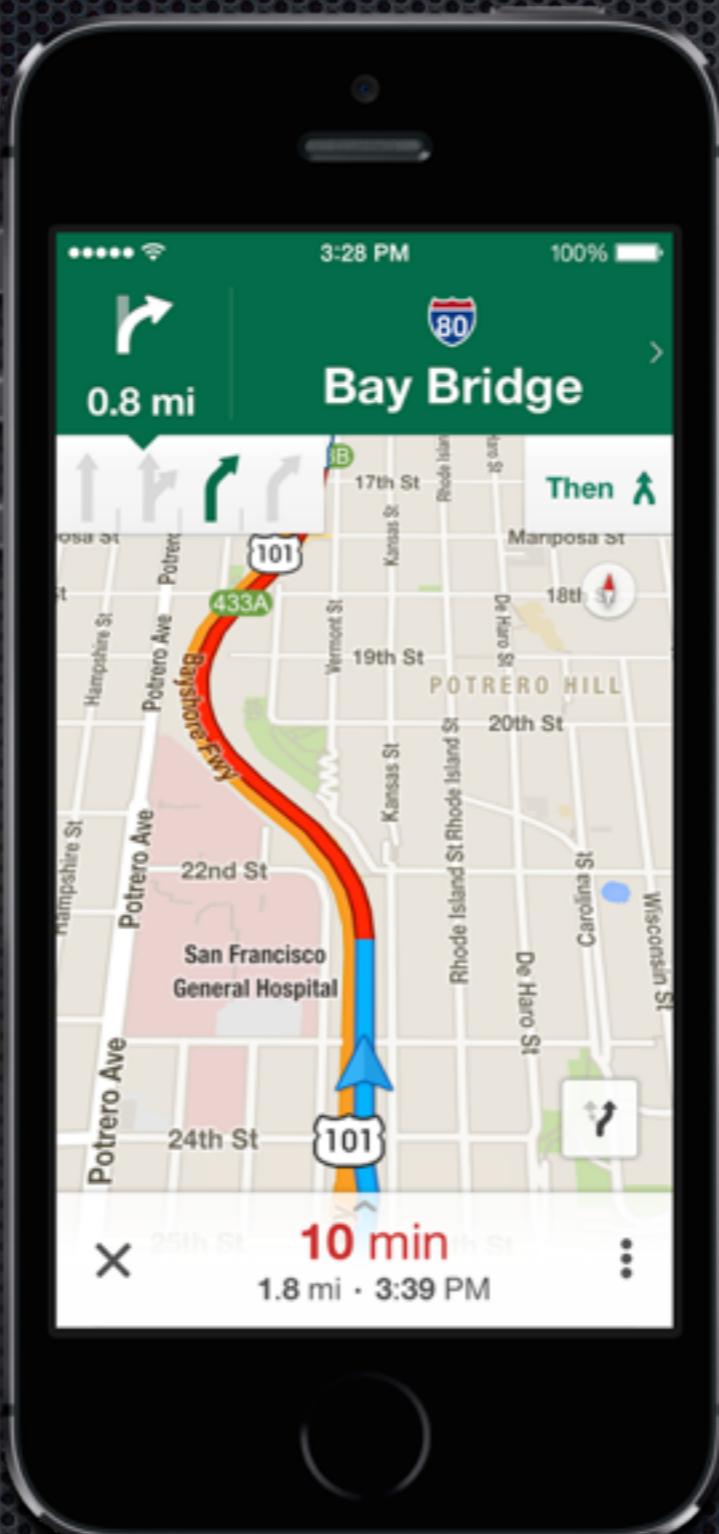


# **Experiences with eNav: A Low-power Vehicular Navigation System**

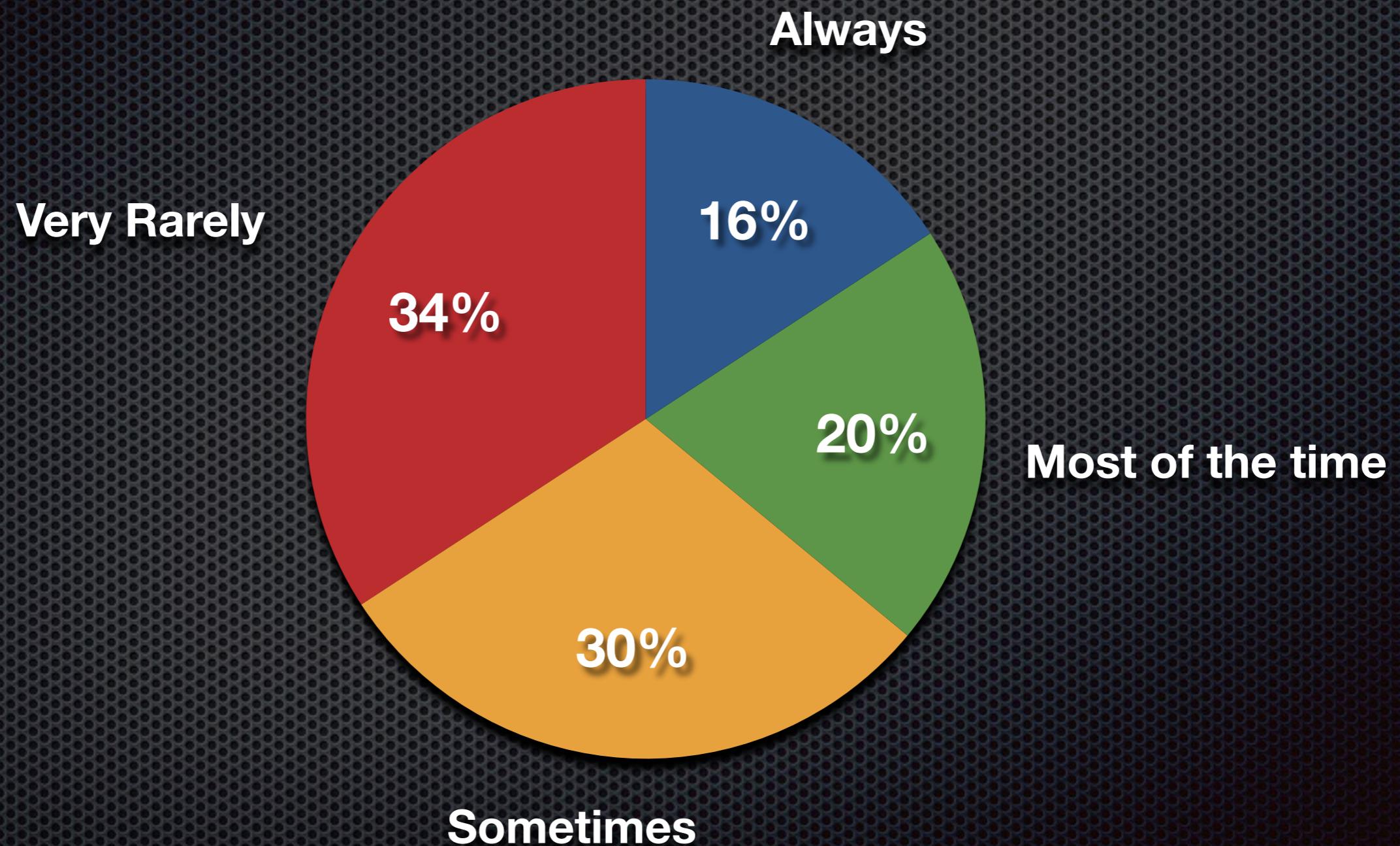
*Shaohan Hu, Lu Su, Shen Li, Shiguang Wang, Chenji Pan, Siyu Gu, Md Tanvir Amin, Hengchang Liu, Suman Nath, Romit Roy Choudhury, Tarek F. Abdelzaher*



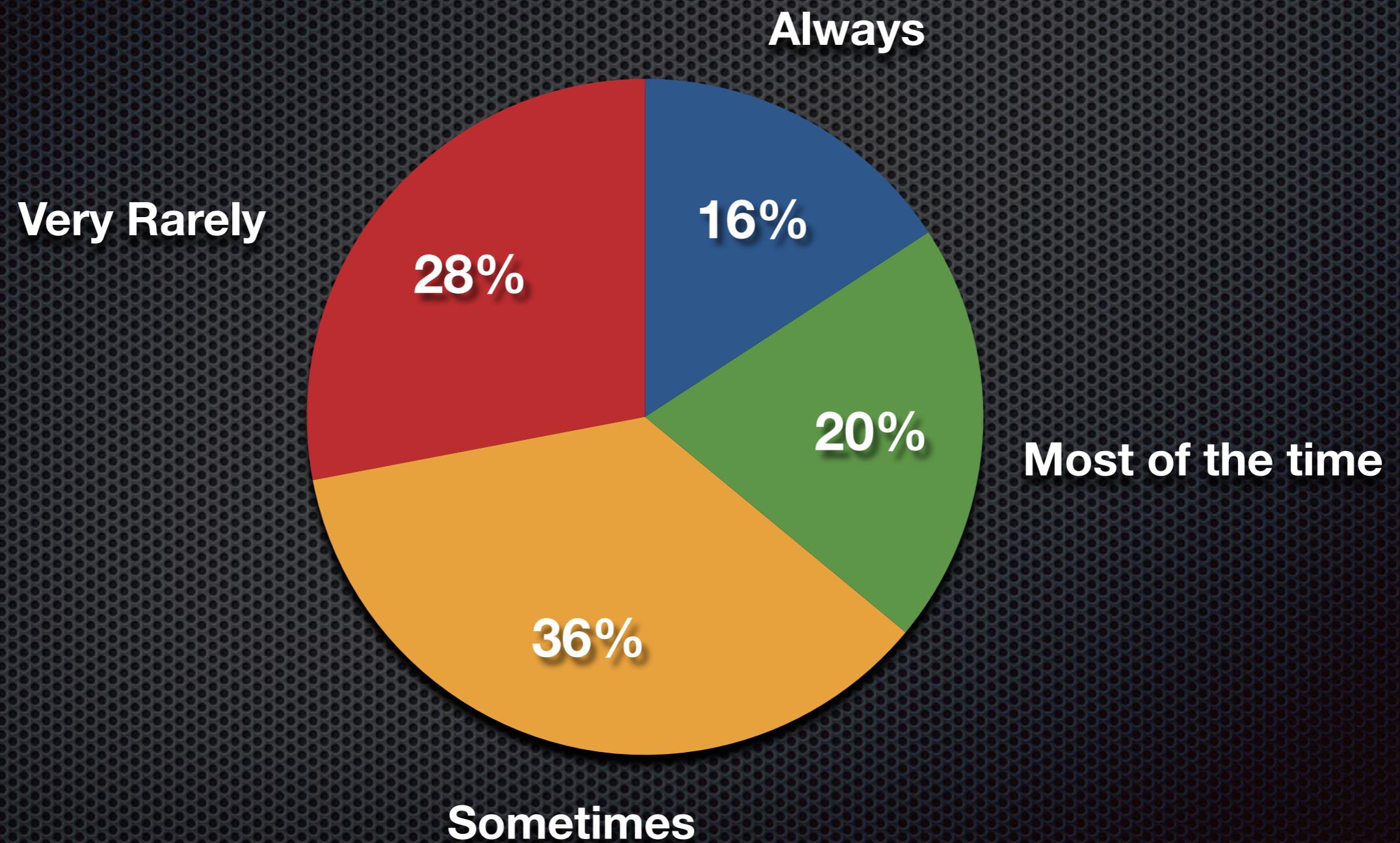


# Keeping Charger in Car?

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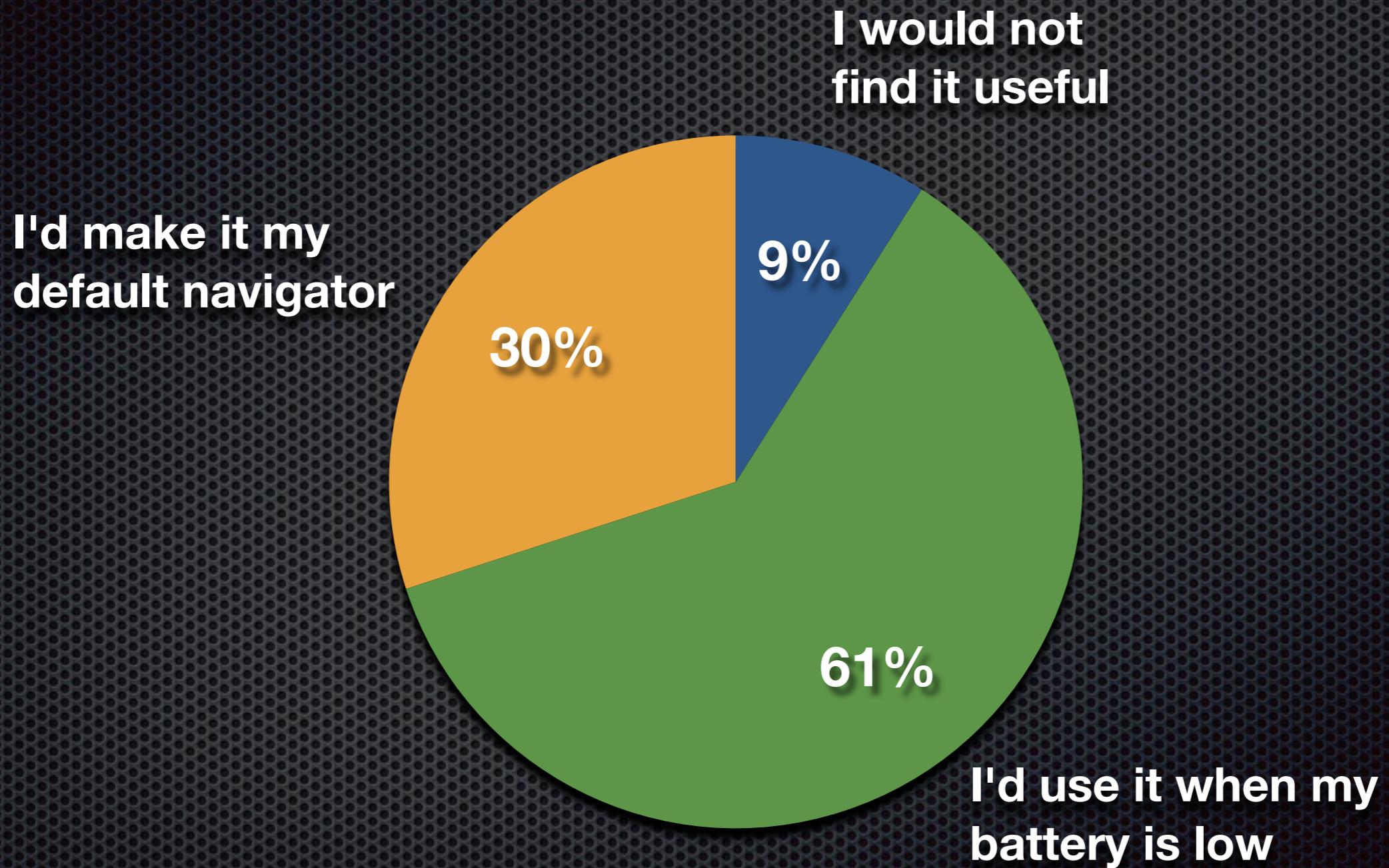


# Plug-in Phone during Navigation?

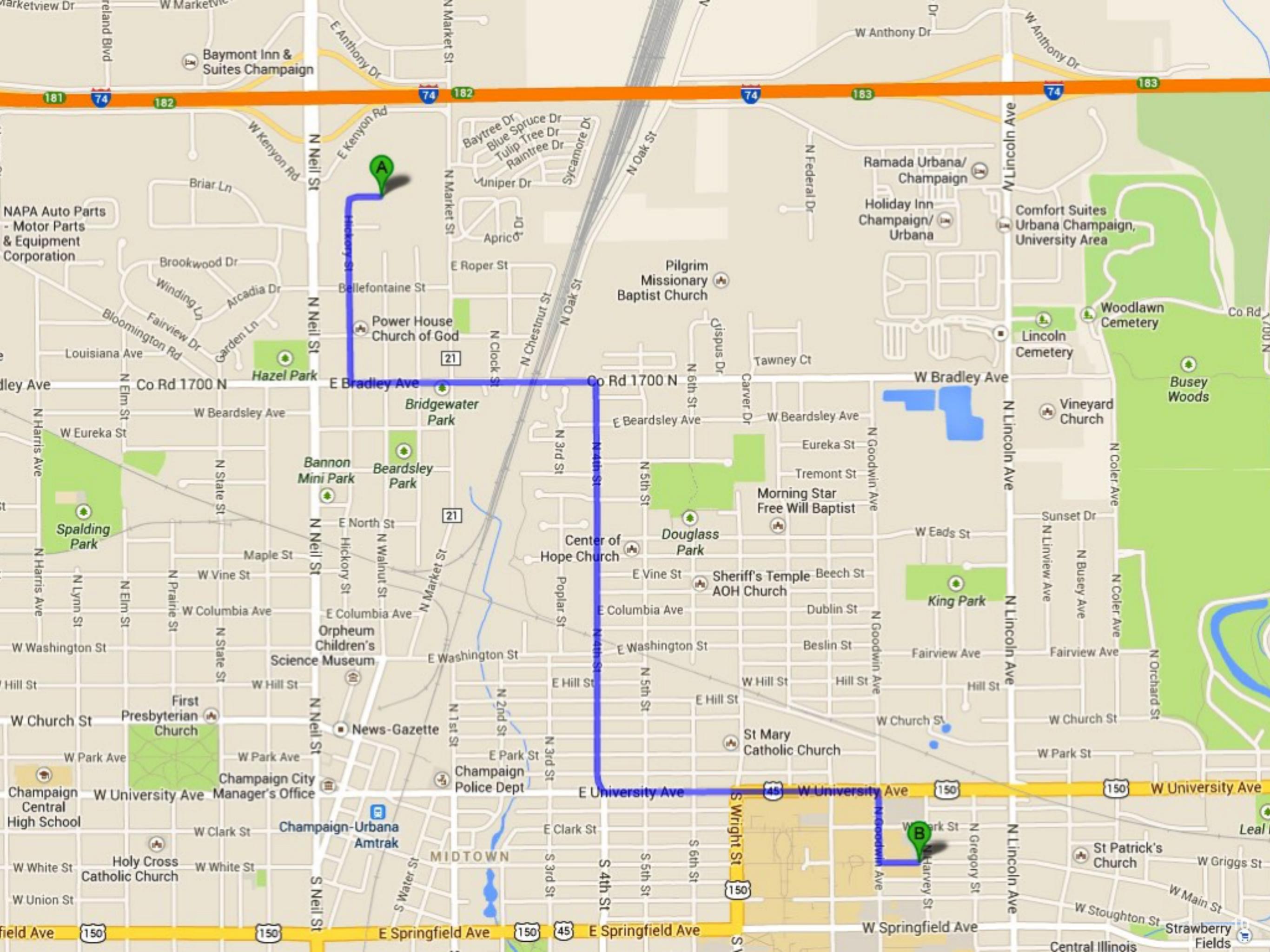


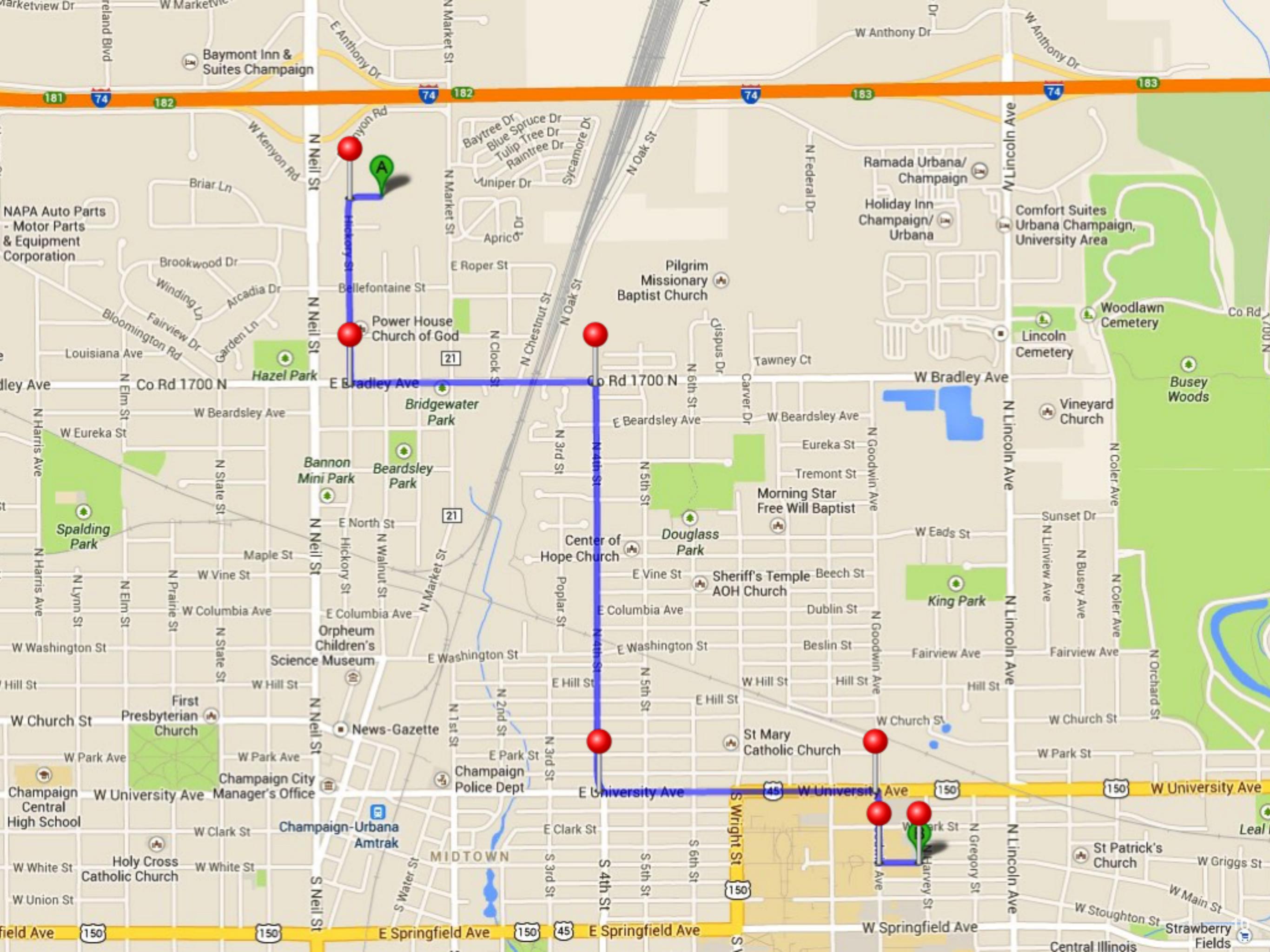
# Energy-Efficient Navigator: Useful?

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# Intuition





# Navigator Design Sketch

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- GPS - **accurate localization** only when approaching way-points

# Navigator Design Sketch

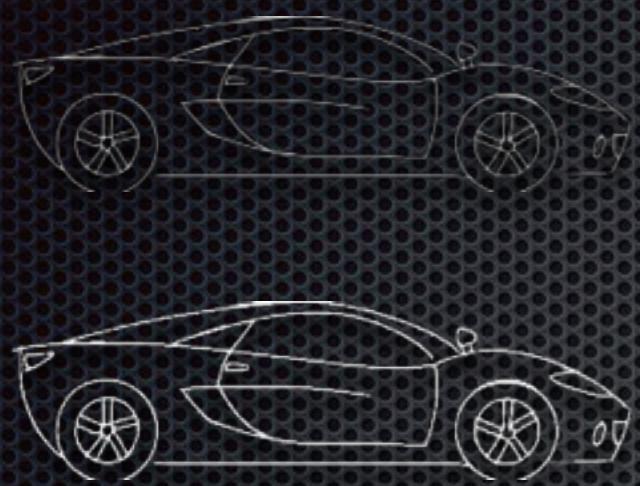
- GPS - **accurate localization** only when approaching way-points
- ACC - **roughly estimation** driving progress

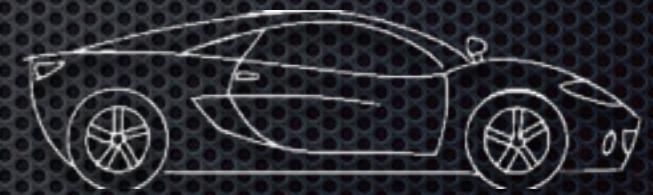
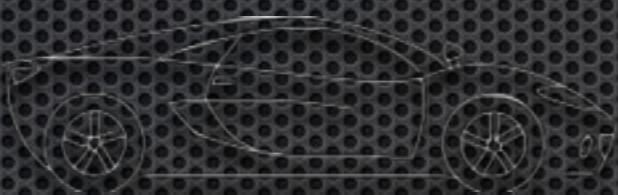
# Navigator Design Sketch

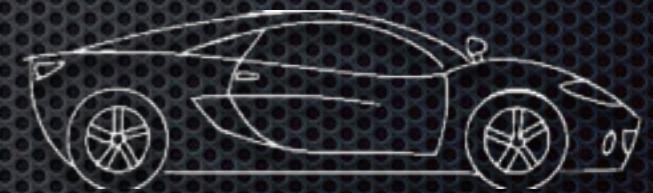
- GPS - **accurate localization** only when approaching way-points
- ACC - **roughly estimation** driving progress
- Under-estimation results in way-point misses

# Navigator Design Sketch

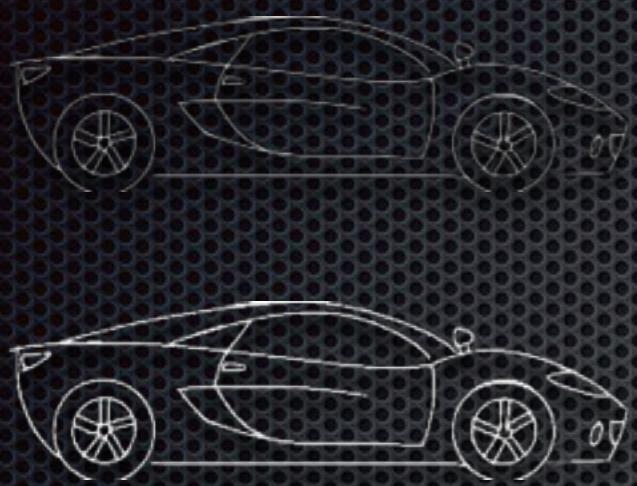
- GPS - **accurate localization** only when approaching way-points
- ACC - **roughly estimation** driving progress
- Under-estimation results in way-point misses
- We want **over-estimation**

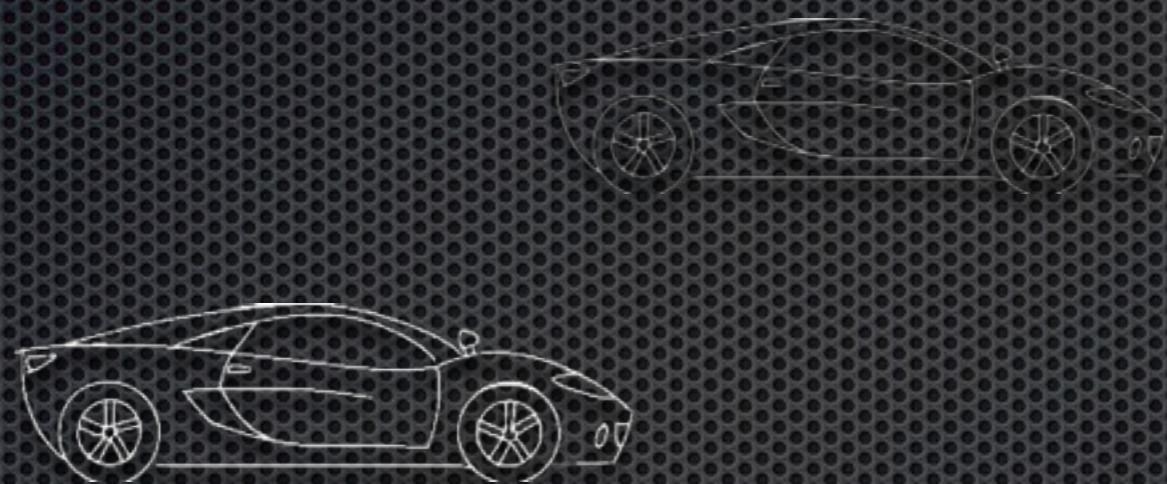


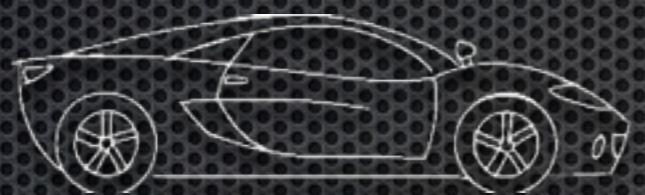




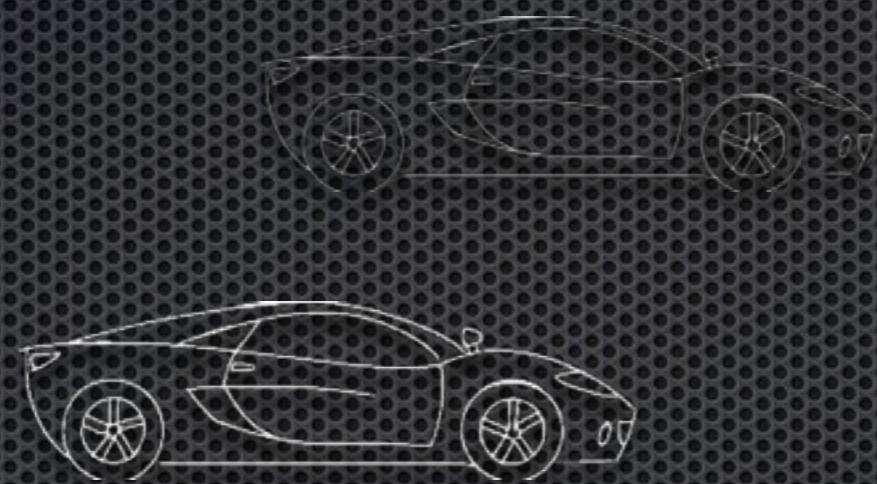
missed :(

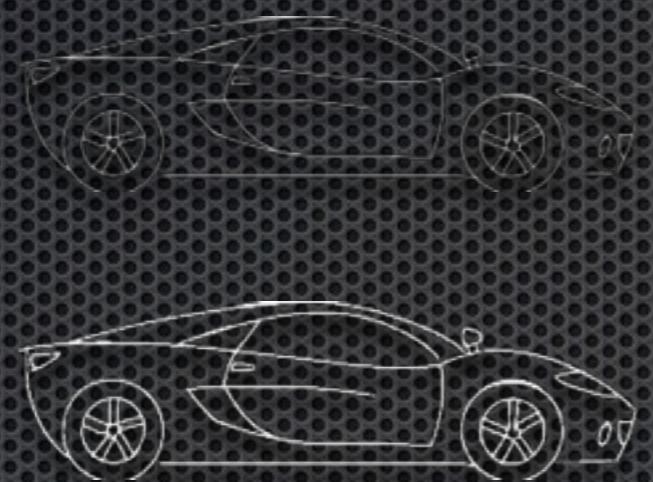


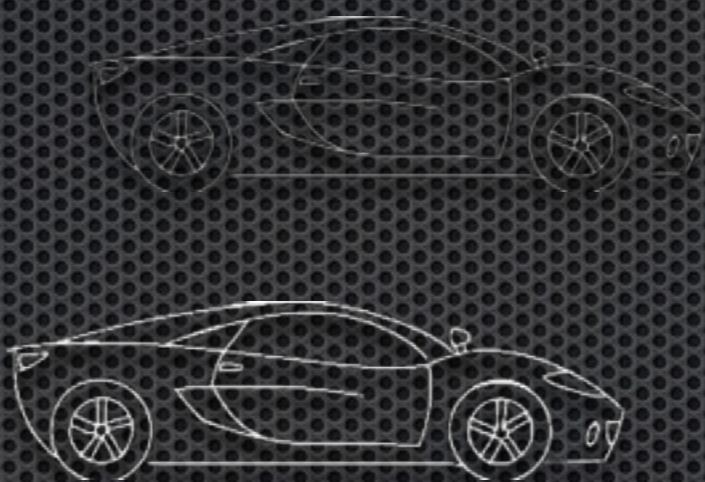


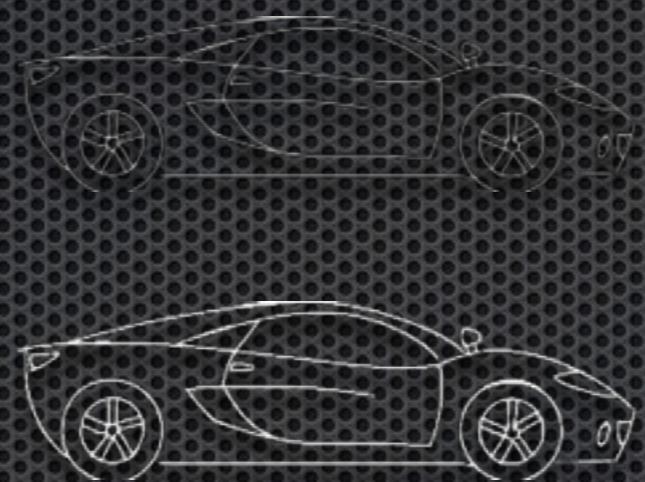


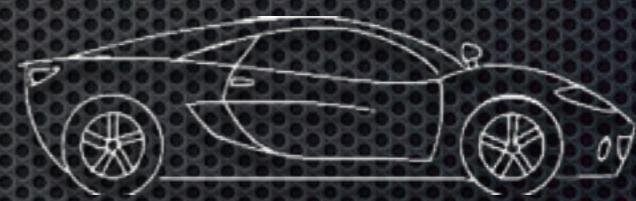
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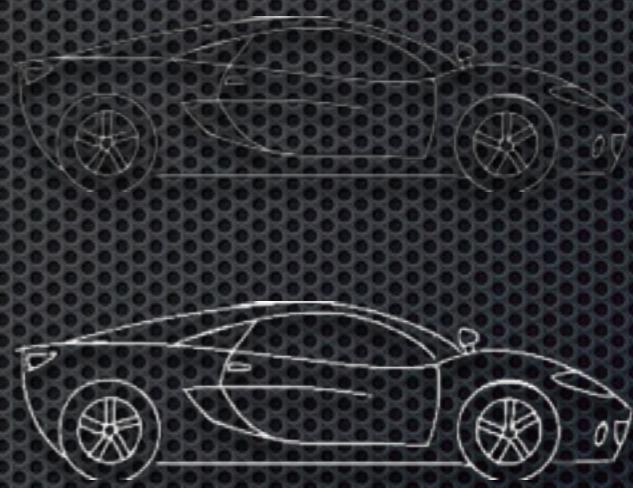






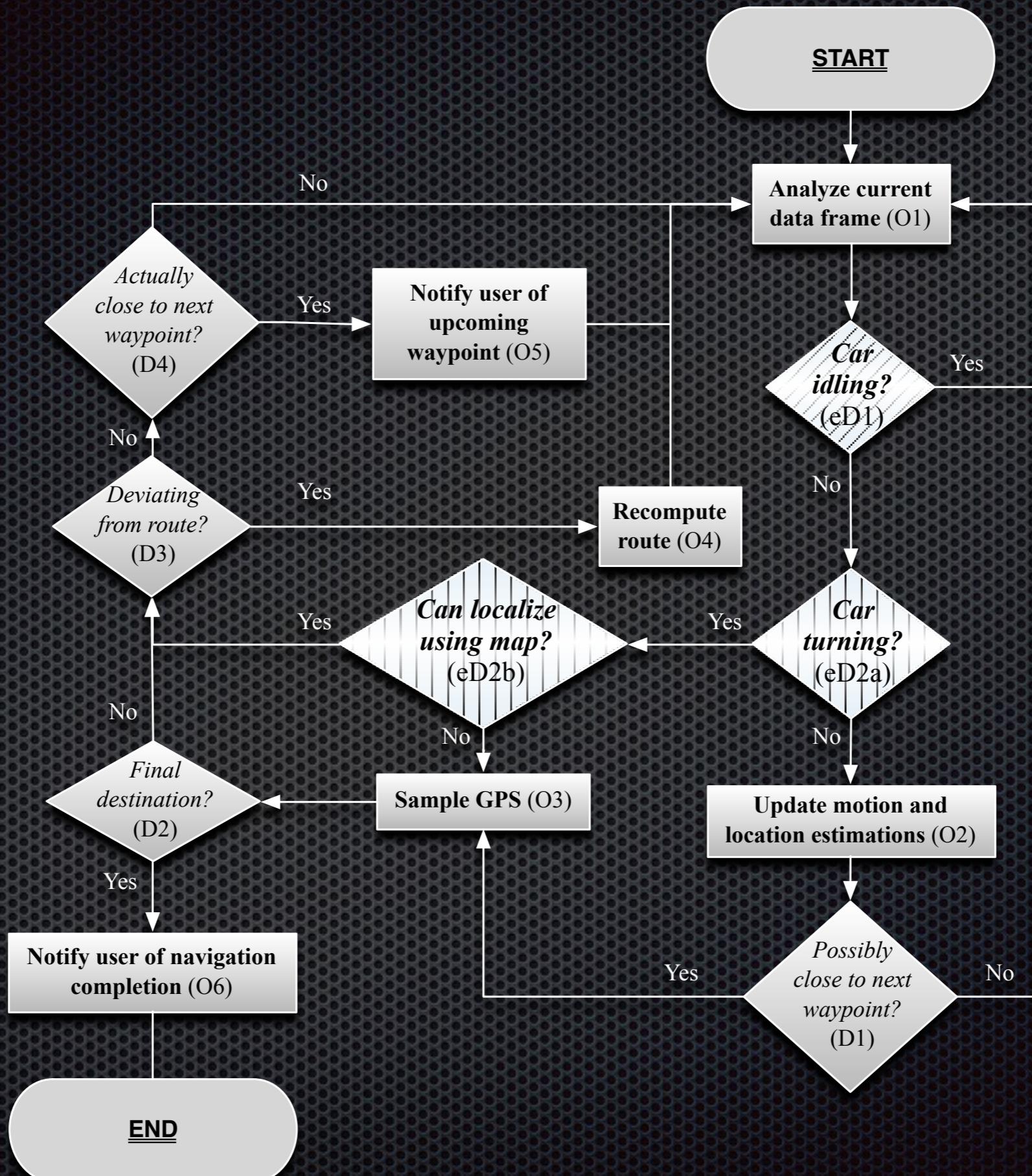






# Also, In Practice...

- PCA-based driving direction extraction
- Car-turning detection
- Car-idling detection

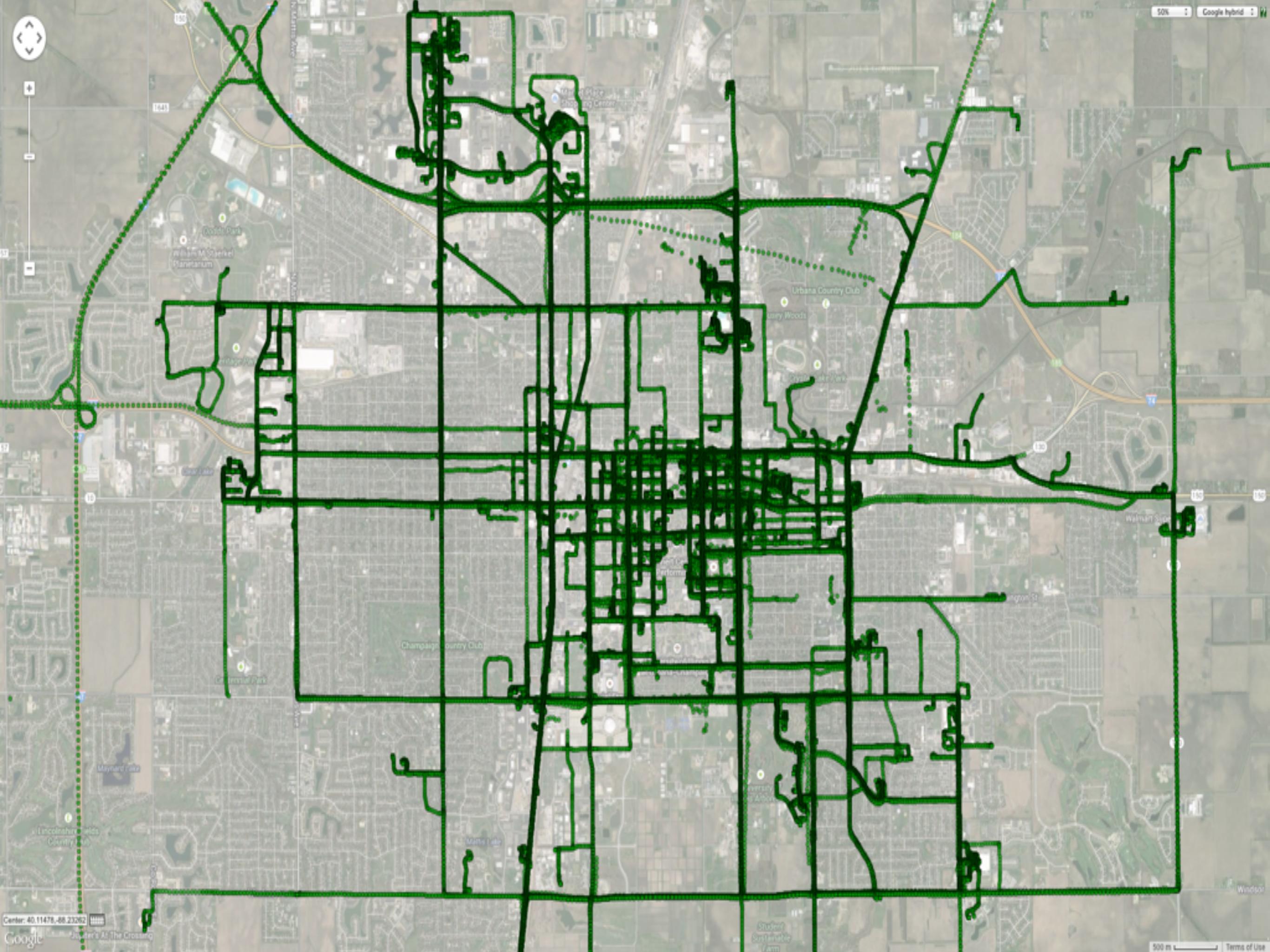


# User Study

- 33 external volunteer participants
- Various road/traffic/weather/time-of-day conditions
  - urban, rural
  - rush hour, quiet hour
  - daytime, nighttime
  - sunny, rainy, snowy

# Phase I - Trace Analysis

- Participants asked to drive as they wished
- GPS+ACC traces logged by vehicle-resident phones
- 2 months total, 3 weeks per participant
- 6,000 km driving data



Center: 40.11478,-88.23262

Google

500 m Terms of Use



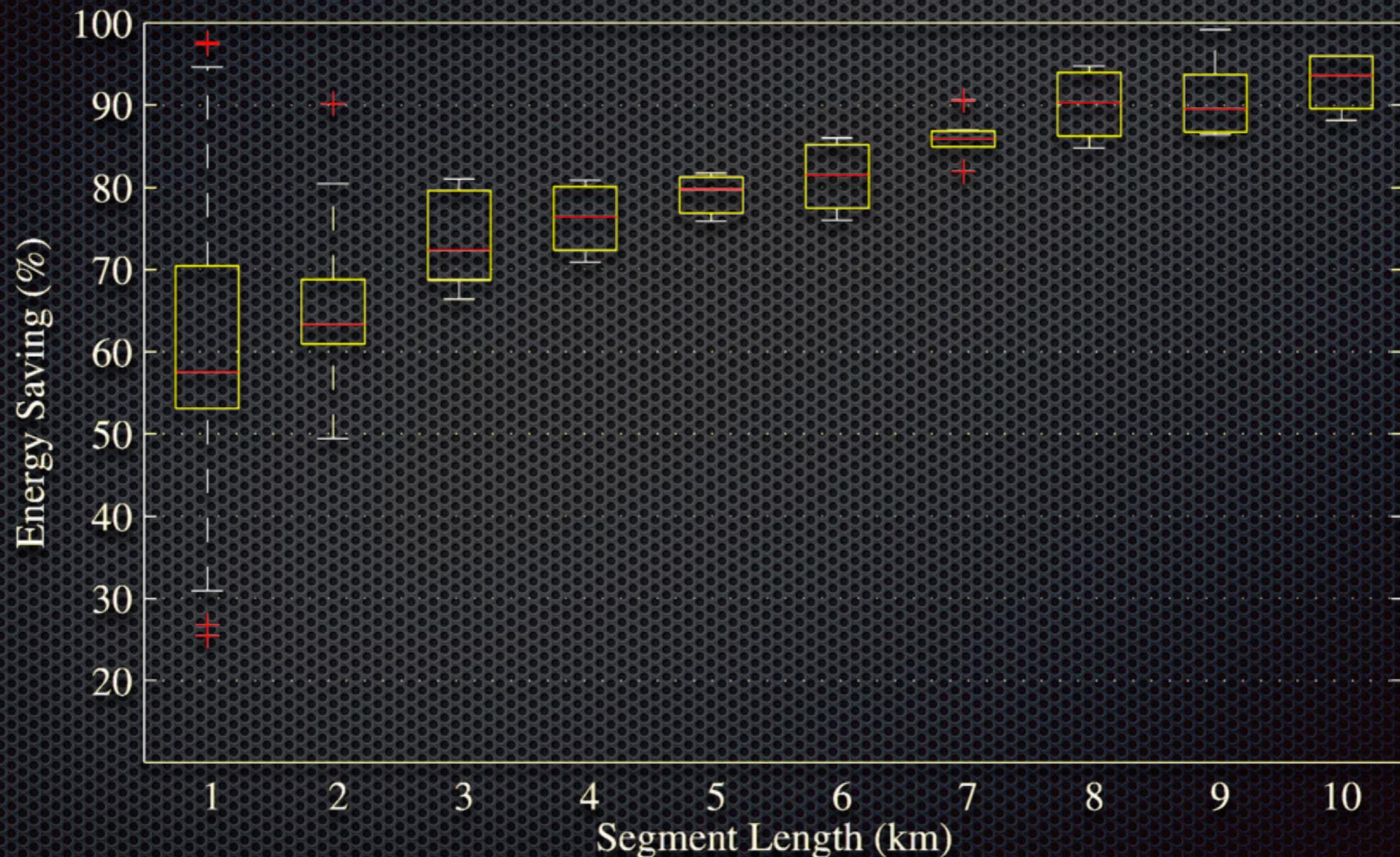


0 way-point misses

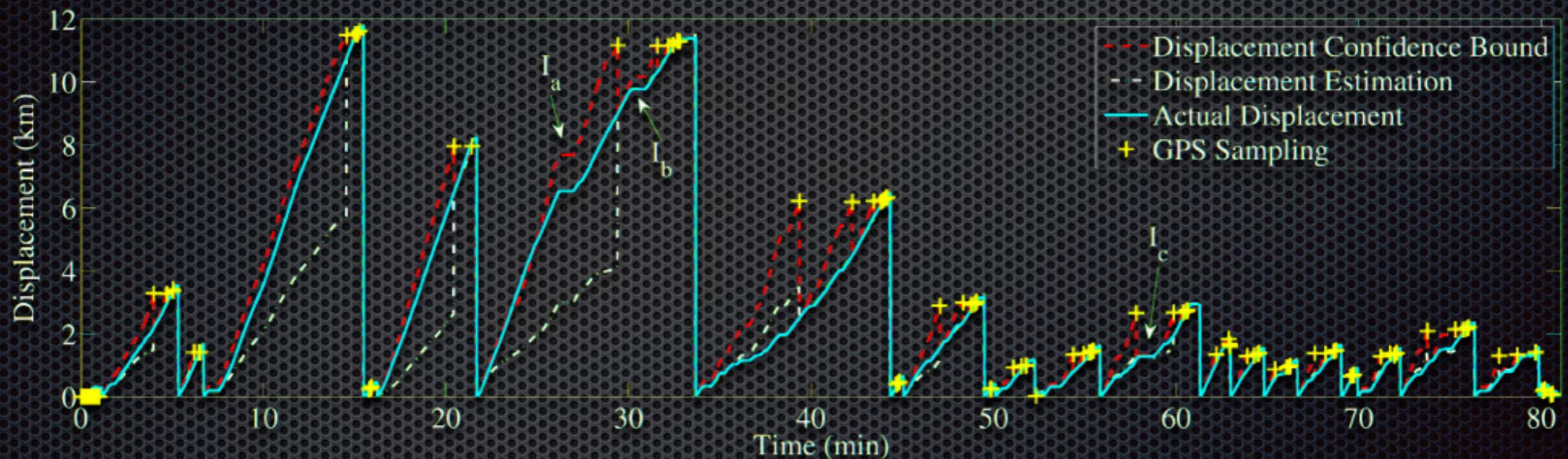
# What if: simply down-sample GPS?

- Sampling period: 1s -> **83s**
- Missing **83.2%** waypoints!

# Energy Savings Break-down



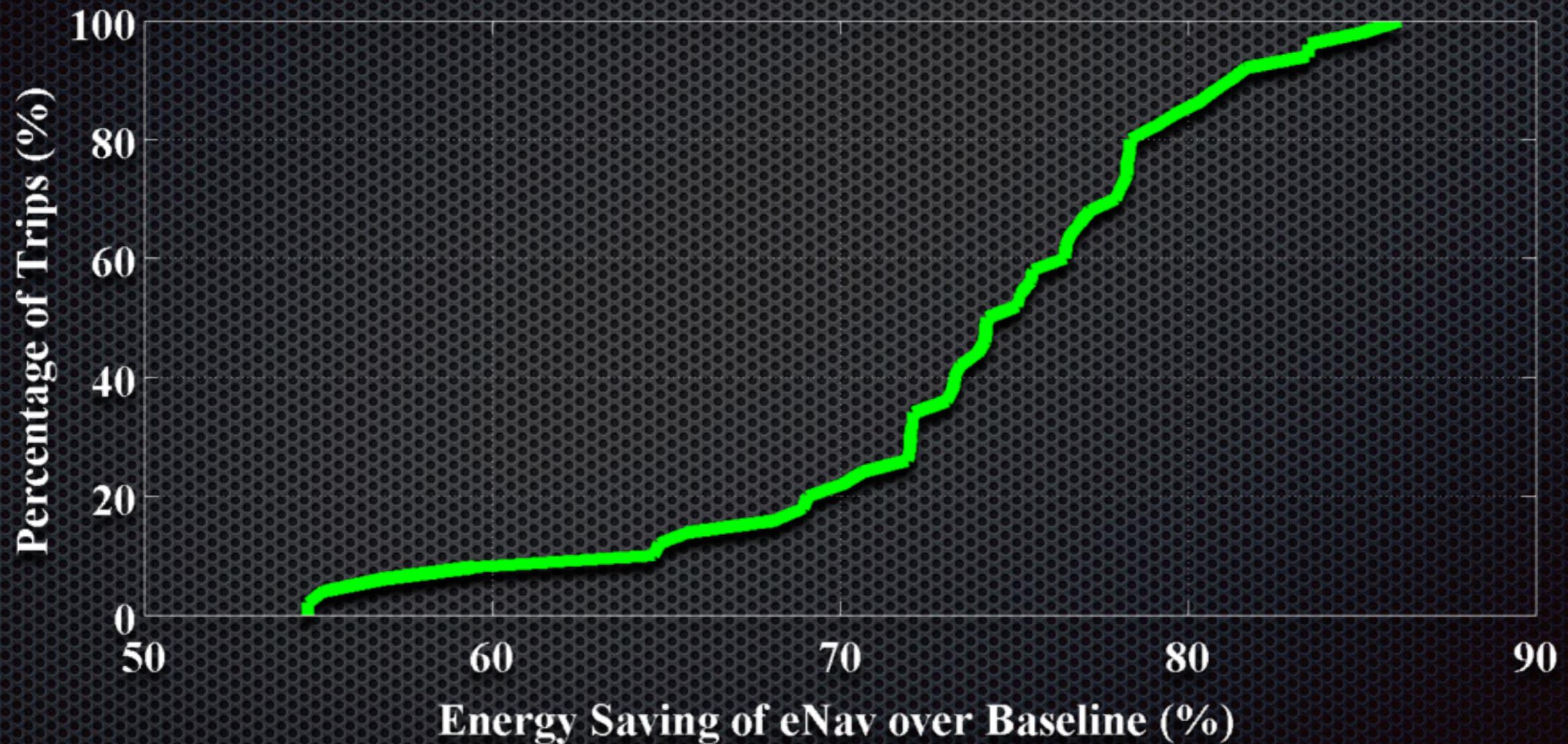
# An Example Trace



# Phase II - eNav Navigation

- Participants asked to drive w/ eNav for navigation
- 3 routes (with strange destinations) per participant
- 2,000 km

# Energy Savings E-CDF



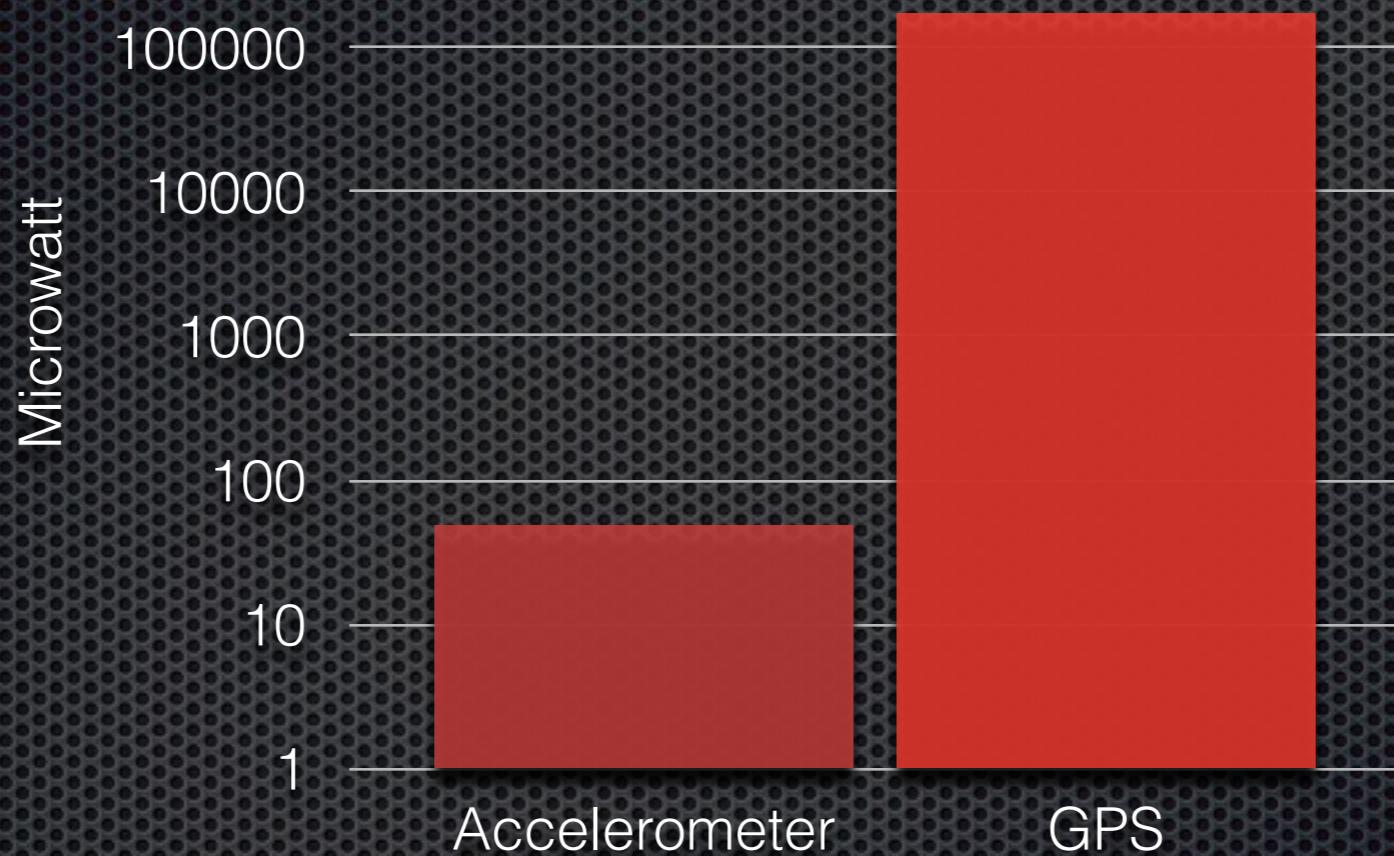
*“It’s hard to tell the difference  
between your service and real GPS!”*

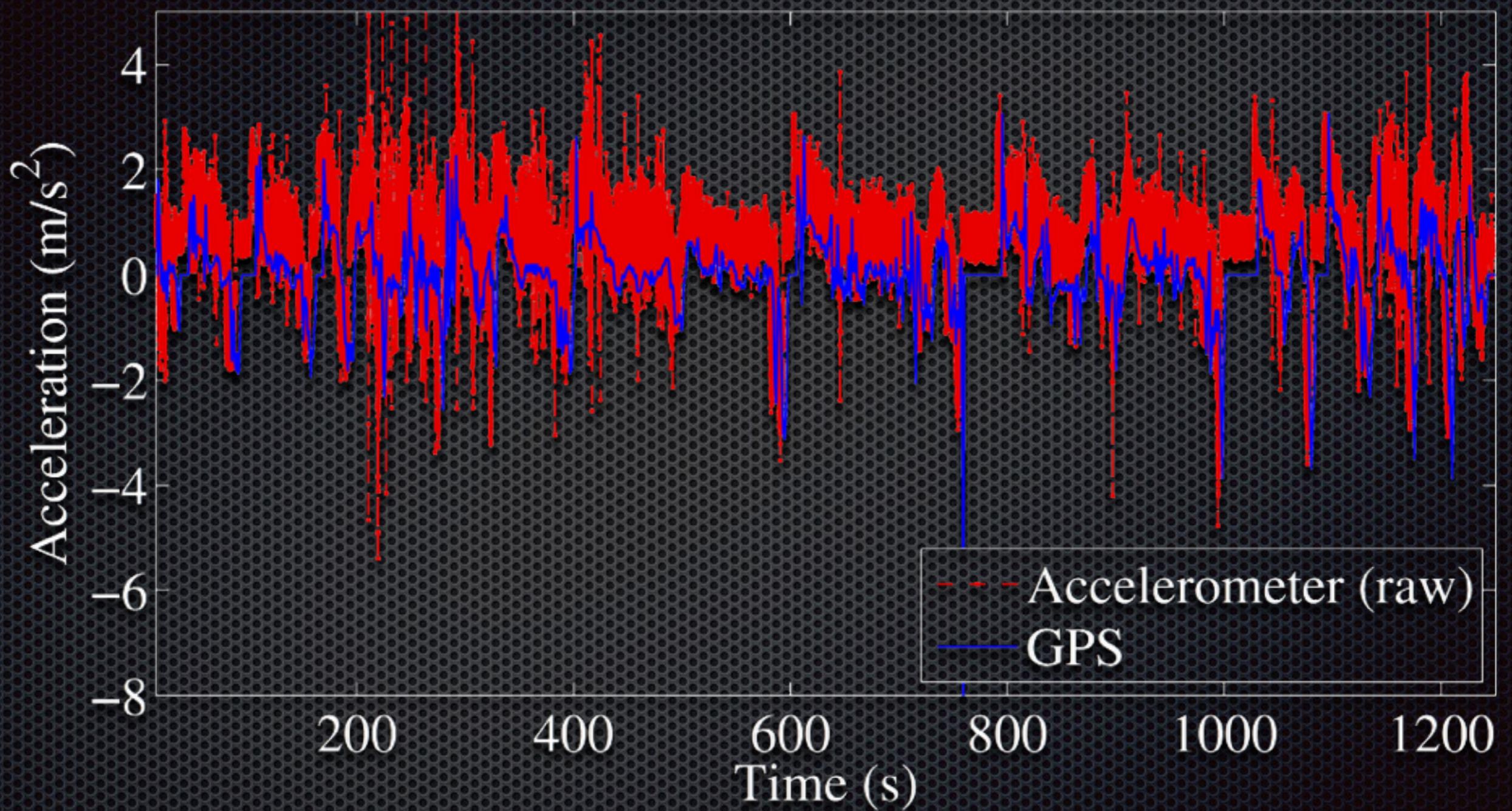
Thanks

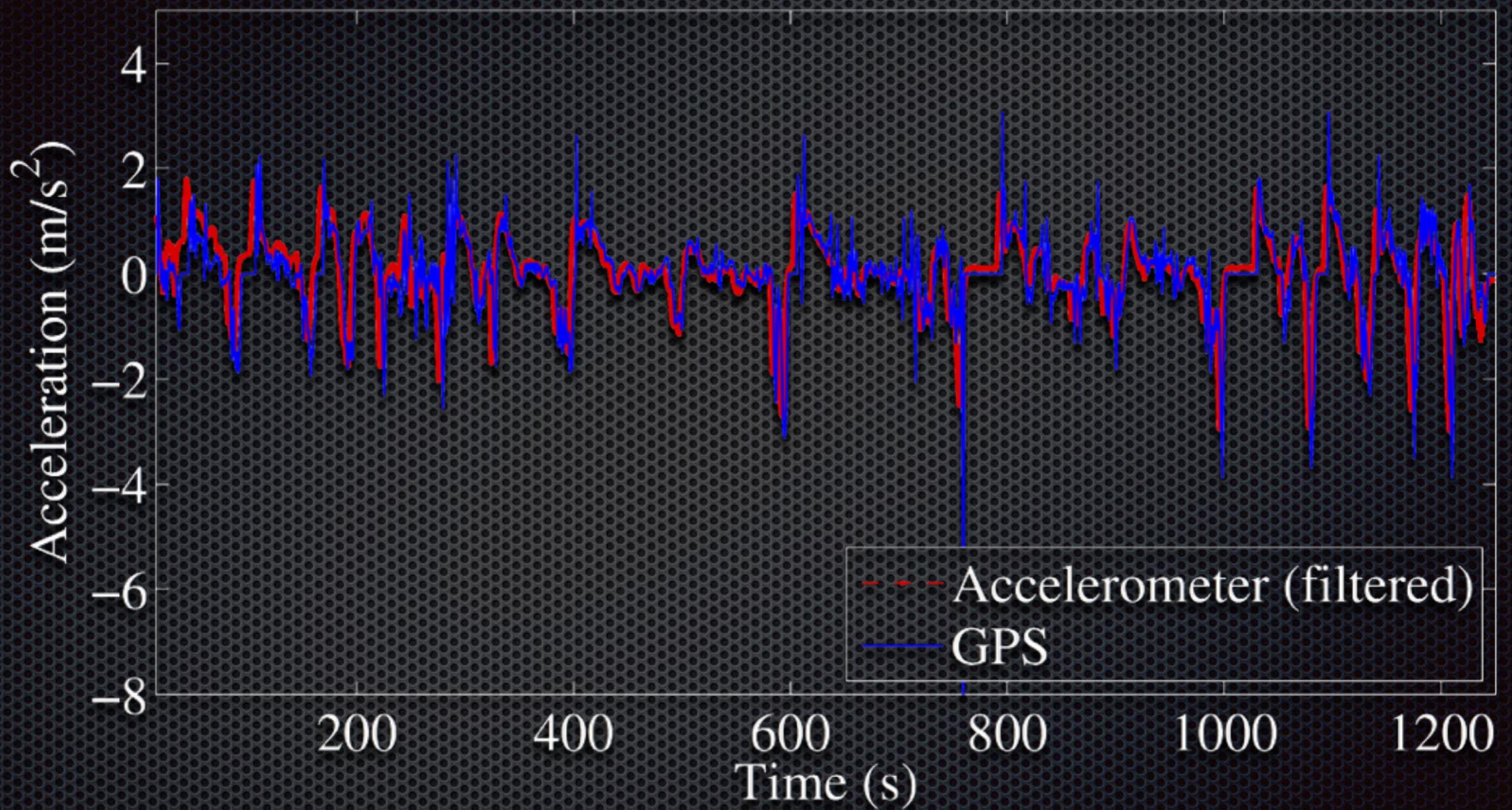


# backups

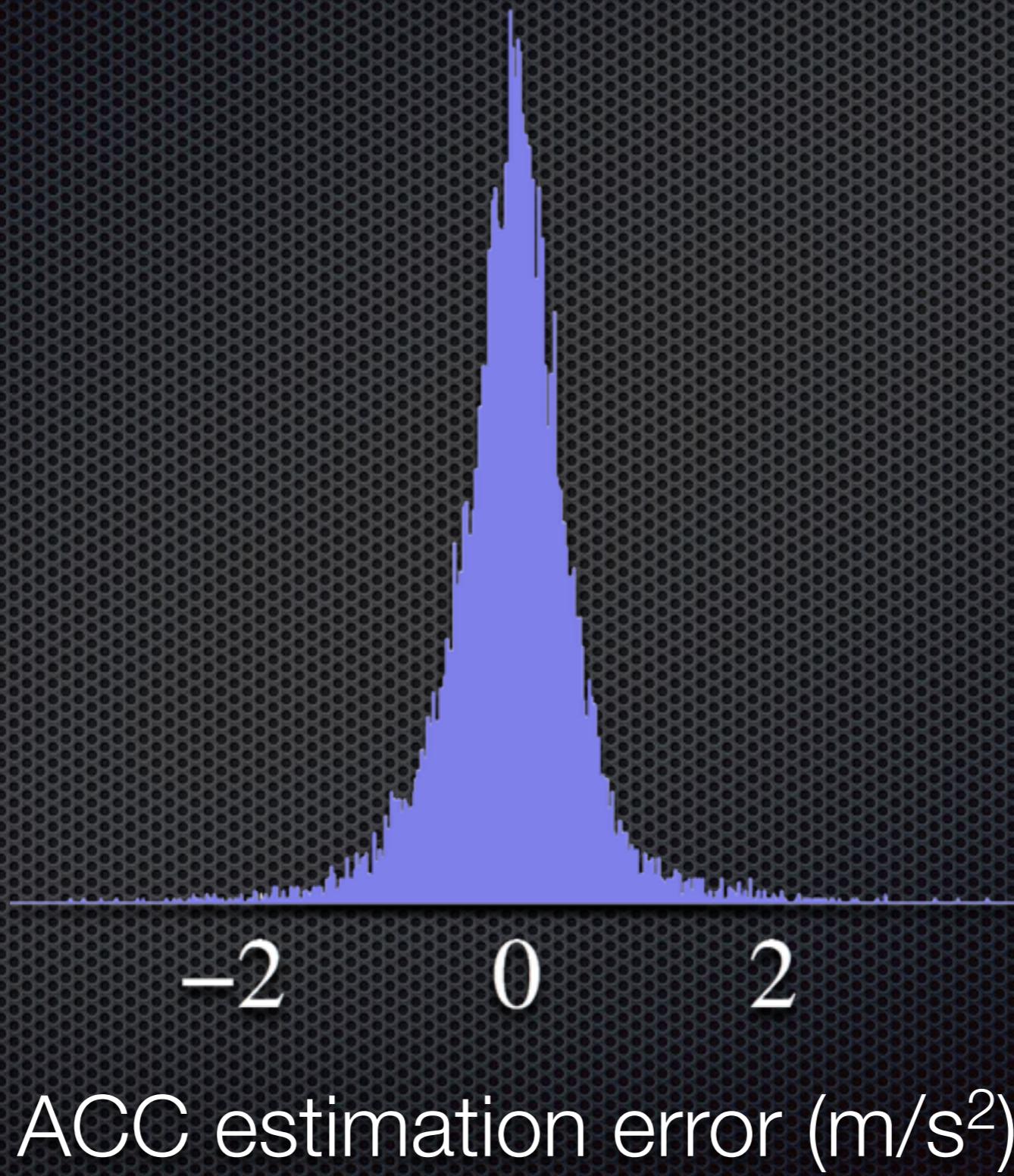
# Accelerometer?







# Acc Estimation Error



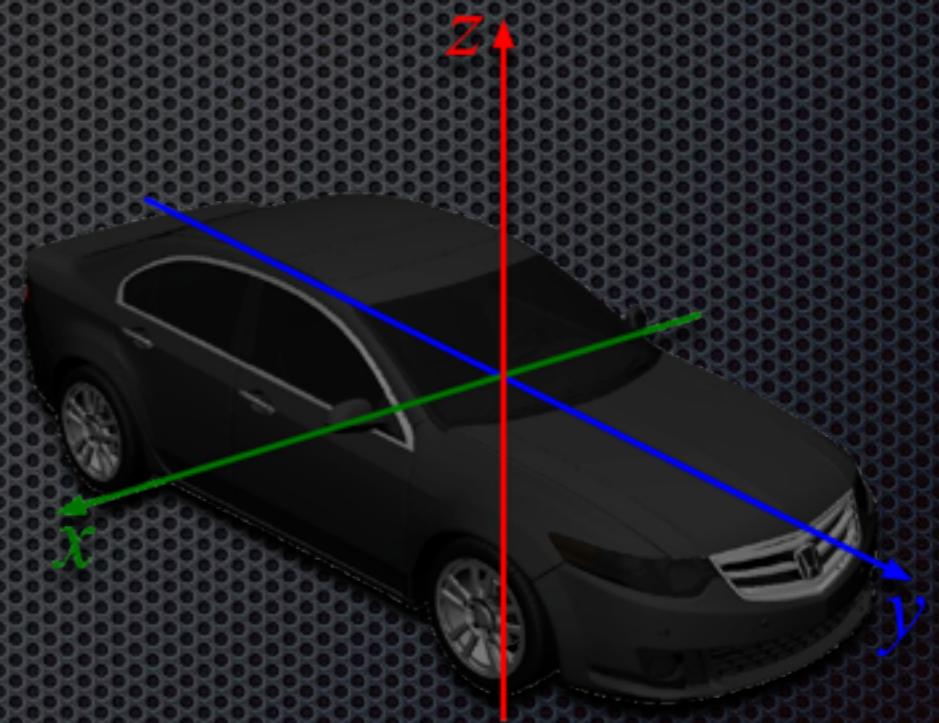
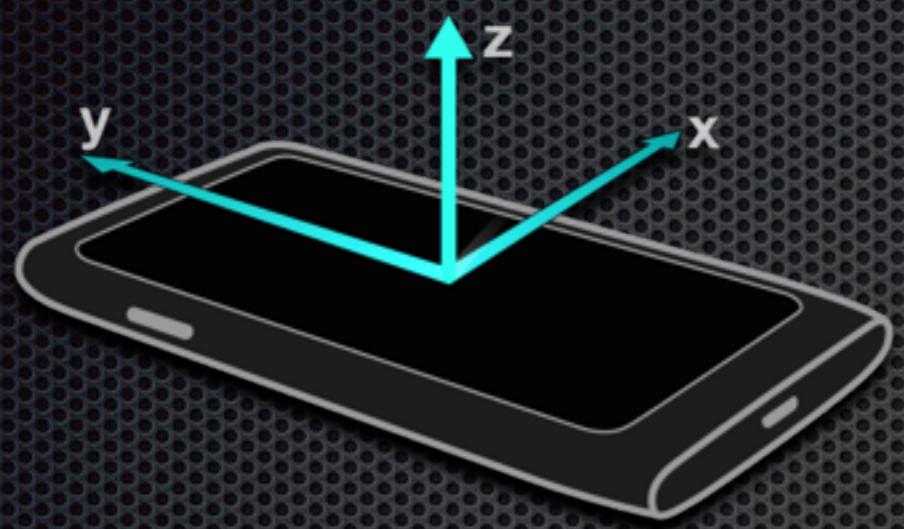
# Deviations

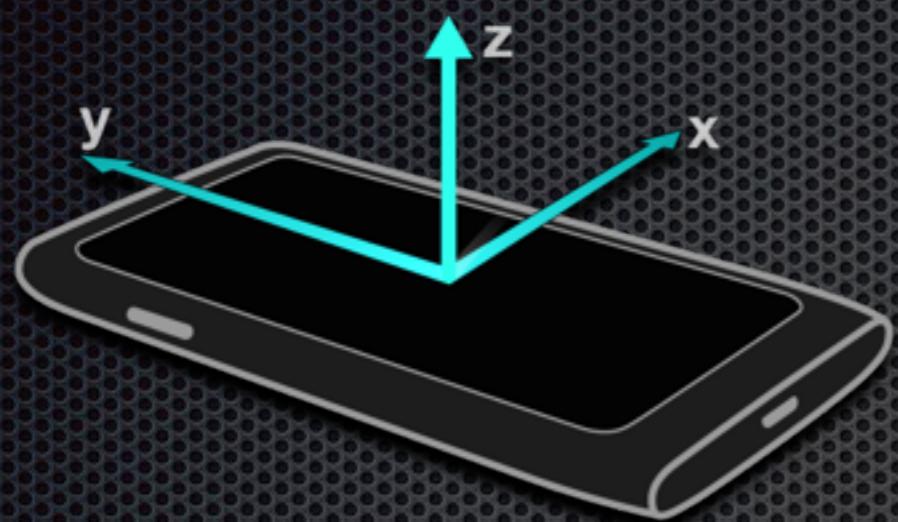
- User makes a turn too early
- User makes a turn too late
- User fails to make a turn and keeps driving

# 2 Driving Motion Detections

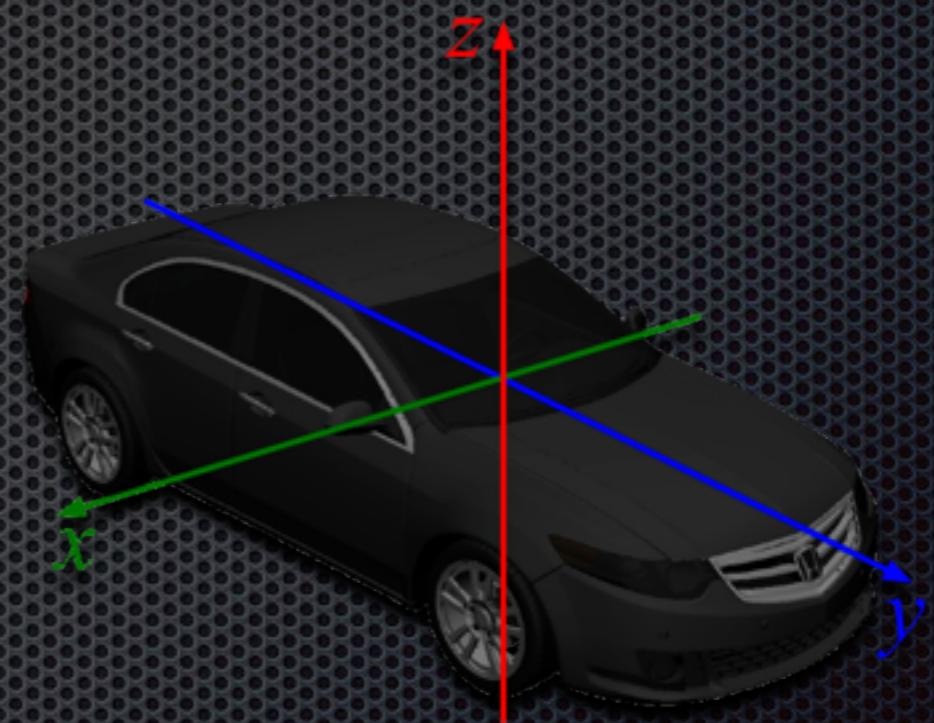
- Turn and Idle detections
- DecisionTree based classifiers
- ~99% accuracies for both

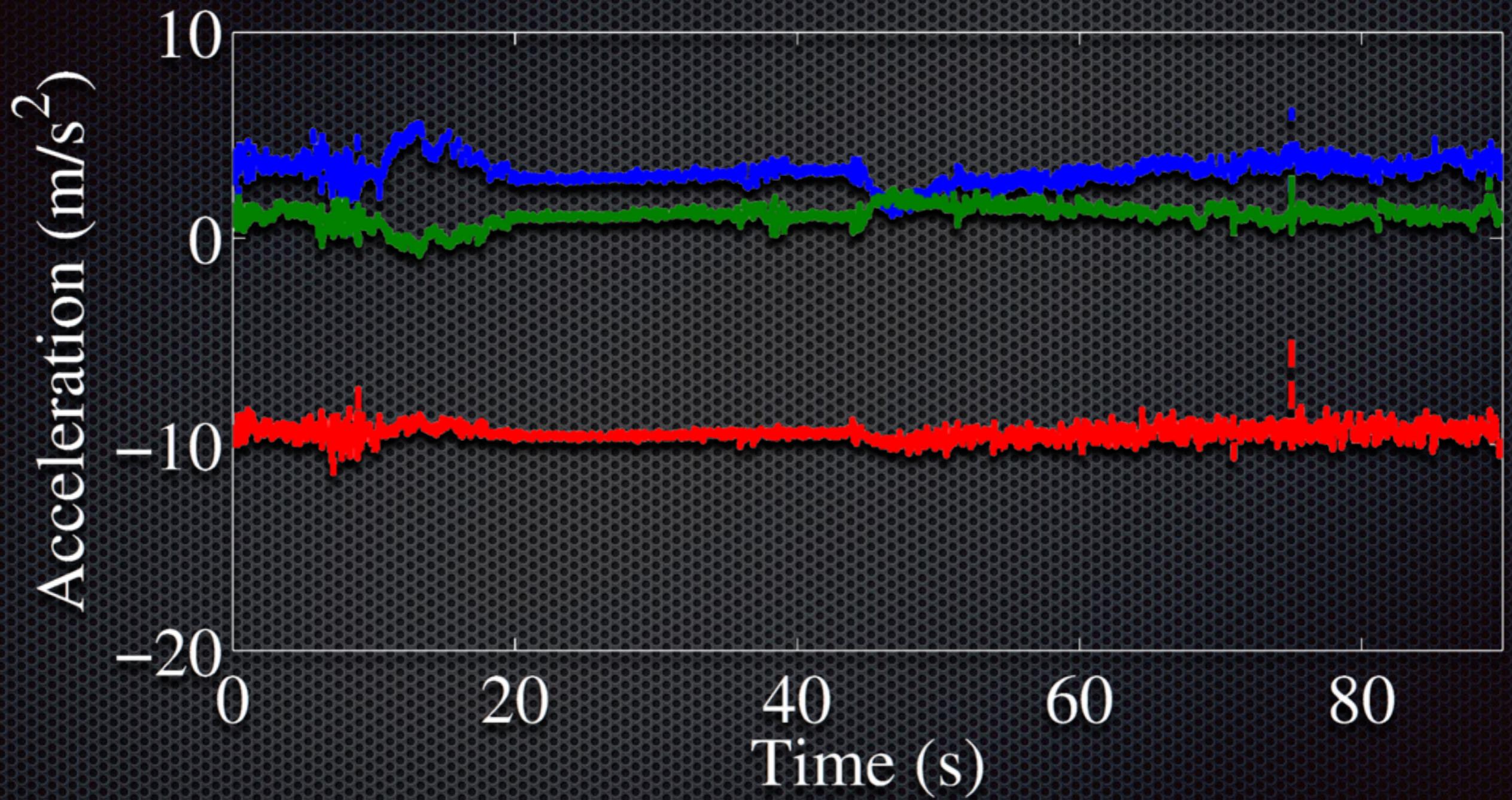
# Orientation?

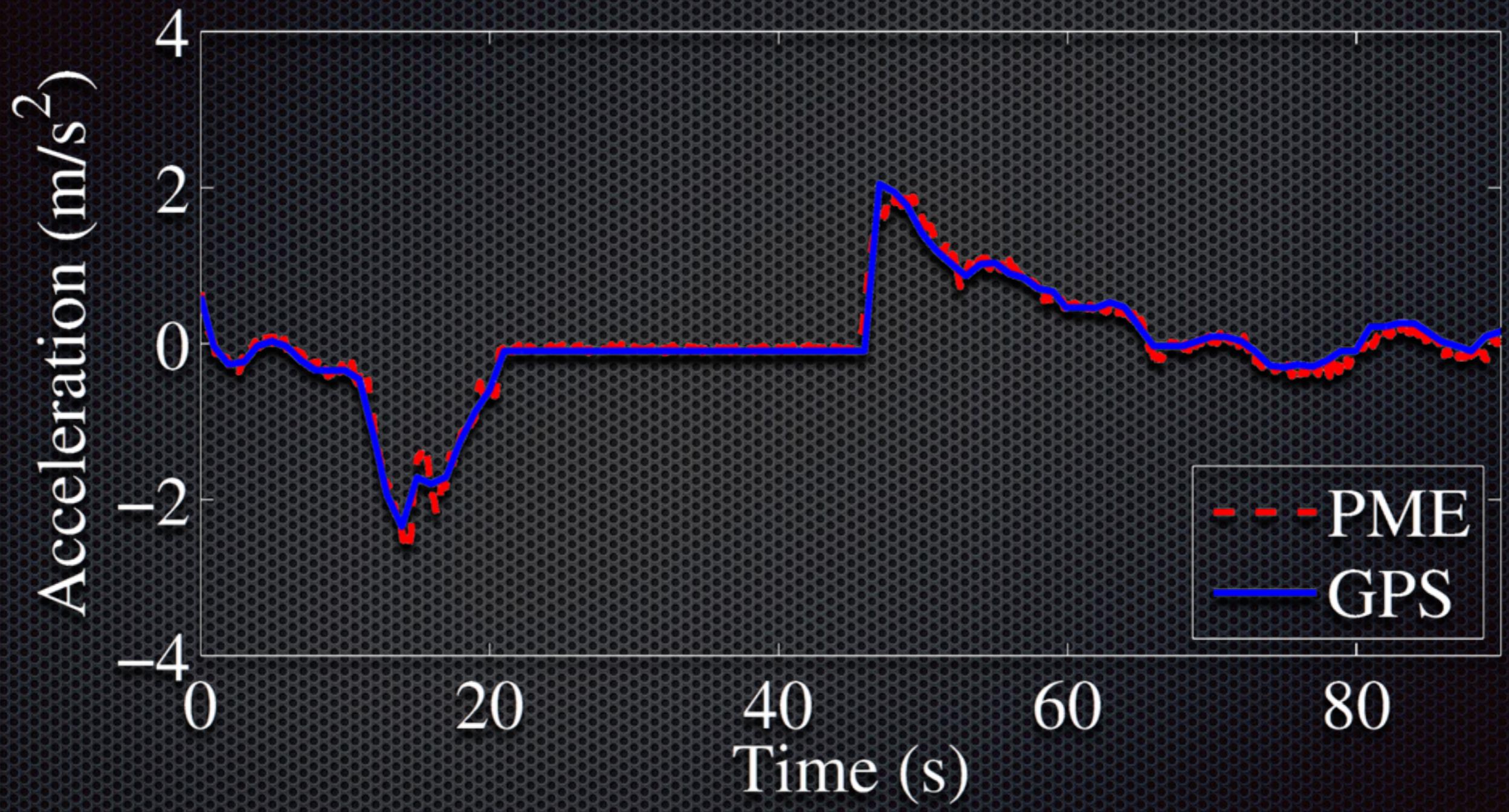




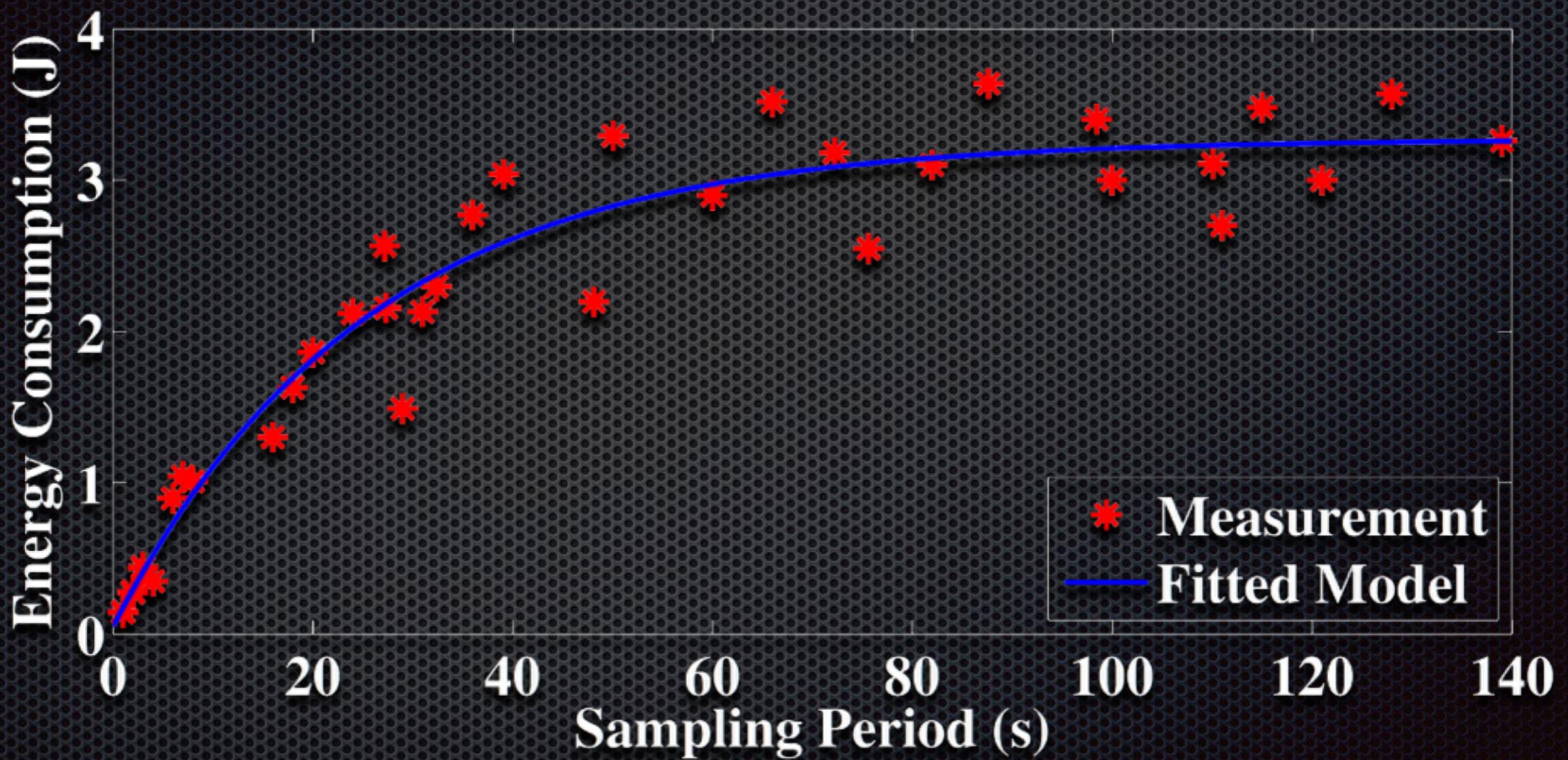
PME





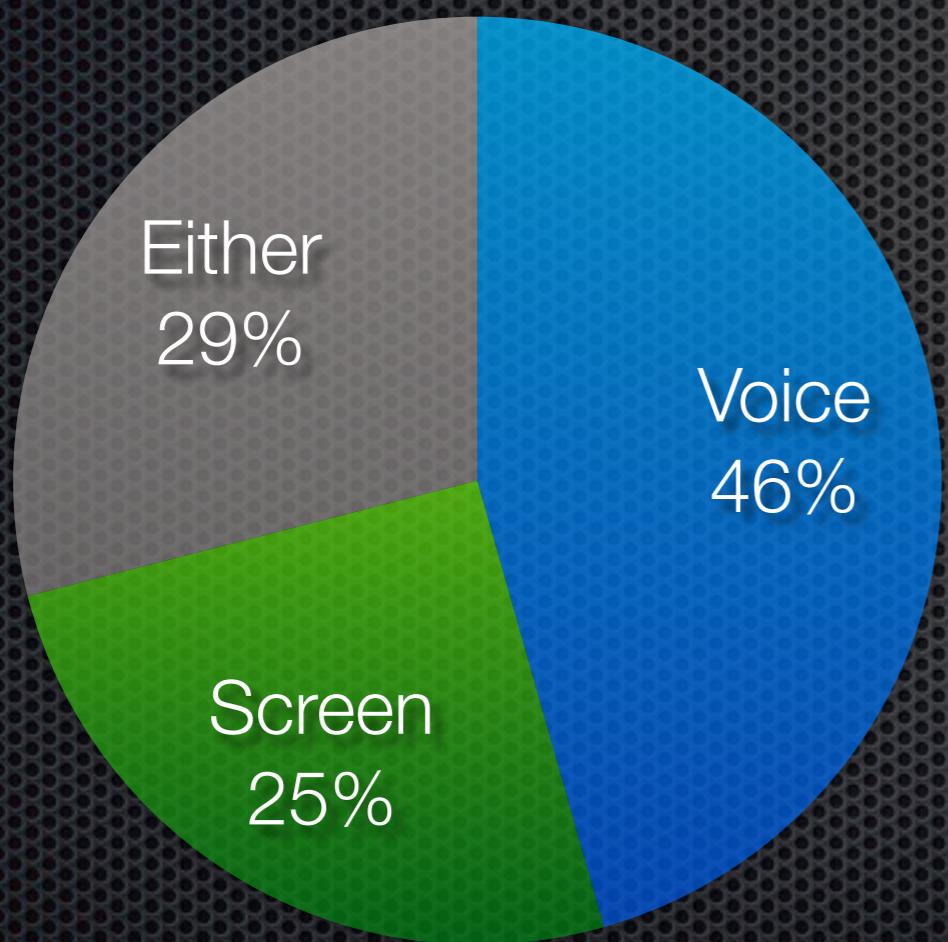


# GPS Energy Profiling

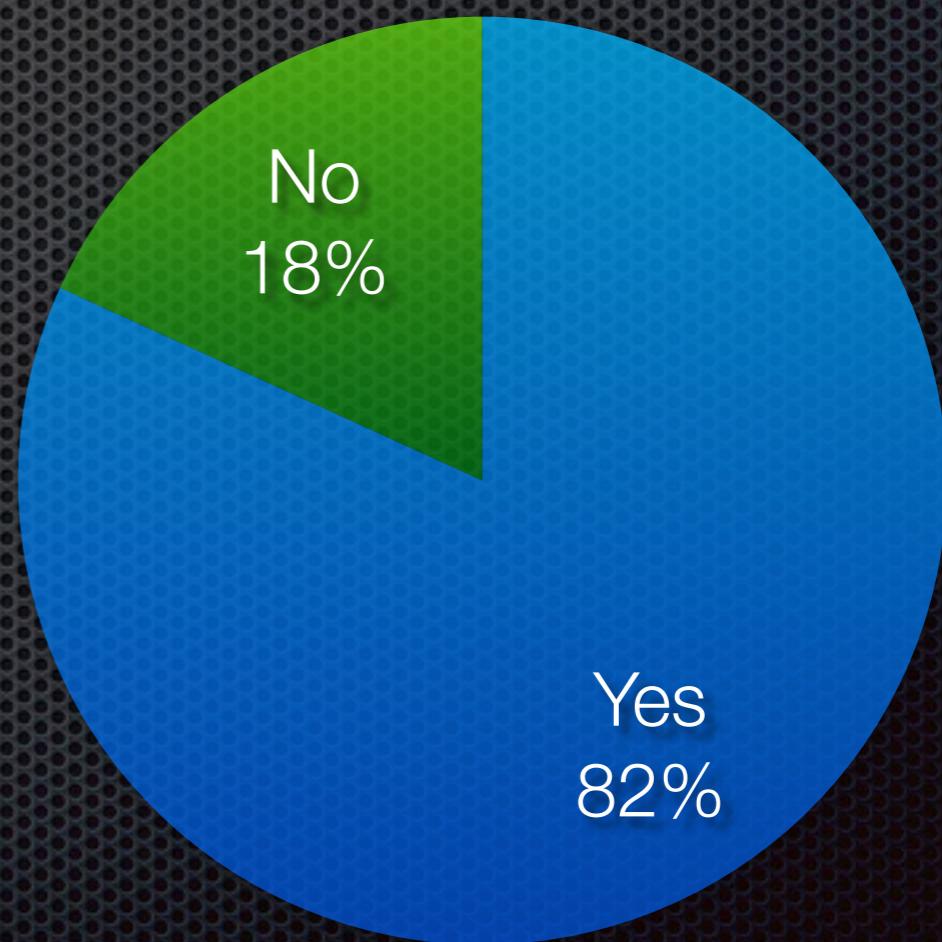


# Screen vs Voice Guidance?

Which do you think is more important for GPS navigation?



If battery is running low, would you be willing to rely just on voice guidance



# Phase II Screen-On e-CDF

