean zero, std deviation one.
- Improves performance of sensitive models.





Machine Leraning Models



- Multilayer perceptron (MLP)
- Support vector machine (SVM)
- Random forest (RF)

MLP

SVM

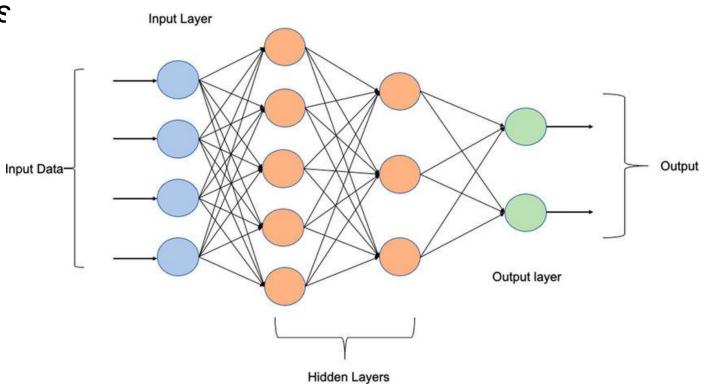
RF



Multilayer perceptron (MLP)



- Learns complex nonlinear patterns
- Parameters:
 hidden_layer_sizes=(128, 64),
 activation='relu', alpha=0.01,
 max iter=20, random state=42.
- Chosen based on trial and error.
- Specifies layer sizes, activation function, regularization, and iterations.



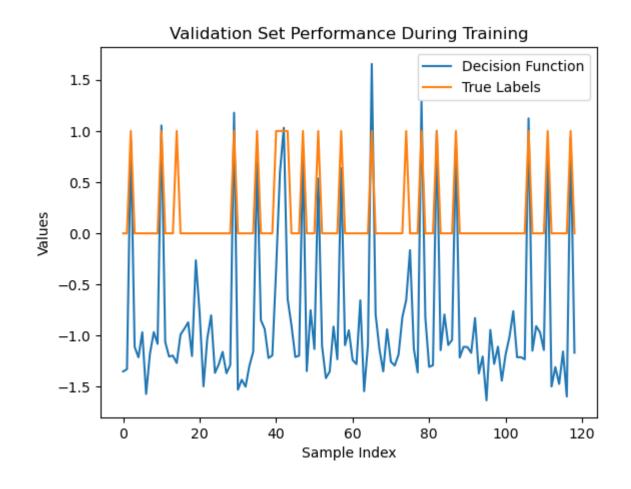
Multi-layer perceptron (MLP-NN) basic Architecture. | Download Scientific Diagram (researchgate.net)



Support vector machine (SVM)



- Finds hyperplane to separate data into classes.
- Can handle nonlinear data using kernel function.
- Default parameters: kernel='rbf', C=1.
- 'rbf' kernel commonly used for nonlinear data.
- C parameter set to 1 for moderate penalty balance.

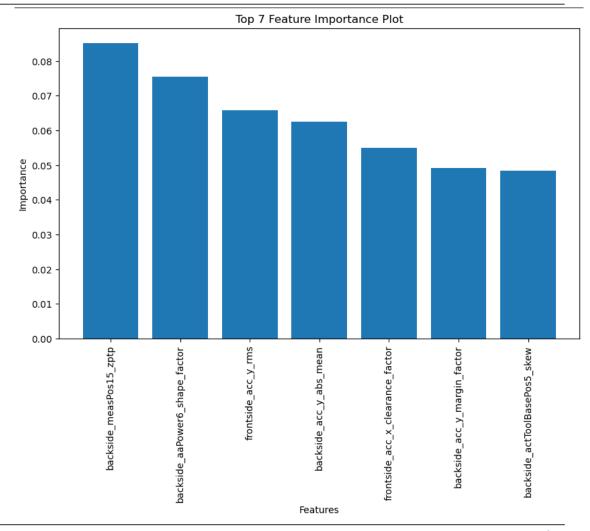




Random forest (RF)



- Ensemble learning combining multiple decision trees.
- Reduces variance and overfitting.
- Chosen based on trial and error.
- n_estimators set to 100 for effective ensemble learning.



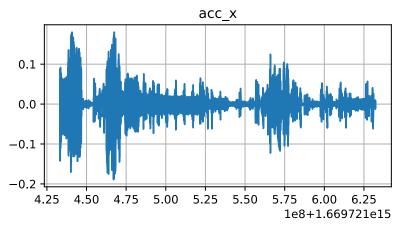


Classification using frontside sensor data

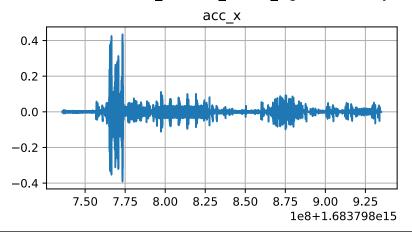


- Frontside acceleration data has visible variations in different anomaly classes
- Used for
 - CNN Time Series Classification
 - Random Forest Classifier
 - Decision Tree Classifier

Part 100101 frontside_external_sensor_signals Anomaly 0



Part 111102 frontside external sensor signals Anomaly 1



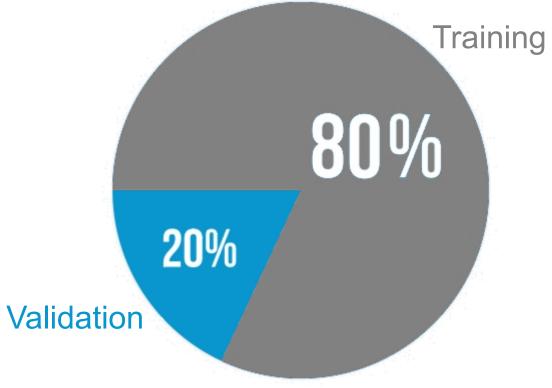


Model Evaluation



Testing the models on the 20% test split

Assessment based on the f1-score





Scores



- Highest Score: Random Forest Classifier using correlation-based features at 94.74%
- Promising: Time Series and Random Forest Classification based on acceleration data

	Correlation-based features (all channels)			Frontside acceleration data		
	Multi Layer Perceptron	Support Vector Machine	Random Forest	CNN (Time Series)	Random Forest	Decision Tree
f1-score	79.07%	89.47%	94.74%	93.33%	94.74%	87.18%
False positives	5.04%	0.84%	0%	0%	0.88%	2.63%
False negatives	2.52%	2.52%	1.68%	1.74%	0.88%	1.75%



Final Model



High number of features → high chance that

useful features can be found

Makes use of all the data channels

Fast actual training

Feature correlation might be coincidental

Can't detect details in the signal course

Needs heavy data preprocessing



Applicability of the ML Models



Models are already quite accurate

Can help reduce quality control expenses

Not reliable yet



Strategies for Improvement



- Stronger oversampling of anormal parts
 - Should improve reliability
 - Might induce losses in general accuracy

Collect further data



