

Assignment – 1 (Linear Algebra)

Q.1. Prove or disprove:

- (a). The set of all vectors (v_1, v_2, v_3) in \mathbb{R}^3 such that $v_1 + v_2 = 0$ is a subspace of \mathbb{R}^3 .
- (b). The set of all vectors (v_1, v_2, v_3, v_4) in \mathbb{R}^4 such that $v_1 - v_2 = 0$, $v_3 = 5v_1$, $v_4 = 0$ is a subspace of \mathbb{R}^4 .

Q.2. Are the following set of vectors linearly independent or dependent?

- (a). $(3, -2, 0, 4)$, $(5, 0, 0, 1)$, $(-6, 1, 0, 1)$, $(2, 0, 0, 3)$
- (b). $(3, 4, 7)$, $(2, 0, 3)$, $(8, 2, 3)$, $(5, 5, 6)$
- (c). $(1, 1, 0)$, $(1, 0, 0)$, $(1, 1, 1)$

Q.3. Find the rank and nullity of the following matrices

(a). $A = \begin{bmatrix} 8 & 2 & 5 \\ 16 & 6 & 29 \\ 4 & 0 & -7 \end{bmatrix}$ (b). $A = \begin{bmatrix} 8 & 0 & 4 \\ 0 & 2 & 0 \\ 4 & 0 & 2 \\ 0 & 4 & 0 \end{bmatrix}$ (c). $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \\ 4 & 5 & 6 & 7 \end{bmatrix}$

Q.4. Solve the following system of equations by using Gauss Elimination Method :

| | | |
|-------------------------|-----------------------|-----------------------------------|
| (a) $3.0x + 6.2y = 0.2$ | (b) $3x + 2y + z = 3$ | (c) $3x + 2y + 2z - 5w = 8$ |
| $2.1x + 8.5y = 4.3$ | $2x + y + z = 0$ | $0.6x + 1.5y + 1.5z - 5.4w = 2.7$ |
| | $6x + 2y + 4z = 6$ | $1.2x - 0.3y - 0.3z + 2.4w = 2.1$ |

Q.5. Determine the inverse of the following matrices by Gauss-Jordan Method :

(a). $A = \begin{bmatrix} 1 & 2 & 5 \\ 0 & -1 & 2 \\ 2 & 4 & 11 \end{bmatrix}$ (b). $A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 5 & 4 & 1 \end{bmatrix}$ (c). $A = \begin{bmatrix} 1 & 2 & -9 \\ -2 & -4 & 19 \\ 0 & -1 & 2 \end{bmatrix}$

Q.6. Apply the Gauss-Jacobi and Gauss-Seidel iteration (3 steps) to the following system, starting from (1,1,1)

$$\begin{array}{ll} \text{(a). } 10x + y + z = 6 & \text{(b). } 8x + 2y - z = 185.8 \\ x + 10y + z = 6 & x + 9y - 2z = 49.1 \\ x + y + 10z = 6 & x + y + 6z = -61.3 \end{array}$$

Q.7. Find the eigenvalues and eigenvectors of the following matrices:

$$\begin{array}{lll} \text{(a). } A = \begin{bmatrix} 5 & -2 \\ 9 & -6 \end{bmatrix} & \text{(b). } A = \begin{bmatrix} 4 & -2 & 3 \\ -2 & 1 & 6 \\ 1 & 2 & 2 \end{bmatrix} & \text{(c). } A = \begin{bmatrix} -3 & 0 & 4 & 2 \\ 0 & 1 & -2 & 4 \\ 2 & 4 & -1 & -2 \\ 0 & 2 & -2 & 3 \end{bmatrix} \end{array}$$

Q.8. Verify Cayley-Hamilton theorem for the following matrices:

$$\begin{array}{ll} \text{(a). } A = \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix}, & \text{(b). } A = \begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{bmatrix}. \end{array}$$

Q.9. Find the inverse of matrix A using Cayley-Hamilton's theorem:

$$\text{(a). } A = \begin{bmatrix} 5 & 3 \\ 3 & 2 \end{bmatrix}, \text{ (b). } A = \begin{bmatrix} 3 & 2 & 4 \\ 4 & 3 & 2 \\ 2 & 4 & 3 \end{bmatrix}, \text{ (c). } A = \begin{bmatrix} 7 & 2 & -2 \\ -6 & -1 & 2 \\ 6 & 2 & -1 \end{bmatrix}.$$

Q.10. Let $\hat{A} = P^{-1}AP$. Prove that A and \hat{A} have the same eigenvalues. Also, prove that if x is an eigenvector of A , then $y = P^{-1}x$ is an eigenvector of \hat{A} . Here, A and P are the following matrices.

$$\begin{array}{ll} \text{(a). } A = \begin{bmatrix} 3 & 4 \\ 4 & -3 \end{bmatrix}, P = \begin{bmatrix} 5 & 2 \\ 2 & 1 \end{bmatrix} & \text{(b). } A = \begin{bmatrix} 4 & 0 & 0 \\ 12 & -2 & 0 \\ 21 & -6 & 1 \end{bmatrix}, P = \begin{bmatrix} 4 & 0 & 6 \\ 0 & 2 & 0 \\ 6 & 0 & 10 \end{bmatrix}. \end{array}$$

Q.11. Diagonalize following matrices by using Similar Transformations:

$$\begin{array}{lll} \text{(a). } A = \begin{bmatrix} 3 & 2 \\ 2 & 6 \end{bmatrix}, & \text{(b). } A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 3 & 2 \\ 0 & 0 & 2 \end{bmatrix}, & \text{(c). } A = \begin{bmatrix} 3 & 10 & -15 \\ -18 & 39 & 9 \\ -24 & 40 & -15 \end{bmatrix}. \end{array}$$

Q.12 Which of the following are Linear Transformations:

(a) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (x + y, x)$

(b) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (xy, x)$

(c) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (x + 1, y + 2)$

(d) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(x, y, z) = (x + y + z, 2x + 3y + 4z)$

(e) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(x, y, z) = (|x|, y + z)$

(f) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(x, y) = (x + 3, 2y, x + y)$

(g) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(x, y, z) = (x + y, x - z, 2x - y + z)$