

A Very Brief Introduction to Group Theory

$$\phi : G \longrightarrow \text{Sym}(X)$$

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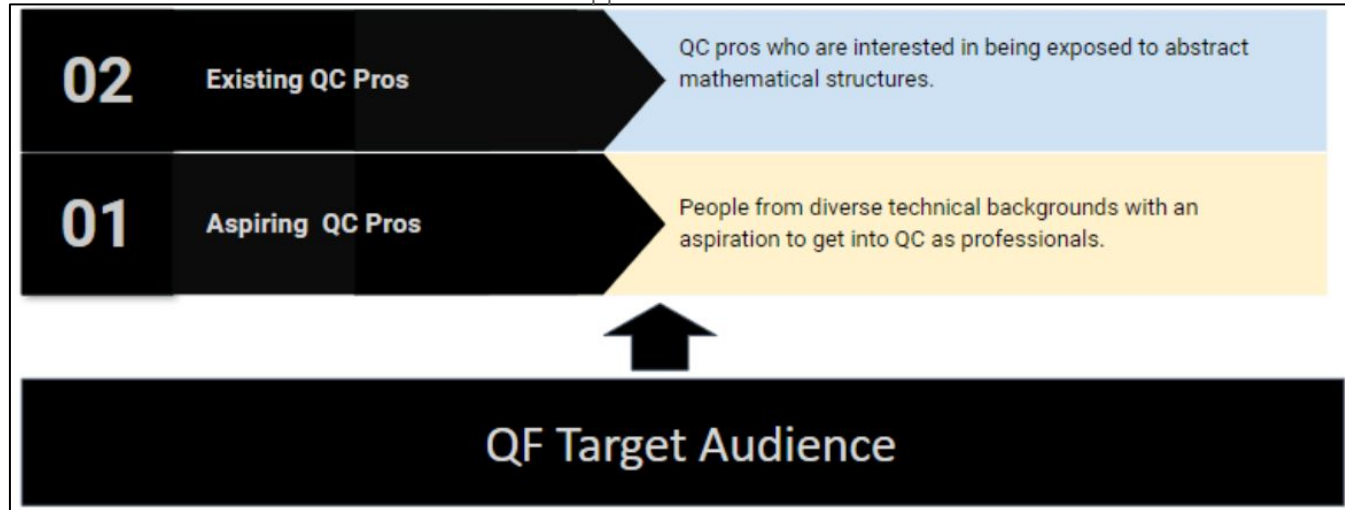
Quantum Computing Hackathon at Zayed University Abu Dhabi

Wednesday, 14/2/2023

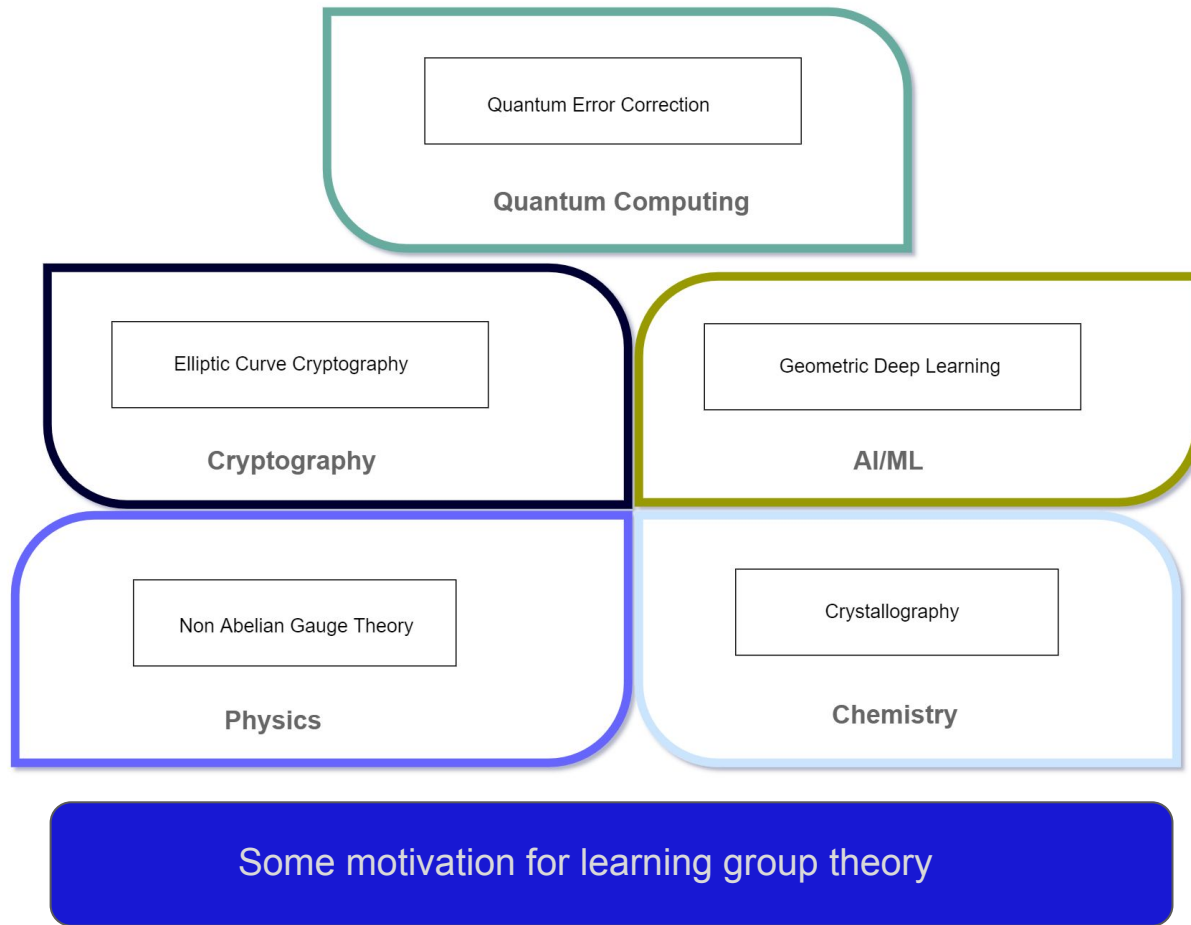
Presenter: Bambordé Baldé

About QF

Quantum Formalism is a free online course series provided by the Zaiku Group, aimed at exposing abstract mathematical topics to a diverse group of STEM professionals looking to break into the nascent quantum computing.



Why should you bother to
learn group theory?



Nice to have prerequisite for this talk

- **Basics of Linear Algebra**

- ① Complex vector spaces.
- ② Linear operators between vector spaces.
- ③ How to multiply two $n \times n$ complex matrices.

- **Basics of Quantum Computing**

- ① Aware that the n - dimensional complex vector space \mathbb{C}^n is a complex Hilbert space. In particular, for a k - qubit system, we use the Hilbert space \mathbb{C}^n with $n = 2^k$.
So for example, a single qubit system uses the space \mathbb{C}^2 and 2-qubit system uses $\mathbb{C}^{2^2} = \mathbb{C}^4$.
- ② Know the basic quantum gates such as; X , Y , Z and H .

Talk structure

- ① The abstract group structure
- ② Basic examples
- ③ Subgroups
- ④ Homomorphisms & Isomorphisms
- ⑤ Complex matrix groups
 - Unitary group
 - Unitary representations
 - Special unitary group

The abstract group structure

Definition 1.0

A group is a pair $(G, *)$ consisting of a nonempty set G and a binary function (operation) $* : G \times G \longrightarrow G$ satisfying the following conditions:

- ❶ $g_1 * g_2 \in G$ for all $g_1, g_2 \in G$ (closure).
 - ❷ $g_1 * (g_2 * g_3) = (g_1 * g_2) * g_3$ for all $g_1, g_2, g_3 \in G$ (associativity).
 - ❸ There exists an element $e \in G$ such that $e * g = g * e = g$ for all $g \in G$ (identity).
 - ❹ For all $g \in G$ there exists a special element $g^{-1} \in G$ such that $g * g^{-1} = g^{-1} * g = e$ (inverse).
- Two important consequences of the definition above are:
 - ❶ The identity element e is unique i.e. if e_1 and e_2 are two identities then we must have $e_1 = e_2$.
 - ❷ The inverse g^{-1} of each element g is also unique i.e. if g_1^{-1} and g_2^{-1} are inverses of g , then $g_1^{-1} = g_2^{-1}$.

Simple examples and counterexamples

- Which of the following are groups?
 - ❶ $(\mathbb{N}, +)$ i.e. the set of natural numbers under ordinary addition.
 - ❷ $(\mathbb{Z}, +)$ i.e. the set of integers under ordinary addition.
 - ❸ (\mathbb{Z}, \times) i.e. the set of integers under ordinary multiplication.
 - ❹ $(\mathbb{R}, +)$ i.e. the set of real numbers under ordinary addition.
 - ❺ (\mathbb{R}, \times) i.e. the set of real numbers under ordinary multiplication.
 - ❻ $(\mathbb{C}, +)$ i.e. the set of complex numbers under ordinary addition.
 - ❼ (\mathbb{C}, \times) i.e. the set of complex numbers under ordinary multiplication.
 - ❽ (\mathbb{C}^*, \times) i.e. the set of nonzero complex numbers under ordinary multiplication.
 - ❾ $\mathbb{Z}_5 = \{0, 1, 2, 3, 4\}$ under mod5 addition giving me the following table:

\oplus	0	1	2	3	4
0	0	1	2	3	4
1	1	2	3	4	0
2	2	3	4	0	1
3	3	4	0	1	2
4	4	0	1	2	3

Terminology

A group $(G, *)$ is called commutative (or abelian) if $g_1 * g_2 = g_2 * g_1$ for all $g_1, g_2 \in G$. Otherwise, if $g_1 * g_2 \neq g_2 * g_1$ for some $g_1, g_2 \in G$, then $(G, *)$ is called noncommutative (or nonabelian).

- All the previous simple examples are abelian groups.
- In quantum computing, the quantum gates form a nonabelian group!

Notation awareness

Whenever the group operation $*$ on G is understood from the context, then we often just write G and omit writing the pair $(G, *)$.

Subgroups

Definition 1.1

Let $(G, *)$ be a group and $H \subseteq G$. Then we say H is a subgroup of G if $(H, *)$ also forms a group under the group operation $*$.

- By definition, G is a subgroup of itself. The same with the subset $\{e\}$ containing only the group identity element. The two are called 'trivial subgroups'!
- From our previous simple examples, we have the set of the integers \mathbb{Z} is a subgroup of the group of reals $(\mathbb{R}, +)$ under the ordinary addition.

How to identify a subgroup structure?

Given a group $(G, *)$ and $H \subset G$. H is a subgroup of G if and only if the following conditions hold:

- 1 $h_1 * h_2 \in H$ for all $h_1, h_2 \in H$ i.e. we have closure in H .
- 2 For each $h \in H$ the group inverse $h^{-1} \in H$ i.e. the group inverse of each element of H also lies in H .

Homomorphisms

Definition 1.2

Let $(G, *)$ and $(G', *')$ be two groups. A map $\phi : G \longrightarrow G'$ is a homomorphism if $\phi(g_1 * g_2) = \phi(g_1) *' \phi(g_2)$ for all $g_1, g_2 \in G$.

- When the map ϕ is bijective (onto and one-to-one), we call it a group isomorphism.
- Two groups $(G, *)$ and $(G', *')$ are isomorphic if there is an isomorphism between them, and we write $G \simeq G'$.
- The isomorphism relationship is transitive i.e. $G_1 \simeq G_2$ and $G_2 \simeq G_3$ then $G_1 \simeq G_3$.

Definition 1.3

Let $(G, *)$, $(G', *')$ be two groups and $\phi : G \longrightarrow G'$ a homomorphism. We can define the following two subsets:

- 1 $Ker(\phi) = \{g \in G \mid \phi(g) = e'\}$ where e' is the identity in G' .
- 2 $Im(\phi) = \{\phi(g) \mid g \in G\}$.

Observation

It's not hard to prove that $\text{Ker}(\phi)$ is a subgroup of G and $\text{Im}(\phi)$ is a subgroup of G' . Also, ϕ is an isomorphism iff $\text{Ker}(\phi) = \{e\}$.

- A very familiar and famous example of a group homomorphism is when we consider the additive group of the reals $(\mathbb{R}, +)$ and the multiplicative group of the nonzero reals (\mathbb{R}^*, \times) . We can take the homomorphism $\phi : \mathbb{R} \longrightarrow \mathbb{R}^*$ to be defined as $\phi(x) = \exp(x)$ for all $x \in \mathbb{R}$ where $\exp(x)$ is the ordinary exponential function.

Notation awareness

We'll write $M_n(\mathbb{C})$ to denote the set of all $n \times n$ matrices with entries in \mathbb{C} .

- Some authors use the notation $\mathbb{C}^{n \times n}$ instead of $M_n(\mathbb{C})$.
- I'll assume everyone knows about the basics of $n \times n$ matrices over the reals \mathbb{C} including; how to compute the transpose, perform addition and multiplication of $n \times n$ matrices.
- When equipped with the ordinary matrix addition or multiplication, which of the following is true?
 - 1 $M_n(\mathbb{C})$ forms an abelian group structure under addition.
 - 2 $M_n(\mathbb{C})$ forms a nonabelian group structure under multiplication.

Important notes: From linear algebra 101 an element $A \in M_n(\mathbb{C})$ induces a linear map $L_A : \mathbb{C}^n \longrightarrow \mathbb{C}^n$, with \mathbb{C}^n equipped with the canonical vector space structure over \mathbb{C} . Likewise, any linear map $L : \mathbb{C}^n \longrightarrow \mathbb{C}^n$ induces an element $A_L \in M_n(\mathbb{C})$ i.e. linear operators on $\mathbb{C}^n \equiv n \times n$ matrices over \mathbb{C} .

Definition 1.4

A subset $G \subset M_n(\mathbb{C})$ is a complex matrix group if it's a group under the ordinary matrix multiplication. This implies the matrices in G must satisfy all the group properties:

- 1 If $A, B \in G$ then $AB \in G$ i.e. matrix multiplication is a closed binary operation in G .
- 2 If $A, B, C \in G$ then $A(BC) = (AB)C$ i.e. matrix multiplication is associative in G . This is trivial to show because it is associative in $M_n(\mathbb{C})$!
- 3 The identity matrix $I_n \in G$.
- 4 For any $A \in G$ there exists an inverse matrix A^{-1} such that $AA^{-1} = A^{-1}A = I_n$.

Interesting example

The set $G = \left\{ \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \mid \alpha, \beta \in \mathbb{C}, |\alpha|^2 + |\beta|^2 = 1 \right\}$ is a complex matrix group under the ordinary matrix multiplication.

- The group G above is a very special type of group known as $SU(2)$!

Conjugate Transpose

Definition 1.5 (using the physicists notation)

Given $A \in M_n(\mathbb{C})$, we define the conjugate transpose of A as $A^\dagger = (\bar{A})^T$.

- Mathematicians normally use A^* instead of A^\dagger !
- For a complex number $\lambda = a + bi \in \mathbb{C}$, we'll write $\bar{\lambda} = a - bi$ to denote its complex conjugate. Be aware, physicists often write λ^* !

Interesting properties of conjugate transpose

Let $A, B \in M_n(\mathbb{C})$ and $\lambda \in \mathbb{C}$. Then the following identities hold:

- 1 $(A^\dagger)^\dagger = A$.
- 2 $(\lambda A)^\dagger = \bar{\lambda} A^\dagger$.
- 3 $(A + B)^\dagger = A^\dagger + B^\dagger$.
- 4 $(AB)^\dagger = B^\dagger A^\dagger$.
- 5 $\det(A^\dagger) = \overline{\det(A)}$.
- 6 If A is invertible then A^\dagger is also invertible.

The Unitary Group

The unitary group

The set $U(n) = \{A \in M_n(\mathbb{C}) \mid A^\dagger A = AA^\dagger = I_n\}$ is a complex matrix group under the ordinary matrix multiplication.

- The group $U(n)$ is known in the literature as the unitary group.
- The group elements of $U(n)$ are indeed linear isometries in \mathbb{C}^n i.e. they preserve the inner product in \mathbb{C}^n and so the norm.
- $U(n)$ is a very important group with applications in many topics such as theoretical physics and quantum information science.
- $U(1)$ is abelian, but for $n \geq 2$, $U(n)$ is nonabelian of course!
- In quantum computation, the quantum gates for a k -qubit system are elements of the unitary group $U(2^k)$. For example, the gates for a 1-qubit system are elements of $U(2)$. Hence, the basic single qubit quantum gates such as; X , Y , Z and H are elements of $U(2)$!
- You can now see why the group structure of $U(2^k)$ is mathematically behind the reversibility of quantum computation!

Side note: $U(n)$ is compact and connected Lie group with 'real' dimension n^2 .

Rotations on the Bloch sphere

We can represent a single qubit geometrically as a point on the Bloch sphere as $|\psi\rangle = \cos\frac{\theta}{2}|0\rangle + e^{i\phi}\sin\frac{\theta}{2}|1\rangle$. Then the 1-qubit gates can be represented as rotations on the Bloch sphere, which then allows you to do arbitrary rotations by an angle α along the x-axis, y-axis and z-axis as follows:

① $R_x(\alpha) = e^{-i\frac{\alpha}{2}X}$, where $X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$.

② $R_y(\alpha) = e^{-i\frac{\alpha}{2}Y}$, where $Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$.

③ $R_z(\alpha) = e^{-i\frac{\alpha}{2}Z}$, where $Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$.

- Each of the rotations above correspond to a 2×2 unitary matrix i.e. to an element of the unitary group $U(2)$.
- We can then view quantum computation as composition of the above rotations on the Bloch sphere!

Unitary representations

Given a group $(G, *)$, a homomorphism $\rho : G \longrightarrow U(n)$ is called an n -dimensional unitary representation of G .

Examples:

- 1 Let $G = (\mathbb{R}, +)$ i.e the reals with the group structure under addition. Then we can build a 1- dimensional unitary representation of \mathbb{R} by defining $\rho : \mathbb{R} \longrightarrow U(1)$ as $\rho(t) = e^{2\pi it}$ for all $t \in \mathbb{R}$.
- 2 Let again $G = (\mathbb{R}, +)$. Then we can build an n - dimensional unitary representation of \mathbb{R} by defining $\rho : \mathbb{R} \longrightarrow U(n)$ as $\rho(t) = e^{-\frac{i}{\hbar} H t}$ for all $t \in \mathbb{R}$, where H is a Hermitian matrix and \hbar is the Planck's constant.

The Special Unitary Group

The special unitary group

The set $SU(n) = \{A \in U(n) \mid \det(A) = 1\}$ is a subgroup of $U(n)$.

- $SU(n)$ is known in the literature as the special unitary group.
- For $n = 2$, we can equivalently obtain $SU(2)$ as follows:

$$SU(2) = \left\{ \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \mid \alpha, \beta \in \mathbb{C}, |\alpha|^2 + |\beta|^2 = 1 \right\}.$$

Observation

Let \mathbb{C}^* be the multiplicative group of the nonzero complex numbers. Then the determinant map $\det : U(n) \rightarrow \mathbb{C}^*$ taking $A \in U(n)$ to $\det(A) \in \mathbb{C}^*$ is a group homomorphism. Then $\text{Ker}(\det) = SU(n)$ right?

Side notes:

- 1 $SU(n)$ is compact and connected Lie group with 'real' dimension $n^2 - 1$.
- 2 The product group $SU(3) \times SU(2) \times U(1)$ is the foundation of the 'Standard Model of Particle Physics'!

Course recommendation

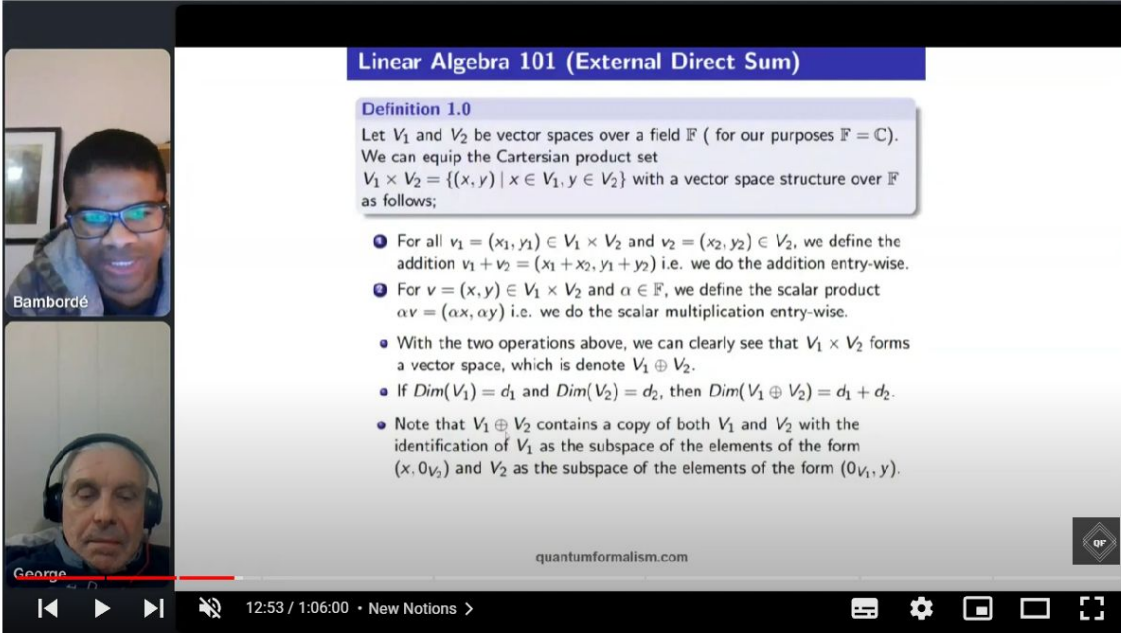
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Linear Algebra 101 (External Direct Sum)

Definition 1.0
Let V_1 and V_2 be vector spaces over a field \mathbb{F} (for our purposes $\mathbb{F} = \mathbb{C}$). We can equip the Cartesian product set $V_1 \times V_2 = \{(x, y) \mid x \in V_1, y \in V_2\}$ with a vector space structure over \mathbb{F} as follows;

- 1 For all $v_1 = (x_1, y_1) \in V_1 \times V_2$ and $v_2 = (x_2, y_2) \in V_2$, we define the addition $v_1 + v_2 = (x_1 + x_2, y_1 + y_2)$ i.e. we do the addition entry-wise.
- 2 For $v = (x, y) \in V_1 \times V_2$ and $\alpha \in \mathbb{F}$, we define the scalar product $\alpha v = (\alpha x, \alpha y)$ i.e. we do the scalar multiplication entry-wise.
- 3 With the two operations above, we can clearly see that $V_1 \times V_2$ forms a vector space, which is denoted $V_1 \oplus V_2$.
- 4 If $\dim(V_1) = d_1$ and $\dim(V_2) = d_2$, then $\dim(V_1 \oplus V_2) = d_1 + d_2$.
- 5 Note that $V_1 \oplus V_2$ contains a copy of both V_1 and V_2 with the identification of V_1 as the subspace of the elements of the form $(x, 0_{V_2})$ and V_2 as the subspace of the elements of the form $(0_{V_1}, y)$.

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Group Theory 20B



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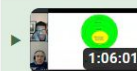
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