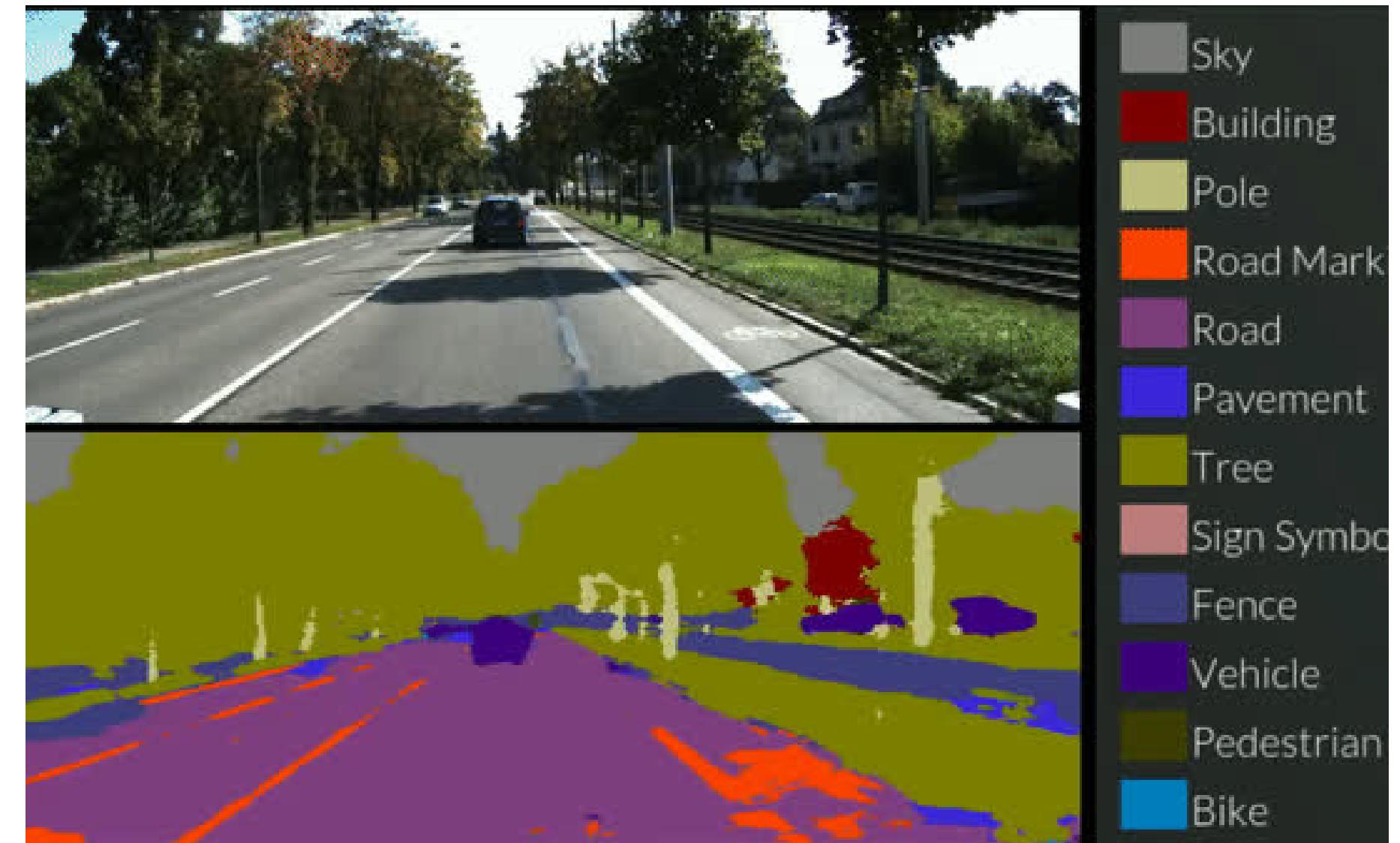
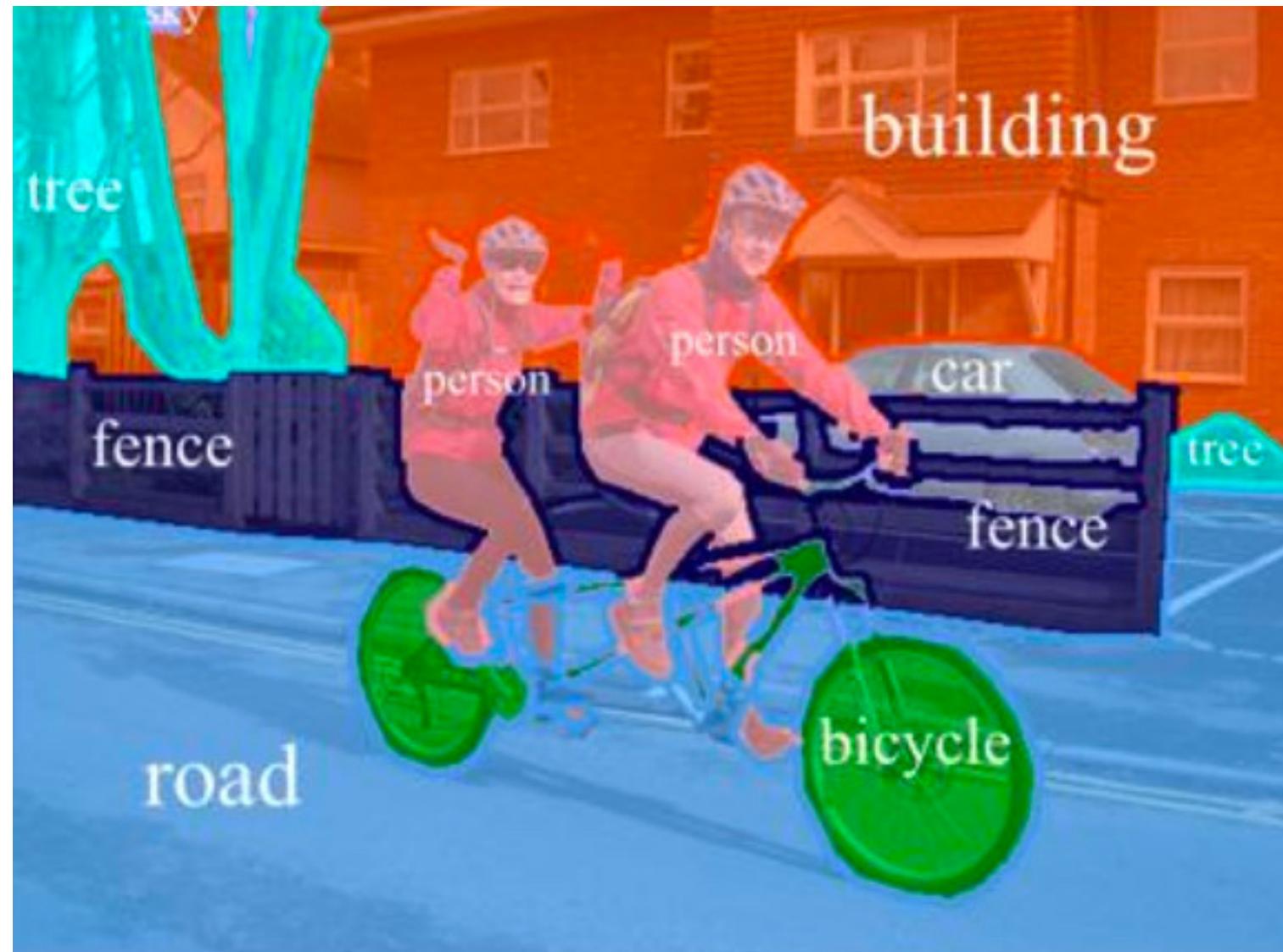


# Image Segmentation

Bigger Then Data (BTD)

- Afnan Alzahrani (Speaker)
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# What is image segmentation?



One of the most important operations in Computer Vision  
semantic image segmentation is the task of labelling each pixel of the image into a predefined set of classes.



Input

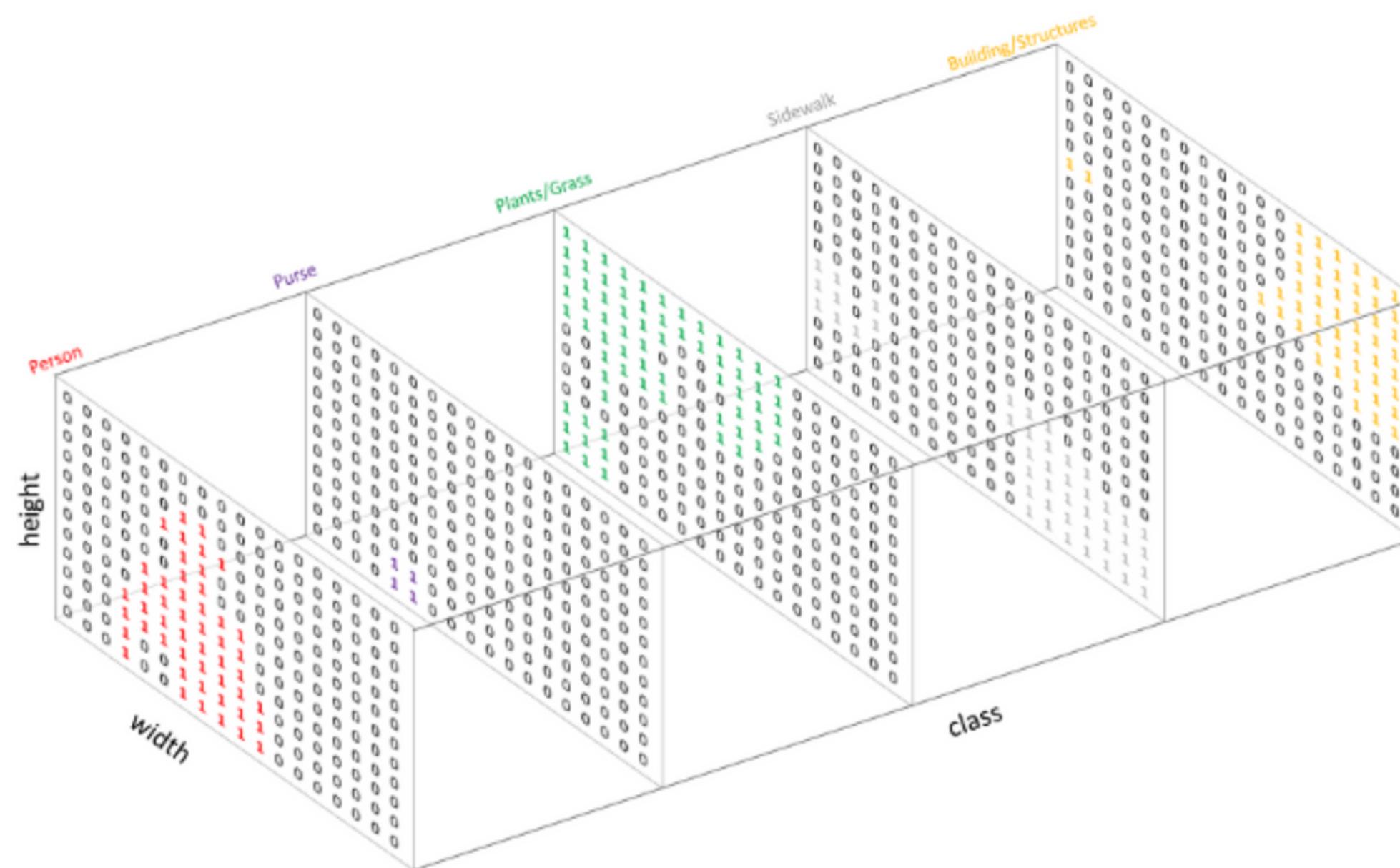
segmented →

- 1: Person
- 2: Purse
- 3: Plants/Grass
- 4: Sidewalk
- 5: Building/Structures

3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3										
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3									
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3									
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3								
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3								
3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3								
5	5	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3							
4	4	3	4	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4							
4	4	3	4	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4					
4	4	4	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4				
3	3	3	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4			
3	3	3	1	2	2	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4		
3	3	3	1	2	2	1	1	1	1	1	1	1	1	1	1	1	1	1	1	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4

Semantic Labels

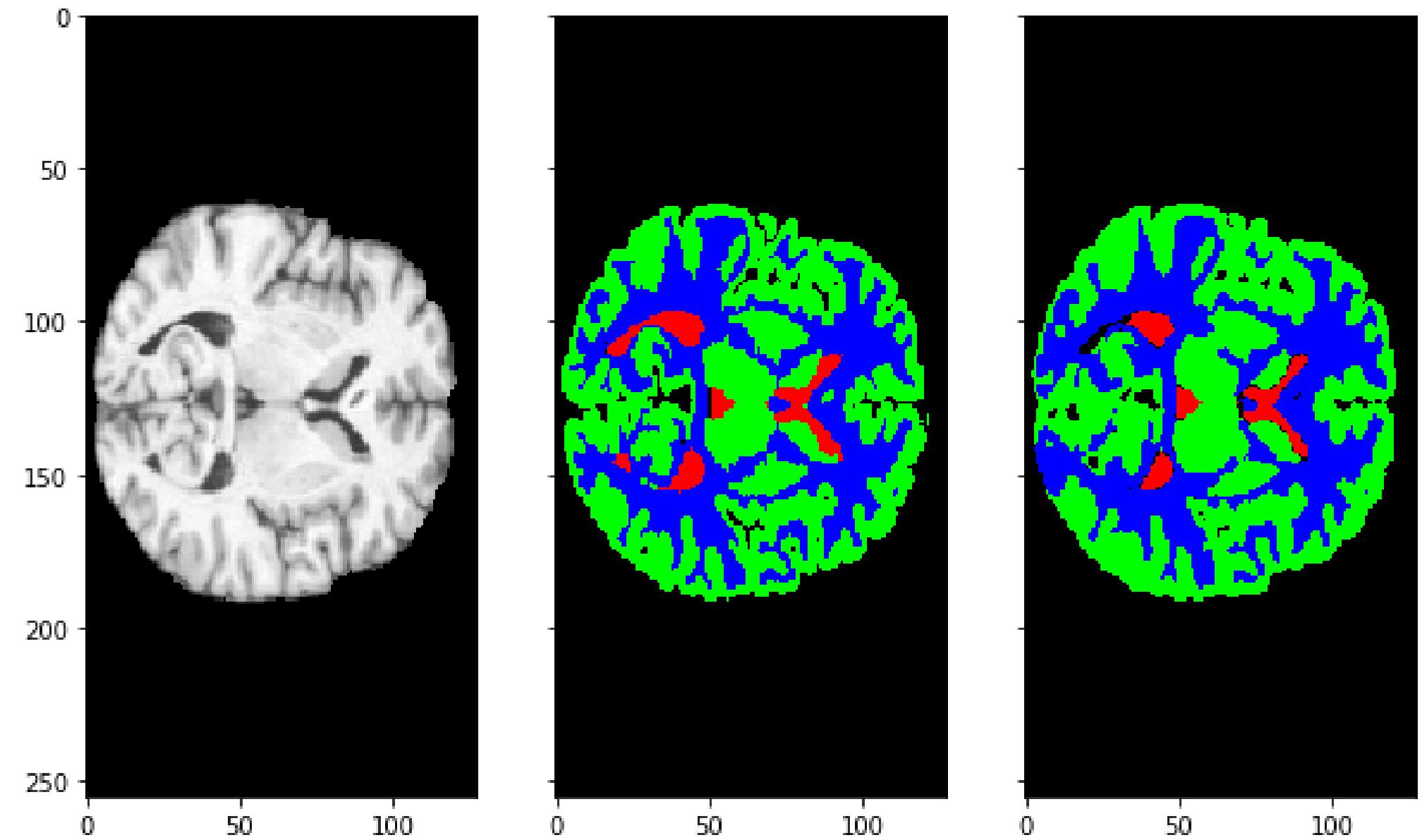
# One-hot Encoded Segmentation Map



# Applications

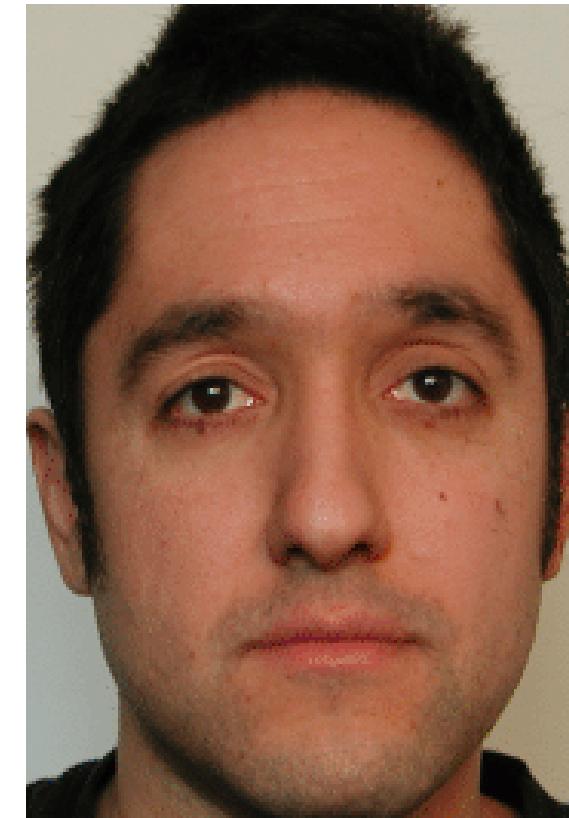
## ■ Bio-medical image analysis

For example, models can be used to segment CT scans to detect tumours



# Applications

Facial segmentation



skin
hair
eyes
nose
mouth
background



# Computer vision using OpenCV

```
In [10]: import matplotlib.pyplot as plt
```

```
In [11]: import cv2
import numpy as np

with open('ENET/enet-classes.txt') as f:
    classes = f.read().splitlines()

with open('ENET/enet-colors.txt') as f:
    colors = f.read().splitlines()
    colors = [np.array(col.split(',')) .astype('int') for col in colors]
    colors = np.array(colors,dtype='uint8')

model = cv2.dnn.readNet('ENET/enet-model.net')
cap = cv2.VideoCapture('telegram_video.mp4')
```

```
In [12]: if not cap.isOpened():
    cap = cv2.VideoCapture(0)

if not cap.isOpened():
    raise IOError('Cannot Open Video File')
```

```
In [13]: classes
```

```
Out [13]: ['Unlabeled',
'Road',
'Sidewalk',
'Building',
'Wall',
'Fence',
'Pole',
'TrafficLight',
'TrafficSign',
'Vegetation',
'Terrain',
'Sky',
'Person',
'Rider',
'Car',
'Truck',
'Bus',
'Train',
'Motorcycle',
'Bicycle']
```

In [14]: cap

Out[14]: <VideoCapture 0x7f8e0694fb0>

In [15]: success,img = cap.read()

In [16]: type(img)

Out[16]: numpy.ndarray

In [17]: plt.imshow(img)

Out[17]: <matplotlib.image.AxesImage at 0x7f8e08d81250>



In [18]: model

Out[18]: <dnn\_Net 0x7f8e0920ba10>

In [19]:

```
while True:
    success,img = cap.read()
    # Using size (1024,512) as ENET was trained on (1024,512) input size images.
    blob = cv2.dnn.blobFromImage(img,1/255,(1024,512),0,True,False)
    model.setInput(blob)
    output = model.forward()

    (numClasses, height, width) = output.shape[1:4]

    classMap = np.argmax(output[0], axis=0)
    mask = colors[classMap]
    mask = cv2.resize(mask, (img.shape[1], img.shape[0]), interpolation=cv2.INTER_NEAREST)
    output = ((0.3 * img) + (0.7 * mask)).astype("uint8")
    cv2.imshow('Output',output)
    cv2.imshow('Input',img)
    if cv2.waitKey(1) & 0xff==ord('q'):
        break
```

# Thank You !

Source:

<https://medium.com/analytics-vidhya/introduction-to-semantic-image-segmentation-856cda5e5de8>