01-09-2016

* GUI
  + Brian, Jin
    - Receive GPS, magnetometer, and science data over UDP.
    - Send motor commands
  + Nathan
    - Receive camera feed with Python
  + Payal, Austin, Faith, Devin
    - Google Maps API
    - Map plotting coordinates (sprites w/ heading)
  + Ryan, Justin
    - Joysticks (Arm, Drive, Science, Cameras)
    - Intuitive Interface (Connect joysticks button, connect rover button)
* Rover
  + Ahmed
    - Script Motors
    - interface w/ sensors and send over UDP
  + Bryan
    - Interface with GPS & magnetometer. Send over UDP
  + Wendy, Maria, Alan
    - anti-skid w/ potentiometer limiting

01-26-2016

* GUI
  + Brian, Jin
    - Fixed bugs with entering coordinates. Object oriented.
  + Nathan, Sebastian, Felix
    - Python script that works. Buffer is set to 300 ms. Will try with two cameras.
  + Payal, Austin, Faith, Devin
    - Captured images and stitched together images. (600 x 600)px is the max image size. Mercator Projection to find coordinates on images. Give coordinates of center and a width and height.
  + Ryan, Justin
    - Just needs to implement UDP. All else is working.
* Rover
  + Ahmed
  + Bryan
    - Magnetometer is set. Sends a char array of headings. Will do the pH sensor next.
  + Wendy, Maria, Alan, Prerna
    - Working on turning speed. Trying to implement an exponential turning control.

01-26-2016

* GUI
  + Brian, Jin
    - Continuing coordinate implementation.
  + Nathan, Sebastian, Felix

* + Payal, Austin, Faith, Devin
  + George
  + Ryan, Justin
    - Will work on emergency buttons now.
    - GUI for joysticks is finished.
* Rover
  + Ahmed
  + Bryan, Abhishek
    - pH probe is finished.
    - Will try to get GPS coords over UDP with the ethernet library and use interrupts on the Arduino.
  + Wendy, Maria, Alan, Prerna
    - In the process of tuning the exponential.
    - Will implement an exponential controller for forward/backward speed.