

T.C.
GEBZE TECHNICAL UNIVERSITY
PHYSICS DEPARTMENT

PHYSICS LABORATORY II
EXPERIMENT REPORT

THE NAME OF THE EXPERIMENT
Momentum and Kinetic Energy in Collisions

PREPARED BY

NAME AND SURNAME:

STUDENT NUMBER :

DEPARTMENT :

Elastic collision :

1. On a SpeedGate screen, the upper line is switched using the single dash button **I**, and the lower line is changed using the double dash button **II** . To reset the values on the screen, the **X** button is pressed.
2. Configure SpeedGate-A and SpeedGate-B with "Speed" on the upper line using the single dash button **I**, and "Previous Value" on the lower line using the double dash button **II**.
3. Place SpeedGate-A near one end of the rail, and SpeedGate-B near the other end of the rail.
4. Attach the side apparatus to the front of the one at the end of the glider.



5. Attach the side apparatus to the middle glider.
 6. Add the weights shown in the table to the m_1 and m_2 gliders , write the total weights added to the Table 1.
 7. Activate by pressing the red button on the back of the air blower to create a frictionless environment.
 8. Gently push the gliders with your fingertip so that it hits the other glider.
 9. Write the masses in columns labeled as m_1 and m_2 , and write the velocities before and after the collision in columns labeled as v_1 , v_2 , v'_1 , and v'_2 . Here, v_1 and v_2 represent the velocities before the collision, while v'_1 and v'_2 represent the velocities after the collision.
- The weights of the gliders is **200 g**.



Table 1 : Masses and velocities before and after the elastic collision.

	m_1 (.....)	m_2 (.....)	v_1 (.....)	v_2 (.....)	v'_1 (.....)	v'_2 (.....)
1						
2		+2				
3	+5					
4		+7				

Signature :

Calculate momenta $p_{\text{tot. before}}$ and $p_{\text{tot. after}}$ and energies $E_{\text{tot. before}}$ and $E_{\text{tot. after}}$ for each measurement. Find the percentage of energy loss. Calculate the energies $E_{\text{tot. before}}$ and $E_{\text{tot. after}}$ of Exp-1 and Exp-2 using equations (8) and (9), respectively. Write down the intermediate steps.

Exp-3

$$p_{\text{tot. before}} =$$

$$p_{\text{tot. after}} =$$

$$E_{\text{tot. before}} =$$

$$E_{\text{tot. after}} =$$

$$\% \text{ Energy Loss} = \frac{|E_{\text{tot. before}} - E_{\text{tot. after}}|}{E_{\text{tot. before}}} 100 =$$

Exp-4

$$p_{\text{tot. before}} =$$

$$p_{\text{tot. after}} =$$

$$E_{\text{tot. before}} =$$

$$E_{\text{tot. after}} =$$

$$\% \text{ Energy Loss} = \frac{|E_{\text{tot. before}} - E_{\text{tot. after}}|}{E_{\text{tot. before}}} 100 =$$

Signature :

Calculate momenta $p_{\text{tot. before}}$ and $p_{\text{tot. after}}$ and energies $E_{\text{tot. before}}$ and $E_{\text{tot. after}}$ for each measurement. Find the percentage of energy loss. Calculate the energies $E_{\text{tot. before}}$ and $E_{\text{tot. after}}$ of Exp-1 and Exp-2 using equations (10) and (11), respectively. Write down the intermediate steps.

Exp-1

$$p_{\text{tot. before}} =$$

$$p_{\text{tot. after}} =$$

$$E_{\text{tot. before}} =$$

$$E_{\text{tot. after}} =$$

$$\% \text{ Energy Loss} = \frac{|E_{\text{tot. before}} - E_{\text{tot. after}}|}{E_{\text{tot. before}}} 100 =$$

Exp-2

$$p_{\text{tot. before}} =$$

$$p_{\text{tot. after}} =$$

$$E_{\text{tot. before}} =$$

$$E_{\text{tot. after}} =$$

$$\% \text{ Energy Loss} = \frac{|E_{\text{tot. before}} - E_{\text{tot. after}}|}{E_{\text{tot. before}}} 100 =$$

Signature :

Conclusion, Comment and Discussion:

(**Tips:** Give detail explanation about what you've learned in the experiment and also explain the possible errors and their reasons.)

-Give detail explanation about what you've learned in the experiment

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-Explain the possible errors and their reasons in the experiment

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Questions

Q1) What kinetic energy and potential energy and write two examples for each?

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Q2) Write two examples of each of elastic and inelastic collision.

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Signature :

Experiment Name: “*The Conservation of Momentum and Kinetik Energy in Collisions*”

Objective:

-Experimental investigation of the conservation of momentum and energy in elastic and inelastic collisions.

-To investigate examination of the relationship between energy and momentum.

Keywords:

Momentum, Energy, elastic collisions, inelastic collisions

Theoretical Information :

The principle of conservation of momentum derives from Newton's second law. If the net external force applied to a system is zero, it means that the momentum of the system is constant with respect to time.

$$F_{ext} = \frac{\Delta p}{\Delta t} \quad (1)$$

F_{net} , Net external force acting on the system.

p , Momentum of the system.

When $F_{ext} = 0, \frac{\Delta p}{\Delta t} = 0$

$$\Delta p = 0 \quad \text{and} \quad p = constant$$

The total energy of a system is the sum of the kinetic and potential energies of the system at any instant.

$$E = K + P \quad (2)$$

given by equality, where K represents kinetic energy and P represents potential energy.

If only conservative forces do work in a system, there is neither a decrease nor an increase in the total energy of the system. The total energy of the system remains constant (Law of Conservation of Energy).

If momentum and kinetic energy are conserved in the collision of two bodies that are not under the influence of an external force, this type of collision is called an elastic collision. A collision in which momentum is conserved and kinetic energy is not conserved is called an inelastic collision.

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Motion with Constant Acceleration in Inclined Plane

PREPARED BY

NAME AND SURNAME:

STUDENT NUMBER :

DEPARTMENT :

Signature:

Experimental Procedure:

1. On a SpeedGate screen, the upper line is switched using the single dash button **I**, and the lower line is changed using the double dash button **II**. To reset the values on the screen, the **X** button is pressed.
2. Configure SpeedGate-A with "Previous Value" on the lower line using the double dash button **II** and SpeedGate-B with "Interval Before" on the lower line using the double dash button **II**.
3. L is the length of the airway (inclined plane, $L =$ m) and H is the height of the airway.
4. x is the distance between SpeedGate-A and SpeedGate-B that the glider covers, which is the distance it travels on the inclined plane.
5. Using small square boards, change the height H of one side of the airway as in Table 1.
6. According to different x values in Table 1, change the distance between SpeedGate-A and SpeedGate-B by changing only the position of SpeedGate-A.
7. Change the height H of one side of the airway using small square boards.
8. Then calculate the average of 5 time measurements for each value of x , write under column t_{avg} in Table 1.

Table 1 : Measured intervals times

H = 0.9 m							
x (m)	t₁ (s)	t₂ (s)	t₃ (s)	t₅ (s)	t₄ (s)	t_{avg} (s)	t²_{avg} (s²)
0.8							
0.6							
0.4							
0.2							

Signature:

Draw the $x-t^2$ graph using the positions x and square the time average t^2_{avg} values above.

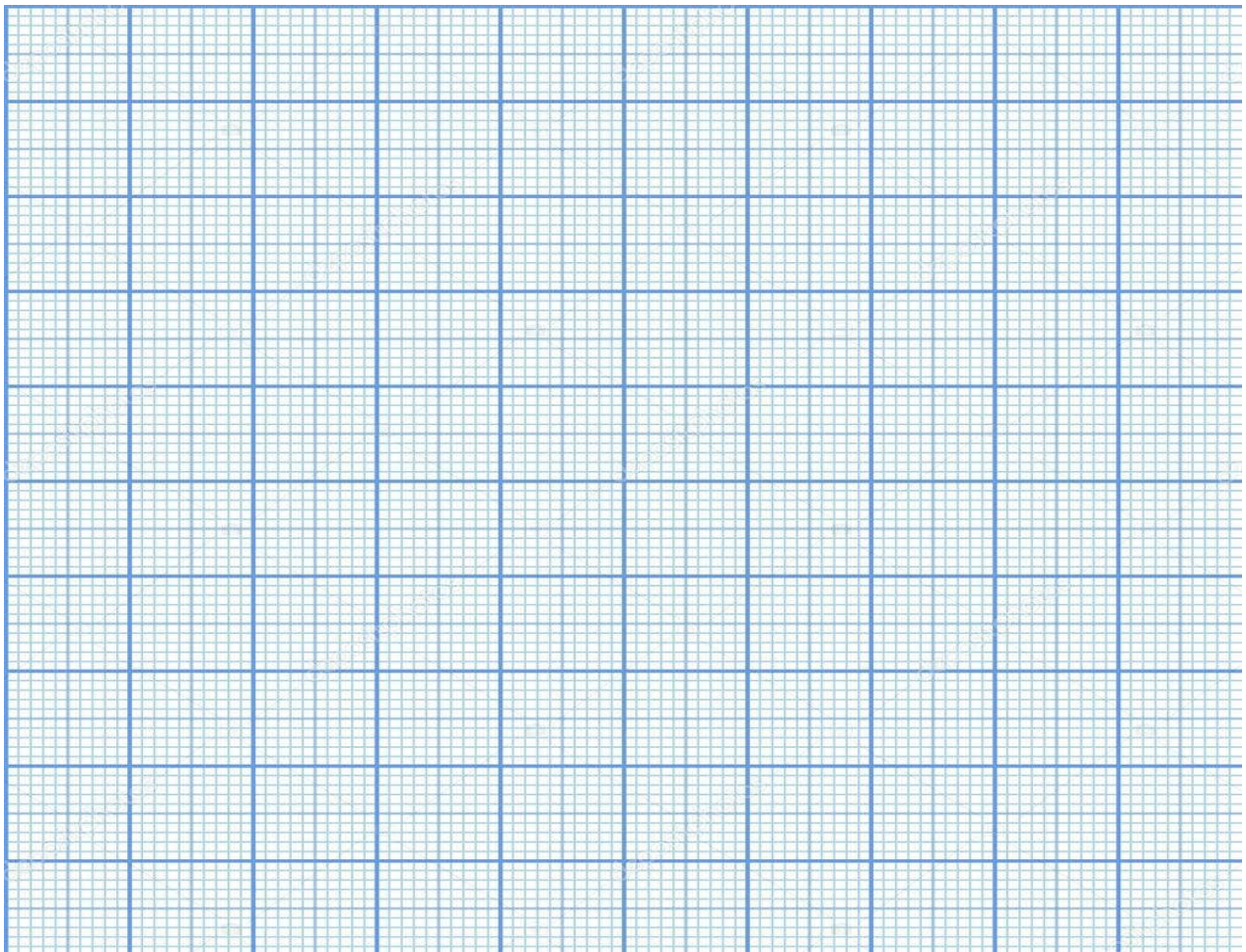


Figure 2: The position x - square the time average t^2_{avg} graph

2) Comment on the velocity of the object from this graph? Explain the reason.

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Signature:

Conclusion, Comment and Discussion:

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-Give detail explanation about what you've learned in the experiment

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-Explain the possible errors and their reasons in the experiment

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Questions

1. Derive Eq.4 and Eq. 5 from Eq. 6 in the theoretical experiment guide.

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2. In the system we have adjusted according to the 30° , 45° , 75° angles of the inclined plane, list the glider speeds released at the same height from the largest to the smallest.(a_{30° , a_{45° , a_{75°)

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Signature:

Experiment Name: "Motion with Constant Acceleration in Inclined Plane"

Objective:

- Experimentally examining motion with constant acceleration in one dimension and on an inclined plane.
- Calculation and compare of the experimental acceleration a_{Exp} and theoretical acceleration a_{Theo} .

Keywords:

Constant acceleration, Inclined Plane, slope, time, distance

Theoretical Information :

Inclined planes are called surfaces that stand at a certain angle θ with the horizontal. Figure 1 shows an object with mass m_1 placed on an inclined plane and the forces acting on this object.

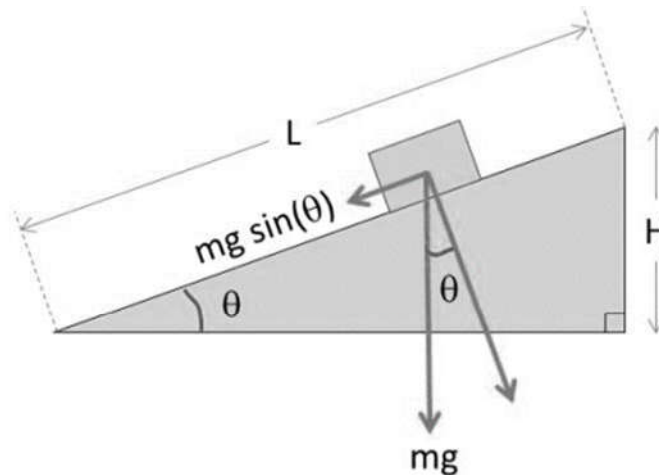


Figure 1. Diagram of a mass m on an inclined plane. The tangential component of the force of gravity accelerates the mass down the incline and is equal to $mg \sin(\theta)$.

Assuming the inclined plane is frictionless, more than one force acting on an object of mass m_1 will be as shown in Figure 1.

All objects near the earth have a uniform downward acceleration due to gravity. By tilting the air track by a small amount, you effectively "reduce" the acceleration due to gravity. This idea was first employed by Galileo, who used an inclined plane rather than tilted air track.

Suppose g is the (downward) acceleration due to gravity. When an object of mass m is placed on an inclined plane, the downward force mg on the object due to gravity may be resolved into two components (see Figure 1). One component is normal (perpendicular) to the plane, and one is tangent to (along) the plane. The component of the force of gravity that is normal to the plane is balanced by the reaction force of the plane on the object (in this case

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Hooke's Law

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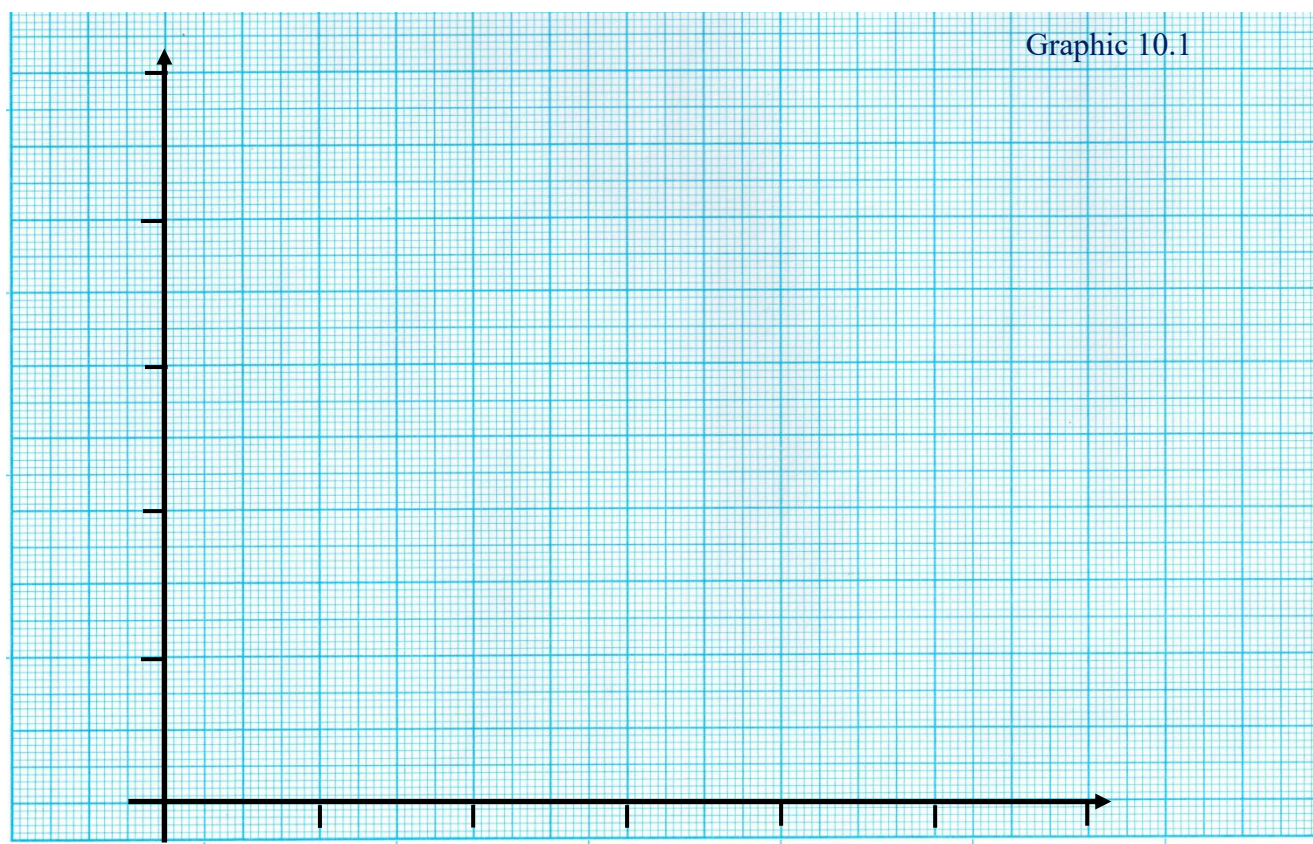
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Table 10.1: Spring length L as a function of the suspended weights.

m (gr)	$F=mg$ (gr.cm/s ²)	x_i^{thin} (cm)	$\Delta L_{thin} = x_i^{thin} - x_0^{thin}$ (cm)	x_i^{thick} (cm)	$\Delta L_{thick} = x_i^{thick} - x_0^{thick}$ (cm)
20					
40					
60					
80					
100					

Use the values in Table 10.1 and plot F - ΔL graphs of each spring on reserved millimetric space as x -axis *the change of length* (ΔL) and y -axis the force (F). Represent the values in the table as points on your graph.



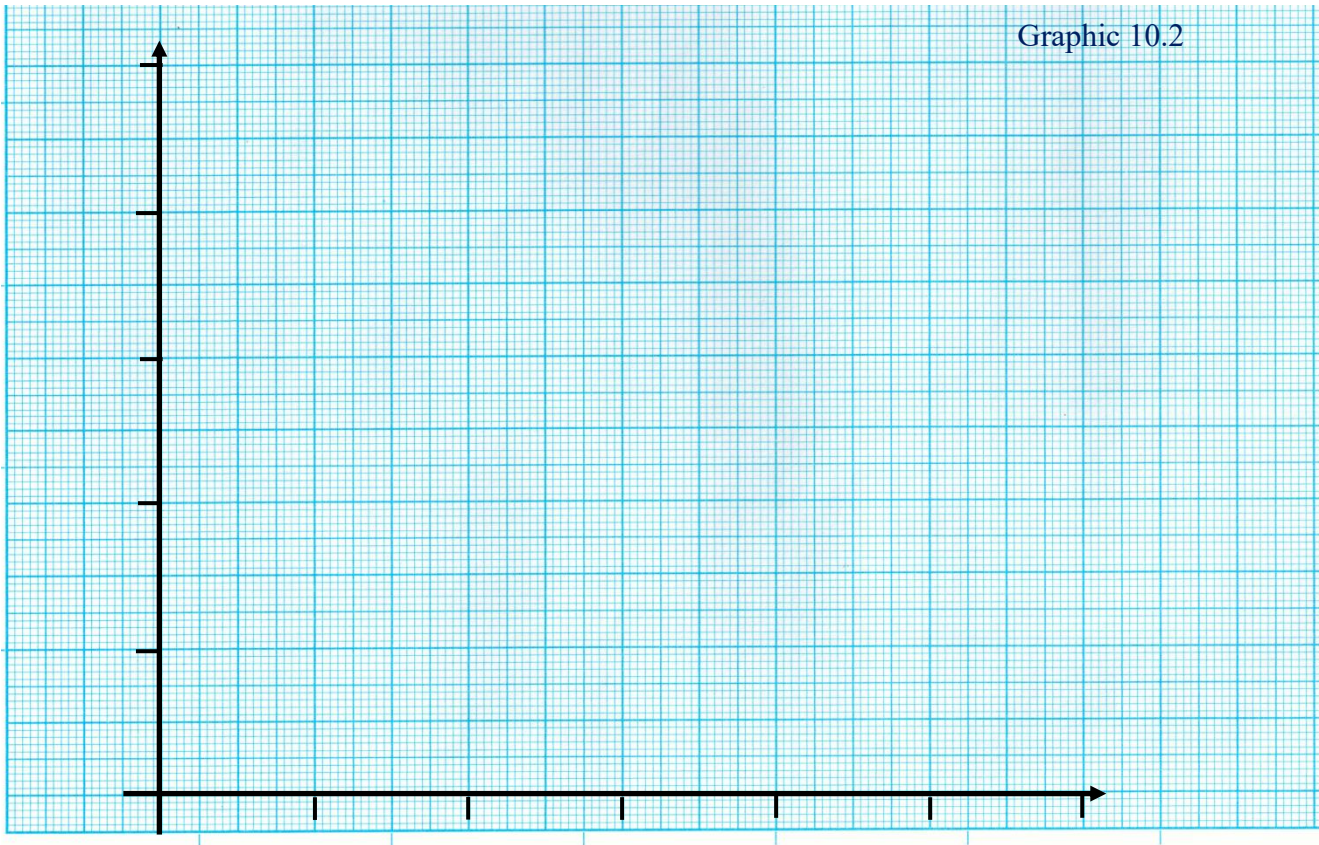
Signature:

Harmonic oscillation:

- 1. In this step, suspend the same masses on each spring in turn. Pull the mass little bit down then release. Measure the time of the oscillation of the spring to complete 10 cycles for each mass by using the stopwatch. Divide each time by 10 to find the time for one period for each mass and record the values in table 10.2.
- 2. Calculate the period of oscillation T and square of the period of oscillation T^2 and fill in Table 10.2.

Table 10.2: Period of oscillation T as function of the suspended mass.

m (gr)	Δt_{thin} (s)	$T_{thin} = \frac{\Delta t_{thin}}{10}$ (s)	T_{thin}^2 (s ²)	Δt_{thick} (s)	$T_{thick} = \frac{\Delta t_{thick}}{10}$ (s)	T_{thick}^2 (s ²)
20						
40						
60						
80						
100						



(Tips: Give detailed explanations about what you've learned in the experiment and also explain the possible errors and their reasons.)

[illegible]

Experiment No : M10

Experiment Name: Hooke's Law

Objective:

1. Determining the change of length ΔL of two helical springs with different turn diameters as a function of the gravitational force F exerted by the suspended weights.
2. Confirming Hooke's law and determining the spring constants k of the two helical springs.

Keywords: Hooke's law, spring constant, oscillation, period.

Theoretical Information:

Holding a spring in either its compressed or stretched position requires that someone or something exerts a force on the spring. This force is directly proportional to the displacement, Δx , of the spring. In turn, the spring will exert an equal and opposite force

$$F = -k\Delta x \quad 10.1$$

where k is called the “spring constant.” This is often referred to as a “restoring force” because the spring exerts a force in the direction opposite to the displacement, indicated by the negative sign. The Eq. 10.1 is known as Hooke's law.

Simple harmonic motion will occur whenever there is a restoring force that is proportional to the displacement from equilibrium, as is in Hooke's law. From Newton's second law, $F = ma$, and recognizing that the acceleration a is the second derivative of displacement with respect to time. The classical equation of motion for a one-dimensional simple harmonic oscillator with a particle of mass m attached to a spring having spring constant k is the Eq. 10.1 can be rewritten as;

$$F = -kx \Rightarrow m \frac{d^2x}{dt^2} = -kx \quad 10.2$$

which can be written in the standard wave equation form;

$$m \frac{d^2x}{dt^2} + kx = 0 \quad 10.3$$

The Eq. 10.3 is a linear second-order differential equation that can be solved by the standard method of factoring and integrating. The resulting solution to Eq. 10.3 is

$$x(t) = x_0 \sin(\omega t + \phi) \quad 10.4$$

where x_0 is the amplitude of oscillation and

$$\omega = \sqrt{\frac{k}{m}} \quad 10.5$$

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20					
40					
60					
80					
100					

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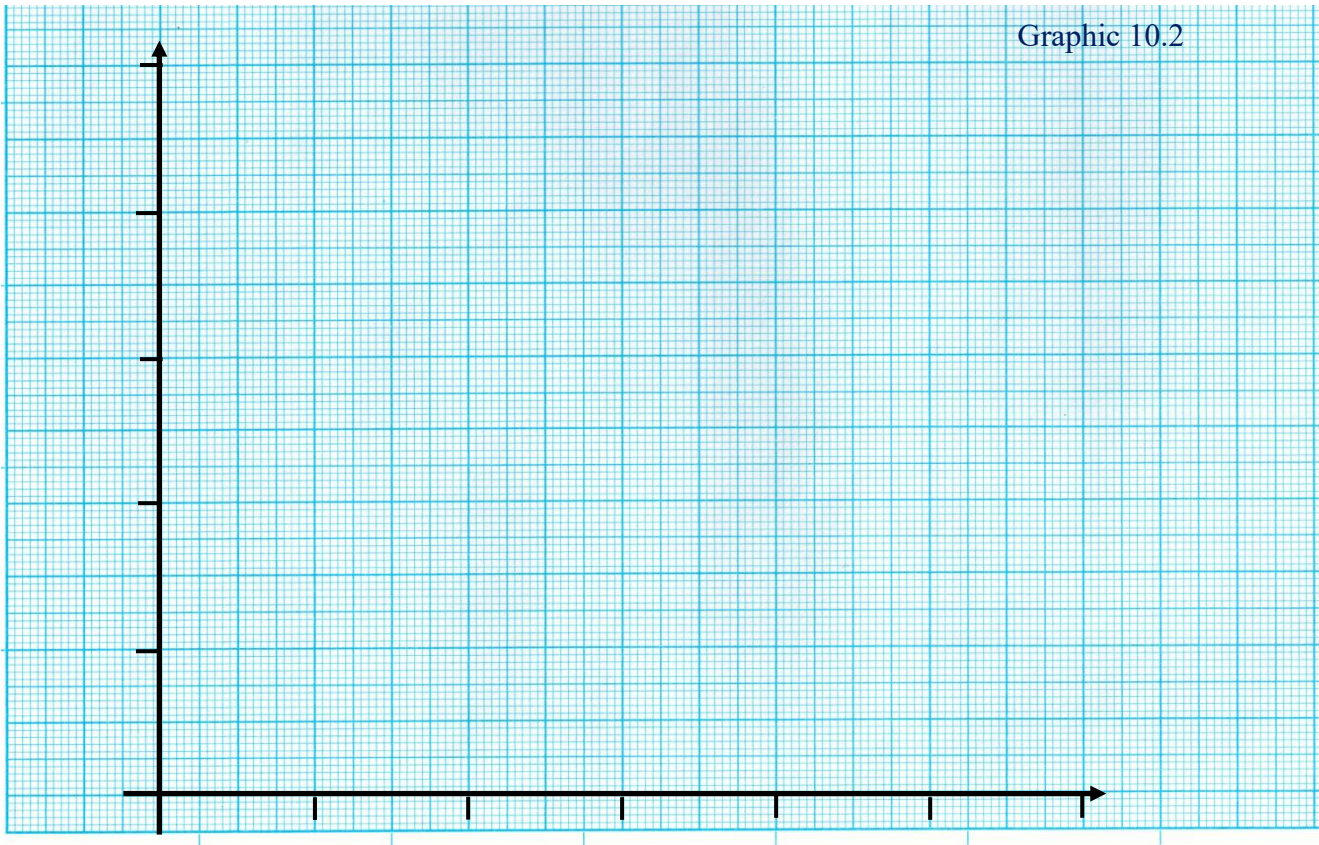
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20						
40						
60						
80						
100						



[illegible]

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